

CNC MELD/IS 600 Series MELD/IS 60/60S Series

PLC DEVELOPMENT SOFTWARE MANUAL (MELSEC TOOL SECTION)



MELSEC and MELDAS are the registered trademarks of Mitsubishi Electric Corporation.

Microsoft, Windows and Microsoft Windows NT are the registered trademarks of Microsoft Corporation in the United States and/or other countries.

Other company and product names herein may be the trademarks or registered trademarks of their respective owners.

INTRODUCTION

In the MELDAS600, 60/60S Series, the user PLC development environment is supported using MELSEC PLC development tool, which is Mitsubishi integrated FA software MELSOFT series (GX Developer), in addition to the conventional MELDAS PLC programming tool (PLC4B) and onboard ladder tool. This manual explains user PLC development environment using GX Developer, mainly usage specific to MELDAS.

Details described in this manual

A Items not described in this manual must be interpreted as "not possible".

▲ Some screens and functions may differ depending on the NC system or its version, and some functions may not be possible. Please confirm the specifications before use.

General precautions

Refer to the respective manuals for details of the MELDAS series PLCs and for details of various tools described in this manual. Refer to the MELSEC Series manual for details on the various tools and instructions for the MELSEC Series.

[MELDAS Series PLC related documents]

[MELSEC Series Software Package Manual]

GX Developer Version 8 Operating Manual (Startup	Section)	
GXDEV8-0-IN-E	13JU40	SH-080372E
GX Developer Version 8 Operating Manual		
GXDEV8-0-E	13JU41	SH-080373E
GX Converter Version 1 Operating Manual		
SW0D5-CNVW (OPE)-E	13J949	IB-080004E

(Caution)

- The version numbers are current as of the editing of this manual, but may be updated in the future.
- GX Developer Version 8 (Model SW8D5C-GPPW) is the new name of the old "Windows Version GPP Function Software package" (common name GPPW).

Precautions for Safety

Always read the specifications issued by the machine maker, this manual, related manuals and attached documents before installation, operation, programming, maintenance or inspection to ensure correct use.

Understand this numerical controller, safety items and cautions before using the unit. This manual ranks the safety precautions into "Danger", "Warning" and "Caution".



When the user may be subject to imminent fatalities or major injuries if handling is mistaken.

When the user may be subject to fatalities or major injuries if handling is mistaken.

When the user may be subject to bodily injury or when physical damage may occur if handling is mistaken.

Note that even items ranked as "A CAUTION", may lead to major results depending on the situation. In any case, important information that must always be observed is described.

Not applicable in this manual.

Not applicable in this manual.

1. Items related to product and manual

- ▲ For items described as "Restrictions" or "Usable State" in this manual, the instruction manual issued by the machine maker takes precedence over this manual.
- An effort has been made to describe special handling of this machine, but items that are not described must be interpreted as "not possible".
- ▲ This manual is written on the assumption that all option functions are added. Refer to the specifications issued by the machine maker before starting use.
- ▲ Refer to the Instruction Manual issued by each machine maker for details on each machine tool.

☆ Some screens and functions may differ depending on the NC system or its version, and some functions may not be possible. Please confirm the specifications before use.

2. Precautions for startup and maintenance

A Before starting program modification, forced output, RUN, STOP or similar operation during running, read the manual carefully and ensure safety fully. Not doing so can cause machine damage or accidents due to operation mistakes.

(Continued on next page)

3. Items related to program development

- Always observe the cautions before development to develop a program.
- ▲ If the data transferred does not follow the file name rule, the NC will mistake it for another data, resulting in unexpected operation, e.g. PLC program erasure.
- A Do not read a ladder file on which a conversion error occurred into the GX Developer side. The file may include unexpected contents to result an illegal operation.
- Multiply When an error occurred at GX Developer On-line function, the error message may not explain exactly the state in the CNC controller side. Always refer to the error list.

CONTENTS

1.	PLC DEVELOPMENT ENVIRONMENT	1
	1.1 System Configuration	
	1.2 Software Configuration	
	1.3 Outline of GX Developer Functions and List of Supported Functions	
	1.3.1 Function support conditions (general section)	
	1.3.2 Function support conditions (on-line section)	
	1.4 Memory Specifications	
	1.4.1 Memory configuration	
	1.4.2 PLC data storage method	
	1.4.3 Selecting the memory with GX Developer	.12
2.	SETUP	.14
	2.1 Setting up Each Tool	
	2.2 RS-232C Connection Procedures	
	2.3 Setting the CNC Parameters	
_		
3.	PLC PROGRAM DEVELOPMENT	
	3.1 User PLC (Ladder) Development Procedure	
	3.2 Precautions before Development	
	3.3 Newly Creating a PLC Program	
	3.4 Specifying the Connection Target	
	3.4.1 Operation procedure	
	3.5 Starting/Stopping the PLC of the CNC Controller	
	3.5.1 Operation procedure	.23
	3.6 Writing the PLC Program to the CNC Controller	
	3.6.1 Operation procedure	
	3.6.2 Operation to be performed at write error	
	6.6.3 How to confirm the error step number	
	3.7 Reading the PLC Program from the CNC Controller	
	3.7.1 Operation procedure	
	3.8 Verifying the PLC Programs	
	3.8.1 Operation procedure	
	3.9 Monitoring the PLC Program	
	3.9.1 Operation procedure	
	3.10 Using PLC4B Type PLC Programs	
	3.10.1 Development procedure	
	3.10.2 Starting GX Converter and specifying the file to be converted	
	3.10.3 Conversion format setting	.31

4.	PLC MESSAGE DEVELOPMENT	34
	4.1 Development Procedure	34
	4.1.1 Using a general text editor	35
	4.1.2 Entering messages directly from GX Developer	35
	4.2 Message Data Description Method	
	4.2.1 Description format	36
	4.2.2 Description method	37
	4.2.3 Precautions	
	4.3 Converting Data into GX Developer Format	
	4.3.1 Starting GX Converter and specifying the file to be converted	
	4.3.2 Conversion format setting	
	4.4 Entering/Editing Data Using GX Developer	
	4.4.1 Interlinear statement display using circuit display	
	4.4.2 Interlinear statement display using list display	
	4.4.3 Editing of integrated type interlinear statements	
	4.5 Writing to the CNC Controller	
	4.6 Reading and Verifying from the CNC Controller	
	4.6.1 Menu selection/screen operation	
	4.6.2 Message read format	45
5.	DEVICE COMMENT CREATION	46
	5.1 Development Procedure	46
	5.2 Description Method for Indirect Entry	47
	5.3 Converting Device Comments	
	5.3.1 Starting GX Converter and specifying the file to be converted	48
	5.3.2 Conversion format setting	48
c	RELATIONSHIPS BETWEEN GX DEVELOPER AND ONBOARD FUNCTIONS	E 4
0.	6.1 Function Differences	
	6.2 Specification Differences	
7.	PROCEDURE FOR WRITING PLC PROGRAMS, ETC. TO ROM	
	7.1 Data That Can Be Written to ROM	
	7.2 ROM Writing Operation Procedure	53
8.	LIST OF ERROR STATES	55

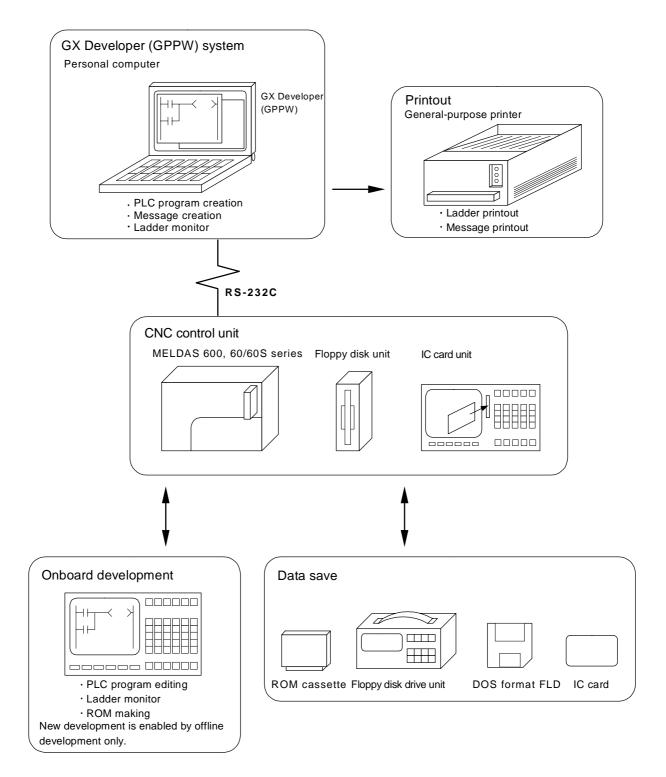
APPENDIX 1. OPERATION METHODS USING GPPQ	57
Appendix 1.1 GPPQ Function Outline and Functions Supported by the M600,	
M60/60S Series	
Appendix 1.1.1 Function support conditions (general section)	57
Appendix 1.1.2 Function support conditions (on-line section)	60
Appendix 1.2 Ladder Transfer to the CNC Controller	65
Appendix 1.2.1 Menu selection	65
Appendix 1.2.2 Screen operation	65
Appendix 1.2.3 Operation during a transfer error	66
Appendix 1.2.4 Error step No. confirmation method	66
Appendix 1.3 Ladder Read from the CNC Controller	67
Appendix 1.3.1 Menu selection	67
Appendix 1.3.2 Screen operation	67
Appendix 1.4 Ladder Comparison with CNC Controller	68
Appendix 1.4.1 Menu selection	
Appendix 1.4.2 Screen operation	68
Appendix 1.5 PLC-Related Data Development Procedure	69
Appendix 1.5.1 Conversion to GPPQ data	69
Appendix 1.5.2 Commercially available software QnA conversion setting	70
Appendix 1.5.3 Conversion execution	
Appendix 1.5.4 Operation with the GPPQ	71
Appendix 1.5.5 Transfer to the controller	
Appendix 1.5.6 Reading and comparing from the controller	
Appendix 1.6 Procedure for ROM Writing	75
Appendix 1.6.1 Procedure to write to ROM	75
Appendix 1.6.2 PLC data region formatting	76
Appendix 1.6.3 ROM writing from the GPPQ	76
APPENDIX 2. DIFFERENCES IN DEVELOPMENT ENVIRONMENT BETWEEN	
PLC4B AND M600, M60/60S	79
Appendix 2.1 Development Tools, etc.	
Appendix 2.2 Devices and Device Assignments	
Appendix 2.3 PLC Instructions	
Appendix 2.3.1 Instructions that cannot be handled with the GX Developer	
Appendix 2.3.2 Instructions with the format that differs from that of the	-
GX Developer	85
Appendix 2.3.3 Instructions that can be used with the GX Developer, but cannot	
be used by the M600, M60/60S	
APPENDIX 3. LIST OF INSTRUCTIONS USABLE WITH GX DEVELOPER	07
Appendix 3.1 Sequence Instructions	
Appendix 3.2 Comparison Operation Instructions	
Appendix 3.3 Application Instructions	.30

1. PLC DEVELOPMENT ENVIRONMENT

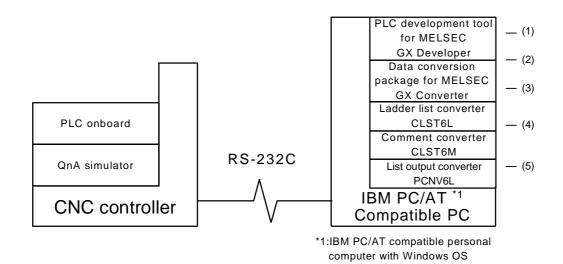
1.1 System Configuration

Most of the development work can be done by connecting a personal computer and a CNC unit by an RS-232C cable.

[Note] The supported peripheral devices and like change depending on the model.



1.2 Software Configuration



(1) GX Developer (PLC development software package)

GX Developer is a programming software package (model name: SW8D5C-GPPW) designed for Mitsubishi Electric's MELSEC series programmable logic controllers. By performing operations similar to those of the MELSEC series, you can develop user PLC ladders for the MELDAS series. Note that some functions specific to the "MELSEC series" may not be unavailable.

For MELDAS series ladder development, we recommend you to use GX Developer Version 4 (SW4D5C-GPPW) or later. For function details, refer to the Operating Manual supplied. The DOS version "GPPQ" (SW2IVD/NX-GPPQ GPP function software package) of this package is also usable. Refer to Appendix "OPERATION METHODS USING GPPQ" for details.

(2) GX Converter (data conversion software package)

The GX Converter is a tool that carries out data conversion of GX Developer data files and the following (Start up GX converter from the GX Developer menu as a add-on tool for GX Developer):

- Ladder list files and comment text files output by the CLST6L
- Alarms and operator messages created by the text editor

• Data files of commercially available spreadsheet software, word processors and editors This tool is a software package for various MELSEC support. GX Converter needs to be used with the versions following GX Developer Version 3 (SW3D5C-GPPW). Refer to the enclosed Operating Manual for function details.

The DOS version "CNVQ" (SW0IVD/NX-CNVQ data conversion software package) of this tool can also be used. Refer to Appendix "OPERATION METHODS USING GPPQ" for details.

(3) CLST6L (Ladder list converter)

This tool converts the user PLC ladder list data developed for the PLC4B to M600, M60/60S specification instructions and devices, and outputs the data in a ladder list format. The user PLC ladder developed in the PLC4B can be used for M600, M60/60S Series with the GX Developer by using the GX Converter to further convert the conversion results of this tool. This tool runs on Windows DOS.

(4) CLST6M (Device comment converter)

This tool outputs the contact/coil comment data of a user PLC ladder developed for the PLC4B in the text format of the M600, M60/M60S series device specifications. The contact/coil comment data developed in the PLC4B can be used with GX Developer by using GX Converter to further convert the conversion results of this tool. This tool runs on Windows DOS.

(5) PCNV6L (List output converter)

This tool outputs a MELDAS specification ladder printout image with cross information in a text format from the GX Developer specification ladder list and comment data. This tool runs on Windows DOS.

1.3 Outline of GX Developer Functions and List of Supported Functions

The GX Developer functions explained here are those supported by the M600, M60/60S Series in the "off-line functions" operated with the GX Developer independently and "on-line functions" carried out connected to the M600, M60/60S controller.

Refer to the enclosed Operating Manual for function details.

Refer to "APPENDIX 1. OPERATION METHODS USING GPPQ" for the GPPQ-specific functions and operations when the DOS version "GPPQ" (SW2IVD/NX-GPPQ GPP function software package) of this package is used.

1.3.1 Function support conditions (general section)

The following shows a list of GX Developer outline functions supported by the M600, M60/60S Series.

A \bigcirc mark indicates functions that can be used by the M600, M60/60S Series. An \times mark indicates that the function cannot be used because it is related to "MELSEC Series" characteristic functions. The function details during on-line are described in the next section.

Program type	Support	Remarks
Ladder	O	
List	O	
SFC	×	
MELSAP-L	×	
Function block	×	

Function	Menu	Sub menu	Support	Remarks
Project	New project		Ø	
	Open project		O	
	Close project		O	
	Save		O	
	Save as		O	
	Delete project		O	
	Verify		O	
	Сору		O	
	Edit Data	New	O	
		Сору	O	
		Delete	O	
		Rename	O	
	Change PLC type		Δ	Fixed Q4A
	Import file	Import from GPPQ format file	O	
		Import from GPPA format file	×	
		Import from FXGP(DOS) format file	×	
		Import from FXGP(WIN) format file	×	
		Import from TEXT ,CSV format file	O	
	Export file	Export to GPPQ format files	O	
		Export to GPPA format files	×	
		Export to FXGP(DOS) format file	×	
		Export to FXGP(WIN) format file	×	
		Export to TEXT ,CSV format file	Ø	

List of general section functions (2) O : Possible	, \triangle : Limitedly possible, \mathbf{X} : Not possible
--	---

Function	Menu	Sub menu	Support	Remarks
(Project)	Macro	Registration macros	Ø	
		Macro utilize	O	
		Delete macros	Ô	
		Macro reference path	Ô	
	Printer setup		Ô	
	Print		Ô	
	Start new GX Developer session		Ô	
	Exit GX Developer		Ô	
Edit	Undo		Ô	
	Restore after ladder conversion		Ô	
	Cut		O	
	Сору		O	
	Paste		O	
	Insert line		O	
	Delete line		O	1
	Insert row		O	
	Delete row		O	
	Insert NOP batch		O	
	Delete NOP batch		Ô	
	Draw line		Ô	
	Delete line		Ő	
	Change TC setting		Ő	
	Read mode		Ő	
	Write mode		Ő	
	Ladder symbol	Open contact	Ô	
		Close contact	Ô	
		Open branch	Ő	
		Close branch	Ő	
		Coil	Ő	
		Application instruction	0	
		Vertical line	Ő	
		Horizontal line	Ő	
		Delete vertical line	Ő	
		Delete horizontal line	Ő	
		Rising pulse	\triangle	Instead of DEFR
		Falling pulse	×	
		Rising pulse open branch	x	
		Falling pulse close branch	x	
		Invert operation results	×	
		Convert operation results to	X	
		rising pulse		
		Convert operation results to falling pulse	×	
	Documentation	Comment	Ø	
		Statement	Ő	1
		Note	Ő	1
		Statement/Note block edit	Ő	

Function	Menu	Sub menu	Support	Remarks
Find/Replace	Find device		O	
	Find instruction		O	
	Find step no.		Ø	
	Find character string		Ø	
	Find contact or coil		Ø	
	Replace device		O	
	Replace instruction		O	
	Change open/close contact		O	
	Replace character string		O	
	Replace unit head I/O No.		×	
	Replace statement/note type		Ô	
	List of used contact coils		Ø	
	List of used devices		Ø	
Convert	Convert		Ø	
	Convert (All programs being edited)		Ø	
	Convert (Online change)		×	
View	Comment		Ø	
	Statement		Õ	
	Note		Ô	
	Alias		Ō	
	Macro instruction format display		Ō	
	Comment format	4*8 characters	Ó	
		3*5 characters	Ô	
	Alias format display	Replace device name and display	Ô	
		Arrange with device and display	Ô	
	Toolbar		Ô	
	Status bar		Ô	
	Zoom	50%	Ô	
		75%	Ô	
		100%	O	
		150%	O	
		Specify	O	
		Auto	O	
	Project data list		Ø	
	Instruction list		O	
	Set the contact	9 contacts	Ø	
		11 contacts	Ô	
	Elapsed time		×	
Online	Refer to "List of on-line section functions"	Refer to "List of on-line section functions"		
Diagnostics	PLC diagnostics		×	
	MELSECNET(II)/10/H diagnostics		×	
	Ethernet diagnostics		×	
	CC-Link/CC-Link/LT diagnostics		x	
	System monitor		×	
	Online module change	1	×	

List of general section functions (3) \odot : Possible, \triangle : Limitedly possible, \mathbf{X} : Not possible

Function	Menu	Sub menu	Support	Remarks
Tools	Check program		O	1
	Merge data		O	
	Check parameter		×	
	Transfer ROM	Read	×	
		Write	×	
		Verify	×	
		Write to file	×	
	Delete unused comments		O	
	Clear all parameters		×	
	IC memory card	Read IC memory card	×	
		Write IC memory card	×	
		Read image data	×	
		Write image data	×	
	Start ladder logic test		×	
	Set TEL data	Connection	×	
		Disconnection	×	
		TEL data	×	
		AT command	×	
		Call book	×	
	Intelligent function utility	Utility list	×	
	Customize keys		O	
	Change display color		Ő	
	Options		$\overline{\Delta}$	Limited partly
	Create start-up setting file		0	
Vindow	Cascade		Ő	
	Tile vertically		Ő	
	Tile horizontally		Ő	
	Arrange icons		Ő	
	Close all windows		- Ŭ	
Help	CPU error		×	
	Special relay/register		×	
	Key operation list		0	1
	Product information		0	
	Connect to MELFANSweb		0	

List of general section functions (4) \odot : Possible, \triangle : Limitedly possible, \mathbf{x} : Not possible

1.3.2 Function support conditions (on-line section)

The following shows a list of GX Developer on-line functions supported by the M600, M60/60S Series.

A \bigcirc mark indicates functions that can currently be used by the M600, M60/60S Series. An \times mark indicates that the function cannot be used because it is related to "MELSEC Series" characteristic functions.

Menu	Sub menu	Detailed function	Support	Remarks
Transfer setup		PC side I/F	O	
		PLC side I/F	Δ	Only for QnACPU
		Other station	×	
		Network route	×	
		Co-existence network	×	
		route		
Read from PLC		Target memory	O	
		Title	O	
		File selection	O	
		Device data	×	
		Program	×	
		Common	×	
		Local	×	
		Refresh view	O	
		Free space volume	O	
		Create title	×	
Write to PLC		Target memory	\triangle	
		Title	O	
		File selection	Ô	
		Device data	×	
		Program	×	
		Common	×	
		Local	×	
		Free space volume	O	
		Create title	×	
Verify with PLC		Target memory	O	
		Title	O	
		File selection	O	
		Program	×	
		Refresh view	O	
		Free space volume	O	
		Create title	×	
Write to PLC (Flash ROM)	Write the program memory to ROM		×	
	Write to PLC (Flash ROM)		×	
Delete PLC data	, ,	Target memory	O	
		Title	0	
		File selection	Ō	
		Refresh view	Ō	
		Free space volume	Õ	
		Create title	×	
Change PLC data attributes			×	
PLC user data	Read PLC user data		×	
	Write PLC user data		×	
	Delete PLC user data	1	×	

List of on-line section functions (1)	\bigcirc : Possible, \triangle : Lin	nitedly possible, $ imes$: N	lot possible

Menu	Sub menu	Detailed function	Support	Remarks
Ionitor	Monitor mode	ON/OFF state	Ø	
		Scan time display	X	
		CPU state display	O	
	Monitor [Write mode]		X	
	Start monitor		O	
	[All windows]			
	Stop monitor [All windows]		O	
	[All windows] Start monitor		0	
	Stop monitor		0	
	Change current value		0	
	monitor [Decimal]		_	
	Change current value monitor [Hexadecimal]		O	
	Local device monitor			
	Device batch	Device	Ô	
		Connect	O	
		Coil	O	
		Setting value	O	
		Current value	Ô	
		Monitor format : Bit & word	Ô	
		Monitor format : Bit	O	
		Monitor format : word	O	
		Display : 16bit integer	O	
		Display : 32bit integer	O	
		Display : Real number	×	
		Display : ASCII character	×	
		Value : DEC	O	
		Value : HEX	O	
		T/C set value Reference program	Ø	
		Device test	0	
	Entry data monitor	Device	O	
		ON/OFF/Current	O	
		Setting value	0	
		Connect	O	
		Coil	O	
		Display : 16bit integer	Ô	
		Display : 32bit integer	Ô	
		Display : Real number	X	
		Display : ASCII character	×	
		Value : DEC	O	
		Value : HEX	O	
		T/C setting value, Local label Reference program	Ø	
		Device test	0	
	Buffer memory batch		X	
	Monitor condition setup	Device	0	
		Step No.	Ő	
	Monitor stop condition setup	Device	0	
		Step No.	0	
	Program monitor list	· · · · · · · · · · · · · · · · · · ·	×	
	Interrupt program monitor list		×	
	Scan time measurement		×	
	Entry ladder monitor		O	
	Delete all entry ladder		0	

List of on-line section functions (2) \odot : Possible, \triangle : Limitedly possible, \mathbf{x} : Not possible

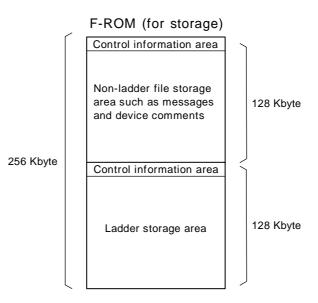
Menu	Sub menu	Detailed function	Support	Remarks
Debug	Device test	FORCE ON	O	
-		FORCE OFF	Ô	
		Toggle force	Ô	
		Device	Ô	
		Buffer memory	×	
	Forced input output registration/cancellation		×	
	Debug		×	
	Skip execution		×	
	Partial execution		×	
	Step execution		×	
Trace	Sampling trace		×	
Remote operation		PLC status	O	
		RUN	O	
		STOP	O	
		PAUSE	×	
		Latch clear	×	
		STEP-RUN	×	
		Reset	×	
		Operation during RUN, STEP-RUN	×	
		Specify execution destination	×	
Keyword setup	Register		×	
	Delete		×	
	Disable		×	
Clear PLC memory			×	
Format PLC memory		Target memory	Δ	Only internal RAM other than ladder storage area.
		Format Type	×	
Arrange PLC memory			×	
Set time		YY MM DD Hr. Min. Sec.	O	
		Day of week	×	
		Specify execution destination	×	

List of on-line section functions (3) \odot : Possible, \triangle : Limitedly possible, \mathbf{x} : Not possible

1.4 Memory Specifications

1.4.1 Memory configuration

The M600, M60/60S series stores PLC data onto flash ROM (hereafter abbreviated to the F-ROM). The following shows the storage area structure.

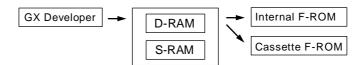


1.4.2 PLC data storage method

The PLC data transferred from GX Developer are stored in either of the following two storage methods, which differs depending on the model.

(1) Two-step storage method (M600 series)

As for the transferred data, the PLC ladder code is first stored into the nonvolatile RAM area (hereafter abbreviated to the S-RAM) designed for execution. The non-ladder PLC data are stored into the normal RAM area (hereafter abbreviated to the D-RAM). Write them to the F-ROM on the CNC controller side I/O screen. At power-ON of the CNC controller, the data are transferred from the F-ROM to the S-RAM and D-RAM areas, where they will be executed.



(2) Direct storage method (M60/60S series)

The transferred data are stored into the F-ROM area designed for both storage and execution. They can also be copied to the cassette F-ROM area for maintenance purpose.

1.4.3 Selecting the memory with GX Developer

(1) Areas that can be selected on GX Developer

The following table indicates the storage areas that can be selected for the online functions (Write to PLC, Read from PLC, Verify with PLC) of GX Developer.

Function	M600 series	M60/60S series
Write to PLC	S-RAM	Internal F-ROM
Read from PLC, Verify with PLC	S-RAM Internal F-ROM Cassette F-ROM	Internal F-ROM

(2) Display of storage area on GX Developer

Any of the storage areas that can be selected for the online functions (Write to PLC, Read from PLC, Verify with PLC) of GX Developer can be specified as a [Target memory] item on the corresponding operation screen.

Also, pressing the [Title] button displays the comment of that storage area if PLC data exists. It is not displayed if the storage memory is not fitted or the data does not exist.

Further, pressing the [Free space volume] button displays [Total free space volume] and [Largest continuous volume] of the selected area.

Write to PLC	x
Connecting interface COM1 PLC Connection Network No Station No. Host PLC type Q4A Target memory PLC RAM/Device memory Title File selection Device data Program Common Local Param+Prog Select all Cancel all selections Program Pogram Program Device comment Parameter PLC/Network PLC/Network	Execute Close Related functions Transfer setup Keyword setup Remote operation Clear PLC memory
File register Whole range Range specification ZR 0 - 32767	Format PLC memory Arrange PLC memory Create title
Free space volume Largest contiguous Total free space volume Bytes volume	Bytes

Some storage areas displayed as the target memory differ from the actual storage areas of the CNC controller. The following tables indicates the relationships between the [Target memory] items and storage areas.

Table	1.4.3.1	M600	series

Screen indication	Meaning in M600 series	Title indication	Free area indication
Internal RAM	Internal S-RAM (ladder program)	ON BOARD S-RAM + (D-RAM)	Target : All storage areas of Internal RAM
IC Card A[RAM]	Internal D-RAM (non-ladder data)	ON BOARD D-RAM	Target : Non-ladder file storage area
IC Card A[ROM]	Internal F-ROM	ON BOARD F-ROM	Target : All storage areas of Internal F-ROM
IC Card B[RAM]	Not used		
IC Card B[ROM]	Cassette F-ROM	ADD ON F-ROM	Target : All storage areas of cassette F-ROM

Table 1.4.3.2 M60/60S series

Screen indication	Meaning in M60/60S series	Title indication	Free area indication
Internal RAM/	Internal F-ROM	ON BOARD F-ROM	Target : All storage areas
Device memory			of Internal F-ROM
IC Card A[RAM]	Not used		
IC Card A[ROM]	Not used		
IC Card B[RAM]	Not used		
IC Card B[ROM]	Not used		

2. SETUP

2.1 Setting up Each Tool

In the M600 M60/60S Series PLC development environment, it is assumed that the various tools are used with an IBM PC/AT compatible personal computer. Prepare each tool so that it is IBM PC/AT compatible personal computer.

Refer to the enclosed Operating Manual (Startup) and Operating Manual for the setup and start procedures of each tool.

2.2 RS-232C Connection Procedures

The serial port connected with the CNC controller differs depending on the model. Also, it may require a special branch cable. Refer to the connection manual of that model.

Between the IBM PC/AT compatible personal computer that uses GX Developer and the CNC controller, use an RS-232C serial cable equivalent to the one shown below in the RS-232C connection diagram.

[Note]

The cables given in the connection diagrams of the GX Developer Operating Manual cannot be used.

Settings such as the GPPW communication speed are not required on the NC side.

NC side (25-pin D-SU	B)			Personal mputer side -pin D-SUB)
Signal name	Pin No.	Cable connection and signal direction	Pin No.	Signal name
CD	8		1	DC
SD	2		2	RD
RD	3	•	3	SD
DR (DSR)	6	•	4	ER (DTR)
SG	7	\longleftrightarrow	5	SG
ER (DTR)	20		6	DR (DSR)
CS (CTS)	5	←───	7	RS (RTS)
RS (RTS)	4		8	CS (CTS)
	22		9	RI

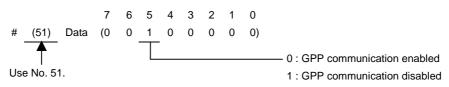
* The above shows a general RS-CS method connection format.

* The pin Nos. of dotted lines are not used.

2.3 Setting the CNC Parameters

Each model of the M600, M60/60S series has bit selection parameters related to GX Developer. If an appropriate value is not set in the parameters, an error will occur in communication with GX Developer.

(1) M600M series



[Reference] #51 corresponds to the low side of the file register R5025.

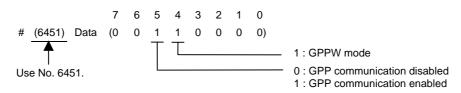


The serial port is used for communication with GX Developer. (This serial port cannot be used concurrently with the other function.)

<u>Bit 5 = 1</u>

The serial port is not used for communication with GX Developer. (When the serial port is used for another function)

(2) M600L series



[Reference] #6451 corresponds to the low side of the file register R2925.

<u>Bit 4 = 1</u>

The PLC development environment of GX Developer is used.

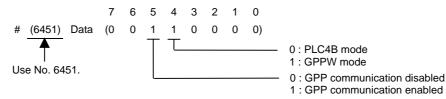
<u>Bit 5 = 0</u>

The serial port is not used for communication with GX Developer. (When the serial port is used for another function)

<u>Bit 5 = 1</u>

The serial port is used for communication with GX Developer. (This serial port cannot be used concurrently with the other function.)

(3) M60/60S series



[Reference] #6451 corresponds to the low side of the file register R2925.

(a) PLC environment selection parameter

Choose the PLC development environment. Independently of the setting of this bit, the currently stored ladder of either format operates.

Note that the onboard function is inactive if the format of the currently stored ladder differs from the environment selected here.

$$Bit 4 = 0$$

The PLC development environment of PLC4B is used.

The PLC development environment of GX Developer is used.

(b) GPPW serial port use selection parameter

When using the PLC development environment of GX Developer, choose whether the serial port used for communication with GX Developer will be used or not.

<u>Bit 5 = 0</u>

The serial port is not used for communication with GX Developer. (When the serial port is used for another function)

<u>Bit 5 = 1</u>

The serial port is used for communication with GX Developer.

At this time, the onboard function is not started if bit 4 = 1.

When the GPPW serial port use selection parameter is set to "1" (enabled),

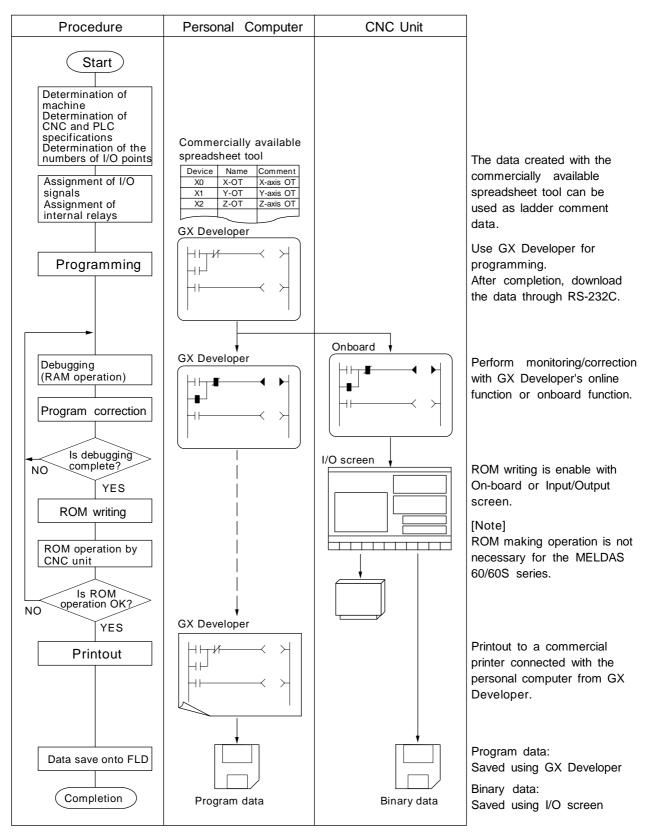
GPPW occupies the communication so communication (input/output) other than GPPW cannot be used.

3. PLC PROGRAM DEVELOPMENT

This chapter mainly describes MELDAS-specific usage about the PLC program development procedure.

3.1 User PLC (Ladder) Development Procedure

The following indicates a procedure for creating a general user PLC ladder.

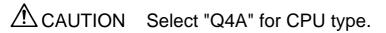


3.2 Precautions before Development

Pay careful attention to the following items before developing ladder programs using the GX Developer.

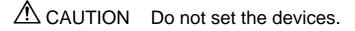
(1) PLC Type Selection

The PLC type must be set when newly creating programs, etc. Select the following CPU type when requested to select the PLC type by the GX Developer. An error will occur during transfer of the ladder program to the CNC controller if another PLC type is selected.



(2) Device Setting

Do not set the devices when developing the ladder program for the CNC controller. Develop the program with the device settings (No. of points, etc.) left at their default values applied when GX Developer was started. The ladder program cannot be transferred to the CNC controller normally when it is developed with settings other than the default values.



(3) PLC Instructions

MELSEC-specific PLC instructions cannot be used in the ladder program development for the CNC controller. Only PLC instructions and formats in PLC programming manual can be used. The format, etc., are changed with some instructions. Refer to "Appendix 2. DIFFERENCES IN DEVELOPMENT ENVIRONMENT BETWEEN PLC4B AND M600, M60/60S" for details.

\triangle CAUTION MELSEC-specific PLC instructions cannot be used.

(4) Label at the beginning of ladder program

In a MELDAS ladder program, a processing unit is differentiated by specifying a reserved label number at the beginning of processing. There are the following different processing units. (Since programmable processings are changed depending on the model, refer to the PLC programming manual of that model.)

P251 : PLC high-speed processing program starting label

P252 : PLC main processing program starting label

P253 : Initial processing program starting label

If only the PLC main processing is to be performed, do not omit but describe the above label at the beginning of a ladder program. Unless the label is described, normal RUN cannot be performed.

 \triangle CAUTION Specify a label at the beginning of a ladder program.

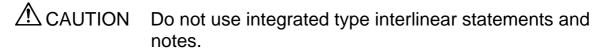
(5) Statements and notes

GX Developer allows a ladder program to be commented (with interlinear statements and notes). They are available in two types: integrated and peripheral.

Integrated type : Can be downloaded together with a ladder program to the CNC controller.

Peripheral type : Cannot be downloaded.

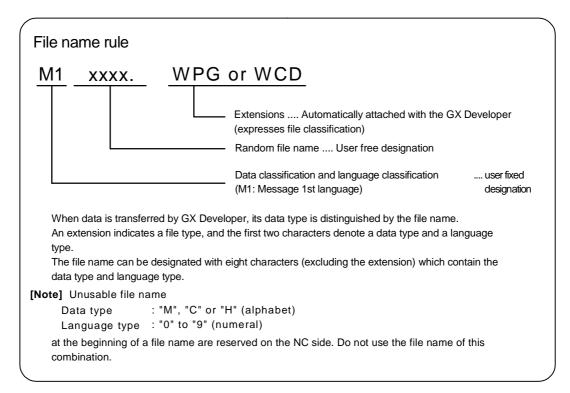
The integrated type cannot be used with the M600, M60/60S series. If it is used, a ladder program cannot be transferred to the CNC controller properly.



(6) File Name

Inside the M600, M60/60S series, PLC-related data are controlled and stored in the following categories. Therefore, they are also developed in the same categories.

If the data transferred does not follow the file name rule, the NC will mistake it for another data, resulting in unexpected operation, e.g. PLC program erasure.



	Related data classification	File name (GX Developer)	Remarks
1 2	PLC program (ladder) PLC program comment	zzzzzz.WPG zzzzz.WCD	PLC ladder code Comment data for GX Developer
3	Message 1st language	M1xxxx.WPG	1st language for alarm/operator messages, PLC switches, tool registration comments/load meter comments
4	Message 2nd language	M2xxxx.WPG	Same as above (2nd language data)

List of PLC related data

(a) PLC program (ladder)

- Ladder program developed using GX Developer.
- Only one file can be stored in the NC.

(b) PLC program comment

- Program comment for GX Developer display
- Only one file can be stored in the NC with the same file name as the ladder program.
- A device comment (32 characters) and a device name (10 characters) can be defined for each device.
- Stored mainly when it is read to GX Developer and used as a comment.

(c) Message 1st language, (d) Message 2nd language

- Alarm message/operator message/PLC switch/comment message data.
- One 1st language file and one 2nd language file can be stored in the NC.
- The messages can be handled and edited as "integrated type interlinear statements" by GX Developer.
- The maximum message length and the number of messages can be specified for each message type.

3.3 Newly Creating a PLC Program

The ladder program is newly created with GX Developer. Refer to the Operating Manual for details on newly creating a program.

3.4 Specifying the Connection Target

You must specify the connection target before performing online operations from GX Developer to the CNC controller.

3.4.1 Operation procedure

Perform the following operation from GX Developer to start the setting screen.

[Online] \rightarrow [Transfer setup]

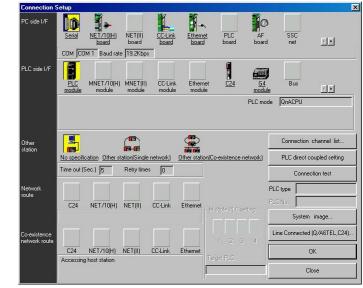
Set only the following items. Leave the other items unchanged from the initial values.

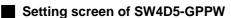
(1) Personal computer side

Interface	: [Serial interface]
Serial port name	: [COM1] or [COM2]
Baudrate	: [19.2Kbps]

(2) PLC side

Interface : [CPU unit]





3.5 Starting/Stopping the PLC of the CNC Controller

Before writing a PLC program, you must stop the PLC of the CNC controller.

3.5.1 Operation procedure

Perform the following operation from GX Developer to start the operation screen.

 $[Online] \rightarrow [Remote operation] \text{ or } Alt + 6$

On the following screen, set "STOP" or "RUN" in the [PLC] part under [Operation] and click [Execute]. The current status is displayed in [PLC status] under [Connection target information].

Remote operation		
Connection target information		
Connection interface COM1	<> PLC module	
Target PLC Network, No.	Station No. Host PLC type Q4A	
PLC status STOP Mer	mory card information	
Operation	Specify execution destination	
PLC STOP	Currently specified station	
C Extract memory card	C All stations	
Coperation during RUN, STEP-RUN	C Specific group	
Device Do not clear	Specify execution unit	lte
Signal flow Save 💌	1 Board No. Close	

[Note] Operations other than RUN and STOP are not possible.

The operation is completed when the following dialog appears. Click [OK]. The status after completion appears in [PLC status] on the remote operation screen displayed behind. If the status does not change, check whether an alarm is displayed or not on the CNC controller side.

MELSOF	T series GX Developer	\times
•	Completed.	
	(OK)	

3.6 Writing the PLC Program to the CNC Controller

The following indicates how to write ladders from GX Developer to the CNC controller (especially the restrictions and M600, M60/60S series-specific operations).

3.6.1 Operation procedure

Perform the following operation from GX Developer to start the operation screen.

[Online] \rightarrow [Write to PLC]

On the following screen, choose the ladder file to be written from the [File selection] tab and click [Execute].

You can command RUN/STOP of the PLC using [Remote operation] under [Related functions].

Write to PLC	×
Connecting interface COM1 <-> PLC module PLC Connection Network No. 7 Station No. Host PLC type Q4A Target memory PLC RAM/Device memory Title File selection Device data Program Common Local Param+Prog Select all Cancel all selections	Execute Close
	Related functions Transfer setup Keyword setup Remote operation Clear PLC memory
File register Image Image </td <td>Format PLC memory Arrange PLC memory Create title</td>	Format PLC memory Arrange PLC memory Create title
Free space volume Largest contiguous volume Total free space volume	Bytes

[Note] As [Target memory], only [PLC RAM/Device memory] is valid. Do not set the other tabs ([Device data], [Program], [Common], [Local]) than [File selection].

3.6.2 Operation to be performed at write error

As soon as a ladder is written from GX Developer to the CNC controller, the CNC controller converts it into the CNC-specific ladder machine code. A conversion error occurs if any of the devices and instruction formats not supported by the M600, M60/60S series is used. At a conversion error, the CNC side ladder machine code is converted into the "NOP code", the ladder up to the last step is transferred, and the following dialog is then displayed on the GX Developer screen.



When the file that resulted in a conversion error is displayed with the [File selection] tab of the [Read from PLC] screen, the following warning appears in the title field.

Read from PLC	×
Connecting interface COM1 <-> PLC module PLC Connection Network No. 0 Station No. Host PLC type 044.	
Target memory PLC FIAM/Device memory Title File selection Device data Program Common Local	Execute
Param+Prog Cancel all selections Device data MAIN	Close
Program LDTEST ** WARNING : Checksum ERROR!! ** 02/0 Device memory Device data Image: Device data Image: Device data	Related functions Transfer setup Keyword setup Remote operation Clear PLC memory Format PLC memory Arrange PLC memory Create title
Free space volume Largest contiguous Volume Total free space Volume Volume Volume	Bytes

"** WARNING Checksum ERROR!! **"

If you execute RUN the PLC as-is, an alarm occurs on the CNC side and the PLC does not RUN.

Do not read a ladder file on which a conversion error occurred into the GX Developer side. The file may include unexpected contents to result an illegal operation.

3.6.3 How to confirm the error step number

The PLC verification function can be used to confirm the error step. Executing verification with PLC displays mismatches as in the following example. For details of the PLC verification function, refer to "3.8 Verifying the PLC Programs".

Following example shows the step where CNC controller outputs a conversion error because NOP instructions mismatched between CNC and GX Developer.

Double-click the mismatch to display and to edit the corresponding part of the GX Developer side. </Nemory> indicates the GX Developer side, and <PLC> the CNC controller side.

Princt End/Banlace Convert Vi	en Dirite Exposition Look Window Help
Program *	
×	Verify results Program
TEST TEST Project Program	[PLC verify: Program]
Parameter	Verify source Project name -C:\NELSEC\TEST
Device memory Device init	Data name -LDTEST Verify destination
- Concent	Project name - none Data name -LDTEST
1	<pre></pre> (Nenory)
1	Step Instruction Step Instruction
1	6895 AND= R2500 K44 6895 NOP
1	6983 + K10080 D1822 D643 6981 NOP
	2 items unmatched.
1	
1	
1	
1	
1	
1	GX Developer side CNC controller side
1	
1	
1	
1	
1	
Project	
Deady	Q44 Host station NUM

3.7 Reading the PLC Program from the CNC Controller

The following indicates how to read a ladder from the CNC controller to GX Developer.

3.7.1 Operation procedure

Perform the following operation from GX Developer to start the operation screen.

[Online] \rightarrow [Read from PLC]

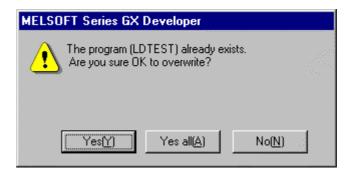
On the following screen, choose the ladder file to be read from the [File selection] tab, and click [Execute].

Read from PLC	×
Connecting interface COM1 <> PLC modu PLC Connection Network No. Station No. Host PLC type Q4A Target memory PLC RAM/Device memory Title	
File selection Device data Program Common Local	Execute
Param+Prog Cancel all selections Device data MAIN	Close
Program	
LDTEST TEST LADDER 02/01/22 13	····
	- Related functions
	Transfer setup
	Keyword setup
	Remote operation
	Clear PLC memory
- File register	Format PLC memory
Whole range	Arrange PLC memory
Refresh view C Range specification ZR 0 32767	Create title
Largest contiguous Total free space	
Free space volume volume Bytes volume	e Bytes

[Note] As [Target memory], the fitted memory is valid.

Do not set the other tabs ([Device data], [Program], [Common], [Local]) than [File selection].

If a ladder file with the same name already exists in the GX Developer side, following dialogue will appear.



[Note] Choosing [Yes (Y)] in the dialogue will overwrite the GX Developer side ladder file. The file before overwriting will be erased.

Confirm the file enough before choosing [Yes (Y)].

The [Read from PLC] screen can also be used as a CNC controller side file listing function. Move the scroll bar of the [File selection] tab to the right to display the write date and size of each file. Click [Free space volume] to display the free area of the target memory.

Read from PLC	×
Connecting interface COM1 <-> PLC module PLC Connection Network No. 7 Station No. Host PLC type (0.44.	
Target memory PLC RAM/Device memory Title ON BOARD S-RAM	+ (D-RAM)
File selection Device data Program Common Local	Execute
Param+Prog Cancel all selections Device data MAIN	Close
LDTEST TEST LADDER 02/01/22 134 M2TEST TEST MESSAGE LANG.1 02/01/22 M2TEST TEST MESSAGE LANG.2 02/01/22 P Device comment Device memory	Related functions Transfer setup Keyword setup Remote operation Clear PLC memory
File register Image: State of the stat	Format PLC memory Arrange PLC memory Create title
Free space volume Largest contiguous 96256 Bytes Total free space volume	96256 Bytes

3.8 Verifying the PLC Programs

The following indicates how to verify ladders between the CNC controller and GX Developer.

3.8.1 Operation procedure

Perform the following operation from GX Developer to start the operation screen.

[Online] \rightarrow [Verify with PLC]

On the following screen, choose the ladder files to be verified from the [File selection] tab, and click [Execute].

[Verify source] : GX Developer side [Verify dest] : CNC side

Verify with PLC	X
Connecting interface COM1 <> P	LC module
PLC Connection Network No. J Station No. Host PLC type	Q4A
Target memory PLC RAM/Device memory Title	
File selection Device data Program	Execute
Param+Prog	Close
Edit data(Verify source) PLC data (Verify dest.)	
MITEST	Transfer setup
MITEST Device Intendity Spec	iffication Keyword setup
LDERR	32767 Remote operation
PLC/Network PLC/Network Device comment	Clear PLC memory
	Format PLC memory
Comment verify type	Arrange PLC memory
C GX Developer Data C PLC Data	Create title
Refresh view	
Free space volume Largest contiguous Bytes Total free s volume	pace Bytes

[Note] As [Target memory], the fitted memory is valid. Do not set tabs ([Program]) other than [File Selection].

If verification mismatches occur, the following mismatch screen appears. Double-click the mismatch to display the corresponding part of the GX Developer side file.

MELSOFT series GX Develop	er C:\MELSEC\TEST		_ 8
	ам Qnline Diagnostics Icols Window Help		
) QQQ 4% QQ BQ <u>B</u> BXXX	EX XXX HO FI FI & HIHH F	
Program 💌			
日常無数調査な			
X	Verify results Program	International London London London London London London	- 🗆 ×
TEST TEST Project Program Program Program Program Procement Procement Procement Procement Procement Device init	[PLC verify: Program] Verify source Project name -C:\MELSEC\TEST Data name -LDTEST Verify destination Project name -LoTEST Data name -LDTEST		
	<nenory></nenory>	(PLC)	
	Step Instruction 6895 AND= 82588 K44	Step Instruction 6895 NOP	
	6983 + K10800 D1022 D643	6901 NOP	
	6983 * K18888 01822 0843	0281 HOL	
	2 items unmatched.		
	GX Developer side	CNC controller side	
Project		DAS. Hart delice	NUM

3.9 Monitoring the PLC Program

There are no MELDAS-specific operations to monitor a PLC program. Refer to the Operating Manual for the operation methods. For usable functions, refer to "1.3.2 Function support conditions (on-line section)". This section explains the operation procedure outline and precautions.

3.9.1 Operation procedure

Perform the following operation from GX Developer to start monitoring.

(1) Display the ladder program to be monitored and move to the circuit part to be monitored.

(2) Perform the following operation to start monitoring.

[Online] \rightarrow [Monitor] \rightarrow [Monitor mode] or F3

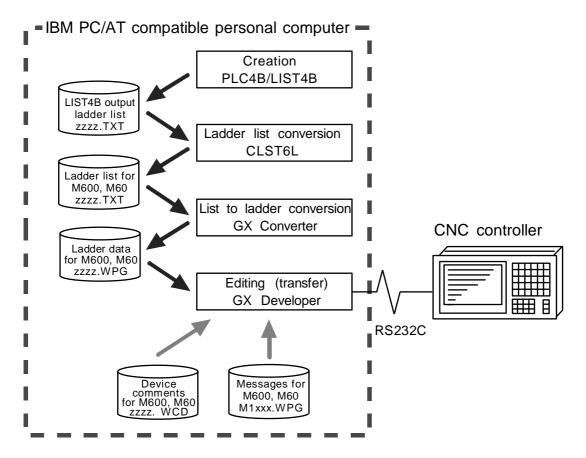
(3) Perform the following operation to stop monitoring.

[Note] If the ladder program being run by the CNC controller differs from the one being displayed on GX Developer, <u>monitoring will not result in an error but will continue</u>.

3.10 Using PLC4B Type PLC Programs

The PLC program developed with the conventional MELDAS PLC programming tool (PLC4B) can be used.

3.10.1 Development procedure



(1) Creation

The PLC program created for the old model is output in a list format.

(2) Conversion

Using CLST6L (ladder list converter), the output program is converted into a PLC program for M600, M60/60S series (list format). Using GX Converter (data conversion software package), the list format program is converted into the GX Developer data.

(3) Editing/transfer

The resultant program can be handled like a newly created PLC program.

3.10.2 Starting GX Converter and specifying the file to be converted

Perform the following operation from GX Developer to start GX Converter (read).

 $[Project] \rightarrow [Import file] \rightarrow [Import to TEXT, CSV format file]$

On the following screen, choose the file to be converted (LDTEST.TXT) and click [OK].

Open file		X
Drive Drive CMNT.TXT DTEST.txt LD_ERB.txt mltest.txt M2TEST.txt	[·o·] 🔽 🔁	
Path: File name: File type:	C:\MELSEC\DemoDT\ LDTEST.txt Text Files(*.txt, *.csv)	OK Cancel

3.10.3 Conversion format setting

Set the conversion format on the following data conversion wizard screen.

(1) Data conversion wizard 1/4

Choose [Original Data Type]-[Delimited] and [Data Type]-[List], and click [Next>].

Data Conversion Wizard - Step 1 of 4	×
Choose Next, or choose the Data Type that best describes your data.	
Original Data Type Choose the file type that best describes your data	
 Delimited - Characters such as commas or tabs separate each field. 	
C Fixed Width - Fields are aligned in columns with spaces between each field.	
Data Type	
End Import at Row:	
Data Preview	
1 P251	1
2 LDIDDM0408	1
3 OUTDIM0409	
4 LD00M0409	
5 OUTUEM0408	
Cancel < Back Next > Einish	

(2) Data conversion wizard 2/4

Choose [Delimiters]-[Tab] and click [Next>].

Data Co	nversion	Wizard - Step	2 of 4		×
This sc	reen lets yo	u set the delimit	ers your data coi	ntains.	
Delim	iters				
		Se <u>m</u> icolon 🔽 🖸	omma 🥅 <u>S</u> pac	e <u> </u>	
\sim	/				
	Preview —				
0.0					
P25	L				_
LDI		M0408			
OUT		M0409			
LD		M0409			
OUT		M0408			
التهـ		10 400			
_ <u>↓</u>					•
				1	1
		Cancel	< <u>B</u> ack	Next>	<u>F</u> inish

(3) Data conversion wizard 3/4

Choose to highlight the Instruction column part in the [Data Preview] list and choose [Column Data Format]-[Instr].

Data Conversion N		lumn and set the Data Column Data Forma C Step number C Line statement	t © P/I statement	X Skip)
Data Preview	Instruction	1		1.
P251				-
LDI	M0408			
OUT	M0409			
LD	M0409			
OUT	M0408			-1
•			•	
	Cancel	< <u>B</u> ack	lext > <u>F</u> inis	sh

(4) Data conversion wizard 3/4

Further, choose to highlight the Argument column part in the [Data Preview] list and choose [Column Data Format]-[I/O(Device)]. Click [Next>].

Data Conv	ersion W	'izard - Step	3 of 4		×
This scre	en lets yo	u select each :	C Line state	Format nber CP/Is ement CNote ce CDon	
– Data Pre	view				
Instr	Line	I/O(Devic	e)		
P251					<u>^</u>
LDI		M0408			
OUT		M0409			
LD		M0409			
OUT		M0408			_
•	1				
	Γ	Cancel	< <u>B</u> ack	Next >	<u>F</u> inish

(5) Data conversion wizard 4/4

Set the program name used on GX Developer at [Data name] column and a ladder annotation at [Title] column, and click [Finish].

Data Conversi	ion Wizard - Step 4 of 4	×
This screen let	s you select the data for import.	
Data type	Program	
Data name	LDTEST	
Title	TEST Ladder	
Conversion	type for wrong instruction Do not Import(Skip)	
	Cancel < <u>B</u> ack Next > <u>Finish</u>	

(6) Completion

The setting is complete when the following completed dialog appears after the converting dialog. Click [OK].

GX Converter	
Converting Program LDTEST	GX Converter
72%	Completed
Cancel	[0K]

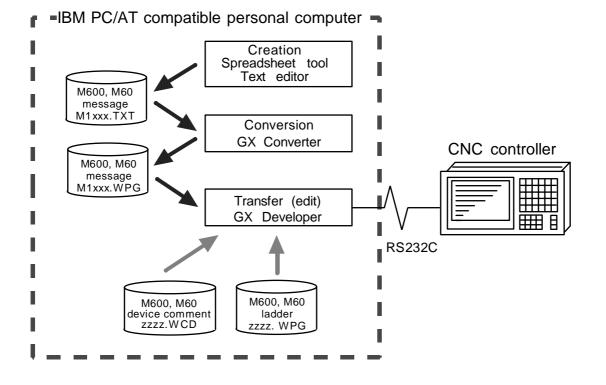
4. PLC MESSAGE DEVELOPMENT

This chapter describes a procedure for developing PLC-related data such as alarm messages, operator messages, and PLC switches.

4.1 Development Procedure

There are the following two methods as a general development procedure of message data.

- Making conversion into GX Developer data using a general text editor or spreadsheet tool and data conversion package.
 (When there is a large volume of message data and you want to control them with a commercially available tool, for example)
- (2) Entering messages directly from GX Developer (When there is a small volume of message data or when addition or correction is to be made, for example)



4.1.1 Using a general text editor

(1) Creation

The message data is described using a general text editor. The description method and format will be described later.

(2) Conversion

The conversion from text data to GX Developer data is carried out using the "GX Converter (data conversion software package)".

(3) Transfer

With the GX Developer, the message data is handled as a PLC program interlinear comment, and can also be edited.

The message data is transferred to the CNC controller using the GX Developer, in the same manner as the ladder program.

4.1.2 Entering messages directly from GX Developer

(1) Creation

The message data is described directly from GX Developer. The message data is handled as a PLC program interlinear comment by GX Developer. The description method and format will be described later.

(2) Transfer

The message data is transferred from GX Developer to the CNC controller in the same manner as the ladder program.

4.2 Message Data Description Method

The message data can be described as text data by a general text editor and also by commercially available spreadsheet software in addition to the direct input with GX Developer.

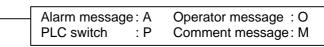
4.2.1 Description format

Message data is classified into setting areas to store the setting for each message and message areas to store message data. It is described in the following respective description format.

(1) Setting area

The message length and No. of messages are set for each message in the setting area. The message data region secured by the CNC controller can be adjusted to the most efficient status using these settings. The respective maximum values are set if nothing is set. (Refer to "4.2.3 Precautions" for the maximum values.)

;\$, message classification code, maximum message length, No. of messages [CR]



(2) Message area

The message area is described using the following description format. The description format cannot be abbreviated. Comma(,) and [CR] must be described, even the message character string is blank.

Message classification	Description format
Alarm message	;A, index No., data register No., message character string [CR]
Operator message	;O, index No., data register No., message character string [CR]
PLC switch	;P, switch No., message character string [CR]
Comment message	;M, device, device No., message character string [CR]
Message classification code Index No. Switch No. Data register No. Device Device No. Message character string	 A one-byte alphabetic character expressing each message classification One-byte number (0 to No. of messages in the setting area - 1) One-byte number (0 to No. of messages in the setting area - 1) One-byte number One-byte number (1 or 2) One-byte number (0 to 10) One-byte alphanumeric character, No. of characters in the setting area message length. Semicolons, commas, spaces and tabs can also be used. Note that the tab at the head of the message character string is ignored.
Semicolon(;) Comma(,)	 Message data identification code Separator between each description (a comma only is used to leave a message character string blank)
[CR]	: Line feed code, (CR/LF) or (LF).

4.2.2 Description method

The message data is described as text data by the following description format.

1		Υ.	
	:#M635 ladder ver1. '97.08.01		Comment
	;\$, A,32, 200 ;\$, 0, 40, 200		Setting area
	;\$, P, 14, 32		Setting area
	;\$, M, 60, 20 NOPLF		
	;A, 0, 0, Emergency stop		
	;A, 11, 1, Spindle alarm :		
	NOPLF :		Message area (alarm messages)
	NOPLF :		
	NOPLF ;0, 1, 9000, MELDAS 600LADDER Ver1.0		Page break code
	;0, 20, 9000, BND-400W000-A0		Message area (operator messages)
	NOPLF		
	;P, 1, Program restart ;P, 2, Automatic power OFF		Message area (PLC switches)
			······································
	NOPLF		
	;M, 1, 0, [Spindle]		
	;M, 1, 0, [Standby 1]		Message area (comments)
	END	J	End code

(1) Comment

Statements having a semicolon (;) at the head of the line, in a different format than described in "4.2.1 Description format", are regarded as comments. These comments are handled as comment data in the GX Developer also, but are erased during the transfer to the CNC controller. An error will occur if there is no semicolon at the head of the line.

(2) Setting area

Each message is set here. This area must be described before the message area of the relevant message. That setting will be ignored if it is described in the middle of or after the relevant message description.

(3) Message area

Collect similar messages in a group and describe them. There is no description order in the respective messages, but the latter description is validated if there are descriptions with the same factors (index No., etc.).

(4) Page break code

A page break code is described at one or more places approx. every 15 lines in the setting area and message area. The message data may skip if there is no page break code.

(5) End code

An end code is described at the end of the description. Description after the end code are ignored.

An error will occur if there is no end code.

4.2.3 Precautions

No. of characters, quantity limitations, handling of information other than settings, handling of information other than format are described below.

(1) Message data maximum value

Processing will be carried out with the following values considered as the maximum values if the setting is not carried out in the setting area, or if the description position in the setting area is illegal.

Message classification	Max. message length	Max. No. of messages	Data size by multiplying max. message length by max. No. of messages
Alarm messages	32 byte	512	16 Kbyte
Operator messages	60 byte	512	30 Kbyte
PLC switches	14 byte	32	0.5 Kbyte
Comments	60 byte	100	6 Kbyte

[[]Note] Two-byte data in the message character string is handled as two characters. GX Developer accepts 64 characters as an interlinear comment. However, since that includes information other than a message character string (e.g. message classification code, index No. and data register No.), the message character string is actually up to 58 characters long.

(2) When the setting value and message data do not match

When the message data contents (such as index No., switch No. and message character string) overflows from the settings in the setting area, the data that overflowed is ignored.

4.3 Converting Data into GX Developer Format

Convert the message data, which was described using a text editor or like, into GX Developer data in the following method. Use "GX Converter (data conversion software package)" for conversion. GX Converter can be started from the GX Developer menu.

4.3.1 Starting GX Converter and specifying the file to be converted

Perform the following operation from GX Developer to start GX Converter (read).

 $[Project] \rightarrow [Import file] \rightarrow [Import from TEXT, CSV format file]$

On the following screen, specify the file to be converted (M1TEST.TXT) and click [OK].

Open file				X
Drive	[·c·] 💌 主			
CMNT.TXT				
 Ⅲ CMNT.TXT Ⅲ LDTEST.txt Ⅲ LD_ERR.txt 				
M1 TEST.txt				
Path:	C:\MELSEC\DemoDT\		OK]
File name:	M1 TEST.txt		Cancel	
File type:	Text Files(*.txt, *.csv)	•		

4.3.2 Conversion format setting

Set the conversion format on the following data conversion wizard screen.

(1) Data conversion wizard 1/4

Choose [Original Data Type]-[Fixed Width] and [Data Type]-[List], and click [Next>].

Data Conversion Wizard - Step 1 of 4
Choose Next, or choose the Data Type that best describes your data. Original Data Type Choose the file type that best describes your data C Delimited - Characters such as commas or tabs separate each field.
 ✓ Deminied "ginaracters such as commas of racs separate each rield. ✓ Fixed Width - Fields are aligned in columns with spaces between each field.
Data Type: List Start Import at Row: 1
End Import at Row:
1 ;#M635f%f_D[
2 ;\$,Å,32,200 3 ;\$,0,40,200
4 ;\$,P,14,32 5 ;\$,M,60,20
<pre>v v v v v v v v v v v v v v v v v v v</pre>
Cancel < Back Next > Emish

(2) Data conversion wizard 2/4

Just click [Next>].

ta Conversion Wiza his screen lets you set				×
Lines with arrows signi To CREATE a brea To DELETE a brea To MOVE a break	ak line, click a ak line, double	t the desired po click on the line		
Data Preview				
10	20	30	40	50
;#M635f%f_D[-
;\$,A,32,200				
;\$,0,40,200				
;\$,P,14,32				
;\$,M,60,20				-1
0	Cancel	< Back	Next>	Finish

(3) Data conversion wizard 3/4

Choose to highlight the Instruction column part in the [Data Preview] list and choose [Column Data Format]-[Instruction ,Statement ,Note]. Click [Next>].

This screen lets you sel	ct each column and set the Data Format. Column Data Format C Step number C P/I statement C Line statement C Note C I/0[Device] C Do not Import[Skip] C Instruction,Statement,Note
Data Preview Instruction,Sta ;#M635f%f_D[ement,Note
;\$,A,32,200 ;\$,0,40,200 ;\$,P,14,32 ;\$,M,60,20	
▲	

(4) Data conversion wizard 4/4

Set the program name used on GX Developer in [Data name] and a data annotation in [Title], and click [Finish]. Data conversion is completed when the Completed dialog appears. Click [OK].

X

mpleted.

Data Conversion Wizard - Step 4 of 4	3
This screen lets you select the data for import.	
Data type Program	
Data name M1TEST	
Title Message Test Lang.1	
Conversion type for wrong instruction Do not Import(Skip)	
	GX Convert
	🤅 C.
Cancel < Back Next> Einish	

4.4 Entering/Editing Data Using GX Developer

The message data in GX Developer are handled as the "integrated type interlinear statements" of a PLC program. "Integrated type interlinear statements" are interlinear comments provided to assist the understanding of the PLC program, and those transferred to the controller together with the PLC program are called the "integrated type".

"Interlinear statements" can be displayed and edited using [Ladder] or [Instruction list].

4.4.1 Interlinear statement display using circuit display

(1) Display of project data list

Perform the following operation to display the "Project data list" window and double-click the file name to display the edit screen. First, the normal ladder screen appears.

[View] \rightarrow [Project data list], then double-click [File name you want to display].

(2) Display of message data

Perform the following operation to display the message data that are integrated type interlinear statements.

[View] \rightarrow [Statement]

	Developer C:\MELSEC\Project\M6TEST
Program	
王 聖 課 課 部 日 記	
	LD(Read mode) M1TEST Message Test Lang. 1 987 Step
⊡- <mark>&</mark> M6TEST ⊡-₩ Program	\$,A,26,512 \$,O,42,20
MAIN M60	
SBCKM6C	0(NOPLF]
LDVR1A0	A,0,0,Alarm Message No.0.
- M2VR1A0	A,1,1,Alarm Message No.1.
LDHR2A0	0.33 Alarm Message No.3
M2TEST1	ME A,4,4,Alarm Message No.4. A,5,5,Alarm Message No.5.
MINILAD2	A,6,6,Alarm Message No.6.
	A,7,7,Alarm Message No.7. A,8,8,Alarm Message No.8.
M1LINK1 L	ini A, S, Alarm Message No.9.
📕 🔤 LDLINKB I	inł A,10,10,Alarm Message No.10. A,11,11,Alarm Message No.11.
M64TEST	HE A,12,12,Alarm Message No.12.
STAND2B	A, 13, 13, Alarm Message No. 13. A, 14, 14, Alarm Message No. 14.
SBCKM6E	A, 15, 15, Alarm Message No. 15.
LDVR1A30	A, to, to, Alanti Message No. To.
M2SMPL N	A 19 19 Alarm Message No 19
M1TEST N	es
🗄 😵 Device comme	nt 29[NOPLF]
🗄 📝 Parameter	0,0,0,0perator Message No.0.
Device memory	
🖳 🖳 🖫 Device init	0,2,2,0perator Message No.2. 0,3,3,0perator Message No.3.
	0,4,4,0perator Message No.4. 0,5,5,0perator Message No.5.
	0,6,6,Operator Message No.6.
	0,7,7,0perator Message No.7. 0,8,8,0perator Message No.8.
	0,9,9,Operator Message No.9.
	0,10,10,Operator Message No. 10. 0,11,11,Operator Message No. 11.
Project	U,11,11,Uperator Message No.11.
Ready	Q4A Host station NUM

4.4.2 Interlinear statement display using list display

(1) Display of project data list

Perform the following operation to display the "Project data list" window and double-click the file name to display the edit screen. First, the normal ladder screen appears.

[View] \rightarrow [Project data list], then double-click [File name you want to display].

(2) Display of list data

Perform the following operation to display the list data. The list display also shows the message data that are integrated type interlinear statements.

 $[View] \rightarrow [Instruction list]$

Perform the following operation to return to the circuit display.

 $[View] \rightarrow [Ladder]$

	Noper C:\MELSEC\Project\M6TEST
	onvert View Online Diagnostics Iools Window Help
	10 0 0 0 11 0 0 11 0 0 11 0 0 0 0 0 0 0
Program 🗾	····································
	🖬 List(Read mode) 🛛 M1TEST Message Test Lang. 1 987 Step
🖃 🖏 M6TEST	0 ; \$,&;26,512
🗄 🖼 Program	7 ; \$,0,42,20
MAIN M600L	14 ; \$,P,14,32
- 🔤 SBCKM6CP N	21 : \$,19,26,20
SBCKM6B	28 NOPLF
LDVR1A01	29 : 8,0,0,81am Message Bo.0.
M2VR1A02	44 : A,l,l,Alarm Message No.1.
LDHR2A0T	59 : A,2,2,Alam Message No.2.
M2TEST1 Me	74 : A.3.3.Alam Message No.3.
STAND2	89 : A.4.4.Alarn Message No.4.
MINILAD2	104 ; A.S.S.Alam Message No.S.
LDLINK Link	119 : A,6,6,Alarm Message No.6.
M1LINK1 Link	124 / A.7.7.Alarm Uessage No.7.
📫 LDLINKB Linł 📫 M64TEST Re	149 / A,8,8,81am Message No.8. 164 / A,9,9,81am Message No.9.
STAND2B	191 ; A, 5, 5, Alam Message Bo. 5. 179 ; A, 10, 10, Alam Message Bo. 10.
SBCKM6ER N	195 : A.11.11.Alarm Message No.11.
LDVR1A30	210 7 Aylzyläylain dessage Royla.
	227 ; A.12,12,Alam Message No.12.
DEVCHCK1 E	243 ; A,14,14,Alam Message No.14.
M2SMPL Me:	259 : A,15,15,Alam Message Bo.15.
M1TEST Mes	275 ; A,16,16,Alam Message Bo.16.
🗄 😵 Device comment	291 ; A,17,17,81arm Message No.17.
🗄 률 Parameter	307 : Å,18,31am Message No.18.
🔄 🔄 Device memory	323 : A,19,19,Alam Message No.19.
🔄 🖳 🖳 Device init	339 : A,20,20,Alam Message No.20.
	355 NOPLF
	356 ; 0,0,0,0perator Message No.0.
	372 ; 0,1,1, Operator Hessage No.1.
	288 / 0,2,2,0perator Message No.2.
	404 / 0,3,3,0perator Hessage No.3.
	420 ; 0,4,4,0perator Message No.4.
Project	
Ready	Q4A Host station NUM

4.4.3 Editing of integrated type interlinear statements

(1) Circuit display

On the circuit display screen that shows the integrated type interlinear statements, doubleclicking the interlinear statement you want to edit displays the following dialog. Perform editing operation on the dialog and click [OK] or press [Enter].



(2) List display

On the list display screen, double-clicking the interlinear statement you want to edit displays the following dialog. Perform editing operation on the dialog and click [OK] or press [Enter].

Enter list			×
A,12,12,Alarm Message No.12.	OK	Exit	Help

(3) Entering new message data

• Displaying new edit screen

Perform the following operation to display the [New] dialog, and set the [Data name] and [Title]. After setting, click [OK].

$[Project] \rightarrow [Edit Data] \rightarrow [New]$

New	×
Data type	ОК
Program 💌	Cancel
Program type	
Cadder	
O SFC 🗖 MELSAP-L	
Data name	
M1TEST	•
Title	
Message TEST	

• Changing to list display mode

Perform the following operation to display the list data.

 $[View] \rightarrow [Instruction list]$

• Entering message data

Press "Enter" at the "END" line, and input the data in the same manner as 4.4.3 (2) above. Then, press "Enter" on the next line, and input the message data.

Enter list	×		
END	OK	Exit	Help

4.5 Writing to the CNC Controller

The following shows the method of transferring a message from the GX Developer to the CNC controller. The transfer method is the same as the ladder code transfer method. Ladder codes and message data are distinguished by their file names only.

Perform the following operation to display the [Write to PLC] screen, and choose the file to be written.

[Online] \rightarrow [Write to PLC]

The following example transfers a message first language file "M1TEST.WPG".

Write to PLC	×
Connecting interface CDM1 <→ PLC module PLC Connection Network No. ① Station No. Host PLC type Q4A Target memory PLC RAM/Device memory ▼ Title File selection Device data Program Common Local Param+Prog Select all Cancel all selections □ #2 Program	Execute Close
HOTEST TEST LADDER MITEST TEST MESSAGE LANG.1 M2TEST TEST MESSAGE LANG.2 Device comment Parameter PLC/Network	Related functions Transfer setup Keyword setup Remote operation Clear PLC memory
File register Whole range Range specification ZR 0 - 32767	Format PLC memory Arrange PLC memory Create title
Free space volume Largest contiguous Total free space volume Bytes volume	Bytes

4.6 Reading and Verifying from the CNC Controller

The following shows the method of reading and verifying a message from the CNC controller to the GX Developer. The method of reading and verifying is the same as that of ladder codes. Ladder codes and message data are distinguished by their file names only.

4.6.1 Menu selection/screen operation

Refer to the following sections for operation methods. For read : "3.7 Reading the PLC Program from the CNC Controller"

For verification : "3.8 Verifying the PLC Programs"

4.6.2 Message read format

The message description format was shown in "4.2.1 Description format", but there are no special rules concerning provision of descriptions in the setting area or the order of message description in the message area. For that reason, the description format may differ between transfer and reading of the message data.

The following shows the format during reading as the "Standard description format".

Standard description format of message data

\frown			
	Alarm message setting	(1)	
	Operator message setting		
	PLC switch setting		
	Comment message setting		
	Alarm messages	(2)	
	Operator messages	(3)	
	PLC switches	(4)	
	Comment messages	(5)	
	NOPLF		
	END		
۱			

(1) Setting area

The settings are described in order of alarm, operator, PLC switch and comment. The maximum value is described if the setting is abbreviated.

(2) Alarm messages

Each message data is described in order of the index Nos.

(3) Operator messages

The same as the alarm messages.

(4) PLC switches

Each message data is described in order of the switch Nos.

(5) Comment messages

These messages are described in the same order as described before transfer.

(6) Others

- Spaces and tabs are not included before and after the comma(,) separating the message data factors.
- The message character string is handled the same as normal data even when blank.
- The NOPLF code between messages is described to the position to which the message data following the NOPLF code during transfer moved.

5. DEVICE COMMENT CREATION

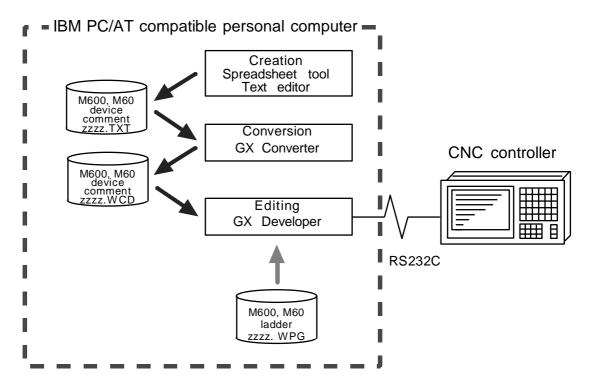
There are no MELDAS-specific operations for device comments. Therefore, refer to the Operating Manual for the development method. This section describes the device comment development procedure outline and the development method using a general-purpose tool.

5.1 Development Procedure

The following two methods can be used as general development procedures of message data.

(1) Indirect entry

In this method, device comments are converted into GX Developer data using a general text editor or spreadsheet tool and data conversion package. Use this method when you want to divert the device comments of the old model or when a device comment volume is large and you want to control them with a commercially available tool, for example.



(2) Direct entry

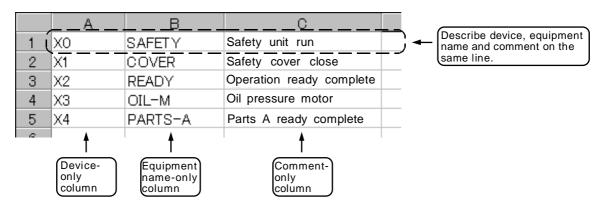
In this method, device comments are entered directly from GX Developer. Use this method when a device comment volume is small or when addition or correction is to be made, for example.

There are the following three methods for direct entry from GX Developer. Refer to the Operating Manual for details.

- Creating comments on the device comment edit screen
- Creating device comments after circuit creation during ladder circuit creation
- Making addition/correction to device comments in the created ladder circuit

5.2 Description Method for Indirect Entry

The following explains the description method for creating device comments using a spreadsheet tool or like. The following example describes device comments using a spreadsheet tool.



Column data format	Explanation
Device	(1) Describe a device.
	 Conversion cannot be made if a device has not been described. Always describe a device.
	(2) A device is a required item. Describe it in one-byte code.
Equipment name	(1) Describe an equipment name.
	 It is not registered if the device part on the same row is blank or the device is illegal.
	(2) You can describe an equipment name of up to 8 characters.
Comment	(1) Describe a comment.
	 It is not registered if the device part on the same row is blank or the device is illegal.
	(2) You can describe a comment of up to 32 characters.

[Note] Describe data in any of the following combinations.

- (1) Device, equipment name, comment
- (2) Device, comment
- (3) Device, equipment name

Save the above data in the CSV format. The following example shows the above data saved in the CSV format.

X0, SAFETY, Safety unit run X1, COVER, Safety cover close X2, READY, Operation ready complete X3, OIL-M, Oil pressure motor X4, PARTS-A, Parts A ready complete

5.3 Converting Device Comments

Convert the comment data (CSV format), which was created using a spreadsheet tool or like, into GX Developer data in the following method. Use "GX Converter (data conversion software package)" for conversion. GX Converter can be started from the GX Developer menu.

5.3.1 Starting GX Converter and specifying the file to be converted

Perform the following operation from GX Developer to start GX Converter (read).

 $[Project] \rightarrow [Import file] \rightarrow [Import from TEXT, CSV format file]$

On the following screen, specify the file to be converted (cmnt_all.txt) and click [OK].

Open file		X
Drive	[·c·] 💌 🔁	
CMNT.TXT		
 Emnt_all txt LDTEST.txt LD_ERR.txt M1 TEST.txt M2TEST.txt 		
I M1 TEST.txt M2TEST.txt		
Path:	C:\MELSEC\DemoDT	ОК
File name:	cmnt_all.txt	Cancel
File type:	Text Files(*.txt, *.csv)	•

5.3.2 Conversion format setting

Set the conversion format on the following data conversion wizard screen.

(1) Data conversion wizard 1/4

Choose [Original Data Type]-[Delimited] and [Data Type]-[Comment], and click [Next>].

Data Conversion Wizard - Step 1 of 4	×			
Choose Next, or choose the Data Type that best describes your data. Original Data Type Choose the file type that best describes your data				
 Delimited - Characters such as commas or tabs separate each field. C Fixed Width - Fields are aligned in columns with spaces between each field. 				
Data Type: Comment Start Import at Row: 1				
Data Preview				
1 X0000DLS1DLS1 Carrier clampA				
2 X0001DLS2DLS2 Carrier clampB 3 X0002DLS3DLS3 Ejector forward edge				
4 X0003DLS4DLS4 Ejector forward edge				
5 X0004DLS5DLS5 Spindle discrimination	1			
Cancel < Back Next > Einish				

(2) Data conversion wizard 2/4

Choose [Delimiters]-[Tab] and click [Next>].

ata Conv	ersion \	√izard - Step 2 of 4	×
This scree	n lets you	i set the delimiters your data contains.	
- Delimiter:	s		
🔽 🖬	Γs	e <u>m</u> icolon 🖵 <u>C</u> omma 🦳 <u>S</u> pace 🖵 <u>O</u> ther:	
Data Pre	view		
X0000	LS1	LS1 Carrier clampA	1
	LS2	LS2 Carrier clampB	
X0002		LS3 Ejector forward edge	
X0003	LS4	LS4 Ejector forward edge	
X0004	LS5	LS5 Spindle discriminationl	
العوممة.	1.00	has annot decomposition	
<u> </u>			
		Cancel < <u>B</u> ack Next>	Einish

(3) Data conversion wizard 3/4

Make sure that the column parts in the [Data Preview] list are in order of [Device Number], [Label] and [Comment], and click [Next>].

		Column Data Format C Device Number C Label C Comment C Do not Import(Skip)
Data Pre	view	
Devic	Label	Comment
Devic X0000	Label LS1	Comment LS1 Carrier clampA
X0000 X0001	LS1	LS1 Carrier clampA
X0000 X0001 X0002	LS1 LS2	LS1 Carrier clampA LS2 Carrier clampB
X0000 X0001 X0002 X0003	LS1 LS2 LS3 LS4	LS1 Carrier clampA LS2 Carrier clampB LS3 Ejector forward edge

(4) Data conversion wizard 4/4

Choose [Data type]-[Common comment] or [Program comment], set the comment file name used on GX Developer in [Data name] and a comment annotation in [Title], and click [Finish].

Data Conversi	ion Wizard - Step 4 of 4	×
This screen let	ts you select the data for import.	
Data type	Program comment	
Data name	CMNTALL 💌	
Title	NSK Comment ALL	
	Cancel < <u>B</u> ack Next> <u>F</u> inish	

(5) Completion

The setting is complete when the following dialog appears. Click [OK].

GX Converter	×
Completed	ł.

(6) Error status

If an error occurred during conversion, its status and the line where it occurred are displayed.

GX Converter	
Conversion error has occurred.	
The device is incorrect(7 Line)	
,	Save OK

6. RELATIONSHIPS BETWEEN GX DEVELOPER AND ONBOARD FUNCTIONS

The CNC controller has onboard functions as the PLC development environment that does not use GX Developer. The onboard functions have monitoring and editing functions for ladder program testing and adjustment.

This chapter explains the items related to GX Developer and onboard functions.

6.1 Function Differences

The onboard functions do not have the following functions among the main functions as the PLC development environment.

- Function to create a new ladder program
- All PLC message-related functions
- All device comment-related functions

6.2 Specification Differences

There are the following differences in specifications between GX Developer and onboard functions.

(1) Restriction specifications related to circuit display/editing

The restriction specifications related to circuit display/editing differ between GX Developer and onboard functions. Since the restriction specifications of the onboard functions are narrower than those of GX Developer, care should be taken when creating a circuit on the GX Developer side.

(a) Limits according to circuit handling specifications

		Onboard	GX Developer
Display	Number of contacts	8 contacts, 1 coil	11 contacts, 1 coil
specifications of single screen	Number of lines	9 lines	Depending on window size and screen reduction ratio
Restriction specifications of single circuit		18 lines (return count: 0) (Note 1)	24 lines of 200 or more series contacts

(Note 1) The relationships between the return count and the maximum value of the vertical width of the circuit that can be created at that time are as follows.

Return count (times)	0	1	2	З	4	5	6	7	8
Vertical width of circuit (lines)	18	11	7	5	4	3	3	2	2

Excess over the above will result in "LADDER ERROR".

(b) Handling a circuit exceeding the 18-line restriction specifications

If the circuit created on the GX Developer side exceeds the circuit restriction specifications of the onboard functions, the following message is displayed.

Operation	Message	Handling
When "read" or "monitor" function is used to display circuit	"DISPLAY OVER FLOW"	Circuit is not displayed. (Only bus is displayed)
When "write", "insertion", "deletion" or "conversion" function is selected	"NOT WRITE"	Editing operation is inhibited.

(2) Step count calculation specifications

The step count specifications in the individual instructions of the MELSEC and MELDAS differ in some instructions. Therefore, steps may be different when the same circuit is displayed by GX Developer and onboard functions.

This will give rise to a problem especially when the circuit diagram printed from GX Developer is used for maintenance with the onboard functions. To resolve this problem, a tool (PCNV6LM) to print a circuit diagram in the MELDAS step specifications is available.

(3) NC instructions which cannot be used with GX Developer

MELDAS original specification instructions that cannot be handled with GX Developer are used after being replaced with alternate instructions which can be handled by GX Developer. The specifications when these instructions are displayed with the onboard are shown below.

Classification	Instruction symbol	Onboard display	GX Developer display
Bit	DEFR	{DEFR D}	D ↑
Average value	AVE	[AVE S D n]-	[S.AVE S D n]
Carry flag set	STC		[S.STC]
Carry flag reset	CLC		[S.CLC]-
ATC	ATC	—[ATC Kn Rn Rm Mm]—	—[S.ATC Kn Rn Rm Mm]⊣
ROT	ROT	—[ROT Kn Rn Rm Mm]-	[S.ROT Kn Rn Rm Mm]-
TSRH	TSRH	—[TSRH Rm Rn Mn]—	—[S.TSRH Rm Rn Mn]⊣
DDBA	DDBA	[DDBA Rn/Dn]	[S. DDBA Rn/Dn]
DDBS	DDBS	[DDBS Rn]-	[S. DDBS Rn]
CAL1	CAL1	[CAL1 Pn]	[S. CAL1 Pn]
	LDBIT	-[<= S1 n]	├-[<= S1 n]
	ANDBIT	[<= S1 n]	—[<= S1 n]—
DIT	ORBIT	└_[<= S1 n]┘	└-[<= S1 n]┘
BIT	LDBII	-[<> S1 n]	[<> S1 n]—
	ANDBII	—[<> S1 n]—	—[<> S1 n]—
	ORBII	└_[<> S1 n]┘	└_[<> S1 n]┘

Table of alternate instruction correspondence

(4) Circuit representation specifications

The circuit of the END instruction is not displayed by the onboard functions.

7. PROCEDURE FOR WRITING PLC PROGRAMS, ETC. TO ROM

This chapter explains the procedure for ROM writing for the ladder programs and PLC-related data that have been developed. For the M60/60S series, this operation is not required since data is written to the ROM as soon as it is written from GX Developer.

7.1 Data That Can Be Written to ROM

The following four data can be written to ROM. Note that multiple data of the same type cannot be written to ROM.

	Related data classification	Remarks
1 2	PLC program (ladder) PLC program comment	PLC program code Comment data for GPPQ/W
3	Message 1st language	1st language data of message data such as alarm messages, operator messages, and PLC switches
4	Message 2nd language	Same as above (2nd language data)

7.2 ROM Writing Operation Procedure

GX Developer does not have the ROM writing function for ladder programs, etc. from GX Developer by remote operation. Perform ROM writing operation from the I/O screen of the CNC controller. By specifying the transfer source information (internal RAM) and transfer destination information (F-ROM) on the I/O screen and starting transfer, the ladder program, etc. stored in the RAM are written to the ROM. The contents of ROM is erased automatically before write is performed. The following shows the I/O screen example of the M600M. (Write from internal RAM to external cassette F-ROM)

Input/Ou	tput 🔻	Monitor Setup Edit Diagnos Mainte
Prog entry Character Device	0 Rema 0 Rema Memory	A:Device Memory Directory /MEM File LAD.DAT
<program></program>	<char> <comment></comment></char>	
		B:Device Memory Directory/FRB File LAD.DAT
		CMP data:
RDY:JOG	:	14:48
Area Devid change selec		Trnsfr Compare Erase A Erase B Rename e A->B A:B A->B

The following gives the common operations and individual operations of the M600M and M600L operation procedures. For details of the I/O screen, refer to the instruction manual of that model.

(1) Common operation

Set the [Device], [Directory] and [File] of [A:Device] and [B:Device] respectively. Selecting any of the following functions on the menu keys starts the corresponding operation.

- (a) [Trnsfr A->B] Data is transferred from Device A to Device B. If Device B is an F-ROM, the F-ROM contents is erased and the data of Device A is written to it. Devices A, B may be other than the internal RAM or F-ROM (storage such as the hard disk).
- (b) [Compare A:B]

Data of Device A and Device B are compared. Devices A, B may be other than the internal RAM or F-ROM.

(c) [Erase A]

The data of Device A is erased. Note that it is not erased when the internal RAM is specified.

(d) [Erase B]

The data of Device B is erased. Note that it is not erased when the internal RAM is specified.

(2) Individual operations (How to set the [Device], [Directory] and [File])

- (a) M600M
 - (i) Device selection
 - Specify [Memory] from the menu key.
 - (ii) Directory designation
 - Type the storage region type in the setting box. Internal RAM : "/MEM" Internal F-ROM: "/FRA" External cassette F-ROM: "/FRB"
 - (iii) File name designation Type the file name in the setting box. Fixed to "LAD.DAT"

(b) M600L

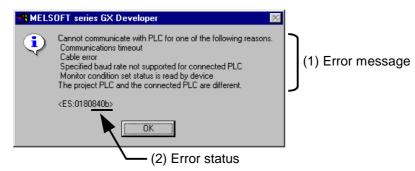
(i) Device selection

Specify [Memory] from the menu key.

- (ii) Directory designation Specify [PLC prog] from the menu key.
- (iii) File name designation
 Specify the storage region type from the menu key.
 [Inside RAM], [Inside F-ROM] or [Outside F-ROM]

8. LIST OF ERROR STATES

If an error has occurred in GX Developer, the following dialog appears. The error message and error status are displayed in the dialog.



[Note] When an error occurred at GX Developer On-line function, the error message may not explain exactly the state in the CNC controller side. Always refer to the error list.

The following table indicates the causes and remedies of the errors that can occur during online operation with the CNC controller. For other errors, refer to the GX Developer Operating Manual.

Status	Message	Cause	Remedy
2056	The executed function is not supported. Please check the manual and other documentation.	The GX Developer version and NC do not match.	This occurs if the GX Developer version is 7.10L to 7.14Q. Upgrade the version to 7.17T or above. The version upgrade can be downloaded from MELFANS web.
4002	The executed function is not supported. Please check the manual and other documentation.	An operation not supported by the specifications was attempted.	Check the operation procedures.
4010	Cannot write because the PLC is executing a RUN command. Stop the PLC, then execute again.	The PLC of the NC is running.	After stopping the PLC of the NC, start execution again.
4021	The applicable drive is not ready. Check the applicable drive, then execute again.	The specified target memory does not exist or is not in a usable status.	Change the target memory.
4029	Insufficient file capacity. Execute again after deleting unnecessary files.	An attempt was made to write a file that exceeds the storage capacity.	Examine the file structure so that the data falls within the limited capacity.
402b	The file cannot be accessed. Carry out formatting, then execute again.	An attempt was made to write the same type of file.	After deleting the same type of file from the NC side, start execution again.
4031	The specified device No. exceeds the permissible range. Specify a device No. that is within the range set in the parameter.	The access request given is outside the accessible device range.	Check the number range of each device.
4052	The file is write protected. Change the file attributes to enable writing to the file.	The specified target memory is a write-disabled device (F-ROM).	Specify "internal RAM" as the target memory.
4053	Writing to the flash ROM failed.	An error occurred in the process to erase or to write data into the flash ROM. (Only MELDAS 60/60S Series)	The hardware may be faulty or deteriorated. Contact a Mitsubishi Sales Office.

[Note] Read "PLC" in the messages as "CNC controller".

8. LIST OF ERROR STATES

Status	Message	Cause	Remedy
4070	The program before correction differs from the registered program.	A ladder instruction outside the specification is included.	Perform verification to identify the instruction that is the cause of the problem.
4080	Incorrect abnormal.	When executing "Read from PLC" or "Verify PLC" function: Data not included in the specifications was found in the designated file.	The sequence program or message data in the CNC controller may be damaged. Delete the corresponding file and start again, or initialize the PLC data storage area. If the problem cannot be resolved, contact the Mitsubishi System Department.
		When executing "Write to PLC": Multiple END instructions were found in the designated sequence program file.	Edit the sequence program in the list mode to delete END instructions except only one at the last line.
8201	Cannot communicate with the PLC. Execute again after checking the connections with the PLC.	The serial communication cable is faulty. • Not connected • DTR signal off	Check the serial port setting and cable connection.
840b	Cannot communicate with PLC for one of the following reasons. Communications timeout Cable error Specified baud rate not supported for connected PLC Monitor condition set status is read by device The project PLC and the connected PLC are different.	 There is no response from the NC. The CNC has not started properly. The connection channel of the CNC side serial port is different. The serial cable outside the specifications is used for signal connection. An incorrect Ethernet address is set on the NC side 	 Check the following. CNC side status Cable connection Bit selection: GPP communication valid Set the Ethernet address

APPENDIX 1. OPERATION METHODS USING GPPQ

This section explains the GPPQ proper operation method of the function explanation and the PLC program development procedure when "MELSEC QnA Series GPP Function Software Package (GPPQ)" is used as development tool.

Appendix 1.1 GPPQ Function Outline and Functions Supported by the M600, M60/60S Series

The GPPQ functions explained here are those supported by the M600, M60/60S Series in the "offline functions" operated with the GPPQ independently and "on-line functions" carried out connected to the CNC controller.

Refer to the enclosed Operating Manual (off-line section and on-line section) for function details.

Appendix 1.1.1 Function support conditions (general section)

The following shows a list of GPPQ outline functions supported by the M600, M60/60S Series. A \bigcirc mark indicates functions that can be used by the M600, M60/60S Series. An \times mark indicates that the function cannot be used because it is related to "MELSEC Series" characteristic functions. The function details during on-line are described in the next section.

Mode	Function	Support	Remarks
Initialization	New creation	Ø	
	File new read	Ø	
	PLC new read	\rightarrow	Refer to the List of on-line section functions
	File quit	Ø	
	PLC type change	×	Q4ACPU only
Option	Environment setting	Ô	
	Display and operation option	O	
	Startup setting	Ô	
Circuit	Write	\rightarrow	Refer to the List of on-line section functions
	Read	\rightarrow	Refer to the List of on-line section functions
	Monitor	\rightarrow	Refer to the List of on-line section functions
	Test	\rightarrow	Refer to the List of on-line section functions
	Debug	\rightarrow	Refer to the List of on-line section functions
	File access	\rightarrow	Refer to the List of on-line section functions
	PLC access	\rightarrow	Refer to the List of on-line section functions
	Program search	\rightarrow	Refer to the List of on-line section functions
	Comment display	\rightarrow	Refer to the List of on-line section functions
	Program edit	\rightarrow	Refer to the List of on-line section functions
	Monitor and test	\rightarrow	Refer to the List of on-line section functions
	Window changeover	\rightarrow	Refer to the List of on-line section functions
	Option	\rightarrow	Refer to the List of on-line section functions
List	Write	O	
	Read	O	
	File access	Ø	
	PLC access	\rightarrow	Refer to the List of on-line section functions
	Program search	O	
	Comment display	O	
	Program edit	O	
	Window changeover	Ø	
	Option	O	

List of general section functions (1) ① : Possible, × : Support not possible/not determined

APPENDIX 1. OPERATION METHODS USING GPPQ APPENDIX 1.1 GPPQ Function Outline and Functions Supported by the M600, M60/60S Series

Mode	Function	Support	Remarks
Parameter	PLC name setting	×	
	PLC system setting	×	
	PLC file setting	×	
	Device setting	×	
	PLC RAS setting	×	
	I/O assignment	×	
	MELSECNET (II,10)/Ethernet setting	×	
	MELSECNET/MINI setting	×	
	MELSECNET/J setting	×	
	Miscellaneous setting	×	
	Duplex PLC setting	×	
	SFC	×	
	X/Y assignment confirmation	×	
	File access	×	
	PLC access	×	
	Parameter search	×	
	Parameter edit	×	
	Miscellaneous setting	×	
	Window changeover	×	
	Option	×	
Device	Device value input	\rightarrow	Refer to the List of on-line section functions
	Device initialization	\rightarrow	Refer to the List of on-line section functions
	Buffer memory simulation	\rightarrow	Refer to the List of on-line section functions
	File access	O	
	PLC access	\rightarrow	Refer to the List of on-line section functions
	Device search	O	
	Device display	O	
	Device edit	\rightarrow	Refer to the List of on-line section functions
	Window changeover	0	
	Option	O	
On-line	Drive name selection	\rightarrow	Refer to the List of on-line section functions
	File name selection	\rightarrow	Refer to the List of on-line section functions
	File access	\rightarrow	Refer to the List of on-line section functions
	PLC access	\rightarrow	Refer to the List of on-line section functions
	Data search		Refer to the List of on-line section functions
		\rightarrow	
	Trace	\rightarrow	Refer to the List of on-line section functions
	Trace device edit	\rightarrow	Refer to the List of on-line section functions
	Device test	\rightarrow	Refer to the List of on-line section functions
	Window changeover	\rightarrow	Refer to the List of on-line section functions
	Diagnosis target selection	×	
liagnosis	Current error display	×	
	Fault history display	×	
	CPU message	×	
	Unit detailed display	×	
	File access	×	
	PLC access	\rightarrow	Refer to the List of on-line section functions
	Data search		
		×	
	Error display Network monitor and test	×	
		×	
	Window changeover		
	Option	×	

List of general section functions (2) (2) : Possible, × : Support not possible/not determined

APPENDIX 1. OPERATION METHODS USING GPPQ APPENDIX 1.1 GPPQ Function Outline and Functions Supported by the M600, M60/60S Series

Mode	Function	Support	Remarks
Text	Device comment	O	
creation	Pointer statement	O	
	Interlinear statement	O	
	Note	O	
	Print statement	O	
	File access	O	
	PLC access	\rightarrow	Refer to the List of on-line section functions
	Comment search	O	
	Comment edit	O	
	Window changeover	O	
	Option	O	
Printer	Printer data setting	O	
	Print execution	O	
	Printer setting	O	
	Paper size change	O	
	Edit	O	
	Window changeover	Ô	
	Option	O	
File	Machine name/File name selection	O	
maintenance	File access	O	
	PLC access	\rightarrow	Refer to the List of on-line section functions
	File search	O	
	Display	Ø	
	IC memory card	×	
	Window changeover	Ø	
	Option	Ø	
Program	Label name definition	O	
generation	File access	Ø	
	Program generation	Ø	
	Label display	O	
	Display	O	
	Label edit	O	
	Window changeover	O	
	Option	O	
SFC		×	
Quit		O	

List of general section functions (3) (2) : Possible, x : Support not possible/not determined

Appendix 1.1.2 Function support conditions (on-line section)

The following shows a list of GPPQ on-line functions supported by the M600, M60/60S Series. A \bigcirc mark indicates functions that can currently be used by the M600, M60/60S Series. An \times mark indicates that the function cannot be used because it is related to "MELSEC Series" characteristic functions.

Mode	Function	Menu	Detailed function	Support	Remarks
	6.2 Circuit write	6.2.1 Write during run		×	
	6.3 Circuit read	6.3.1 Step No. read		Ø	
		6.3.2 Instruction read		O	
		6.3.3 Device read		O	
		6.3.4 Contact and coil designation read		Ø	
		6.3.5 Statement and note designation read		Ø	
		6.3.6 Last circuit designation read		Ø	
	6.4 Monitor	6.4.1 Monitor screen common			
		display	Monitor destination CPU name	O	
			No. of Monitor program steps	0	
			Monitor program name	O	
			Scan time	×	
			Monitor interval	Ø	
			CPU operation status	Ø	
			Monitor destination	Ø	
			Flicker during communication	Ø	
		6.4.2 Circuit monitor			
			Bit device monitor display	Ø	
			Word device monitor display	Ø	
			Digit designation monitor display	Ø	
			Timer/counter monitor display	Ø	
			Double word monitor display	Ø	
0			Index modification monitor display	Ø	
Circuit mode			Monitor step changeover	Ø	
mode			Changeover to next circuit block	Ø	
			Changeover to previous circuit block	Ø	
			Monitor stop	O	
			Monitor column numeric value/No. of display levels changeover	Ø	
		6.4.3 Device registration monitor			
			Bit device monitor display	O	
			Word device monitor display	Ø	
			Digit designation monitor display	Ø	
			Timer/counter monitor display	Ø	
			Double word monitor display	Ø	
			Index modification monitor display	Ø	
			16-bit integer designation	Ø	
			32-bit integer designation	Ø	
			Real number designation	×	
			Character designation	×	
			Registration device erase	Ø	
		6.4.4 ON/OFF cause automatic search		Ø	
	6.5 Test	6.5.1 Monitor trigger stop			
			Stop at bit device rising edge	×	
			Stop at bit device falling edge	×	
			Stop at word device designation value	×	
			Monitor restart	×	

List of on-line section functions (1)	\bigcirc : Possible, \mathbf{X} : Support not possible/not determined
---------------------------------------	---

Mode	Function	Menu	Detailed function	Support	Remarks
	6.5 Test	6.5.2 Forced ON/OFF			
			Forced ON	×	
			Forced OFF	×	
Mode		6.5.3 Current value change			
			16-bit change	×	
			32-bit change	×	
		6.5.4 Setting value change	Tt ¹ a a a		
				×	
	6.6 Debug	6.6.1 Step execution	Counter	×	
	0.0 Debug	6.6.2 Partial execution		×	
	6.7 File menu	6.7.1 Read		Ô	
	0.7 The menu	6.7.2 Write		0	
		6.7.3 Compare		0	
	6.8 PLC menu	6.8.1 Read		0	
		6.8.2 Write			
			Parameter	×	
			Sequence program	Ô	
			Entire range	Õ	
			Range designation	×	
			Device comment	Ø	
			Device default value	×	
			Simulation data	×	
			File register	×	
			Device memory	×	
			Entire range	×	
			Range designation	×	
Circuit		6.8.3 Compare		Ø	
		6.8.4 New edit target read		×	
		6.8.5 List of files			
			File name	0	
			Classification	0	
			Size	0	
			Date	0	
			Time	0	
			Header statement	0	
			No. of files	0	
			Continuous max. open capacity Entire open capacity	0	
		6.8.6 Connection designation			
		0.0.0 Connection designation	Peripheral side interface	0	
			PLC side interface	×	Fixed
			Target CPU	×	Fixed
			Target memory	×	Fixed
		6.8.7 Remote operation	CPU status display	Ô	
			RUN	©	
			STOP	0	
			PAUSE	×	
			STEP-RUN		
				×	
			Latch clear	×	
			Reset	×	
			Operation during RUN, STEP-RUN	×	
			Execution destination designation	×	L
			Execution unit designation	×	
		6.8.8 Write option		×	For write during run

List of on-line section functions (2) ③: Possible, × : Support not possible/not determined

Mode	Function	Menu	Detailed function	Support	Remarks
	6.9 Display	6.9.1 Circuit display changeover			
	menu		Device name display	O	
			Comment display	Ø	
			Statement display	0	
			Display with note	Ø	
	6.10 Monitor and test	6.10.1 Device batch monitor			
	menu		Bit device monitor display	0	
			Word device monitor display	0	
			Bit and word monitor	0	
			Bit multipoint monitor		
			Word multipoint monitor	0	
			Timer/counter mulipoint monitor	0	
			Target device change Decimal/hexadecimal display	-	
			changeover	Ø	
			Integer/real number display changeover	Ø	
				0	
			$0 \rightarrow F/F \rightarrow 0$ display changeover Forced ON	0	
			Forced OFF	0	
		6.10.2 Multiple device batch monitor			
		0.10.2 Multiple device batch monitor	Bit device monitor display	0	
			Word device monitor display	0	
			Decimal/hexadecimal display		
			changeover	Ø	
			Integer/real number display changeover	Ø	
			Registration device erase	O	
			Forced ON	Ø	
			Forced OFF	Ø	
Circuit node		6.10.3 ON/OFF cause automatic search		Ø	
		6.10.4 Scan time measure		×	
		6.10.5 Device registration monitor	Bit device monitor display	O	
			Word device monitor display	O	
			Digit designation monitor display	Ø	
			Timer/counter monitor display	Ø	
			Double word monitor display	Ø	
			Index modification monitor display	Ø	
			16-bit integer designation	Ø	
			32-bit integer designation	Ø	
			Real number designation	Ø	
			Character designation	O	
			Registration device erase	Ø	
		6.10.6 Monitor and test menu			
			Constant monitoring	×	
			Word device condition	0	
			Bit device condition	Ø	
			Step No.	×	
		6.10.7 Monitor stop condition setting			
			Monitoring does not stop	0	
			Word device condition	0	
			Bit device condition	0	
		6.10.8 Monitor data	Operation status	×	
		registration/application		Ø	
		6.10.9 Device test	Earoad ON		
			Forced ON	0	<u> </u>
				0	
			Forced ON/OFF reverse	0	
			Current value change	\bigcirc	L

List of on-line section functions (3) \bigcirc : Possible, \mathbf{x} : Support not possible/not determined

APPENDIX 1. OPERATION METHODS USING GPPQ APPENDIX 1.1 GPPQ Function Outline and Functions Supported by the M600, M60/60S Series

Mode	Function	Menu	Detailed function	Support	Remarks
	6.10 Monitor	6.10.10 Sampling/monitoring trace		×	
	and test	6.10.11 Step execution		×	
	menu	6.10.12 Partial execution		×	
		6.10.13 Skip execution		×	
		6.10.14 Simulation		×	
Circuit mode		6.10.15 Monitor column numeric			
mode		value display changeover	Numeric value display format	0	
			No. of display level	O	
		6.10.16 Program execution status monitor		×	
	6.11 Option	6.11.1 Monitor destination setting			
	menu	of the morned accuration county		×	
	8.2 PLC menu				
Para-					
meter				\rightarrow	Refer to 6.8
mode				,	PLC menu
	9.2 Device				
	value input			×	
	9.3 Default				
	value			×	
	range			^	
Device	9.4 Buffer				
mode	memory				
	simulation			×	
	9.5 PLC menu			\rightarrow	Refer to 6.8
	9.6 Edit menu	9.6.1 Simulation range		x	PLC menu
	10.2 Drive	9.0.1 Simulation range	Internal RAM	Ô	Fixed
	name		IC memory card		Fixed
	selection			×	Tixea
	10.3 File			O	
	selection				
	10.4 File menu	10.4.1 Read		0	
		10.4.2 Write		0	
		10.4.3 Compare 10.4.4 New edit target read			
		10.4.5 List of files		Ö	
		10.4.6 Delete		Ő	
		10.4.7 File quit		Ő	
	10.5 PLC	10.5.1 Read		Õ	
	menu	10.5.2 Write			
			Parameter	×	
On- line			Sequence program	Ø	
mode			Entire range	0	
			Range designation	X	
			Device comment Device default value	0	
			Simulation data	×	
			File register	X	
			Device memory	×	
			Entire range	×	
			Range designation	X	
		10.5.3 Compare		Ø	
		10.5.4 New edit target read		O	
		10.5.5 List of files			
			File name	0	ļ
			Classification	0	1
			Size	0	
			Date Time	0	<u> </u>
			Header statement		1
			No. of files		1
			Continuous max. open capacity	 0	+
			Entire open capacity	Ő	1
		10.5.6 Connection designation			1
			Peripheral side interface	Ø	1
			PLC side interface	×	Fixed
			Target CPU	×	Fixed
	1		Target memory	×	Fixed

List of on-line section functions (4) (2) : Possible, × : Support not possible/not determined

APPENDIX 1. OPERATION METHODS USING GPPQ APPENDIX 1.1 GPPQ Function Outline and Functions Supported by the M600, M60/60S Series

List of on-line section functions (5) () : Possible, X : Support not possible/not determined

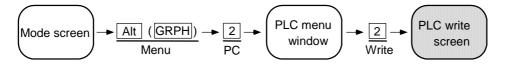
Mode	Function	Menu	Detailed function	Support	Remarks
On- line mode	10.5 PLC	10.5.7 Remote operation	CPU status display	O	
	menu		RUN	O	
			STOP	O	
			PAUSE	×	
			STEP-RUN	×	
			Latch clear	×	
			Reset	×	
			Operation during RUN, STEP-RUN	×	
			Execution destination designation	×	
			Execution unit designation	×	
		10.5.8 Write option			For write
				×	during run
		10.5.9 Key word registration		×	
		10.5.10 Device memory operation		×	
		10.5.11 PLC memory batch			
		operation		×	
		10.5.12 Delete		O	
		10.5.13 Header statement creation		×	
	10.6 Search	10.6.1 Head/end search		×	
		10.6.2 File search			
	menu			X	-
		10.6.3 Frequency search		×	
		10.6.4 Time search		X	
		10.6.5 Data search		X	
	10.7 Trace	10.7.1 Sampling trace		×	
	menu	10.7.2 Monitoring trance		×	
		10.7.3 Status latch		×	
		10.7.4 Program trace		×	
	10.8 Edit menu	10.8.1 Cut/copy/paste		×	
	10.9 Test menu	10.9.1 Device test		×	
			Forced ON	Ö	
			Forced OFF	Ŏ	
			Forced ON/OFF reverse	Ő	
			Current value change	Ö	
	10.10 Window	40.40.4 Display window shares			
	menu	10.10.1 Display window change		Ø	
	11.2 Diagnosis				
	target			×	
	selection			~	
	11.3 Current				
	error			×	
	display			~	
	11.4 Fault				
	history			×	
	display			~	
	11.5 CPU				
PLC diagno- sis mode	message			×	
	11.6 Unit				
	detailed			×	
	display			^	
	11.7 File menu			×	
				^	
	11.8 PLC			×	
	menu				-
	11.9 Search			×	
	menu				-
	11.10 Display			×	
	menu				
	11.11 Network			×	
	menu		1		
	11.12 Window			×	
	menu				
	11.13 Option			×	
	menu			^	
File	13.2 PLC				Refer to 6.8
File mainte-	menu			\rightarrow	PLC menu
nance	13.3 IC card			~	
				×	1
mode	menu				

Appendix 1.2 Ladder Transfer to the CNC Controller

The method of transferring a ladder to the CNC controller with the GPPQ (especially the restrictions and M600, M60/60S characteristic operations) is explained below.

Appendix 1.2.1 Menu selection

The screen is selected from the menu using the following GPPQ basic operation.



Appendix 1.2.2 Screen operation

The required options are selected and executed on the following screen.

[Write to PLC]	
Target PLC N Target Mem I 1. File 1. File Na	Internal RAM Title []] ame [] Title []
	1. [*] Parameter
3 4 5	2. [*] Seq/SFC Prog 1. (*) Whole Range 2. () Step Range] - [] 3. [] Device Comment 3. () Step Range P [] - [] 4. [] Dev Init Value 4. () Block Range] - [] 5. [] Simulation Data 6. [] File Register 1. (*) Whole Range 2. () Specify ZR[] - []
2. Device Mem 1	1. [] Internal 1. (*) Whole Range 2. () Specify Detail Range
	Execute(Y) Cancel(N)
	Ctrl+L : filelist Ctrl+D : directo Space : sele Esc : close

[Restrictions]

The following options of [2. Tgt] under [1. File] can be selected.

- [1. Parameter]
- [2. Seq/SFC Prog] and [1. Whole Range]
- [3. Device Comment]

Note that nothing will be transferred even if [1. Parameter] is selected.

Appendix 1.2.3 Operation during a transfer error

The ladder data is converted to the ladder machine code characteristic to the CNC controller simultaneously with the ladder transfer from the GPPQ to the CNC controller. A conversion error will occur if devices or instruction formats are used that are not supported by the M600, M60/60S Series. During a conversion error, the following message appears at the bottom of the GPPQ screen after the M600 ladder machine code is converted to an "NOP code" and transferred to the last step.

Cannot communicate with PLC. Error No.=4070

The following warning statement appears in the header statement item when the file having the conversion error is displayed with the PLC file list function.

[List]					
:					
File	Туре	Size	Data	Time	Title
PLCTEST	QnA Seq	12345	97-11-18	10:34	[**WARNING: Checksum ERROR!!**]
:					

If an attempt is made to run the PLC in this status, the following alarm message will appear on the NC side, and the PLC will not run.

SY0002 User ladder code error

Appendix 1.2.4 Error step No. confirmation method

The error step can be confirmed using the PLC compare function. The mismatched contents appear as in the following example when the PLC comparison is executed. Refer to "Appendix 1.4 Ladder comparison with the CNC controller" for details.

[Sequence Program Diff List]

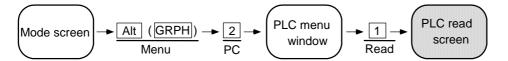
[Sequence Program Diff List]						
	<mem< td=""><td>ory></td><td></td><td></td><td><plc< td=""><td>></td></plc<></td></mem<>	ory>			<plc< td=""><td>></td></plc<>	>
Step	Ins	I/O		Step	Ins	I/O
15	AND=	R4918		15	NOP	
		K106				
18	+	R4916		16	NOP	
		K10000				
		D87				
22	END			17	NOP	
	No Da	ta exists.		18	+	R4916
						K10000
						D87
	No Da	ta exists.		22	END	
PgDn : Next page Esc: Clos			Esc: Close			

Appendix 1.3 Ladder Read from the CNC Controller

The method of reading a ladder from the CNC controller to the GPPQ is explained below.

Appendix 1.3.1 Menu selection

The screen is selected from the menu using the following GPPQ basic operation.



Appendix 1.3.2 Screen operation

The file names are designated and executed on the following screen.

File name designation method

Input the file name stored in the read target memory.

Display the read target memory list screen by pressing Ctrl + D.

Display the file list screen by pressing Ctrl + L.

After selecting the file using \uparrow and \downarrow , display the file name selected in the file name designation column by pressing Enter.

[Read from PL	C]
-	RS232C <> QnACPU Network : 0 Station : FF PC Type : Q4A Internal RAM Title []
	Name [] Title []
	1. [*] Parameter 2. [*] Seq/SFC Prog 1. (*) Whole Range 2. () Step Range] -[] 3. [] Device Comment 3. () Step Range P [] - [] 4. [] Dev Init Value 4. () Block Range] -[] 5. [] Simulation Data 6. [] File Register 1. (*) Whole Range 2. () Specify ZR[] -[] 1. [*] Internal 1. (*) Whole Range 2. () Specify Detail Range
	Execute(Y) Cancel(N)
	Ctrl+L : filelist Ctrl+D : directo Space : sele Esc : close

[Restrictions]

The following options of [2. Tgt] under [1. File] can be selected.

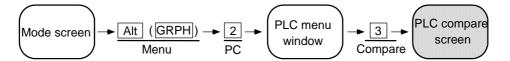
- [2. Seq/SFC Prog] and [1. Whole Range]
- [3. Device Comment]

Appendix 1.4 Ladder Comparison with CNC Controller

The method of comparing the ladders between the CNC controller and GPPQ is explained below.

Appendix 1.4.1 Menu selection

The screen is selected from the menu using the following GPPQ basic operation.



Appendix 1.4.2 Screen operation

The file names are designated and executed on the following screen. The options that can be selected are the same as those of the ladder read.

File name designation method

Input the file name stored in the read target memory.

Display the read target memory list screen by pressing Ctrl + D.

Display the file list screen by pressing Ctrl + L.

After selecting the file using \uparrow and \downarrow , display the file name selected in the file name designation column by pressing Enter.

[PLC compare]					
Interface Target PLC Target Mem	RS232C <> Network : 0 Internal RAM	QnACPU Station : FF Title	PC Type : Q4	4A	1
1. File 1. File I	Name [] 1. [*] Parameter	Title []
	Execute(Y) Cancel(N)			
		Ctrl+L : filelist C	trl+D : directo	Space : sele	Esc : close

When the comparison contents do not match, a screen with the mismatched contents appears.

[Sequence Program Diff List]						
	<mem< td=""><td>ory></td><td></td><td></td><td><plc< td=""><td>></td></plc<></td></mem<>	ory>			<plc< td=""><td>></td></plc<>	>
Step	Ins	I/O		Step	Ins	I/O
15	AND=	R4918		15	NOP	
		K106				
18	+	R4916		16	NOP	
		K10000				
		D87				
22	END			17	NOP	
	No Da	ta exists.		18	+	R4916
						K10000
						D87
	No Da	ta exists.		22	END	
PgDn : Next page					Esc : Close	

Appendix 1.5 PLC-Related Data Development Procedure

This section explains a procedure for developing PLC-related data such as alarm messages, operator messages, PLC switches. The following items are the same as those of GX Developer. Refer to the GX Developer side.

File name, development procedure, message data description method

Appendix 1.5.1 Conversion to GPPQ data

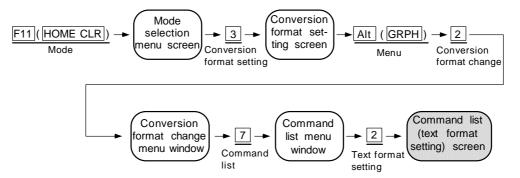
Use the "CNVQ (data conversion software package)" for conversion from text data to GPPQ data. Instead of text data, spreadsheet software data can also be converted to GPPQ data. Refer to the Operating Manual for details.

(1) Initialization

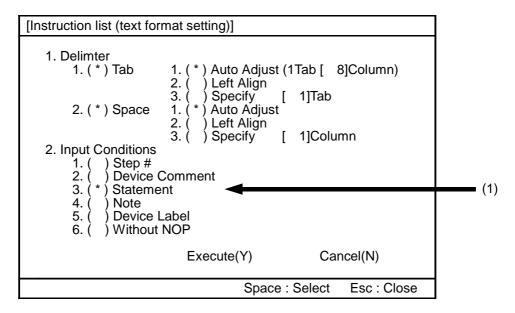
After CNVQ is started, the project file (file for setting the drive/path name, system name, machine name, file name, etc.) is read or newly created. Refer to the Operating Manual for the operation method.

(2) Conversion Format Setting

The screen is selected from the menu using the following CNVQ basic operation.

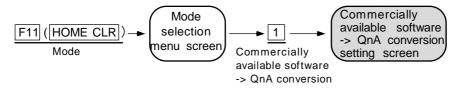


The conversion format is set on the following screen. Select the "Statement" item shown by the arrow (1) when converting message data. Refer to the CNVQ Operating Manual for details.



Appendix 1.5.2 Commercially available software QnA conversion setting

The screen is selected from the menu using the following CNVQ basic operation.

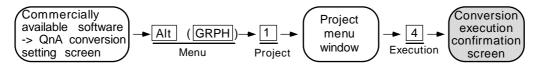


The conversion source/destination directory path and conversion file name, etc., are set on the following screen. Refer to the Operating Manual for details.

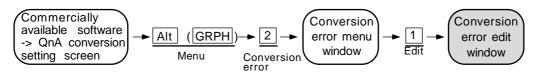
Other> QnA Convert	C:M600\TEST\SETUPM1	<ins></ins>	F11:Mode			
Conversion Destination File Drive/Path[C:\GPPQ\USR						
Conversion Source File Drive/Path[C:\CNVQ\USR\M60	0\TEST					
# Conv SourceFile DestFile	Data	# FileType ConvType	e Another			
000 [] [M1TEST] [M600\TE] <text> < List ></text>				
	j į]< >< ;	> []			
	j []< >< ;	> []			
	j []< >< ;	> []			
004 [] [] [] [] < > < ;	> []			
005 [][][] [] < > < ;	> []			
006 [] []] [] [] < > < 2	> []			
007 [][][] [] < > < ;	> []			
008 [] [] 800] [] < > < ;	> []			
009 [] []] [] [] < > < ;	> []			
010 [] [] [] [] < > < :	> []			
PgUp : Prev Page PgDn : Next	t Page Ctrl+	P :Drive/Path Enter	: Decide			

Appendix 1.5.3 Conversion execution

The screen is selected from the menu using the following CNVQ basic operation.



The conversion status appears at the bottom of the screen. If "There were *n* conversion errors" appears when the conversion is finished, display the conversion error edit screen from the menu using the following CNVQ basic operation to confirm the error contents.



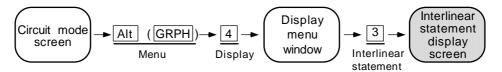
Appendix 1.5.4 Operation with the GPPQ

Message data in the GPPQ is handled as "Integrated type interlinear statements" in the PLC program. "Integrated type interlinear statements" are interlinear comments to help in understanding the PLC program. Interlinear comments transferred with the PLC program to the controller are called "integrated type".

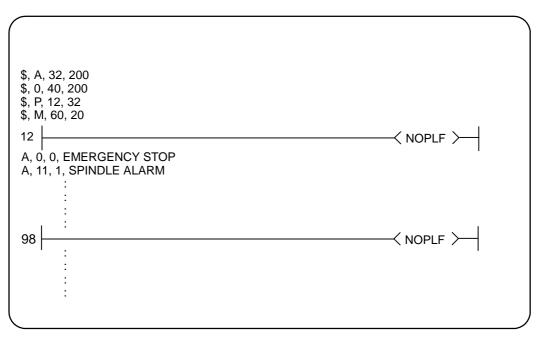
"Interlinear statements" can be displayed in the "Circuit mode", and edited on the "Interlinear statement edit screen".

(1) Interlinear Statement Display in the Circuit Mode

The screen is selected from the menu using the following GPPQ basic operation.

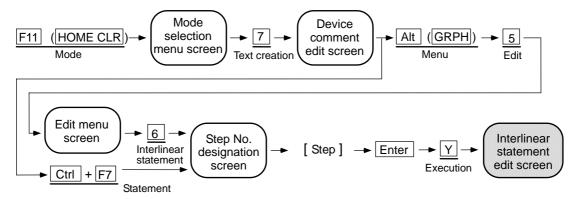


The following appears. At that time, the page break code and end code appear as normal ladder codes.



(2) Interlinear Statement Editing

The screen is selected from the menu using the following GPPQ basic operation.



The message data can be edited on the following screen. The GPPQ data can be converted to text data using the CNVQ to save the edited data as text data. Refer to the CNVQ Operating Manual for details.

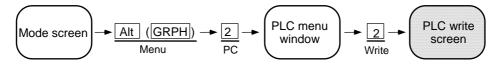
Document Sta	atmnt CPU: Q4A
Step	
Level	1234567890123456789012345678901234567890123456789012345678901234
[0]	[\$, A, 32, 200]
[3]	[\$, 0, 40, 200]
[6]	[\$, P, 12, 32]
[9]	[\$, M, 60, 20]
[12]	[A, 0, 0, EMERGENCY STOP]
[15]	[A, 11, 1, SPINDLE ALARM]
[]	[:]
[]	[:]
[]	[:]
[]	[:]
[]	[:]
[]	[:]
[]	[:]
[]	
[]	[:]

Appendix 1.5.5 Transfer to the controller

The following shows the method of transferring a message from the GPPQ to the CNC controller. The transfer method is the same as that of the ladder code. Ladder codes and message data are distinguished by their file names only.

(1) Menu Selection

The screen is selected from the menu using the following basic operation.



(2) Screen Operation

Transfer is executed in the following screen. An example of transferring a message 1st language file "M1TEST.GPG" is shown here.

[Write to PLC]	
U U	RS232C <> QnACPU Network : 0 Station : FF PC Type : Q4A Internal RAM Title []
1. File 1. File	Name [M1TEST] Title [message 1st language test]
2. Tgt 2. Device Mem	1. [] Parameter 2. [*] Seq/SFC Prog 1. (*) Whole Range 2. () Step Range [] -[]] 3. [] Device Comment 3. () Step Range P[]] - []] 4. [] Dev Init Value 4. () Block Range [] -[]] 5. [] Simulation Data -[]] -[]] 6. [] File Register 1. (*) Whole Range 2. () Specify ZR[]] - []] 1. [*] Internal 1. (*) Whole Range 2. () Specify Detail Range
	Execute(Y) Cancel(N)
	Ctrl+L : filelist Ctrl+D : directo Space : sele Esc:close

Appendix 1.5.6 Reading and comparing from the controller

The following describes the method of reading and comparing a message from the CNC controller to the GPPQ. The method of reading and comparing is the same as that of ladder codes. Ladder codes and message data are distinguished by their file names only.

(1) Menu Selection/Screen Operation

Refer to the following sections for operation methods.

	•
For reading	: "Appendix 1.3 Ladder Read from the CNC Controller"
For comparing	: "Appendix 1.4 Ladder Comparison with CNC Controller"

(2) Message Read Format

The message description format was shown in "5.3.1 Description format", but there are no special rules concerning provision of descriptions in the setting area or the order of message description in the message area. For that reason, the description format may differ between transfer and reading of the message data.

The following shows the format during reading as the "Standard description format".

	Alarm message setting Operator message setting PLC switch setting	(a)	
	Comment message setting	(4)	
	Alarm messages	(b)	
	Operator messages	(C)	
	PLC switches	(d)	
	Comment messages	(e)	
	NOPLF		
	END		
1			

(a) Setting area

The settings are described in order of alarm, operator, PLC switch and comment. The maximum value is described if the setting is abbreviated.

(b) Alarm messages

Each message data is described in order of the index Nos.

(c) Operator messages

The same as the alarm messages.

(d) PLC switches

Each message data is described in order of the switch Nos.

(e) Comment messages

These messages are described in the same order as described before transfer.

(f) Others

- Spaces and tabs are not included before and after the comma(,) separating the message data factors.
- The message character string is handled the same as normal data even when blank.
- The NOPLF code between messages is described to the position to which the message data following the NOPLF code during transfer moved.

(3) Message Data Comparison

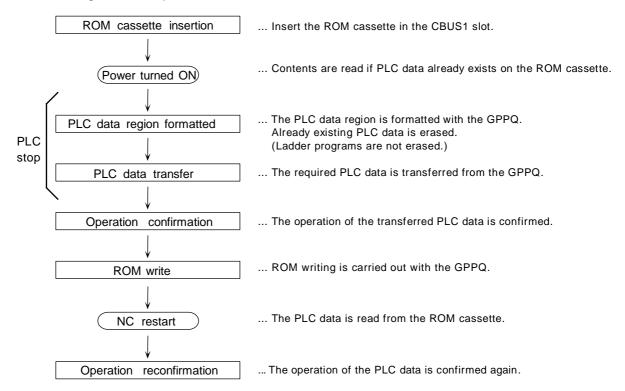
Message data comparison can be executed in the same manner as the ladder program, however, note that the target compared is the ladder code (NOPLF, END) only. Therefore, message data described as "Integrated type interlinear statements" are not compared. When comparing, read the data to the GPPQ side using the read function, then compare using the master file and file comparison function.

Appendix 1.6 Procedure for ROM Writing

The procedure to write the developed PLC program and PLC related data to ROM is explained here. The following item are the same as that of GX Developer. Refer to the GX Developer side. • Target Data to be written to ROM

Appendix 1.6.1 Procedure to write to ROM

The following shows the procedure to write to ROM.

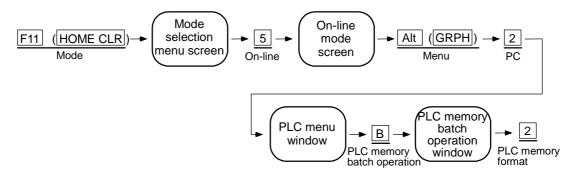


Appendix 1.6.2 PLC data region formatting

It is recommended to initialize the data region before ROM writing. (This is not absolutely required, however.)

The difference from file deletion is that the file control region is initialized.

The screen is selected from the menu using the following basic operation.



The PLC related data (excluding ladder programs) is completely erased by the above operation.

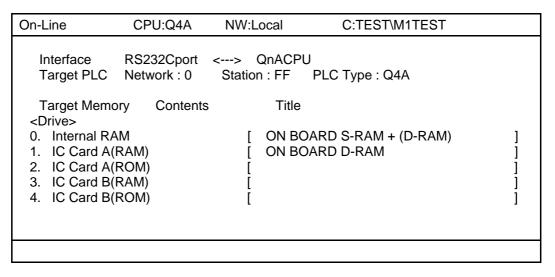
Appendix 1.6.3 ROM writing from the GPPQ

(1) On-line mode

ROM writing operations are carried out on the On-line mode screen. The mode is selected from the menu using the following basic operation.



The following drive name selection screen or file name selection screen appears. If the file name selection screen appears, it can be returned to the drive name selection screen with the Escape [esc] key.



(2) Drive name selection screen

The drive mounted on the CNC controller can be selected, and the following operations carried out, on the drive name selection screen.

- Copying between drives (Including flash ROM writing)
- Displaying the drive details (date of creation, size)
- Confirmation of the drive open capacity, etc.

The mounting and PLC data availability is checked for each drive. The header statement appears when PLC data exists. There are sections in which the drive target memory and the actual CNC controller drive meaning differ, so confirm with the header statement. The following shows the meanings in the CNC controller of each drive.

Drive	Screen display	Meaning in the M600	Header statement display
0	Internal RAM	Internal S-RAM (ladder programs)	ON BOARD S-RAM + (D-RAM)
1	IC memory card A (RAM)	Internal D-RAM (other than ladder programs)	ON BOARD D-RAM
2	IC memory card A (ROM)	Internal F-ROM	ON BOARD F-ROM
3	IC memory card B (RAM)	Expansion S-RAM (for future use)	
4	IC memory card B (ROM)	Expansion F-ROM	ADD ON F-ROM

• Drive 0

This refers to the file groups stored in the internal S-RAM (ladder programs) and internal D-RAM (other than ladder programs).

File transfer with GPPQ is carried out in this drive 0.

Only internal S-RAM information is displayed for the drive capacity.

• Drive 1

This refers to the file groups stored in the internal D-RAM (other than ladder programs). Only internal D-RAM information is displayed for the drive capacity.

• Drive 2

This refers to the file groups stored in the internal F-ROM. The ladder related data storage availability to the internal F-ROM differs depending on the system.

Approx. 30 seconds are required until the finish of the writing (copying to drive 2) process to the internal F-ROM.

• Drive 4

This refers to the file group stored in the cassette F-ROM inserted in the expansion bus. The expansion bus insertion position is automatically judged.

Approx. 10 seconds are required until the finish of the writing (copying to drive 4) process to the cassette F-ROM.

(3) Copying operation between drives (flash ROM writing operations)
$\uparrow, \downarrow \longrightarrow F8 \longrightarrow \uparrow, \downarrow \longrightarrow Enter$
File selection Copy source Copy destination Copy selection selection copy
Select the copy source target memory using \uparrow and \downarrow , and press F8. Set the band cursor to the copy destination target memory drive. The following dialog box appears when Enter is pressed.
Do you want to copy from Internal RAM to IC Card B(ROM)?
Yes(Y) No(N)
Press Y to execute. The copy process between drives is executed in the background. The write process starting message is displayed immediately after execution, and the next operation is not accepted during the copy process. The copy process time differs depending on the copy target. A message will appear at the first operation after the copy process is finished if an error occurred in the copy process. No message will appear if the copy process finished normally. The following shows the meanings of the messages during and after execution.

Cannot communicate with PLC. Error No. = 4068 The drive background writing process has started.

Cannot communicate with PLC. Error No. = 4008 Other processes cannot be accepted during drive writing process. Wait a few seconds and execute again.

Cannot write correctly to the ROM

The flash ROM writing was unsuccessful.

APPENDIX 2. DIFFERENCES IN DEVELOPMENT ENVIRONMENT BETWEEN PLC4B AND M600, M60/60S

This section explains differences between the PLC4B development environment and M600, M60/60S series PLC development environment.

Appendix 2.1 Development Tools, etc.

In the M600, M60/60S, a user PLC development environment that used the MELSEC PLC development tool was constructed. Consequently, the tools used at each development process differ. A comparison of each process is shown in "Table 2.1 List of development tool comparisons". Refer to the respective Instruction Manuals for details on each tool.

Development process		PLC4B development environment	MELSEC PLC development environment	
Application from the old model	Tool	Ladder and message conversion tool (CHG4PB)	Ladder list converter (CLST6L)	
	Hardware	PC9801/PC-AT	PC-AT	
List -> ladder conversion	Tool	PLC development software (list section) (LIST4B)	GX Converter	
	Hardware	PC9801/PC-AT	PC-AT	
Ladder creation	Tool	PLC development software (ladder section) (PLC4B)	GX Developer	
	Hardware	PC9801/PC-AT	PC-AT	
Message creation	Tool	PLC development software (ladder section) (PLC4B)	Text editor -> GX Converter -> GX Developer	
	Hardware	PC9801/PC-AT	PC-AT	
Transfer to the CNC	Tool	PLC4B <-> FLD <-> M500 controller	GX Developer <-> RS232C <-> CNC controller	
	Hardware	Via FLD	Via RS-232C	
Monitor	Tool (1) Hardware		GX Developer PC-AT <-> CNC controller	
	Tool (2) Hardware	PLC onboard (ONBD) M500 controller	PLC onboard CNC controller	
ROM writing	Tool Hardware	PLC onboard -> F-ROM M500 controller	I/O screen -> F-ROM CNC controller	
Print output	Tool (1)	PLC development software (ladder section) (PLC4B)	GX Developer	
	Hardware	PC9801/PC-AT	PC-AT	
	Tool (2) Hardware	PLC onboard (ONBD) M500 controller		

Table 2.1 List of development tool comparisons

Appendix 2.2 Devices and Device Assignments

In the M600 M60/60S, the device types and assignments have been reconsidered by supporting the user PLC development environment that used the MELSEC PLC development tool. A comparison of the differences of each device is shown in the following tables "List of device differences".

Refer to the "List of M600 PLC I/F" for details on assignments.

Device	M500 device No.	M600 device No.	Remarks
Х	X0 to X4FF		
U	U0 to U17F	X0 to XAFF	Integrated to X and assignment changed.
I	I0 to I4BF		changed.
Y	Y0 to Y57F		
W	W0 to W1FF	Y0 to YDFF	Integrated to Y and assignment changed.
J	J0 to J63F		onangea.
S	S0 to S1FF		Divided to X and Y and assignment changed.
М	M0 to N5119	M0 to N5119	Integrated to M and assignment changed.
G	G0 to G3071	M5120 to M8191	
F	F0 to F127	F0 to F255	
L	L0 to L255	←	
E	E0 to E127	SM0 to SM127	
	T0 to T15	T0 to T15	
	Q0 to Q39	T16 to T55	
T/Q	T16 to T95	T56 to T135	Integrated to T and assignment
1/Q	Q40 to Q135	T136 to T231	changed.
	T96 to T103	T232 to T239	
	Q136 to Q151	T240 to T255	
С	C0 to C23	C0 to C23	Integrated to C and assignment
В	B0 to B103	C24 to C127	changed.
D	D0 to D1023	<i>←</i>	
R	R0 to R8191	<i>←</i>	Assignment changed.
А	A0, A1		Discontinued (replaced by D and R registers).
Z	Z	Z0	
V	V	Z1	Discontinued (replaced by Z1).
N	N0 to N17	<i>←</i>	
Р	P0 to P255	←	
к	K-32768 to K32767 K-2147483648 to K2147483647	←	
н	H0 to HFFFF H0 to HFFFFFFFF	←	

Table 2.2.1 List of device differences (M600M series)

	M500 device No.		N	A600 device No.		Remarks
Х	X0 to X4BF	->	X0	to X4BF		
U	U0 to U17F	->	X4C0	to X63F		Input for 2nd part system
Ι	I0 to I3FF	->	X640	to XA3F	Х	Input for 3rd to 8th part system
S	S0 to S3F	->	XA40	to XA7F		Input for 3rd and 4th spindle
S	S80 to SBF	->	XA80	to XABF		Input for 5th and 6th spindle
Υ	Y0 to Y53F	->	Y0	to Y53F		
W	W0 to W1FF	->	Y540	to Y73F		Output for 2nd part system
J	J0 to J63F	->	Y740	to YD7F	Y	Output for 3rd to 8th part system
S	S40 to S7F	->	YD80	to YDBF		Output for 3rd and 4th spindle
S	SC0 to SFF	->	YDC0	to YDFF		Output for 5th and 6th spindle
М	M0 to M5119	->	M0	to M5119	М	
G	G0 to G3071	->	M5120) to M8191		
F	F0 to F127	->	F0	to F127	F	
L	L0 to L255	->	L0	to L255	L	
Е	E0 to E127	->	SM0	to SM127	SM	
Т	T0 to T15	->	Т0	to T15		10ms timer
Q	Q0 to Q39	->	T16	to T55		10ms timer (fixed timer)
Т	T16 to T95	->	T56	to T135	т	100ms timer
Q	Q40 to Q135	->	T136	to T231		100ms timer (fixed timer)
Т	T96 to T103	->	T232	to T239		100ms integrated timer
Q	Q136 to Q151	->	T240	to T255		100ms integrated timer (fixed timer)
С	C0 to C23	->	C0	to C23	с	
В	B0 to B103	->	C24	to C127	Ŭ	
D	D0 to D1023	->	D0	to D1023	D	
R	R0 to R8191	->	R0	to R8191	R	
A	A0, A1	->				Discontinued (replaced by D and R registers).
Ζ	Z	->	Z0		Z	
V	V	->	Z1			
Ν	N0 to N7	->	N0	to N7	Ν	
Р	P0 to P255	->	P0	to P255	Р	
К	K-32768 to K32767 K-2147483648 to K2147483647	->	K-2147	68 to K32767 7483648 to 47483647	к	
Н	H0 to HFFFF H0 to HFFFFFFFF	->	H0 to H H0 to H	HFFFF HFFFFFFFF	Н	

PLC4B device No.			GX Developer device No.		Remarks
Х	X0 to X4BF	->	X0 to X4BF	x	
U	U0 to U17F	->	X4C0 to X63F	^	Input for 2nd part system
Υ	Y0 to Y53F	->	Y0 to Y53F	Y	
W	W0 to W1FF	->	Y540 to Y73F	1	Output for 2nd part system
М	M0 to M5119	->	M0 to M5119	М	
G	G0 to G3071	->	M5120 to M8191		
F	F0 to F127	->	F0 to F127	F	
L	L0 to L255	->	L0 to L255	L	
Е	E0 to E127	->	SM0 to SM127	SM	
Т	T0 to T15	->	T0 to T15		10ms timer
Q	Q0 to Q39	->	T16 to T55		10ms timer (fixed timer)
Т	T16 to T95	->	T56 to T135	Т	100ms timer
Q	Q40 to Q135	->	T136 to T231		100ms timer (fixed timer)
Т	T96 to T103	->	T232 to T239		100ms integrated timer
Q	Q136 to Q151	->	T240 to T255		100ms integrated timer (fixed timer)
С	C0 to C23	->	C0 to C23	с	
В	B0 to B103	->	C24 to C127	Ŭ	
D	D0 to D1023	->	D0 to D1023	D	
R	R0 to R8191	->	R0 to R8191	R	
A	A0, A1	->			Discontinued (replaced by D and R registers).
Ζ	Z	->	Z0	z	
V	V	->	Z1	2	
Ν	N0 to N7	->	N0 to N7	Ν	
Р	P0 to P255	->	P0 to P255	Р	
К	K-32768 to K32767 K-2147483648 to K2147483647	->	K-32768 to K32767 K-2147483648 to K2147483647	к	
Н	H0 to HFFFF H0 to HFFFFFFFF	->	H0 to HFFFF H0 to HFFFFFFFF	Н	

Table 2.2.3 List of device differences (M60 series)

PLC4B device No.			GX D	eveloper device	No.	Remarks
Х	X0 to X4BF	->	X0	to X4BF		
U	U0 to U17F	->	X4C0	to X63F		Input for 2nd part system
Ι	I0 to I3FF	->	X640	to XA3F		Input for 3rd to 8th part system
S	S0 to S1F	->	XA40	to XA5F	Х	Input for 3rd spindle
S	S40 to S5F	->	XA60	to XA7F		Input for 4th spindle
S	S80 to S9F	->	XA80	to XA9F		Input for 5th spindle
S	SC0 to SDF	->	XAA0	to XABF		Input for 6th spindle
Y	Y0 to Y53F	->	Y0	to Y53F		
W	W0 to W1FF	->	Y540	to Y73F		Output for 2nd part system
J	J0 to J63F	->	Y740	to YD7F		Output for 3rd to 8th part system
S	S20 to S3F	->	YD80	to YD9F	Y	Output for 3rd spindle
S	S60 to S7F	->	YDA0	to YDBF		Output for 4th spindle
S	SA0 to SBF	->	YDC0	to YDDF		Output for 5th spindle
S	SE0 to SFF	->	YDE0	to YDFF		Output for 6th spindle
М	M0 to M5119	->	M0	to M5119	М	
G	G0 to G3071	->	M5120	to M8191		
F	F0 to F127	->	F0	to F127	F	
L	L0 to L255	->	L0	to L255	L	
Е	E0 to E127	->	SM0	to SM127	SM	
Т	T0 to T15	->	Т0	to T15		10ms timer
Q	Q0 to Q39	->	T16	to T55		10ms timer (fixed timer)
Т	T16 to T95	->	T56	to T135	т	100ms timer
Q	Q40 to Q135	->	T136	to T231	1	100ms timer (fixed timer)
Т	T96 to T103	->	T232	to T239		100ms integrated timer
Q	Q136 to Q151	->	T240	to T255		100ms integrated timer (fixed timer)
С	C0 to C23	->	C0	to C23	с	
В	B0 to B103	->	C24	to C127	Ŭ	
D	D0 to D1023	->	D0	to D1023	D	
R	R0 to R8191	->	R0	to R8191	R	
А	A0, A1	->				Discontinued (replaced by D, R registers)
Ζ	Z	->	Z0		z	
V	V	->	Z1		~	
Ν	N0 to N7	->	N0	to N7	Ν	
Р	P0 to P255	->	P0	to P255	Р	
К	K-32768 to K32767 K-2147483648 to K2147483647	->	K-2147	68 to K32767 7483648 to 47483647	К	
Н	H0 to HFFFF H0 to HFFFFFFFF	->	H0 to H H0 to H	HFFFF HFFFFFFFF	Н	

Appendix 2.3 PLC Instructions

As for types and numbers of the PLC instructions, those of the PLC4B development environment and of the MELSEC PLC development environment are not different basically. However, some instructions have been changed because the user PLC development environment using the MELSEC PLC development tool has been supported in M600, M60/60S.

The instruction range that can be used in the MELSEC-QnA Series PLC program differs from the instruction range that can be used by the MELDAS Series. Because of this, some instructions that can be used by the M600, M60/60S cannot be handled with the GX Developer. There are also instructions that can be used by the GX Developer but cannot be used by the M600, M60/60S. When these are arranged, they are classified into the three following types.

- M600, M60/60S instructions that cannot be handled with the GX Developer
- M600, M60/60S instructions that the format differs from that of the GX Developer
- Instructions that can be used by the GX Developer, but cannot be used by the M600, M60/60S

Appendix 2.3.1 Instructions that cannot be handled with the GX Developer

Instructions that cannot be handled with the GX Developer are substituted with alternate instructions that can be handled with the GX Developer. Instructions that can be alternated are shown in "Table 2.3.1 Table of alternate instruction correspondence".

When some instructions described in "Table 2.3.1 Table of alternate instruction correspondence" are created with the GX Developer with the M600, M60/60S instruction sign left as is, an error results and creation cannot be carried out. Create the instructions using the GX Developer instruction sign described in the correspondence table.

When PLC programs containing alternate instructions are written from the GX Developer to the M600, M60/60S, they are rewritten to the original MELDAS Series instructions.

	Original I	MELDAS Series instruction	GX D	eveloper instruction
Classification	Instruction sign Symbol		Instruction sign	Symbol
Bit	DEFR	—[DEFR D]—	ANDP	D - ↑
Average value	AVE	[AVE S D n]-	S.AVE	[S.AVE S D n]
Carry flag set	STC		S.STC	[S.STC]
Carry flag reset	CLC		S.CLC	[S.CLC]
ATC	ATC	—[ATC Kn Rn Rm]-< Mm >—	S.ATC	—[S.ATC Kn Rn Rm Mm]-
ROT	ROT	[ROT Kn Rn Rm]-< Mm >	S.ROT	—[S.ROT Kn Rn Rm Mm]-
TSRH	TSRH	—[TSRH Rm Rn]-< Mn >—	S.TSRH	[S.TSRH Rm Rn Mn]
DDBA	DDBA	—[DDBA Rn / Dn]–	S.DDBA	—[S.DDBA Rn / Dn]-
DDBS	DDBS	—[DDBS Rn]-	S.DDBS	—[S.DDBS Rn]−
CAL1	CAL1	—[CAL1 Pn]—	S.CAL1	[S.CAL1 Pn]
	LDBIT	⊣[BIT S1 n]—	LD<=	├-[<= S1 n }
	ANDBIT	—[BIT S1 n]—	AND<=	—[<= S1 n]—
BIT	ORBIT	└-[BIT S1 n]-┘	OR<=	└-[<= S1 n}┘
	LDBII	-[Bll S1 n]	LD<>	├[<> S1 n]
	ANDBII	—[BII S1 n]—	AND<>	—[<> S1 n]—
	ORBII	└-[BII S1 n]-	OR<>	└-[<> S1 n]-

Table 2.3.1 Table of alternate instruction correspondence

[Note] Among the above instructions, the ranges of the usable instructions depends on the model.

Appendix 2.3.2 Instructions with the format that differs from that of the GX Developer

The device types and assignments have been reconsidered as "Appendix 2.2 Devices and Device Assignments".

The format of conventional "instructions used by inputting or outputting an accumulator (A0, A1)" is changed so that the general word register can be designated with arguments without fixing by A0 or A1 input or output because of the discontinuance of accumulator (A0, A1).

Format-changed instructions are shown in "Table 2.3.2 Table of format-changed instruction correspondence".

When some instructions described in "Table 2.3.2 Table of format-changed instruction correspondence" are created with the GX Developer with the conventional instruction sign left as is, an error results and creation cannot be carried out. Create the instructions using the GX Developer instruction sign described in the correspondence table.

		MELDAS Series	Format-c	Remarks	
Classification	Instruction sign	Symbol	Instruction sign	Symbol	Itemarks
Right rotation	ROR	_[ROR n]	ROR	—[ROR D n]-	*1
	RCR	[RCR n]	RCR	—[RCR D n]⊣	
	DROR	[DROR n]-	DROR	—[DROR D n]—	
	DRCR	—[DRCR n]−	DRCR	—[DRCR D n]−	
Left rotation	ROL	[ROL n]	ROL	—[ROL D n]─	
	RCL	[RCL n]	RCL	—[RCL D n]—	
	DROL	—[DROL n]─	DROL	[DROL D n]-	
	DRCL	{ DRCL n }	DRCL	—{ DRCL D n }→	
Search	SER	-{ SER S1 S2 n }	SER	—[SER S1 S2 D n]─	*2
Quantity of 1	SUM	_{SUM S}	SUM	[SUM S D]-	*3

Table 2.3.2 Table of format-changed instruction correspondence

*1 : D is the head No. of the rotation device (word 16-bit device)

*2 : D is the head No. of the device that stores the search results (word bit device)

*3 : D is the head No. of the device that stores the total No. of bits (word bit device)

Appendix 2.3.3 Instructions that can be used with the GX Developer, but cannot be used by the M600, M60/60S

When instructions that cannot be used by the M600, M60/60S are written from the GX Developer to the M600, M60/60S, they are rewritten to "NOP" instructions, and if they are run, an alarm will occur. (Note that instructions described in "Table 2.3.1 Table of alternate instruction correspondence" are rewritten to the corresponding M600, M60/60S instructions.)

"Instructions that can be used by the GX Developer, but cannot be used in the M600, M60/60S " are defined by the following expression.

"Instructions that can be used by the GX Developer, but cannot be used in the M600, M60/60S" = "All instructions described in the QnA Programming Instruction Manual"

- ("All instructions described in the M600, M60/60S PLC Programming Instruction Manual"
 - + "Table 2.3.1 Table of alternate instruction correspondence"
 - + "Table 2.3.2 Table of format-changed instruction correspondence")

Refer to "Appendix 3. MELSEC QnA Series Instructions Lists."

APPENDIX 3. LIST OF INSTRUCTIONS USABLE WITH GX DEVELOPER

The following instruction lists are excerpts from the "QnACPU Programming Manual (Common Instructions)" (model name: QNACPU-P (KYOUTU) 13J522).

In these lists, the instructions "marked ×" are unavailable for the M600, M60/60S series. (When written from GX Developer to the M600, M60/60S series, they are replaced by "NOP" instructions.)

Appendix 3.1 Sequence Instructions

Contact Instructions		
Classifi- cation	Instruction sign	Symbol
Contact	LD	
	LDI	
	AND	
	ANI	
	OR	
	ORI	
		┝─┤╇┝──
		├ ─ ↓ ──
		↑
		_ ↓
		└┤∱┝─┘
	ØRF	

Contact instructions

Coupling instructions Classifi-Instruction Symbol cation sign Coupling ANB ANB ORB I.... ORB -| |-> MPS MPS MRD MRD MPP MPP ÌΝV MÈP MEF Vn EG/F Vn €GF

Shift instructions

Classifi- cation	Instruction sign	Symbol	
Shift	SFT	- SFT D-	
	SFID	- SFTP D-	

Master control instructions

Classifi- cation	Instruction sign	Symbol
Master control	MC	MC n D
	MCR	MCR n

Output instructions

Symbol

Classifi-

cation

Instruction

sign

Output	OUT	\rightarrow \rightarrow
	SET	– SET D–
	RST	RST D
	PLS	PLS D
	PLF	PLF D
	Êξ.	- FF D-
	DELTA	– DELTA D–
	DELTAP	- DELTAP D-

Classifi- cation	Instruction sign	Symbol	
Program end	FEND	FEND	
	END	END	

Other instructions			
Classifi- cation	Instruction sign	Symbol	
Stop	STOP	- STOP -	
No opera-	NOP		
tion	NOPLE	NOPLF	
	PAGE	PAGE n	

Appendix 3.2 Comparison Operation Instructions

Classifi- cation	Instruction sign	Symbol		
16-bit	LD=			
data	AND=			
compar- ison	OR=			
	LQ<>	<>> S1 S2 ⊣ ⊢		
	AND >	HH<> S1 S2		
	OR<>			
	LD>	> S1 S2 ⊣ ⊢		
	AND>	HH> S1 S2		
	OR>	> S1 S2		
	LQ<= /			
	OR<=			
	LD<	└── < S1 S2 I ⊢		
	AND<	HH< S1 S2		
	OR<			
	LQ>=	>= S1 S2 + -		
		>= S1 S2		
	or>=			

Comparison operation instructions

Comparison operation instructions (Continued)				
Classifi- cation	Instruction sign	Symbol		
32-bit	LDD=			
data	ANDD=			
compar- ison	ORD=			
	LQD<>	D<> S1 S2 ⊢		
	ANDO	H H D <> S1 S2		
	ORD <>	D<> S1 S2		
	LDD>	D> S1 S2 ⊣ ⊢		
	ANDD>	H H D > S1 S2		
	ORD>			
	LQD<=	D<= S1 S2++		
	ANDO =			
	ORD<=			
	LDD<	D< S1 S2 ⊢		
	ANDD<	⊢		
	ORD<	D< S1 S2		
		D>= S1 S2 ⊣ ⊢		
	ANDD =	⊣⊢D>= S1 S2		
	ORD>=			

Comparison operation instructions (Continued)

	Instruction sign	Symbol
Real number	LDE=	E= S1 S2 ⊣ ⊢
data compar-i	ANDE=	
son	ORE=	
	LDE<>	E<> S1 S2
	ANDE <>	H H E <> S1 S2
	ORE<>	E < > S1 S2
		E> S1 S2⊣⊢
		H H E> S1 S2
	ORE	E> S1 S2
	LDE ≜ =	E<= S1 S2 ⊢
	ANDEK=	
		E< S1 S2 ⊣ ⊢
	ANDE <	H H E < S1 S2
	ORE<	E< S1 S2
	LDE>=	E>= S1 S2++
	ANDE>=	HH E>= S1 S2
	ORE>=	

Comparison operation instructions (Continued)

Compa	rison operation	instructions (Continued)	
Classifi- cation	Instruction sign	Symbol	
Charac-	LD\$=	 \$= S1 S2 ⊢	
ter string	AND\$=	HH\$= S1S2	
data			
compar- ison	0R\$=	\$= \$1 \$2	
	LD\$<>	\$<> S1 S2 ⊢	
	AND\$<>	HH\$<> S1 S2	
	OR\$<>	\$<> \$1\$2	
	LD\$	\$> \$1 \$2 ⊣ ⊢	
	AND\$	\$ > S 1 S 2	
	OR\$>	+	
	ld\$< ≠ ∖	\$<= S1 S2 ⊣ ⊢	
	and\$≮ +	HH\$<= S1 S2	
	OR\$ 	\$<= \$1\$2	
	LD\$	S1 S2 ⊢	
	AND\$<	HH\$< S1 S2	
		\$< \$1 \$2	
	LØ\$>=	\$>= S1 S2 ⊣ ⊢	
	AND\$>=	H F \$>= S1 S2	
	DR\$>=	\$>= \$1\$2	
Block data	вксмр= /	BKCMP = S1 S2 D n	
compar- ison	BKCMP<>/	-BKCMP<>S1S2Dn	
	вксмр> /	- BKCMP> S1 S2 D n -	
	вкомр<≠	-BKCMP<=S1S2Dn-	
	вксмр∮	- BKCMP < S1 S2 D n	
	вксмр∕>=	BKCMP>=S1 S2 D n	
	вксмр⊨р	BKCMP=P S1 S2 D n	
	ВКСМРҶ́>Р	BKCMP<>P S1 S2 D n	
	BKØMP>R	BKCMP>PS1S2D n	
	BK∕CMP<=₽	BKCMP<=P S1 S2 D n	
	BKCMP ^{<} P	BKCMP <p d="" n<="" s1="" s2="" td=""></p>	
	₿КСМР>=Р ∖	-BKCMP>=P S1 S2 D n	

Arithmetic operation instructions			
Classifi- cation	Instruction sign	Symbo	ol
BIN 16-bit	+	+	S D
addition/ subtrac-	+P	- +P	S D -
tion	+	-+	S1 S2 D -
	+R	— +P	S1 S2 D
	- X		S D
	<u>∕</u> ₽ ∖	— — P	S D
	_		S1 S2 D
	-₹	— — P	S1 S2 D
BIN 32-bit	D+	— D+	S D -
addition/ subtrac-	D+P	D+P	S D
tion	D+	— D+	S1 S2 D
	D+P	— D+P	S1 S2 D
	d-X	— D—	S D
	р́-р 🔪	— D—P	S D
	D-	- D	S1 S2 D -
		— D—P	S1 S2 D
BIN 16-bit	*	- *	S1 S2 D
multipli- cation/	*	— *P	S1 S2 D
division	/	_ /	S1 S2 D -
	/P	— /P	S1 S2 D -
BIN 32-bit	D*	— D*	S1 S2 D
multipli- cation/ division		— D*P	S1 S2 D
	D/	— D/	S1 S2 D -
	D/B	— D/P	S1 S2 D

Arithmetic operation instructions

		n instructions	(Continued)
Classific ation	Instruction sign	Sym	bol
BCD 4-digit	В+	— B+	S D
addition/	B+P	– B+P	S D
subtracti on	В+	— B+	S1 S2 D
	B+P	— B+P	S1 S2 D
	в	— B—	S D
	B+P	— B-P	S D
	в-	— B—	S1 S2 D
	B-P	— B—P	S1 S2 D
BCD 8-digit	DB+	— DB+	S D –
addition/	DB+P	— DB+F	SD-
subtracti on	DB+	– DB+	S1 S2 D -
	DB+P	— DB+P	S1 S2 D
	DB-	— DB—	S D-
	DB-P	— DB—	P S D
	DB+	— DB—	S1 S2 D -
	DB+P	- DB-P	S1 S2 D
BCD 4-digit	Вж	— B*	S1 S2 D
multipli cation/	В∦Р	— B*P	S1 S2 D
division	В/	— B/	S1 S2 D
	B/P	— B/P	S1 S2 D
BCD 8-digit	DB*	- DB*	S1 S2 D
multipli cation/	DB*P	- DB*P	S1 S2 D -
division	рв/	— DB/	S1 S2 D
	DB/P	— DB/P	S1 S2 D

Arithmetic operation instructions (Continued)

	-	n instructions (Continued)
Classifi- cation	Instruction sign	Symbol
	E+	— E+ SD—
	Ę+P	E+P S D
Floating-	<u>e</u> + /	- E+ S1 S2 D -
point data	E+P	- E+P S1 S2 D -
addition/ subtrac-	e+ /	— E— SD—
tion	E-P	- E-P S D-
	E-\	- E- S1 S2 D -
	E-P	- E-P S1 S2 D -
Floating- point	E*	- E* S1 S2 D -
data	E*P	E*P S1 S2 D
multiplic- ation/	E/	- E/ S1 S2 D
division	E/P	E/P S1 S2 D
BIN block	BK+	BK+ S1 S2 D n
addition/ subtrac-	вк+р	BK+P S1 S2 D n
tion	ВК—	- BK- S1 S2 D n -
	BK⊂P	BK-P S1 S2 D n
Charac-	\$ \	- \$+ S D -
ter string	\$+P \	- \$+P S D -
data coupling	\$+ 	- \$+ S1 S2 D
BIN data	\$+P	- \$+P \$1 \$2 D
incre- ment	INC	
ment		
	DINC	
	\geq	ersion instructions
Classifi- cation	Instruction sign	Symbol
BCD conver-	BCD	BCD S D
sion	BCDP	BCDP S D
	DBCD	- DBCD S D-
	\sim	

	cation	sign		,			
	BIN conver-	BIN		BIN	S	D	-
	sion	BINP	_	BINP	S	D	-
		DBIN		DBIN	S	D	-
		DBIMP	_	DBINP	S	D	-
	BIN -> floating-	FLT	_	FLT	S	D	-
	point conver-	FLTP	_	FLTP	S	D	-
	sion		_	DFLT	S	D	-
		DFLTP	_	DFLTP	S	D	-
	Floating- point ->	INT	_	INT	S	D	\neg
	BIN	INTP	_	INTP	S	D	\neg
	conver- sion			DINT	S	D	_
		DINTP		DINTP	S	D	-
	BIN 16-bit <->	DBL		DBL	S	D	-
	32-bit	DBLR	_	DBLP	S	D	-
-	conver- sion	WORD		WORD	S	D	-
		WORDP		WORDP	S	D	-
	BIN -> gray code	GRY		GRY	S	D	-
-	conver-	GRYP		GRYP	S	D	-
	sion	DGRY	_	DGRY	S	D	-
		DGRYP		DGRYP	S	D	-
	Gray code ->	GBIN	_	GBIN	S	D	-
	BIN	GBINP	_	GBINP	S	D	-
	conver- sion	DGBIN		DGBIN	S	D	-
		DGBINP		DGBINP	S	D	-
	2's comple-	NEG		- NEG		D	+
	ment	NEGP		- NEGP		D	-
		DNEG /		- DNEG		D	-
		DNEGP/		- DNEGF	2	D	-
-4		ENEG		- ENEG		D	-
				- ENEGF	2	D	_
Н	Block conver-	вкесо	— Bł	(BCD S	D	n	_
<u>. </u>	sion	вквсор	— Bł	(BCDP S	D	n	_
	<u></u>]]	вквіл 🔪	— Bł	(BIN S	D	n	_
		H + + + + + + + + + + + + + + + + + + +	i				

ued) Data conversion instructions (Continued)

Instruction

sign

Symbol

Classifi-

cation

S D

- DBCDP

DBCDP

вквілр

BKBINP

S D n

		sfer instructions
Classifi- cation	Instruction sign	Symbol
16-bit data	MOV	- MOV SD-
transfer	MOVP	- MOVP SD-
32-bit data	DMOV	- DMOV SD-
transfer	DMOVR	DMOVP S D
Floating- point	ĘMOV ∕	- EMOV SD-
data transfer	EMOVP	EMOVP S D
Charac- ter string	\$мф∨/	- \$MOV SD-
data transfer	\$МОУР	- \$MOVP SD-
16-bit data NOT	см⊭∖	- CML SD-
transfer		CMLP S D
32-bit data NOT		DCML SD
transfer	ОСМЦР	- DCMLP SD-
Block transfer	BMOV	BMOV SDn
	BMOVR	BMOVP S D n
Same data	FMOV	- FMOV S D n
block transfer	FMOVE	- FMOVP S D n
16-bit data	хсн	- XCH S D
change	XCHP	- XCHP SD-
32-bit data	DXCH	DXCH S D
change	DXCHIR	DXCHP S D
Block data	вхсн	BXCH SD n
change	вхонр	BXCHP S D n
Upper/ lower	SWAP	- SWAP D
byte change	SWAPP	SWAPP D

Data transfer instructions

Program branch instructions

Classifi- cation	Instruction sign	Symbol
Jump	CJ	– CJ Pn–
	sej	- SCJ Pn-
	ЈМР	JMP Pn
	ØOEND	GOEND

Program execution control instructions

Classifi- cation	Instruction sign	Symbol
Interrupt disable	by /	— DI
Interrupt enable	EI	– El
Interrupt disable/ enable setting	IMASK	- IMASK S-
Return		- IRET

I/O refresh instructions

Classifi- cation	Instruction sign	Symbol
I/O refresh	RFS	RFS D n

Other useful instructions

Classifi- cation	Instruction sign	Symbol
Up/down	UDCNT1	UDCNT1 S D n
counter		UDCNT2 S D n
Teaching timer		TTMR D n
Special timer	STMR /	- STMR S n D -
Nearest access control	ROTC	ROTC S n1 n2 D
Ramp signal	RAM	RAMP n1 n2 D1 n3 D2
Pulse density	SPD	SPD S n D
Pulse output		PLSY n1 n2 D
Pulse width modula- tion	PWM	PWM n1 n2 D
Matrix input	MTR	MTR S D1 D2 n

Appendix 3.3 Application Instructions

l	• ·	ration instructions
Classifi- cation	Instruction sign	Symbol
AND	WAND	WAND S D
	WANDP	WANDP S D
	WAND	WAND S1 S2 D
	WANDR	WANDP S1 S2 D
	DAND	DAND S D
		DANDP S D
		DAND S1 S2 D
		DANDP S1 S2 D
	BKAND	BKAND S1 S2 D n
		BKANDP S1 S2 D n
OR	WOR	WOR S D
	WORP	WORP S D
	WOR	- WOR S1 S2 D -
	WORR	WORP S1 S2 D
	DOR	DOR S D
		DORP S D
	DOR	DOR S1 S2
	DOR	DORP S1 S2 D
	вког	BKOR S1 S2 D n
		BKORP S1 S2 D n
Exclusive OR	WXQR	WXOR S D
	WXORP	WXORP S D
	WXOR	WXOR S1 S2 D
	WXORR	WXORP S1 S2 D
	DXOR	DXOR S D
	DXORP	- DXORP S D-
		DXOR S1 S2 D
	DXORP	DXORP S1 S2 D
	BKXOR	BKXOR S1 S2 D n
		BKXORP S1 S2 D n
	v V	

Logical operation instructions

Logical operation instructions (Continued)

	•	
Classifi- cation	Instruction sign	Symbol
NOT- exclusive	wxnr /	WXNR SD
OR	WXNRP /	WXNRP S D
	wxnr /	WXNR S1 S2 D
	WXNRP	WXNRP S1 S2 D
		DXNR SD
	DXNRP	DXNRP S D
		DXNR S1 S2 D
		DXNRP S1 S2 D
		BKXNOR S1 S2 D n
	BKXNORP	BKXNORP S1 S2 D n

Rotation instructions

Classifi- cation	Instruction sign	Symbol
Right rotation	ROR	ROR D n
	BORP	RORP D n
	RCR	RCR D n
	BCRP	RCRP D n
Left rotation	ROL	ROL D n
	ROLP	ROLP D n
	RCL	RCL D n
	RCL	RCLP D n
Right rotation	DROR	DROR D n
	DRORP	DRORP D n
	DRCR	DRCR D n
	DRCRP	DRCRP D n
Left rotation	DROL	DROL D n
	DROLP	DROLP D n
	DRCL	DRCL D n
	DRELP	- DRCLP D n -

	Onine	113110010113
Classifi- cation	Instruction sign	Symbol
n-bit shift	SFR	- SFR D n -
	SERP	- SFRP D n -
	SFL	- SFL D n -
	SELP	- SFLP D n -
1-bit shift	BSFR	BSFR D n
	BSFRF	BSFRP D n
	BSFL	BSFL D n
	BSFLP	BSFLP D n
1-word shift	DSFR	DSFR D n
	DSFR	- DSFRP D n -
	DSFL	– DSFL D n –
	DSFL	– DSFLP D n –

Shift instructions

Bit processing instructions

Classifi- cation	Instruction sign	Symbol	
Bit set/reset	вбет	BSET D n	
	BSETP	BSETP D n	
	BRST	BRST D n	
	BRSTP	BRSTP D n	
Bit test	τest /	- TEST S1 S2 D -	
	TESTP /	- TESTP S1 S2 D -	
	DTEST	DTEST S1 S2 D	
	DTESTP	DTESTP S1 S2 D	
Bit device Batch reset	вкизт	BKRST S n	
		BKRSTP S n	

	Data proce	ssing instructions
Classifi- cation	Instruction sign	Symbol
Data search	SER	- SER S1 S2 D n -
Search	SERP	- SERP S1 S2 D n
	DSER	- DSER S1 S2 D n
	DSERP	DSERP S1 S2 D n
Bit check	SUM	- SUM S D-
	SUMP	- SUMP S D-
	DSUM	- DSUM S D-
		- DSUMP S D-
Decode	DECO	- DECO SD n-
		DECOP S D n
Encode	ENCO	- ENCO S D n -
	ENCOP	- ENCOP S D n -
7- segment	SEG	- SEG S D-
decode	SEGP	- SEGP S D-
Dissocia-t ion	pis /	DIS SDn
• Associa-	disp /	– DISP S D n –
tion	uivi /	UNI SDn
		UNIP S D n
	NDI\$	- NDIS S1 D S2-
	NDIS₽	- NDISP S1 D S2-
		– NUNI S1 D S2–
	NUNIP	- NUNIP S1 D S2-
	wт/ов \	- WTOB S D n -
	WTOBP	WTOBP S D n
	втоw \	BTOW S D n
	втомр	BTOWP S D n

		Instructions (Continued)
Classifi- cation	Instruction sign	Symbol
Retrieval	мах	MAX S D n
	МАХР	- MAXP S D n -
	MIN	- MIN S D n -
	MINP	- MINP S D n -
		- DMAX SDn-
	DMAXP	- DMAXP S D n -
Sort		- DMIN S D n -
	DMINF	- DMINP SD n
	SORT	- SORT S1 n S2 D1 D2 S2:Number of data blocks to be compared at a time. D1:Device to be forced ON at sort completion D2:Used by system
		- DSORT S1 n S2 D1 D2- S2:Number of data blocks to be compared at a time. D1:Device to be forced ON at sort completion D2:Used by system
Total value calcula- tion	wsuм	WSUM S D n
	WSUMP	WSUMP S D n
	фwsum	DWSUM S D n
	DWSUMP	- DWSUMP S D n -

Data processing instructions (Continued)

Table operation instructions

Classifi- cation	Instruction sign	Symbol
Table process- ing	FIFW /	FIFW SD
	FIFWP /	FIFWP SD
		FIFR S D
	FIFRP	FIFRP S D
	FPOR	FPOP S D
	FPOPP	FPOPP S D
		FINS SDn
		FINS SDn
	FOEL	- FDEL SDn
	FDELP	- FDELP S D n

Structuring instructions		
Classifi- cation	Instruction sign	Symbol
Repeat	POR	FOR n
	NEXT	NEXT
	BREAK	BREAK D Pn
	BREAKP	BREAKP D Pn
Sub- routine	CALL	CALL Pn S1~Sn
program call	CALLER	— CALLP Pn S1~Sn—
can	RET	RET
	FCALL	– FCALL Pn S1~Sn–
	FCALLP	- FCALLP Pn S1~Sn-
	ECALL	- SORT * Pn S1~Sn- * : Program name
	ECALLP	- ECALLP * Pn S1~Sn- * : Program name
	EFGALL	- EFCALL * Pn S1~Sn- * : Program name
	EFCALLP	-EFCALLP * PnS1~Sn- *: Program name
	сом	СОМ
Fixed index qualifica- tion		IX S Device qualification circuit IXEND
	IX∉ND	
		IXDEV
	IXSET	Designation of qualification value

Structuring instructions

Revision History

Date of revision	Manual No.	Revision details
Aug. 2002	BNP-B2252B	First edition created.
Sept. 2004	BMP-B2252C	 Order of item configuration changed. Matters related to program development added to "Safety Precautions". Section "1. PLC Development Environment" totally reviewed. Mistakes, etc., corrected.

Notice

Every effort has been made to keep up with software and hardware revisions in the contents described in this manual. However, please understand that in some unavoidable cases simultaneous revision is not possible.

Please contact your Mitsubishi Electric dealer with any questions or comments regarding the use of this product.

Duplication Prohibited

This manual may not be reproduced in any form, in part or in whole, without written permission from Mitsubishi Electric Corporation.

©2002-2004 MITSUBISHI ELECTRIC CORPORATION ALL RIGHTS RESERVED



MODEL	M600 60/60S Series
MODEL CODE	008-244
Manual No.	BNP-B2252C(ENG)