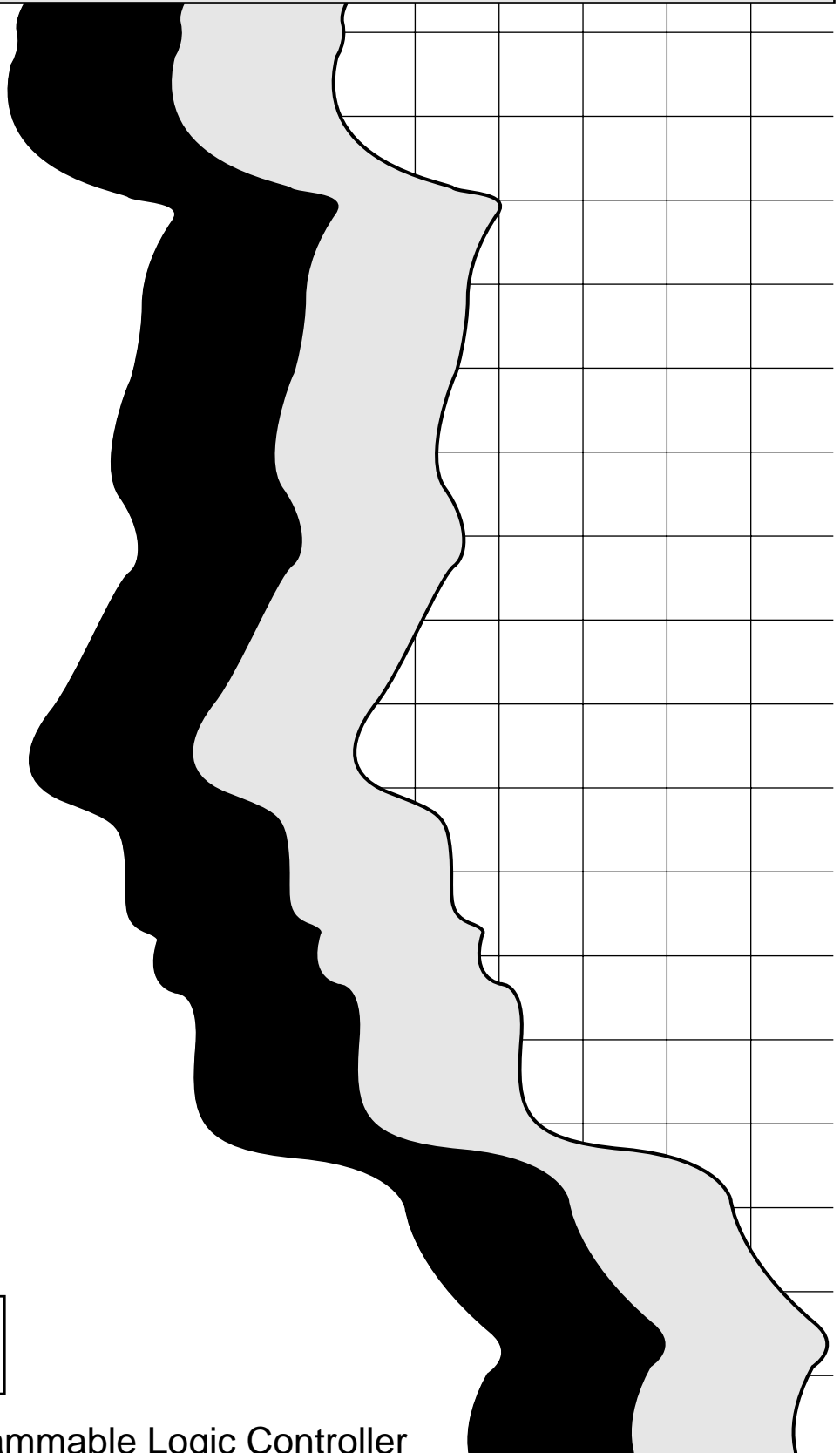


MITSUBISHI

Type A80BDE-J61BT13 CC-Link System
Local Interface Board

User's Manual (For SW4DNF-CCLINK-B)



Mitsubishi Programmable Logic Controller

• SAFETY PRECAUTIONS •

(Be sure to read these instructions before using the product.)

Before using this product, read this manual and the relevant manuals introduced in this manual carefully and handle the product correctly with full attention to safety.

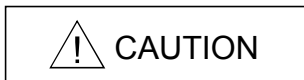
Note that these precautions apply only to this product. Refer to the user's manual of the CPU module for the PLC system safety precautions.

In this manual, the safety instructions are ranked as "DANGER" and "CAUTION".




DANGER

Indicates that incorrect handling may cause hazardous conditions, resulting in death or severe injury.



CAUTION

Indicates that incorrect handling may cause hazardous conditions, resulting in minor or moderate injury or property damage.

Note that failure to observe the  CAUTION level instructions may also lead to serious results depending on the circumstances.

Be sure to observe the instructions of both levels to ensure personal safety.

Please keep this manual in accessible place and be sure to forward it to the end user.

[DESIGN PRECAUTIONS]

DANGER

- When there is a communication error in the data link, the station where the communication is occurring changes to the following status.
Construct an interlock circuit in the sequence program so that the system will operate on the safety side using the communication status information.
There is the risk of an accident occurring due to output error or malfunctioning.
(1) All general purpose inputs from this CC-Link board (A80BDE-J61BT13) are turned off.
(2) All general purpose outputs from this CC-Link board are turned off.
- If a cable dedicated to the CC-Link is disconnected, this may destabilize the line, and a data link communication error may occur in multiple stations. Make sure to create an interlock circuit in the sequence program so that the system will operate safely even if the above error occurs.
Failure to do so may result in a serious accident due to faulty output or malfunctions.
- A failure in the CC-Link board may cause I/O to change to on status or off status.
Establish a circuit to be observed externally for those I/O signals that may threaten to cause serious accident.

CAUTION

- Do not bunch the control wires or communication cables with the main circuit or power wires, or install them close to each other.
They should be installed 100 mm (3.9 inch) or more from each other.
Not doing so could result in noise that would cause malfunction.

[INSTALLATION PRECAUTIONS]

CAUTION

- Use the CC-Link board in an environment as described in the general specifications listed in this operating manual.
If the board is used in an environment outside the ranges described in the general specifications, it may result in an electric shock, fire, malfunctioning, damage to or deterioration of the product.
- Do not directly touch the conductive area of the CC-Link board.
This will result in malfunctioning or failure of the CC-Link board.
- Fix the CC-Link board securely with the installation screws and tighten the installation screws within the specified torque range.
If the screws are loose, this will lead to an error in operation.
If the screws are tightened too much, this will damage the screws and cause a short.
- Always make sure to touch the grounded metal to discharge the electricity charged in the body, etc., before touching the CC-Link board.
Failure to do so may cause a failure or malfunctions of the CC-Link board.

[WIRING PRECAUTIONS]

DANGER

- Always turn off all external power before performing installation, wiring or other work.
If all power is not turned off, there is a risk of electric shock, damage to the product, or malfunctioning.
- When turning on the power and operating the module after installation and wiring are completed, always attach the terminal cover that comes with the product.
There is a risk of electric shock if the terminal cover is not attached.

CAUTION

- Always ground the FG terminal on the PC side using D type grounding (Class 3 grounding) or higher specifically for the PC. Otherwise, there is a risk of malfunctioning.
If a malfunctioning occurs even when the PC unit is grounded, ground both the FG terminal for the PC unit and the SLD terminal for the CC-Link board.
- Tighten the terminal screws within the specified torque range.
If the terminal screws are loose, this will lead to a short or malfunctioning.
If the terminal screws are tightened too much, this will damage the screws and CC-Link board, causing a short or malfunctioning.
- Take care that foreign objects such as chips or wiring debris do not get inside the CC-Link board.
This can result in fire, failure or malfunctioning.

 **CAUTION**

- Always house the communication cable and power cable connected to the CC-Link board in a duct or secure it using clamps.
If the cables are not housed in a duct or secured with clamps, the cable may dangle, move or be pulled inadvertently. This can cause damage to the CC-Link board or cable, or create a faulty contact with the cable which may lead to.
- When disconnecting the communication or power cable connected to the CC-Link board, do not grasp and pull the cable.
First loosen the screws where the cable is connected to the CC-Link board and then remove the cable.
If the cable is pulled while it is connected to the CC-Link board, this can cause damage to the CC-Link board or cable, or create a faulty contact with the cable and lead to malfunctioning.

[STARTING AND MAINTENANCE PRECAUTIONS]

 **DANGER**

- Do not touch the terminal when the power is turned on.
This can cause malfunctioning.
- Always turn off all external power before doing any cleaning or re-tightening the terminal screws.
If all power is not turned off, this can cause a failure or malfunctioning of the CC-Link board.
If the screws are loose, this can cause the terminal to drop, short or operate in error.
If the screws are tightened too much, this can damage the screws and CC-Link board, causing the terminal to drop, short or operate in error.

 **CAUTION**

- Do not dismantle or rebuild the CC-Link board.
This will result in breakdowns, malfunctioning, injury or fire.
Not doing so may cause an electric shock or malfunction.
- Always turn off all external power before installing or removing the CC-Link board.
If all power is not turned off, this will result in failure of the CC-Link board or malfunctioning.
- Always make sure to touch the grounded metal to discharge the electricity charged in the body, etc., before touching the CC-Link board.
Failure to do so may cause a failure or malfunctions of the CC-Link board.

[DISPOSAL PRECAUTION]

 **CAUTION**

- When disposing of this product, treat it as industrial waste.

REVISIONS

* The manual number is given on the bottom left of the back cover.

Print Date	* Manual Number	Revision
Dec., 2000	IB(NA)-0800176-A	First printing
Jun., 2001	IB(NA)-0800176-B	<p>Correction</p> <p>CONTENTS, About the Generic Terms and Abbreviations, Section 1.2, Section 3.4, Subsection 6.1.2, Subsection 7.2.3, Subsection 8.1.2, Subsection 9.3.2, Section 9.4, Section 11.3, Subsection 11.3.1</p> <p>Addition</p> <p>Subsection 7.2.4, Subsection 7.2.5, Section 9.8, Chapter 10</p>
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Apr., 2004	IB(NA)-0800176-E	<p>Correction</p> <p>Precautions for use, Section 4.1</p> <p>Addition</p> <p>CONTENTS, Section 3.4, Section 4.4, Subsection 5.2.1, Chapter 10, Section 11.7</p>
Jun., 2004	IB(NA)-0800176-F	<p>Correction</p> <p>CONTENTS, Generic Terms and Abbreviations</p> <p>Addition</p> <p>Subsection 8.1.2, Appendix 1</p>
Nov., 2005	IB(NA)-0800176-G	<p>Correction</p> <p>Precautions for use, Section 3.4, Subsection 6.1.1, Subsection 6.1.2, Chapter 7, Section 11.2</p>
Jun., 2006	IB(NA)-0800176-H	<p>Correction</p> <p>Section 3.3, Section 4.2, Section 5.4, Chapter 10</p>

Japanese Manual Version IB-0800173-H

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Precautions for use

- (1) **Operating environment of the personal computer used**
Refer to Section 3.4 Operating Environment in this manual.
- (2) **Multi-thread communication**
Multi-thread communication is not supported.
- (3) **Installation**
Install the SW4DNF-CCLINK-B after uninstalling SWnDNF-CCLINK.
- (4) **Overwrite installation**
When performing an overwrite installation, install in the same folder where the previous program is installed.
- (5) **Start menu**
When the software package is uninstalled, items may remain in the start menu.
In this case, reboot the computer.
- (6) **Software version of the CC-Link master and local modules**
For the CC-Link master and local modules, use software version "N" or later.
A module running software version "M" or earlier will not run properly.
- (7) **CC-Link board ROM version**
When connecting to the QCPU (Q mode), be sure to use a CC-Link board whose ROM version is "W" or later.
The system will not operate correctly if a CC-Link board of "V" or older ROM version is used.
- (8) **Multiprocessor PC**
Multiprocessor PCs cannot be used because they are not supported by the driver.
- (9) **Compatibility with Hyper-Threading technology**
Hyper-Threading technology is unavailable as the driver does not support it.
When operating Windows® XP Professional, disable the Hyper-Threading technology on the BIOS setting screen of PC.
When operating Windows® 2000 Professional, disable the Hyper-Threading technology on the BIOS setting screen of PC and then reinstall the operating system.
(For BIOS setting screen, read the manual of the PC used or confirm with the PC manufacturer.)
- (10) **PC supporting PCI bus data parity error detection function**
This board is incompatible with personal computers that detect the PCI bus data parity errors.
For use of such a PC, set the PCI bus data parity error detection function to OFF. Or, use a PC that does not have the function.
For whether the parity error detection function is provided or not and how to set it off, please contact the PC manufacturer.

INTRODUCTION

Thank you for purchasing the Type A80BDE-J61BT13 CC-Link System Local Interface Board.
Before using the equipment, please read this manual carefully to develop full familiarity with the functions and performance of the Type A80BDE-J61BT13 CC-Link System Local Interface Board you have purchased, so as to ensure correct use.
Please forward a copy of this manual to the end user.

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Manuals

The following table list the manuals relevant to this product.
You can order them as necessary.

Relevant Manuals

Manual Name	Manual Number (Type Code)
CC-Link System Master/ Local type AJ61BT11/A1SJ61BT11 User's Manual This manual explains the system configuration, performance specifications, functions, handling, wiring and troubleshooting for the AJ61BT11 and A1SJ61BT11. (Sold separately)	IB-66721 (13J872)
CC-Link System Master/Local Module type AJ61QBT11/A1SJ61QBT11 User's Manual This manual explains the system configuration, performance specifications, functions, handling, wiring and troubleshooting for the AJ61QBT11 and A1SJ61QBT11. (Sold separately)	IB-66722 (13J873)
CC-Link System Master/Local Module type QJ61BT11 User's Manual This manual explains the system configuration, performance specifications, functions, handling, wiring and troubleshooting for the QJ61BT11. (Sold separately)	SH-080016 (13JL91)

How to Read the Manual

"How to Read the Manual" is listed according to the objective when using the CC-Link board. Refer to the following when using this manual.

- (1) To learn about the features of the CC-Link board (Section 1.1)
The features are described in Section 1.1.
- (2) To learn about compatibility with existing software (Section 1.2)
Compatibility with existing software is described in Section 1.2.
- (3) To learn about the correspondence to the EMC command (Chapter 2)
Correspondence to the EMC command is described in Chapter 2.
- (4) To learn about the system configuration (Section 3.1 to Section 3.2)
Configuration of a system using the CC-Link board is described.
- (5) To learn about the operating environment for the CC-Link board (Section 3.3)
The operating environment for the CC-Link board is described in Section 3.3.
- (6) To learn about specifications and functions for the CC-Link board (Chapter 4)
The specifications and functions for the CC-Link board are described in Chapter 4.
- (7) To learn about CC-Link board settings (Chapter 5)
CC-Link board settings are described in Chapter 5.
- (8) When installing or uninstalling a software package (Chapter 6)
How to install and uninstall a software packaged is described in Chapter 6.
- (9) To learn about utilities operating procedure (Chapter 7)
The operating procedure for utilities is described in Chapter 7.
- (10) To learn about devices that can be accessed and range of access (Chapter 8)
Device specifications and contents stored in the system-area information are described in Chapter 8.
- (11) To learn about how to use functions (Chapter 9)
How to use functions is described in Chapter 9.
- (12) To learn about error contents (Chapter 10)
The contents of errors is described in Chapter 10.
- (13) To learn about the actions to take when the system does not run (Chapter 11)
How to troubleshoot is described in Chapter 11.

Generic Terms and Abbreviations

Unless specifically noted, this manual uses the abbreviations and generic terms listed below to explain the Type A80BDE-J61BT13 CC-Link System local interface boards.

Abbreviation/generic term	Description of the abbreviation/generic term
CC-Link board	Abbreviation for the Type A80BDE-J61BT13 CC-Link System local interface board.
IBM PC/AT compatible PC	An IBM PC/AT compatible PC.
AnNCPU	Generic term for A0J2HCPU, A1SCPU, A1SCPU-S1, A1SCPUC24-R2, A1SHCPU, A1SJCPU, A1SJCPU-S3, A1SJHCPU, A1SJHCPU-S8, A1NCPU, A2CCPU, A2CCPUC24, A2CCPUC24-PRF, A2CJCPU, A2NCPU, A2NCPU-S1, A2SCPU, A2SCPU-S1, A2SHCPU, A2SHCPU-S1 and A1FXCPU.
AnACPU	Generic term for A2ACPU, A2ACPU-S1, A2ACPUP21/R21, A2ACPUP21/R21-S1, A3ACPUP21/R21, A3NCPU and A3ACPU.
AnUCPU	Generic term for A2UCPU, A2UCPU-S1, A2ASCPU, A2ASCPU-S1, A2ASCPU-S30, A2USHCPU-S1, A3UCPU and A4UCPU.
QnACPU	Generic term for Q2ACPU, Q2ACPU-S1, Q2ASCPU, Q2ASCPU-S1, Q2ASHCPU, Q2ASHCPU-S1, Q3ACPU, Q4ACPU and Q4ARCPU.
ACPU	Generic term for AnNCPU, AnACPU and AnUCPU.
QCPU (A mode)	Generic term for Q02CPU-A, Q02HCPU-A and Q06HCPU-A
QCPU (Q mode)	Generic term for Q00JCPU, Q00CPU, Q01CPU, Q02CPU, Q02HCPU, Q06HCPU, Q12HCPU, Q25HCPU, Q12PHCPU and Q25PHCPU. Note that especially when the CPU is indicated as a different model, Q00JCPU, Q00CPU and Q01CPU are described as Q00J/Q00/Q01CPU, and Q02CPU, Q02HCPU, Q06HCPU, Q12HCPU and Q25HCPU as Q02/Q02H/Q06H/Q12H/ Q25HCPU. In addition, Q12PHCPU and Q25PHCPU are described as the Process CPU.
Redundant CPU	Generic term for Q12PRHCPU and Q25PRHCPU.
Master station	The station controlling the remote station, local station and intelligent device station.
Local station	A station that has a CPU and can communicate with the master station and local station.
Remote I/O station	A remote station that can only handle bit information. (AJ65BTB□-□□, AJ65BTC□-□□)
Remote station	Generic term for the remote I/O station and remote device station.
Intelligent device station	A slave station such as the AJ65BT-R2 in the CC-Link system that can perform transient transmission.
Master and local modules	Generic term for the AJ61QBT11, A1SJ61QBT11, AJ61BT11, A1SJ61BT11 and QJ61BT11.
Master module	Generic term when the AJ61QBT11, A1SJ61QBT11, AJ61BT11, A1SJ61BT11 and QJ61BT11 are used as master stations.
Remote module	Generic term for AJ65BTB □-□□, AJ65BTC □-□□, AJ65BT-64AD, AJ65BT-64DAV, AJ65BT-64DAI, A852GOT, etc.
Intelligent module	A module such as the AJ65BT-R2 that can perform transient transmission.
Cyclic transmission	Function that periodically updates the contents of the remote I/O and remote register.
Transient transmission	Function that communicates data to the specified station when there is an access request from the PLC CPU.
SB	Link special relay
SW	Link special register
RX	Remote input
RY	Remote output
RWw	Remote register (write area)
RWr	Remote register (read area)

Product List

The product list for the CC-Link board is given in the table below.

Product name	Quantity
A80BDE-J61BT13 CC-Link System local interface board	1
SW4DNF-CCLINK-B model CC-Link software package	1 (Floppy disks; set of 6)
Type A80BDE-J61BT13 CC-Link System local interface board user's manual (this manual)	1
Software use agreement	1

Note

The terminal resistor is packaged with the CC-Link system master and local modules.

1 OVERVIEW

This manual explains the specifications for, and how to handle and monitor the Type A80BDE-J61BT13 CC-Link System local interface board (hereinafter abbreviated as CC-Link board) that is included in the CC-Link system, and loaded as an optional board in the PCI bus of an IBM PC/AT compatible PC.

The A80BDE-J61BT13 is applicable to the following CC-Link system.

- Applicable to the CC-Link system local station(s).

1.1 Features

The I/F board has the features described below.

- (1) An IBM PC/AT compatible PC can be built into the CC-Link system.
The I/F board can be installed in an IBM PC/AT compatible PC and that PC can be used as a local station.
- (2) Using a PCI bus eliminates troublesome switch settings.
Simply installing the board in the PCI bus automatically executes initial setting.
- (3) Displays test and monitor information related to the CC-Link.
Operation becomes easy since the CC-Link system testing and monitoring statuses can be displayed in the IBM PC/AT compatible PC.
- (4) Various functions are available to accommodate user programming.
By using various functions that are compatible with Microsoft® Visual C++® and Microsoft® Visual Basic®, user applications to perform remote control for the PLC CPU as well as reading from and writing to devices can easily be created.
- (5) Drivers for various operating systems are available.
A variety of drivers are provided to make it easier to construct a system that is compatible with the user's environment.
Compatible operating systems :
Microsoft® Windows® 95 Operating System (English Version)
Microsoft® Windows® 98 Operating System (English Version)
Microsoft® Windows NT® Workstation Operating System Version 4.0 (English Version)
Microsoft® Windows® 2000 Professional Operating System (English Version)
Microsoft® Windows® XP Professional Operating System (English Version)
- (6) Support for QCPUs (Q mode) of a multiple PLC system
By specifying the station number of the logical station number via the CC-Link utility, communication with each QCPU (Q mode) of a multiple PLC system can be performed.

1.2 Combinations of Boards with Existing Software

1

This section describes the combinations of boards with existing software.

(1) When using the CC-Link board and other interface boards in the same PC

Board model name	Software package name	Supported OS								
		DOS	NT 3.51	Win 95	Win 98	Win Me	NT 4.0	Win 2000	XP Pro	XP Home
Q80BD-J71LP21-25 Q80BD-J71LP21G Q80BD-J71LP21GE Q80BD-J71BR11	SW0DNC-MNETH-B	×	×	○	○	×	○	○	○* ²	×
A70BDE-J71QLP23 A70BDE-J71QLP23GE A70BDE-J71QBR13	SW0IVDWT-MNET10P	○	○	×	×	×	×	×	×	×
	SW1IVDWT-MNET10P	○	○	○* ¹	○	×	○* ¹	×	×	×
	SW2DNF-MNET10	○	×	○	○	×	○	×	×	×
	SW3DNF-MNET10	○	×	○	○	×	○	×	×	×
A70BDE-J71QLR23	SW3DNF-MNET10	○	×	○	○	×	○	×	×	×
A80BDE-J61BT11	SW3DNF-CCLINK	×	×	○	○	×	○	×	×	×
	SW4DNF-CCLINK-B	×	×	○	○	×	○	○	○* ³	×
A80BDE-A2USH-S1	SW0DNF-ANU-B	×	×	×	×	×	○	×	×	×
	SW1DNF-ANU-B	×	×	×	×	×	○	○	×	×


DOS : MS-DOS 6.2

NT 3.51 : Windows NT[®] Workstation 3.51Win 95 : Windows[®] 95Win 98 : Windows[®] 98Win Me : Windows[®] MeNT 4.0 : Windows NT[®] Workstation 4.0Win 2000 : Windows[®] 2000 ProfessionalXP Pro : Windows[®] XP ProfessionalXP Home : Windows[®] XP Home Edition

○ : Can be operated simultaneously.

× : Cannot be operated simultaneously.

— : No combination available

 indicates an OS that is not supported by the CC-Link board. It cannot be used on the same PC.

*1 : The user program EXE file that was generated using MDFUNC32.LIB must be re-linked using the MDFUNC32.LIB that comes with SW4DNF-CCLINK-B.

*2 : Supports Windows[®] XP Professional from Version 70H or later.

*3 : Supports Windows[®] XP Professional from Version 40E or later.

(2) When using the CC-Link board, Communication Support Software Tool and GX Developer in the same PC

Software name	Software package name	Supported OS								
		DOS	NT 3.51	Win 95	Win 98	Win Me	NT 4.0	Win 2000	XP Pro	XP Home
Communication Support Software Tool	SW1D5F-CSKP-E	×	×	△ *1	△ *1	×	△ *1	×	×	×
	SW2D5F-CSKP-E	×	×	○	○	×	○	×	×	×
	SW2D5F-OLEX-E	×	×	○	○	×	○	×	×	×
	SW2D5F-XMOP-E	×	×	○	○	×	○	×	×	×
	SW3D5F-CSKP-E	×	×	○	○	×	○	×	×	×
	SW3D5F-OLEX-E	×	×	○	○	×	○	×	×	×
	SW3D5F-XMOP-E	×	×	○	○	×	○	×	×	×
	SW0D5C-ACT-E	×	×	○	○	×	○	×	×	×
	SW2D5C-ACT-E	×	×	○	○	○	○	○	×	×
	SW3D5C-ACT-E	×	×	○	○	○	○	○	○	○
SW1D5C-SHEET-E	×	×	×	○	○	○	○	○	○	
GX Developer	SW2D5F-GPPW-E/ SW2D5C-GPPW-E	×	×	△	△ *2	×	△	×	×	×
	SW3D5F-GPPW-E/ SW3D5C-GPPW-E	×	×	○	○	×	○	×	×	×
	SW4D5C-GPPW-E	×	×	○	○	×	○	×	×	×
	SW5D5C-GPPW-E	×	×	○	○	×	○	×	×	×
	SW6D5C-GPPW-E	×	×	○	○	×	○	×	×	×
	SW7D5C-GPPW-E	×	×	○	○	○	○	○	×	×
	SW8D5C-GPPW-E	×	×	○	○	○	○	○	○	○

DOS : MS-DOS 6.2 NT 3.51 : Windows NT® Workstation 3.51 Win 95 : Windows® 95 Win 98 : Windows® 98

Win Me: Windows® Me NT 4.0 : Windows NT® Workstation 4.0 Win 2000 : Windows® 2000 Professional

XP Pro : Windows® XP Professional

XP Home : Windows® XP Home Edition

○ : Can be operated simultaneously.

×

× : Cannot be operated simultaneously.

— : No combination available

△ : Cannot access the CC-Link board, and cannot access other stations via the CC-Link board.

 indicates an OS that is not supported by the CC-Link board. It cannot be used on the same PC.

*1 : Update the version of each software if it is used with the CC-Link board on the same PC.

For details on version update products, contact your local Mitsubishi service center or representative.

*2 : Supports Windows® 98 from Version 30D or later.

2 EMC COMMAND

2.1 Requirements for EMC Command Compliance

EMC commands, which are among the European command sets, are now enforced. The EMC commands regulate "emission (electromagnetic interference)," which requires that a device not emit strong electromagnetic waves externally, and "immunity (electromagnetic sensitivity)," which requires that a device have the ability to resist external electromagnetic waves.

The precautionary items when configuring a machine device using an CC-Link board to conform to EMC commands are described in sections 2.1.1 through 2.1.4.

Although we tried very hard to document these materials according to the requirements for regulation and the standards we have researched, the compatibility to the above commands of the entire device created according to the contents of this material, is not guaranteed. The methods to enable a device to conform to the commands and the compatibility must be determined by the manufacturer who produces the machine device.

2.1.1 EMC commands

The standards relating to EMC commands are listed in the table below:

With all test items, the standard has been tested with each device installed in an IBM PC/AT compatible PC bearing a CE certification logo.

Specification	Test item	Test description	Standard values
EN50081-2 : 1995	EN55011 Radiated noise	Measure the electric wave released by the product.	30 M-230 MHz QP : 50 dB μ V/m (3 m measurement) * ¹ 230 M-1000 MHz QP : 57 dB μ V/m (3 m measurement)
	EN55011 Conduction noise	Measure the noise released by the product to the power line.	150 k-500 kHz QP: 79 dB, Mean: 66 dB * ¹ 500 k-30 MHz QP: 73 dB, Mean: 60 dB
prEN50052-2 : 1991	IEC801-2 Static electricity immunity	Immunity test by applying static electricity to the unit enclosure.	4 kV contact discharge 8 kV air discharge
	IEC801-3 Radiated electromagnetic field	Immunity test by radiating an electric field to the product.	10 V/m, 27 - 500 MHz
	IEC801-4 First transient burst noise	Immunity test by applying burst noise to the power line and signal line.	2 kV
EN50082-2 : 1995	EN61000-4-2 Static electricity immunity	Immunity test by applying static electricity to the unit enclosure.	4 kV contact discharge 8 kV air discharge
	EN61000-4-4 First transient burst noise	Immunity test by applying burst noise to the power line and signal line.	2 kV
	ENV50140 Radiated electromagnetic field AM modulation	Immunity test by radiating an electric field to the product.	10 V/m, 80-1000 MHz, 80 % AM modulation@1 kHz
	ENV50204 Radiated electromagnetic field Pulse modulation	Immunity test by radiating an electric field to the product.	10 V/m, 900 MHz, 200 Hz pulse modulation, 50 % duty
	ENV50141 Conduction noise	Immunity test by inducing electromagnetic field to the power line and signal line.	10 Vrms, 0.15-80 MHz, 80 % AM modulation@1 kHz

*1 QP (Quasi-Peak) : Quasi-peak value, Mean: Average value

2.1.2 Installation on the control panel

Installing devices on the control panel has a considerable effect not only in securing safety but also in shutting down the noise generated from the PC by the control panel.

(1) Control panel

- (a) Use an electrically conductive control panel.
- (b) When fastening/tightening the control panel's top or bottom panel with bolts, mask the coating so that surface contact is feasible.
- (c) To ensure the electrical contact between the inside panel of the control panel and the main control panel, mask any coating around the installation bolts connecting to the main unit to secure conductivity in the largest surface area possible.
- (d) Ground the control panel main unit using a thick ground cable so that a low impedance can be secured even with a high frequency.
- (e) Make the holes on the control panel less than 10 cm (3.94 in.) in diameter. A hole larger than 10 cm (3.94 in.) may leak electric waves.

(2) Layout of power supply cable and ground cable

The layout of power supply cable and ground cable for a PC should be set as described below.

- (a) Specify a grounding point that enables grounding of the control panel close to the power supply to the PC and ground the FG (frame ground) terminal of the PC or the SLD (shield) terminal of the CC-Link board using the thickest, shortest cable possible (about 30 cm (11.81 in.) or less in length). Since the FG and SLD terminals play a role in grounding the noise generated in the PC, it is necessary to ensure the lowest possible impedance. Because the power line is used to allow the noise to escape, it actually contains a great deal of noise. Therefore, shortening the wire length prevents the power line from becoming an antenna.

Note : A long conductive material can become an antenna that emits noise more efficiently.

- (b) Twist the ground cable leading to the ground point with the power supply cable. By twisting them with the ground cable, the noise leaking out of the power supply cable may be grounded at a higher rate. However, when a noise filter is installed to the power supply cable, twisting with the ground cable may not be necessary.

2.1.3 Cable

Because the cable that runs from the control panel contains high frequency noise, outside the control panel it acts as an antenna and radiates noise. Always use shielded cable for cable that runs outside the control panel.

Except for certain models, using the ferrite core is not mandatory. However, the noise radiated via cable can be suppressed more effectively by mounting a ferrite core.

Using a shielded cable is also effective in raising noise resistance. The signal lines used for PLC input/output and special units are designed to ensure a noise resistance level of 2 kV (IEC801-4/EN61000-4-4) if a shielded cable is used. If a shielded cable is not used, or when a shielded cable is not grounded properly, the noise resistance will drop below 2 kV.

Note : With the EN50082-2, the noise resistance of each signal line is specified based on the application of the signal.

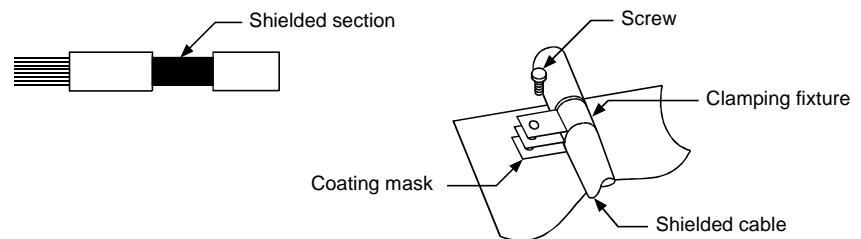
Signals related to control (process control) : 2 kV

Signals not related to control (process control)) : 1 kV

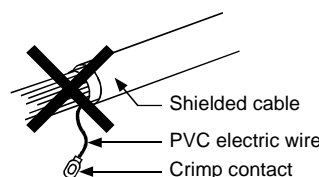
In the EN50082-2, the meaning of “(signals) related to control” is not defined. However, considering the original intent of the EMC command, the signal line that poses possible danger to person or equipment when the panel is incorrectly operated shall be defined as the “signal related to control,” and high noise resistance is considered mandatory.

(1) Grounding treatment for shields

- (a) Perform shielding processing at a position near the exit of the control panel. If the grounding point is far from the exit position, the cable portion after the grounding point will cause electromagnetic induction and generates high-frequency noise.
- (b) Use a grounding method that allows the shield a surface grounding in a large area against the control panel. A clamping fixture as shown below may alternatively be used. When such a fixture is used, mask the coating in the area inside the control panel where the fixture contacts.

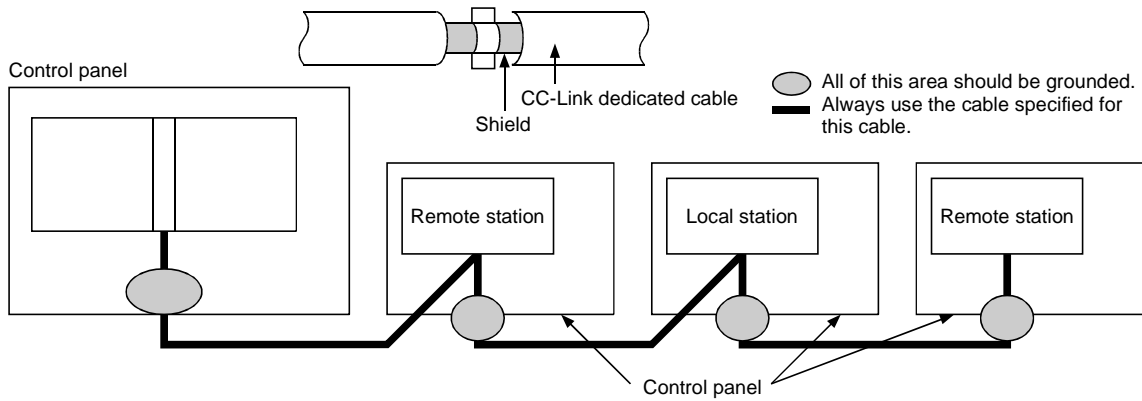


Note : The method shown below in which a PVC electric wire is soldered to the shield of the shielded cable and that end is grounded, increases the high frequency impedance and the effectiveness of the shield is lost.



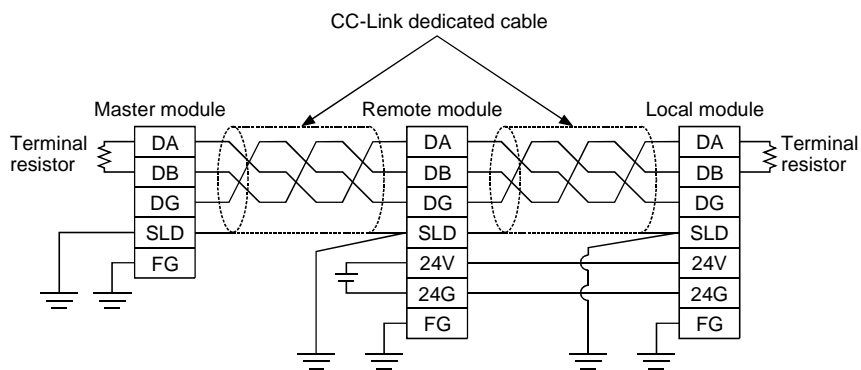
(2) Grounding treatment for the CC-Link dedicated cable

- (a) Always ground the twisted cable connected to the CC-Link master station, local station and remote station.
 Since the twisted cable is a shielded cable, remove part of the outer sheath. Then ground the exposed part of the shield indicated in the figure below as wide a surface area as possible.



Also, ground within 30 cm (11.81.in.) from the board terminal area in addition to grounding at the position closest to the exit of the control panel.

- (b) Always use the specified cable for the CC-Link dedicated cable.
- (c) For each module, do not use a ferrite core for the CC-Link dedicated cable from the board.
- (d) For each module, ground both the FG terminal and SLD terminal of the board.



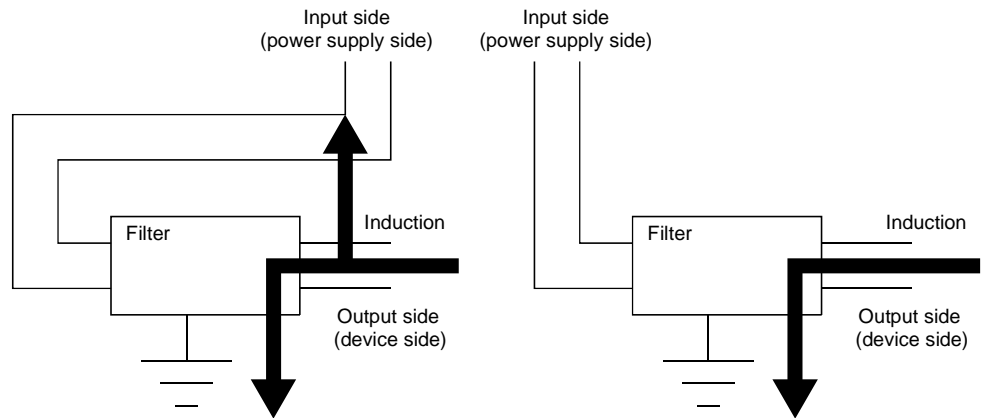
2.1.4 Noise filter (power supply line filter)

A noise filter is a part that has a considerable effect in preventing conductive noise. Except for a few models, installation of a noise filter to the power supply line is not mandatory. However, the installation of a noise filter can suppress noise at a higher rate (a noise filter is effective for reducing noise emitted in the range below 10MHz). Use a noise filter equivalent to the models shown below.

Model	FN343-3/01	FN660-6/06	ZHC2203-11
Manufacturer	SCHAFFNER	SCHAFFNER	TDK
Rated current	3 A	6 A	3 A
Rated voltage	250 V		

Precautions when installing a noise filter are noted below.

- (1) Do not bundle the wiring on the input and output side of the noise filter. If they are bundled, noise on the output side will be inducted to the wiring on the input side where the noise has been removed by a filter.



- (2) Ground the ground terminal for the noise filter to the control panel using as short wiring as possible (about 10 cm (3.94 in.)).

3 SYSTEM CONFIGURATION

The configuration for a system using the CC-Link board is explained below.

3.1 System Configuration for A80BDE-J61BT13

The following indicates the system configuration when an CC-Link board is used. The CC-Link board can be connected to a maximum of up to 26 modules per 1 master station.

However, the following conditions must be fulfilled.

$$(1) \{(1 \times a) + (2 \times b) + (3 \times c) + (4 \times d)\} \leq 64$$

a : Number of modules occupied by 1 station

b : Number of modules occupied by 2 stations

c : Number of modules occupied by 3 stations

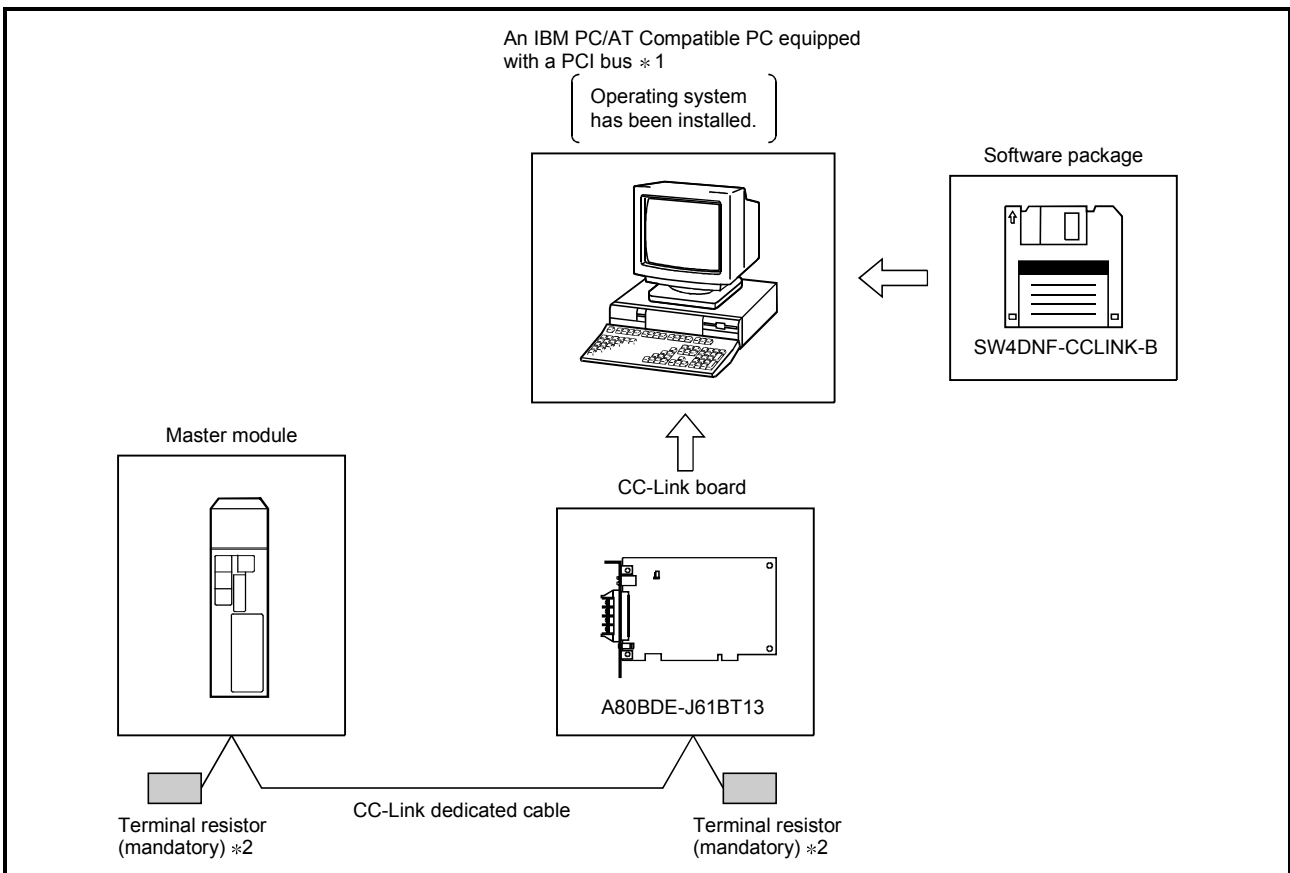
d : Number of modules occupied by 4 stations

$$(2) \{(16 \times A) + (54 \times B) + (88 \times C)\} \leq 2304$$

A : Number of remote I/O stations ≤ 64

B : Number of remote device stations ≤ 42

C : The number of local stations, standby master stations and intelligent device stations ≤ 26



* 1 : A multiprocessor PC cannot be used, since the drivers are not compatible.

* 2 : The terminal resistor comes with the master module.

3.2 Applicable System

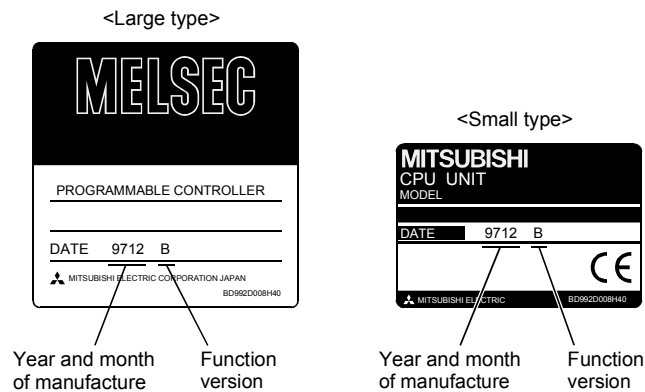
The CC-Link system master module which can use an CC-Link board is explained below.

The master module that can use an CC-Link board is the product with function version B or later and software version N or later.

The product with earlier versions than those listed above cannot use an CC-Link board.

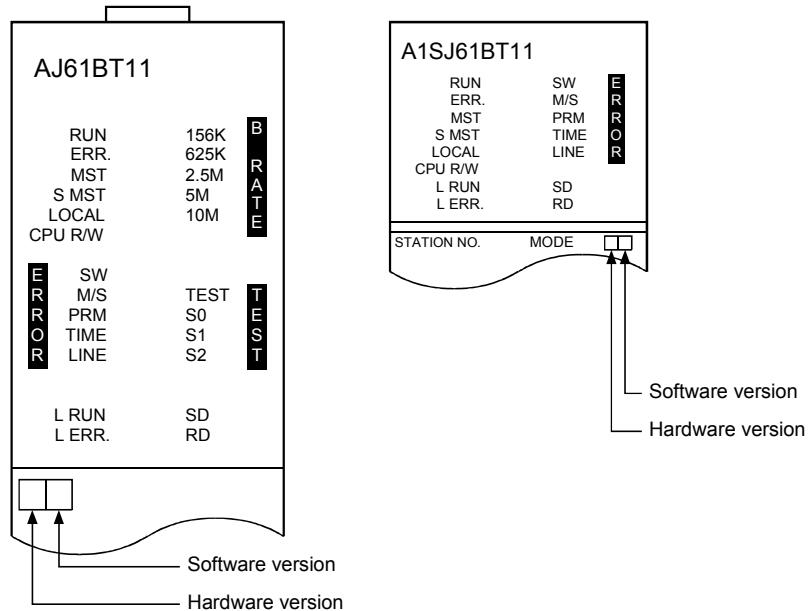
The function version is recorded in the DATE column of the rated plate.

3



* The function version is noted only on products with version B or later.

The software version is indicated on the module version tag located on the front of the module.



3.3 About Ver. 1.10

A product with a cable length of 20cm or longer between stations, which has been achieved by improving the restriction on the conventional cable distance between the stations, is defined as Ver. 1.10.

Whereas, the conventional product is defined as Ver. 1.00.

For the maximum total cable length for the Ver. 1.10 products, see Section 4.2.2.

The conditions requiring the cable length to be 20cm or longer between stations are as follows:

- 1) All the units comprising a CC-Link system must be of Ver. 1.10.
- 2) All the data link cables must be Ver. 1.10-compatible CC-Link dedicated cables.

POINT
<p>If modules of Ver. 1.00 and Ver. 1.10 are mixed in a system, the maximum total cable length and the cable length between stations will be as specified by Ver. 1.00.</p> <p>For the maximum total cable length and the cable length between stations for the Ver. 1.00 products, see Section 4.2.1.</p>

(1) How to check Ver. 1.10

Ver. 1.10-compatible CC-Link boards and modules contain a "CC-Link" logo on the "board" or "rating name plate."

(Example) Rating name plate of AJ61BT11



3.4 Operating Environment

The following table shows the operating environment for the CC-Link board.

Item	Description	
Personal computer	CPU	IBM-PC/AT-compatible personal computer with one or more PCI bus slots, satisfying the specifications described below in "Applicable operating system and the corresponding required PC performance" *1, *2, *3.
	Required memory	
	PCI bus specifications	
Operating system *4, *5	Microsoft® Windows® 95 Operating System (English version) Microsoft® Windows® 98 Operating System (English version) Microsoft® Windows NT® Workstation Operating System Version 4.0 (English version) *6, *7 Microsoft® Windows® 2000 Professional Operating System (English version) *6 Microsoft® Windows® XP Professional Operating System (English version) *6	
Display	Resolution: 800×600 dot or higher (Recommended: 1024×768 dot) *8	
Available hard disk space	15MB or more	
Disk drive (required when installing the driver)	3.5 inch (1.44MB) floppy disk drive	
Programming language *9, *10, *11	Microsoft® Visual Basic® 5.0 (English version), Microsoft® Visual Basic® 6.0 (English version), Microsoft® Visual C++® 5.0 (English version), Microsoft® Visual C++® 6.0 (English version)	

- *1: This product does not work with a multiprocessor IBM-PC/AT-compatible personal computer, as the driver is incompatible.
- *2: Hyper-Threading technology is unavailable as the driver does not support it.
When operating Windows® XP Professional, disable the Hyper-Threading technology on the BIOS setting screen of PC.
When operating Windows® 2000 Professional, disable the Hyper-Threading technology on the BIOS setting screen of PC and then reinstall the operating system.
(For BIOS setting screen, read the manual of the PC used or confirm with the PC manufacturer.)
- *3: PC supporting PCI bus data parity error detection function
This board is incompatible with personal computers that detect the PCI bus data parity errors. For use of such a PC, set the PCI bus data parity error detection function to OFF. Or, use a PC that does not have the function.
For whether the parity error detection function is provided or not and how to set it off, please contact the PC manufacturer.
- *4: This board does not support the Standby (Hibernate) mode of the operating system.
The Standby (Hibernate) mode may be preset to some personal computers so that it will be activated by pressing the Power switch or by the UPS (Uninterruptible Power Supply system) setting.
For Windows® 2000 Professional, select [Settings] – [Control Panel] – [Power Options] and disable the standby mode setting.
- *5: When exiting the operating system, always shut down the computer.
- *6: Installation, uninstallation and usage of utilities are available only by the administrator's authority.
- *7: Service Pack3 or higher is required when using Windows NT® Workstation 4.0.
- *8: This product does not comply with large-sized fonts when Windows® 2000 Professional or Windows® XP Professional is used.
- *9: User programs created in the English environment work only in the English environment.
- *10: Use Visual Basic® 6.0 or Visual C++® 6.0 when using Windows® 2000 Professional or Windows® XP Professional.
(Visual Basic® 5.0 and Visual C++® 5.0 cannot be used.)
- *11: This product is not compatible with Microsoft® Visual Basic® .NET or Microsoft® Visual C++® .NET.

Applicable operating system and the corresponding required PC performance

Operating system	Description	
	CPU	Required memory
Windows® 95	Pentium® 133MHz or higher	32MB or more
Windows® 98	Pentium® 133MHz or higher	32MB or more
Windows NT® Workstation 4.0	Pentium® 133MHz or higher	32MB or more
Windows® 2000 Professional	Pentium® 133MHz or higher	64MB or more
Windows® XP Professional	Pentium® 300MHz or higher	128MB or more

POINT

New functions of Windows® XP

When Microsoft® Windows® XP Professional Operating System is used, the following new functions cannot be used.

If any of the following new functions is used, this product may not operate normally.

- Start of application in Windows® compatible mode

- Fast user switching

- Remote desktop

4 SPECIFICATION

The performance specifications and functions of the CC-Link board are explained below.

4.1 General Specification

(1) The following table indicates general specifications of the CC-Link board.

Item	Specification					
Usage ambient temperature	0 to 55 °C					
Storage ambient temperature	-20 to 75 °C					
Usage ambient humidity	10 to 90 %RH, no condensation					
Storage ambient humidity	10 to 90 %RH, no condensation					
Vibration durability	Conforming to JIS B 3501, IEC 61131-2		Frequency	Acceleration	Amplitude	Sweep count
		When there is intermittent vibration	10 to 57 Hz	—	0.075 mm (0.0030 inch)	10 times in each direction X, Y, Z (80 minutes)
			57 to 150 Hz	9.8 m/s ²	—	
		When there is continuous vibration	10 to 57 Hz	—	0.035 mm (0.0013 inch)	
57 to 150 Hz	4.9 m/s ²		—			
Shock durability	Conforming to JIS B 3501, IEC61131-2 (147 m/s ² , 3 times each in 3 directions)					
Usage environment	No corrosive gas					
Usage height	Less than 2000 m (less than 6562 ft.)					
Installation area	Within the control board					
Over-voltage category *1	Less than II					
Pollution level *2	Less than 2					

*1 Indicates the location where the device is connected from the public cable network to the device structure wiring area.
Category II applies to the devices to which the power is supplied from a fixed equipment.
Surge withstand voltage for devices with up to 300 V of rated voltage is 2500 V.

*2 This is an index which indicates the degree of conductive object generation in the environment. Pollution level 2 is when only non-conductive pollution occurs.
A temporary conductivity caused by condensation must be expected occasionally.

(2) General specifications of the CC-Link board or the IBM PC/AT compatible personal computer, whichever is lower, must be satisfied after installation.

4.2 Performance Specifications

The following table indicates the performance specifications for the CC-Link board.

Item	Specification
Transmission speed	156 kbps, 625kbps, 2.5 Mbps, 5 Mbps or 10 Mbps can be selected
Maximum transmission distance	Differs depending on the transmission speed. (Refer to Section 4.2.1, 4.2.3)
Number of occupied stations	1 or 4 station(s) (switches depending on the setting)
Maximum number of link points per 1 system	Remote I/O (RX, RY) : 2048 Remote registers (RWw) : 256 (master station to local station) Remote registers (RWr) : 256 (local station to master station)
Number of link points per 1 station	Remote I/O (RX, RY) : 30 Remote registers (RWw) : 4 (master station to local station) Remote registers (RWr) : 4 (local station to master station)
Communication method	Broadcast polling method
Synchronous method	Frame synchronous method
Encoding method	NRZI method
Transmission path	Bus (RS-485)
Transmission format	Conforms to HDLC
Error control system	CRC($X^{16}+X^{12}+X^5+1$)
Cable	CC-Link dedicated cable/ CC-Link dedicated high performance cable/ Ver. 1.10-compatible CC-Link dedicated cable * ¹
RAS functions	<ul style="list-style-type: none"> • Automatic return function • Slave station separation function • Error detection using the link special relay and register • Data link status verification • OFF-line test (hardware test, line test) • Abnormal temperature detection • Watchdog timer error (WDT) detection
Number of boards that can be loaded	Maximum of 4 * ²
Loading slot	IBM PC/AT compatible PC PCI bus slot
Number of slots occupied	1 slot
Internal voltage consumption (5 V DC)	0.4 A
Weight	0.16 kg

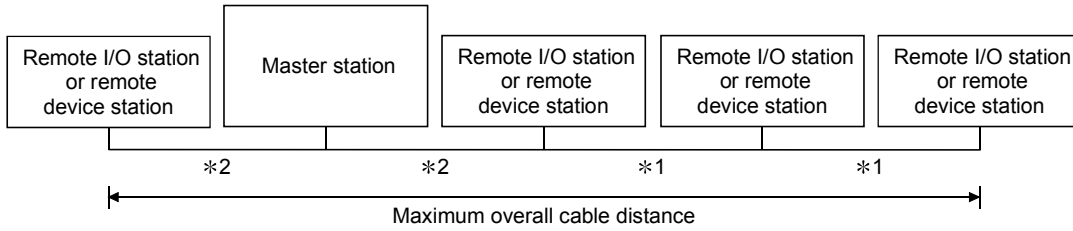
*1: Ver.1.10-compatible CC-Link dedicated cables, CC-Link dedicated cables (Ver.1.00) and CC-Link dedicated high-performance cables cannot be used together. If used together, correct data transmission will not be guaranteed. Also attach the terminating resistor which matches the kind of the cable. (Refer to section 5.4)

*2: This indicates the total number of A80BDE-J61BT11 and A80BDE-J61BT13 boards.

4.2.1 Maximum overall cable distance (for Ver. 1.00)

The relationship between the transmission speed and the maximum overall cable distance is described below:

- (1) For a system consisting of only remote I/O stations and remote device stations



- *1 Cable length between remote I/O stations or remote device stations.
- *2 Cable length between the master station and the adjacent stations.

CC-Link dedicated cable (uses terminal resistor 110 Ω)

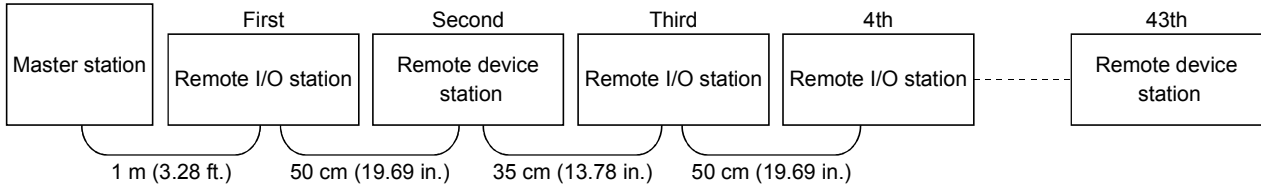
Transmission rate	Station-to-station cable length		Maximum overall cable distance
	*1	*2	
156 kbps	30 cm (11.81 in.) or more	1 m (3.28 ft.) or more	1200 m (3937.2 ft.)
625 kbps			600 m (1968.6 ft.)
2.5 Mbps			200 m (656.2 ft.)
5 Mbps	30 cm (11.81 in.) to 59 cm (23.23 in.) *		110 m (360.9 ft.)
	60 cm (23.62 in.) or more		150 m (492.15 ft.)
10 Mbps	30 cm (11.81 in.) to 59 cm (23.23 in.) *		50 m (164.1 ft.)
	60 cm (23.62 in.) to 99 cm (38.98 in.) *	80 m (262.5 ft.)	
	1 m (3.28 ft.) or more	100 m (328.1 ft.)	

CC-Link dedicated high performance cable (uses terminal resistor 130 Ω)

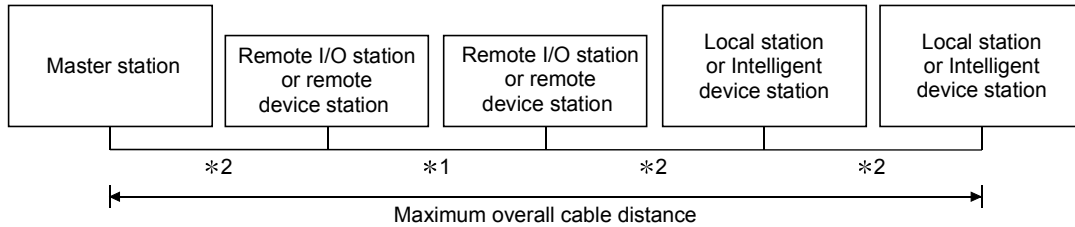
Transmission rate	Station-to-station cable length		Maximum overall cable distance	
	*1	*2		
156 kbps	30 cm (11.81 in.) or more	1 m (3.28 ft.) or more	1200 m (3937.2 ft.)	
625 kbps			900 m (2952.9 ft.)	
2.5 Mbps			400 m (1312.4 ft.)	
5 Mbps			160 m (524.96 ft.)	
10 Mbps	Number of connected stations: 1 to 32		100 m (328.1 ft.)	
			80 m (262.5 ft.)	
	Number of connected stations: 33 to 48		30 cm (11.81 in.) to 39 cm (15.35 in.) *	100 m (328.1 ft.)
			40 cm (15.75 in.) or more	20 m (65.52 ft.)
			30 cm (11.81 in.) to 39 cm (15.35 in.) *	30 m (98.43 ft.)
Number of connected stations: 49 to 64	40 cm (15.75 in.) to 69 cm (27.17 in.) *		100 m (328.1 ft.)	
	70 cm (27.56 in.) or more			

* The cable length between remote I/O stations or remote device stations is within this range and if even one location is wired, the maximum overall cable distance will be as indicated above.

(Example) When the transmission rate is 10 Mbps, and 43 remote I/O stations and remote device stations are connected using the CC-Link dedicated high performance cable, because the cable connecting the second and third stations is "35 cm (13.78 in.)", the maximum overall cable distance will be "80 cm (31.5 in.)".



(2) For a system consisting of remote I/O stations, remote device stations, local stations and intelligent device stations



- *1 Cable length between remote I/O stations or remote device stations
- *2 Cable length between the master station or the local or intelligent device station and the adjacent stations

CC-Link dedicated cable (uses terminal resistor 110 Ω)

Transmission rate	Station-to-station cable length		Maximum overall cable distance
	*1	*2	
156 kbps	30 cm (11.81 in.) or more	2 m (6.56 ft.) or more	1200 m (3937.2 ft.)
625 kbps			600 m (1968.6 ft.)
2.5 Mbps			200 m (656.2 ft.)
5 Mbps	30 cm (11.81 in.) to 59 cm (23.23 in.) *		110 m (360.9 ft.)
10 Mbps	60 cm (23.62 in.) or more		150 m (492.15 ft.)
	30 cm (11.81 in.) to 59 cm (23.23 in.) *		50 m (164.1 ft.)
	60 cm (23.62 in.) to 99 cm (38.98 in.) *	80 m (262.5 ft.)	
	1 m (3.28 ft.) or more	100 m (328.1 ft.)	

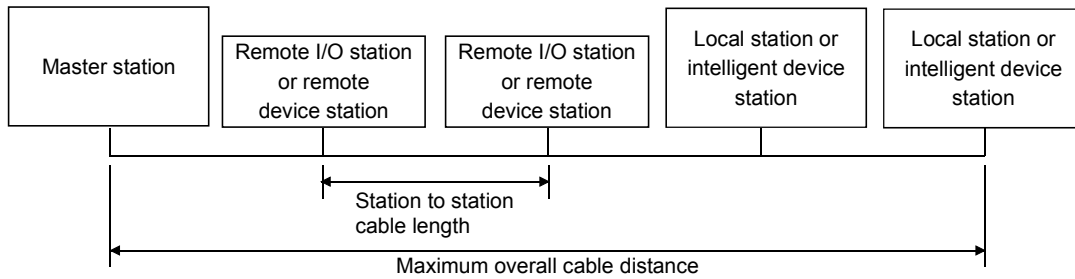
CC-Link dedicated high performance cable (uses terminal resistor 130 Ω)

Transmission rate	Station-to-station cable length		Maximum overall cable distance
	*1	*2	
156 kbps	30 cm (11.81 in.) or more	2 m (6.56 ft.) or more	1200 m (3937.2 ft.)
625 kbps			600 m (1968.6 ft.)
2.5 Mbps			200 m (656.2 ft.)
5 Mbps	30 cm (11.81 in.) to 59 cm (23.23 in.) *		110 m (360.9 ft.)
	60 cm (23.62 in.) or more		150 m (492.15 ft.)
10 Mbps	70 cm (27.56 in.) to 99 cm (38.98 in.) *		50 m (164.1 ft.)
	1 m (3.28 ft.) or more	80 m (262.5 ft.)	

* The cable length between remote I/O stations or remote device stations is within this range and if even one location is wired, the maximum overall cable distance will be as indicated above.

4.2.2 Maximum overall cable distance (for Ver. 1.10)

The relation of the transmission speed and maximum overall cable distance when configuring the entire system with Version 1.10 modules and cable is shown below.



Version 1.10 compatible CC-Link dedicated cable (terminal resistor of 110Ω used)

Transmission speed	Station to station cable length	Maximum overall cable distance
156kbps	20cm (7.88 in.) or longer	1200m (3937.2 ft.)
625kbps		900m (2952.9 ft.)
2.5Mbps		400m (1312.4 ft.)
5Mbps		160m (524.96 ft.)
10Mbps		100m (328.1 ft.)

4.3 CC-Link Dedicated Cable

Use the CC-Link dedicated cable for the CC-Link system. If a cable other than the CC-Link dedicated cable is used, the performance of the CC-Link system cannot be guaranteed.

If you have any questions regarding the CC-Link dedicated cable, or if you wish to see its specifications, see the CC-Link Partner Association homepage <http://www.cc-link.org/>.

4.4 List of Functions

The following table lists the CC-Link board functions.

Name	Contents
Data communication function	(1) Communication for remote input (RX), remote output (RY), remote register (RWw, RWr) via the CC-Link is possible using the cyclic transmission function. <ul style="list-style-type: none"> • Number of link points per station <ul style="list-style-type: none"> Remote I/O (RX, RY) : 30 Remote register (RWw) : 4 Remote register (RWr) : 4 (2) Communication with the master station and intelligent device station is possible using the transient transmission function.
Test function	Tests can be performed and the hardware checked using the test mode setting.
RAS functions	Automatic return function, slave station separation function, verification of data link status, off-line test
Self-diagnostic function	<ul style="list-style-type: none"> • An error message is displayed according to the error code. • Contents of the fault detected are stored in the special relay or special register.

POINT

Refer to the QJ61BT11N User's Manual for whether the cyclic data can be transmitted to/from stations compatible with CC-Link Ver.2.

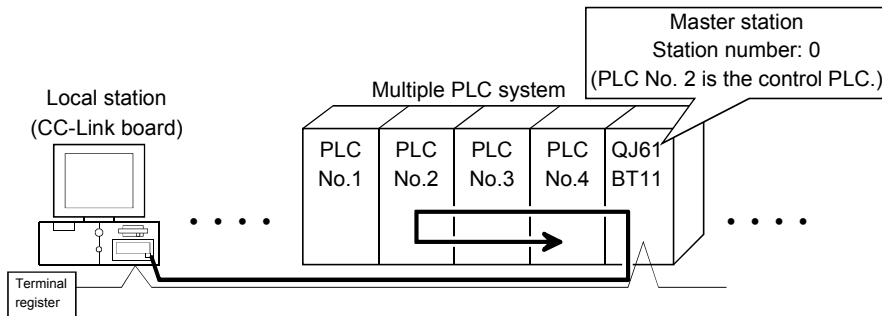
(Please read the reference section replacing "QJ61BT11N" with "CC-Link board".)

4.4.1 Multiple PLC system support

By setting the logical station number using the CC-Link utility, any PLC of a multiple PLC system in which a QJ61BT11 is installed can be accessed by an IBM PC/AT compatible PC in which a CC-Link board is installed.

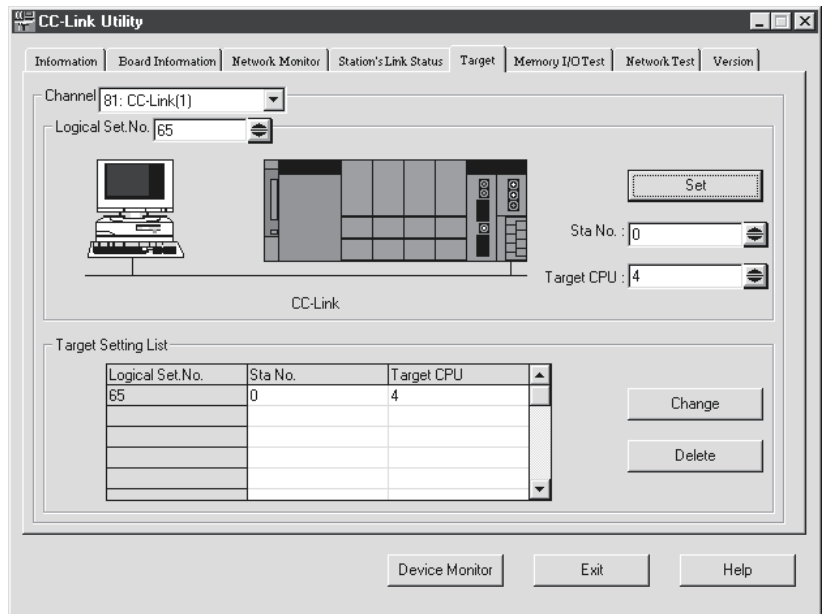
<Access example>

Using logical station number "65," an access can be made from an IBM PC/AT compatible PC in which a CC-Link board is installed to the PLC No. 4 via a QJ61BT11 (the control PLC is the PLC No.2).



[Setting the logical station number]

Set the logical station number in the "Target" window of the CC-Link utility. For details on the "Target" window, see Section 7.2.6.



POINT

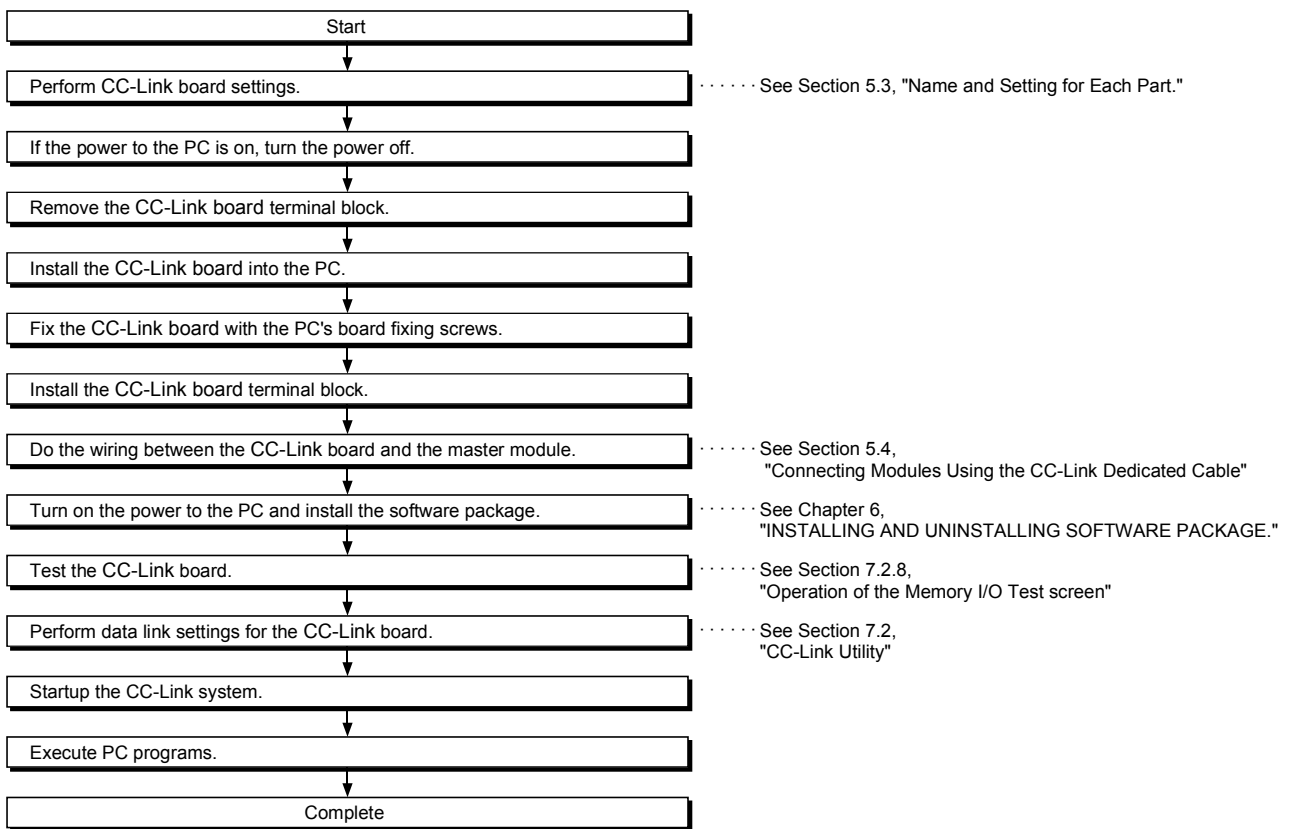
Use a QJ61BT11 of functional version B or later in order to access a multiple PLC system.
 A QJ61BT11 of functional version A cannot be used.

5 PROCEDURE AND SETTINGS UP TO THE POINT OF OPERATION

This section explains the operating procedure up to the point the CC-Link board is operated, as well as the names and setting for each part of the CC-Link board, wiring method and hardware testing.

5.1 Procedure Up to the Point of Operation

An outline of the procedure up to the point of CC-Link board operation is explained below.



Note


Setting on the master module side is mandatory in order to run the CC-Link system. Perform the settings for the master module side as required. See the user manual for the master module regarding the master module settings.


5.2 Installation

This section gives precautions when handling the CC-Link board and explains the installation environment.

5.2.1 Precautions when handling

The followings are precautions to be noted when handling the CC-Link board.

 DANGER	<ul style="list-style-type: none"> • Do not touch the terminal or the connector while the power is turned on. Doing so may result in electric shock or cause malfunctioning.
---	---

 CAUTION	<ul style="list-style-type: none"> • Fasten the CC-Link board securely using the installation screws and tighten the installation screws securely within the specified torque range. If the screws are loose, this may cause malfunctioning. If the screws are tightened too much, this could cause damage to the screws or module, leading to malfunctioning. • Do not directly touch the conductive section of the CC-Link board. Doing so could result in malfunctioning or breakdown of the CC-Link board. • Before handling the CC-Link board, touch a grounded metal object to discharge the static electricity from the human body. Failure to do so may cause failure or malfunction of the CC-Link board. • Tighten the terminal screws within the specified torque range. If the terminal screws are loose, this may lead to a short or malfunctioning. If the terminal screws are tightened too much, this could cause damage to the screws or CC-Link board, leading to a short or malfunctioning. • Handle the CC-Link board in a location where there is no static electricity. Static electricity could result in failure or malfunctioning. • Take care that foreign objects such as chips or wiring debris do not get into the PC. This could result in fire, breakdowns or malfunctioning. • Do not dismantle or rebuild the CC-Link board. This will result in failure, malfunctioning, injury or fire. • Always turn off all external power before installing or removing the CC-Link board. If power is not turned off at all phases, there is a risk of electric shock or damage to the product. • When discarding the product, handle it as an industrial waste. • Do not drop the CC-Link board or subject it to strong impact. This will result in failure or malfunctioning of the board.
--	---

(1) The tightening torque for the CC-Link board terminal screws and fixing screws should fall within the range indicated in the table below.

Screw locations	Tightening torque range
Terminal block terminal screws (M3.5 screw)	59 to 88 N·cm
Terminal block installation screws (M3.5 screw)	59 to 88 N·cm

(2) See the manual attached to the PC unit for the tightening torque of CC-Link board installing screws.

5.2.2 Installation environment

See the instruction manual accompanying the PC unit regarding installation of the PC unit in which the CC-Link board is mounted.



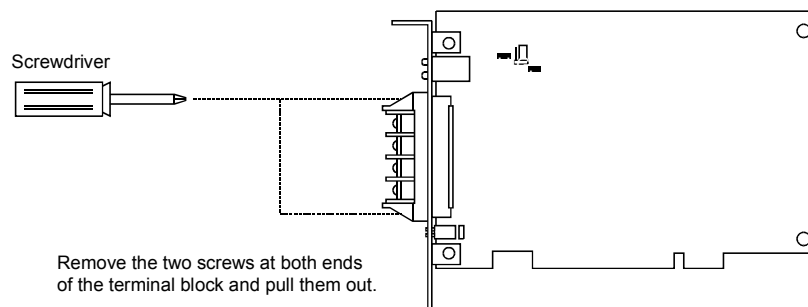
CAUTION

- Always ground the PC unit using grounding type D (Class 3 grounding). Otherwise, there is the risk of malfunctioning.
If there is an error in operation even when the PC unit is grounded, ground the FG terminal of the PC unit as well as the SLD terminal of the CC-Link board.

5.2.3 How to remove the terminal block

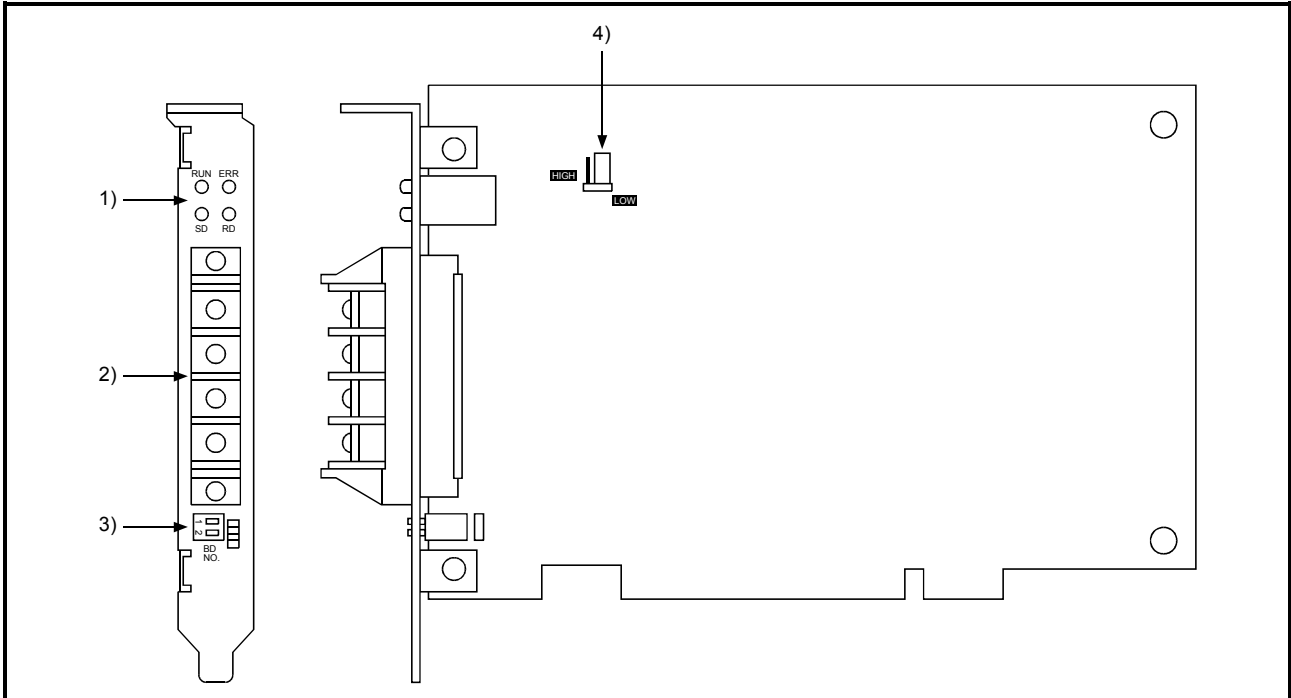
The CC-Link board uses a two-piece terminal block, so that the CC-Link board can be replaced without disconnecting the signal line to the terminal block.

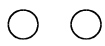
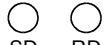
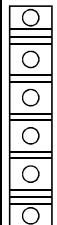
The illustration below shows how to remove the block.


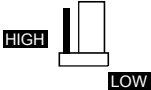


5.3 Name and Setting for Each Part

This section explains the name and settings for each part of the CC-Link board.



Number	Name	Contents			
		LED nomenclature	Contents	ON	OFF
1)	Operation display LED RUN ERR  SD RD 	RUN	Lights when the CC-Link board is running properly and turns off when a WDT error occurs	CC-Link board is normal	WDT error PC power is OFF
		ERR.	Lights when there is an error in the network communication status	Data link communication error	Data link communication normal
		SD	Flashes when the data link is transmitting data	Flashes while the data link is transmitting	
		RD	Flashes when the data link is receiving data	Flashes while the data link is receiving data	
2)	Terminal block for the data link  ↑ Upper surface of the board	Connect a CC-Link dedicated cable to perform the data link. (2-piece terminal block)			

Number	Name	Contents				
3)	Channel number setting switch  BD NO.	Sets the channel number for the CC-Link board.				
		Board number	Channel number	Switch		Notes
				1	2	
		0	81	OFF	OFF	Default setting
		1	82	ON	OFF	
		2	83	OFF	ON	
		3	84	ON	ON	
		Set the board number, so that there is no duplication when two or more CC-Link boards are installed.				
4)	Switch setting pin for abnormal temperature detection 	Sets the temperature at which to be detected when there is an abnormal temperature.				
		Setting	Contents		Notes	
		HIGH	Set the detect temperature at 55 °C.			
		LOW	Set the detect temperature at 45 °C.		Default setting	

5.4 Connecting Modules Using the CC-Link Dedicated Cable

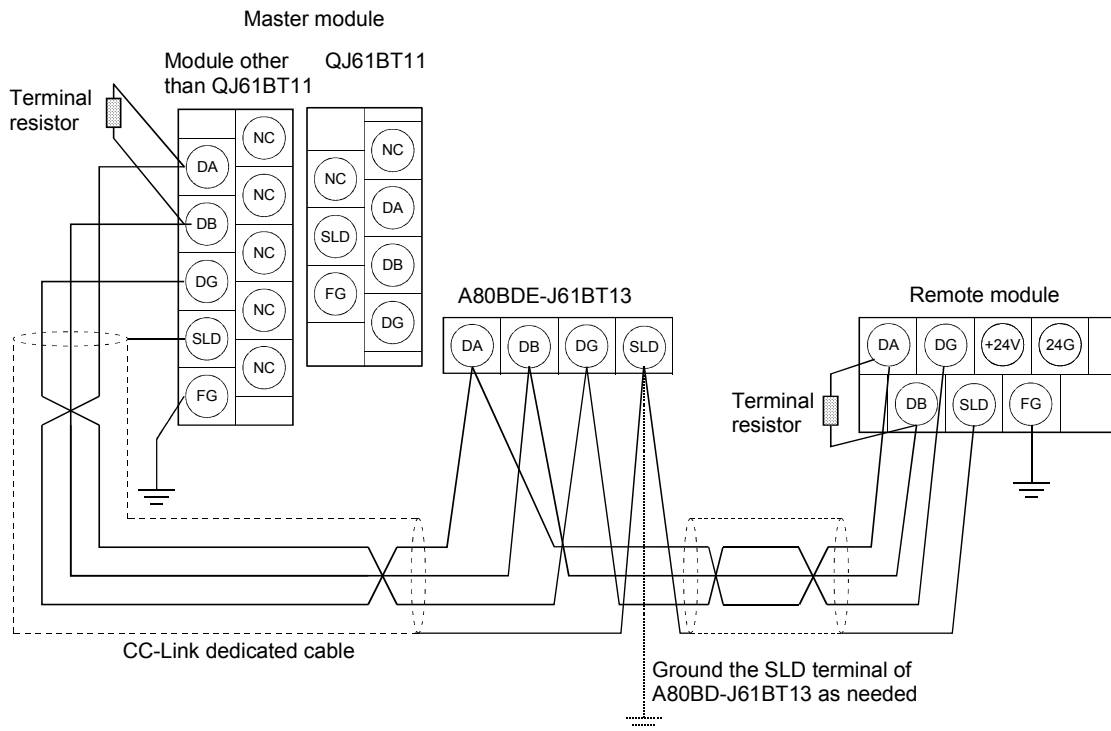
This section describes how to connect the CC-Link board, master module, local module, standby master module, remote module, and intelligent device module using the CC-Link dedicated cable.

IMPORTANT
<p>(1) Be sure to turn off the power to the corresponding station before attaching and removing a terminal block. If the terminal block is attached or removed without turning off the power to the corresponding station, normal data transfer will not be guaranteed.</p> <p>(2) The CC-Link dedicated cables, the high-performance CC-Link dedicated cables and Ver.1.10-compatible CC-Link dedicated cables cannot be used together. If they are used together, normal data transfer will not be guaranteed.</p> <p>(3) Be sure to ground the main body of an IBM PC/AT compatible PC using Class-D grounding (Class 3 grounding) or higher. Otherwise, malfunction may occur. If malfunction occurs when only the main body of an IBM PC/AT compatible PC is grounded, ground the FG terminal of the IBM PC/AT compatible PC and the SLD terminal of the CC-Link board.</p>

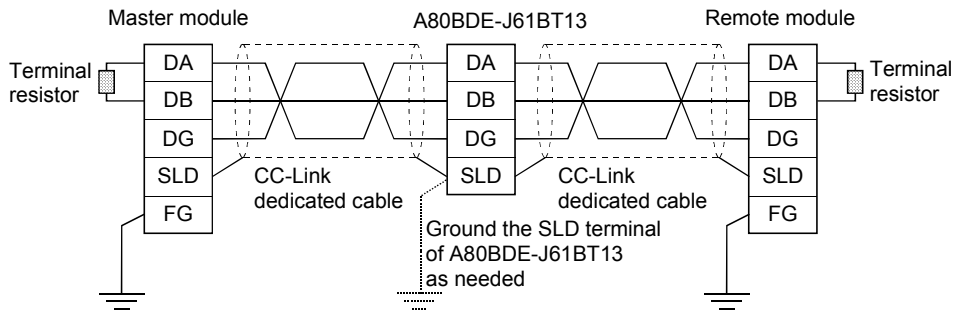
- (1) The order of cable connection is irrelevant to the station number.
- (2) Be sure to connect a "terminal resistor," which is provided with the module, to the modules at both ends of the CC-Link system.
Connect it between DA and DB.
- (3) Terminal resistors to be connected are different depending on the cable used by the CC-Link system:

Cable type	Terminal resistor
CC-Link dedicated cable	110 Ω 1/2 W (brown - brown - brown)
Version 1.10-compatible CC-Link dedicated cable	
CC-Link dedicated high-performance cable	130 Ω 1/2 W (brown - orange - brown)

- (4) The master module can be connected to locations other than both ends.
- (5) Star connection is not allowed.
- (6) The connection method is shown below.



[Simplified Diagram] The following shows a simplified diagram of the connection diagram on the previous page.



POINT

- (1) The layouts of the terminal block for the QJ61BT11 and of the terminal blocks for other than the QJ61BT11 are different. Exercise caution when wiring them.
- (2) Be sure to connect a "terminal resistor," which is provided with the master module, to the modules at both ends of the data link. (Connect it between DA and DB.)

5.5 T-Branch Connection Using the CC-Link Dedicated Cable

For details on the T-branch connection using the CC-Link Dedicated cable, refer to the following manuals:

- CC-Link System Master/Local Module Type QJ61BT11 User's Manual
- CC-Link System Master/Local Module Type AJ61BT11/A1SJ61BT11 User's Manual
- CC-Link System Master/Local Module Type AJ61QBT11/A1SJ61QBT11 User's Manual
- A80BDE-J61BT11 CC-Link System Master/Local Interface Board User's Manual (For SW4DNF-CCLINK-B)

6 INSTALLING AND UNINSTALLING THE SOFTWARE PACKAGE

This section explains how to install and uninstall the software package.

6.1 Installing the Software Package

The following explains the installation procedure of the driver and the installation procedure of the utility.

6.1.1 Installing the driver

The following explains the installation procedure of the CC-Link board driver.

POINT

- (1) When Microsoft® Windows NT® Workstation Operating System Version 4.0 is used, the installation of the CC-Link board driver is not required.
- (2) When using the following Operating systems, logon as a user who has administrator authority.
 - Windows® XP Professional
 - Windows® 2000 Professional
- (3) Disassociate all applications registered in the startup procedure, then execute installation after restarting Windows®.
- (4) Make sure to close other applications running on Windows® (including resident software such as antivirus software) before installation.

- (1) When Microsoft® Windows® 2000 Professional Operating System is used

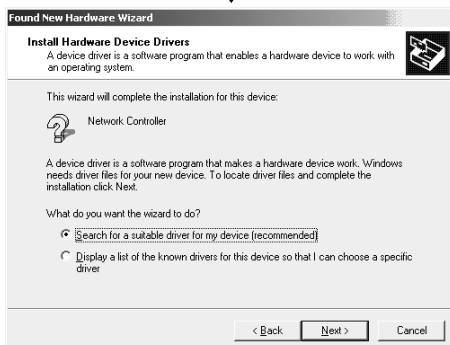
1. Mount the CC-Link board to a PC, then power on the PC to start Windows® 2000 Professional.

6

2. When the screen shown left is displayed, click the **Next>** button.

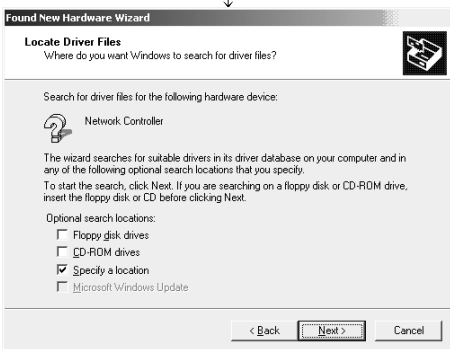


3. When the screen shown left is displayed, select "Search for a suitable driver for my device [recommended]," then click the **Next>** button.



(To the next page)

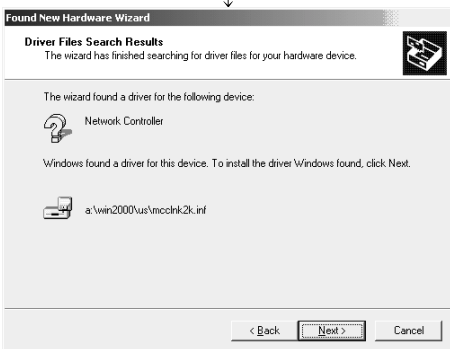
(From the previous page)



4. When the screen shown left is displayed, select "Specify a location" and click the **Next>** button.



5. When the screen shown left is displayed, enter "A:\Win2000\Us" for "Copy manufacturer's files from." Insert Disk 6 into the floppy disk drive, then click the **OK** button.



6. When the screen shown left is displayed, click the **Next>** button.



7. The installation is complete when the screen shown left is displayed. Click the **Finish** button.

(Complete)

(2) When Microsoft® Windows® XP Professional Operating System is used.

1. Mount a CC-Link board to a PC, and then power on the PC to start Windows® XP Professional.



2. When the screen shown left is displayed, select "Install from a list or specific location (Advanced)" and then click the **NEXT** button.



3. As the screen shown left is displayed, select "Search for the best driver in these locations".

Check "Include this location in the search" and enter "A:\Win2000\Us".

Insert Disk 6 into the floppy disk drive, and then click the **Next>** button to start the driver installation.



4. When the screen shown left is displayed, this means that the installation is completed.

Click the **Finish** button.

(Complete)

(3) When Microsoft® Windows® 95 Operating System or Microsoft® Windows® 98 Operating System is used

1. Mount the CC-Link board to a PC, then power on the PC to start Windows® 95 or Windows® 98.



2. When the screen shown left is displayed, click the **Next>** button.



3. When the screen shown left is displayed, select "Search for the best driver for your device [Recommended]," then click the **Next>** button.



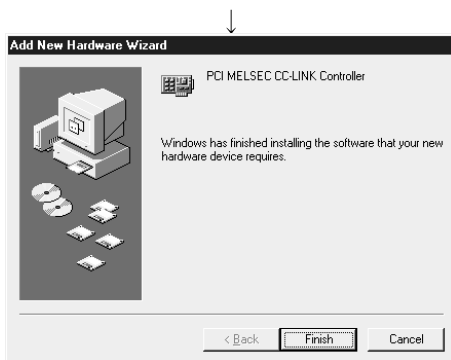
4. When the screen shown left is displayed, check "Specify a location," enter "A:\Win9x\Us" for the search location, then insert Disk 6 into the floppy disk drive.

(To the next page)

(From the previous page)



5. The driver file for the device will be searched.
Click the **Next>** button.



6. The installation is complete when the screen shown left is displayed.
Click the **Finish** button.

(Complete)

6.1.2 Installing the utility

The following explains the installation procedure of the utility.

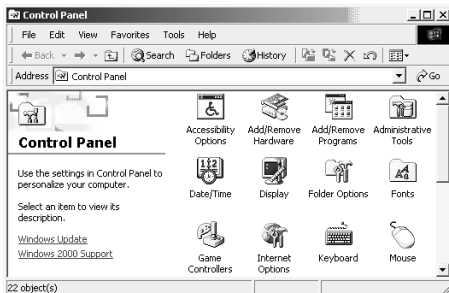
The screens of Windows® 2000 Professional are used in the explanation.

Therefore, these screens are slightly different from other operating systems.

Install the utilities with reference to **REMARK**.

POINT
<p>(1) When using the following Operating systems, logon as a user who has administrator authority.</p> <ul style="list-style-type: none"> • Windows® XP Professional • Windows® 2000 Professional • Windows NT® Workstation 4.0 <p>(2) Disassociate all applications registered in the startup procedure, then execute installation after restarting Windows® .</p> <p>(3) Make sure to close other applications running on Windows® (including resident software such as antivirus software) before installation.</p> <p>(4) Be sure to uninstall SWnDNF-CCLINK first, then install SW4DNF-CCLINK-B. Since all the data set by each utility will be erased, it is necessary to set them again.</p> <p>(5) To install the utility, use "Add/Remove Programs" in "Control Panel." As an alternative method, you can execute "Setup.exe". Double-click "Setup.exe" in Disk 1, then start the installation from item [6.] below.</p>

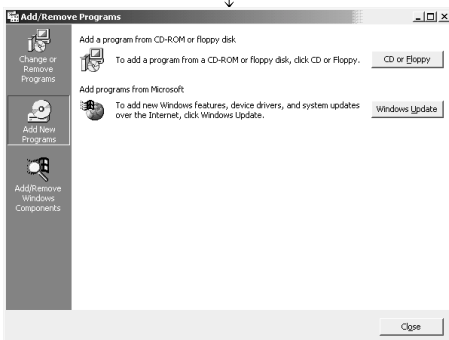
1. Power on the PC and start Windows® .



2. Open [Start] - [Settings] - [Control Panel].

REMARK

When Windows® XP Professional is used, open [Start] - [Control Panel].



3. Open "Add/Remove Programs" and select "Add New Program." When the screen shown at the left is displayed, click the **CD or Floppy** button.

REMARK

When Windows® 95, Windows® 98, or Windows NT® Workstation 4.0 is used, open "Add/Remove Programs" and click the **Install...** button.

(To the next page)

(From the previous page)



4. When the screen shown left is displayed, insert Disk 1 into the floppy disk drive and click the **Next>** button.



5. When the screen shown left is displayed, "Setup.exe" has been found. Click the **Finish** button and start the installation.

If "Setup.exe" was not found, click the **Browse...** button and change to the location where "Setup.exe" exists.

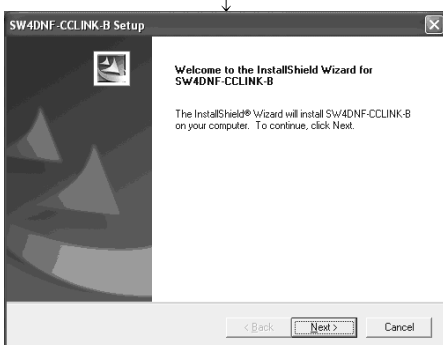


6. When the screen shown left is displayed, select "English" and click the **OK** button.

REMARK

Do not select Japanese.

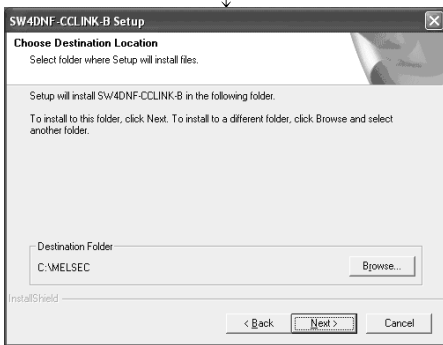
When selecting Japanese, the message in the following dialog box will not be displayed correctly.



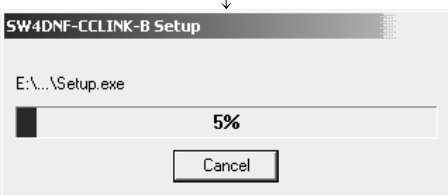
7. When the screen shown left is displayed, click the **Next>** button.

(To the next page)

(From the previous page)



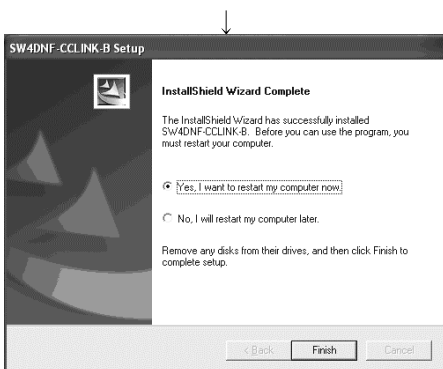
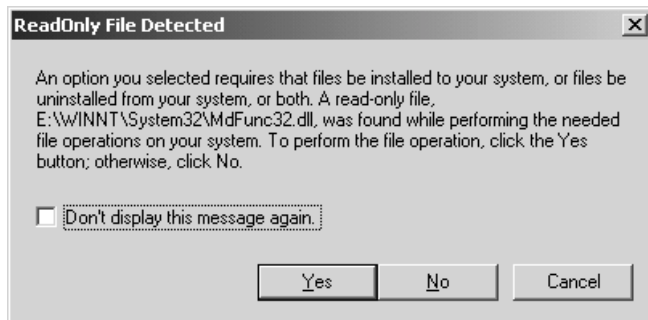
8. Specify the installation destination folder.
 The default installation destination folder of SW4DNF-CCLINK-B is "C:\MELSEC."
 To accept the default, click the **Next>** button.
 To change the installation destination folder, click the **Browse...** button.



9. The installation will start. Switch floppy disks in the order, as instructed on the screen.

REMARK

If the following screen is displayed during installation, click the **Yes** button and continue with the installation.



10. The installation is complete when the screen shown left is displayed.
 To restart, confirm that "Yes, I want to restart my computer now" is checked, then click the **Finish** button.
 To restart later, check "No, I will restart my computer later," then click the **Finish** button.

(Complete)

POINT



- (1) If the installation failed to complete and it is possible to uninstall the software package, execute the uninstall procedure.
- (2) To reinstall the software package, uninstall it first, restart the PC, and then reinstall.

6.2 Icons to be Registered

When the software package is installed, the following icons are registered in [Start] - [Programs] - [MELSEC].

REMARK

When Windows® XP Professional is used, the following icons are registered in [Start] - [All Programs] - [MELSEC].

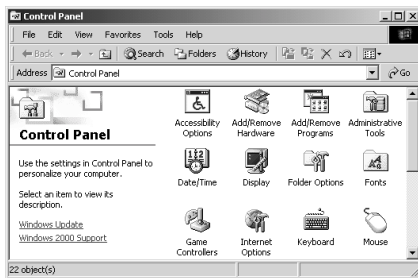
Icon	Utility name	Description
	CC-Link utility	Starts the CC-Link utility.
	Error Viewer *1	Starts Error Viewer.

*1: Supported for Windows® 95 and Windows® 98 only.

6.3 Uninstalling the Software Package

The following explains how to uninstall the software package. The screens of Windows® 2000 Professional are used in the explanation. Therefore, these screens are slightly different from other Operating systems. Uninstall the utilities with reference to **REMARK**.

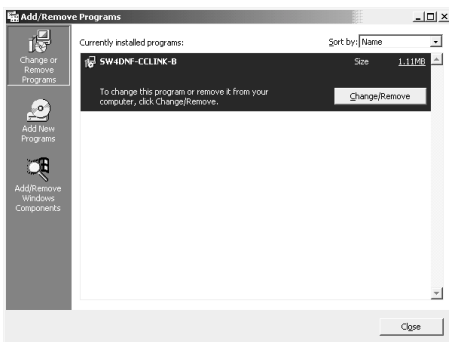
POINT
<p>(1) When using the following Operating systems, logon as a user who has administrator authority.</p> <ul style="list-style-type: none"> • Windows® XP Professional • Windows® 2000 Professional • Windows NT® Workstation 4.0 <p>(2) Disassociate all applications registered in the startup procedure, then execute uninstallation after restarting Windows®.</p> <p>(3) Make sure to close other applications running on Windows® (including resident software such as antivirus software) before uninstallation.</p> <p>(4) Always uninstall from Control Panel. Do not directly start the installed "UnInstaller.exe."</p> <p>(5) To reinstall the software package, uninstall it first, restart the PC, and then reinstall.</p>



1. Open [Start] - [Settings] - [Control Panel].

REMARK

When Windows® XP Professional is used, open [Start] - [Control Panel].



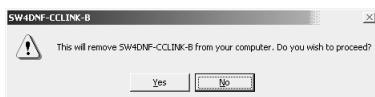
2. Open "Add/Remove Programs" and select "Change or remove programs."

Select SW4DNF-CCLINK-B and click the **Change/Remove** button.

REMARK

When Windows® 95, Windows® 98, or Windows NT® Workstation 4.0 is used, select SW4DNF-CCLINK-B and click the **Add/Remove...** button.

When Windows® XP Professional is used, select SW4DNF-CCLINK-B and then click on the **Change/Remove** button.



3. When the screen shown left is displayed, click the **Yes** button to begin uninstalling the software package.



4. After the uninstall procedure of the software package is complete, click the **OK** button.

(Complete)

7 UTILITY OPERATION

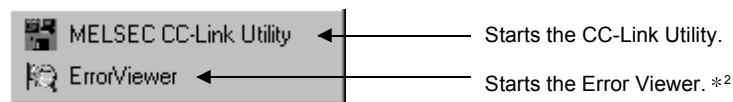
POINT
<p>When using the following Operating systems, logon as a user who has administrator authority.</p> <ul style="list-style-type: none"> • Windows® XP Professional • Windows® 2000 Professional • Windows NT® Workstation 4.0

7.1 Utility Common Operations

This section explains the common operations for each utility.

7.1.1 Starting a utility

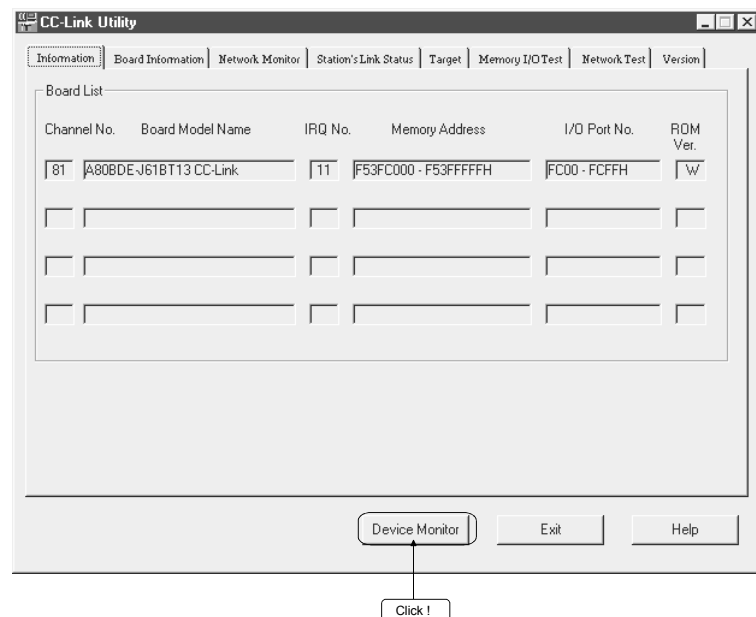
An utility can be started by clicking on the following menus found in the [Start] – [Program * 1] – [MELSEC] menu.



- * 1: When Microsoft® Windows® XP Professional Operating System is used, [All programs] is displayed.
- * 2: The error viewer is registered only when the operating system is Microsoft® Windows® 95 Operating System or Microsoft® Windows® 98 Operating System.

7.1.2 Starting the device monitor utility

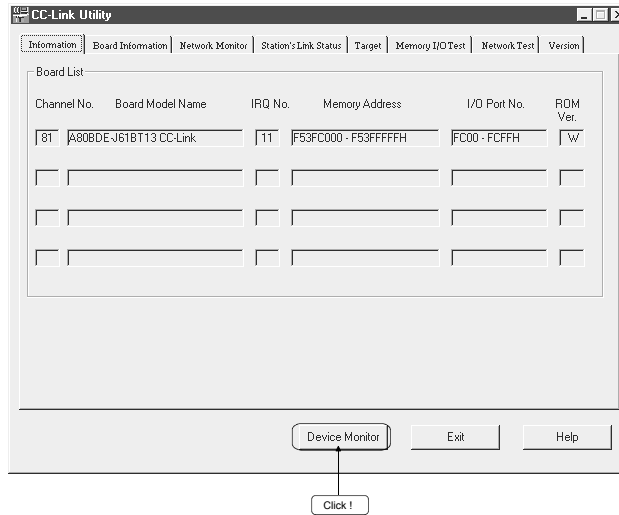
The following explains how to start the device monitor utility from the CC-Link utility. The device monitor utility can be started by clicking on the **Device Monitor** button found at the bottom of the CC-Link utility screen.



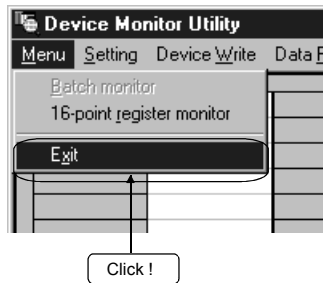
7.1.3 Ending a utility

This section explains how to end a utility.

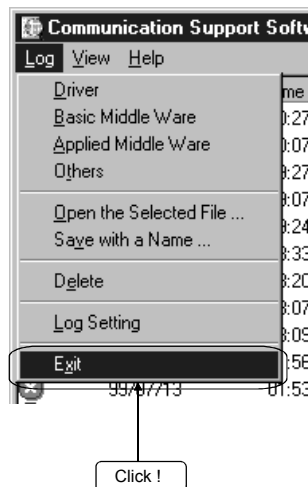
- (1) To end the utility, click the **Exit** button at the bottom of the utility screen.



- (2) To end the device monitor utility, click [Menu] – [Exit] from the menu bar. When a dialog box is displayed, clicking the **Yes** button ends the device monitor utility.



- (3) To end the error viewer, click [Log] – [Exit] menu from the menu bar.

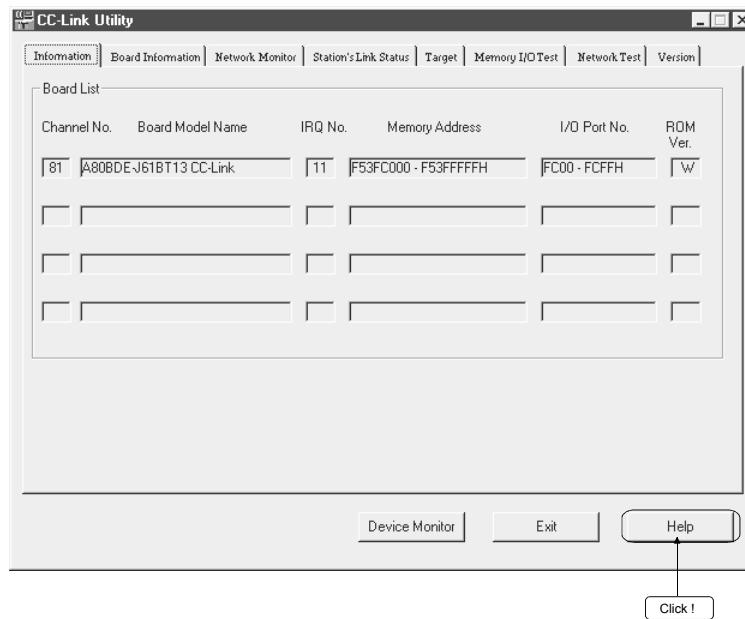


7

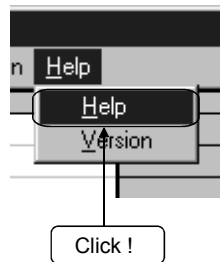
7.1.4 Displaying the help screen

This section explains how to display the utility's help screen.

- (1) To display the utility's help screen, click the **Help** button at the lower right-hand corner of the utility screen.



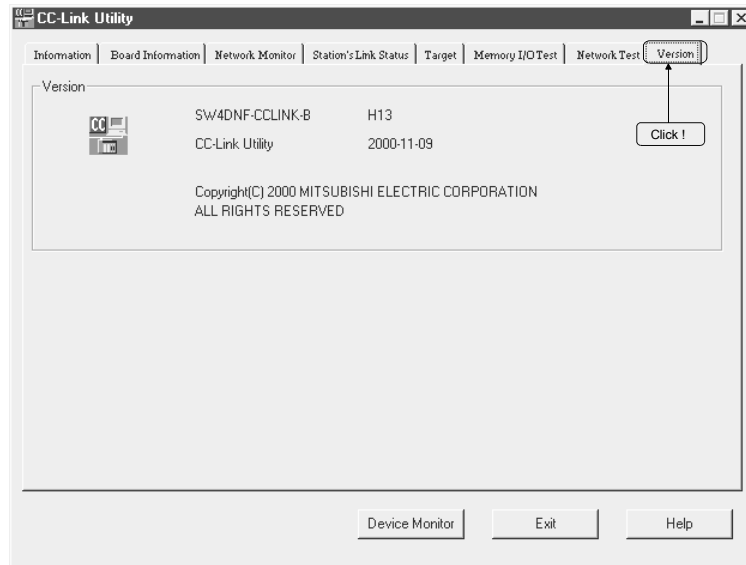
- (2) To display the help screen for the device monitor utility and error viewer, click **[Help] – [Help]** from the menu bar.



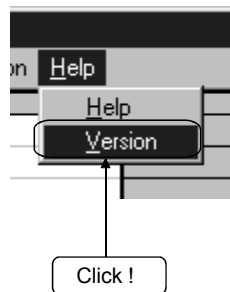
7.1.5 Verifying the version

This section explains how to verify the utility version.

- (1) To verify a utility's version, click the "Version" tab.



- (2) To verify the version for the device monitor utility and error viewer, click [Help] - [Version] from the menu bar.

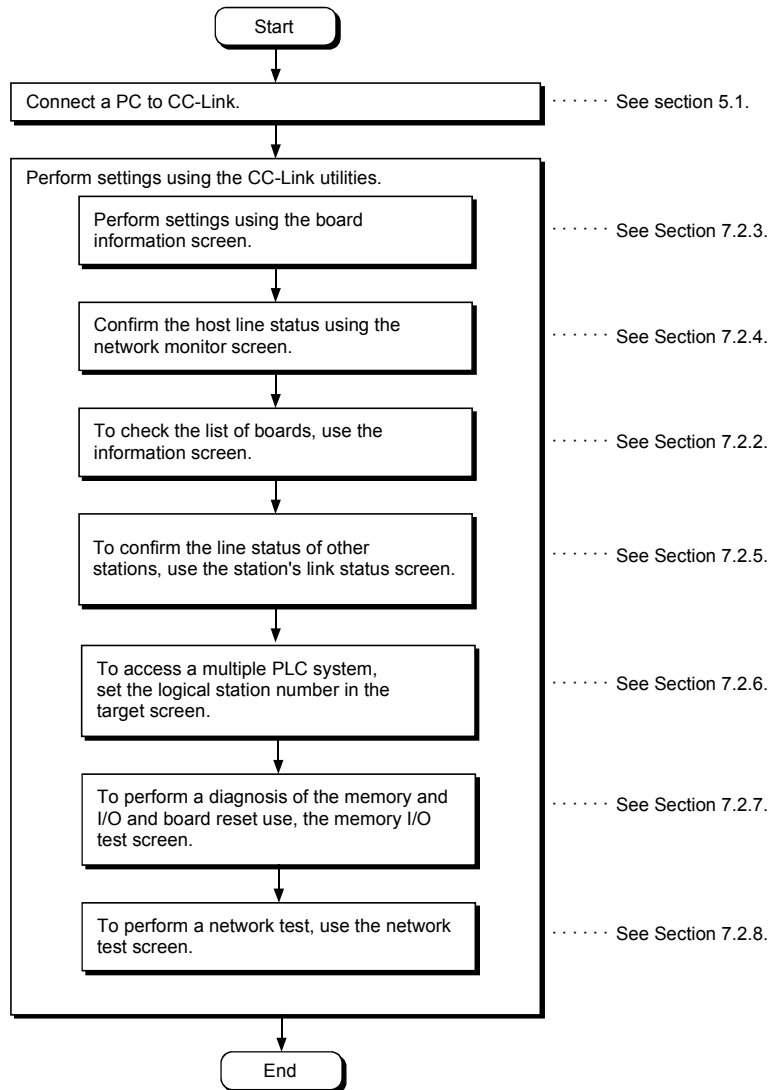


7.2 CC-Link Utility

This section explains how to operate the CC-Link utilities.

7.2.1 Operation procedure

The following explains the operation procedure for the CC-Link utilities.



7.2.2 Operations on Information screen

The hardware information that is set for CC-Link board is displayed.

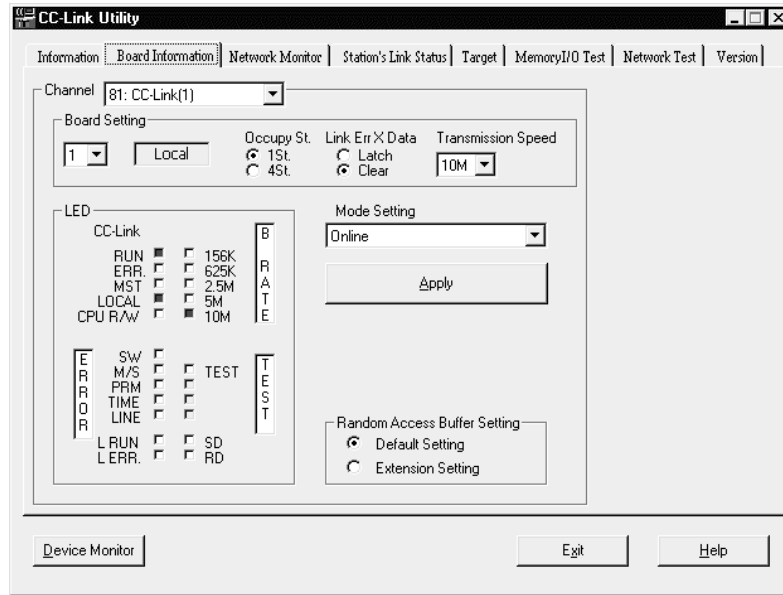


Item	Description
Channel No.	Displays the channel number.
Board Model Name	Displays the model of CC-Link board that is connected.
IRQ No.	Displays the IRQ number that CC-Link board uses.
Memory Address	Displays the range of dual-port memory that CC-Link board occupies.
I/O Port no.	Displays the ranges of I/O port that CC-Link board occupies.
ROM Ver.	Displays the ROM version of CC-Link board.

7.2.3 Operations on Board Information screen

The card information screen is used to set and to display various information about the installed CC-Link board.

POINT
When switching screens, set the mode setting to "On-line" or "Off-line."



Item	Description										
Channel	Sets a channel to be used.										
Board Setting	Sets information on the host.										
	<table border="1"> <thead> <tr> <th>Item</th> <th>Setting</th> </tr> </thead> <tbody> <tr> <td>Station number</td> <td>Station 1 to 64</td> </tr> <tr> <td>Number of stations occupied</td> <td>1 station/4 stations</td> </tr> <tr> <td>Data entered at fault</td> <td>Latch/clear</td> </tr> <tr> <td>Transmission Speed</td> <td>156 k/625 k/2.5 M/5 M/10 Mbps</td> </tr> </tbody> </table>	Item	Setting	Station number	Station 1 to 64	Number of stations occupied	1 station/4 stations	Data entered at fault	Latch/clear	Transmission Speed	156 k/625 k/2.5 M/5 M/10 Mbps
	Item	Setting									
	Station number	Station 1 to 64									
	Number of stations occupied	1 station/4 stations									
Data entered at fault	Latch/clear										
Transmission Speed	156 k/625 k/2.5 M/5 M/10 Mbps										

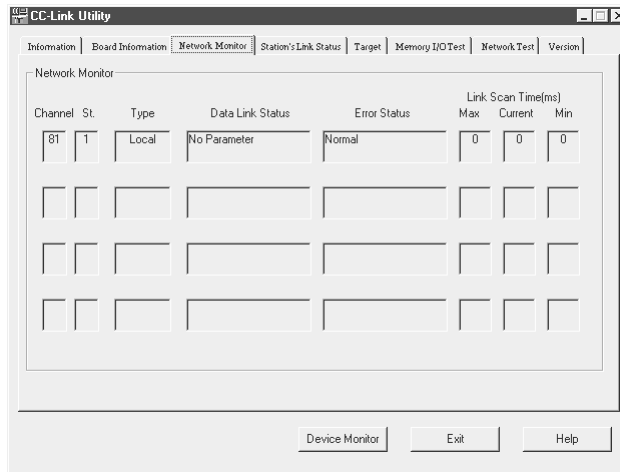
Item		Description	
LED	Display present status of CC-Link board.		
	LED name		LED On
	RUN		CC-Link system normal
	ERR.		Communication abnormal
	MST		Master station
	LOCAL		Local station
	CPU R/W		Communicating
	SW		Switch setting error
	M/S		Master station duplication error
	PRM		Parameter error
	TIME		No response is received from all stations due to cable disconnection or the transmission path being affected by noise.
	LINE		Cable disconnection error
	L RUN		Data link running
Mode Setting	Perform the mode setting for the CC-Link board, and display the present mode status.		
	Mode		Data
	Online		Used for normal communication
	Offline		Becomes the state when not connected to the network.
	Hardware test		Executes a test of the A80BDE-J61BT13 hardware. [Procedure] Connect a terminal resistor between the terminal DA and DB. Set the mode setting to "Hardware test" and press the <input type="button" value="Apply"/> button.
	<input type="button" value="Apply"/> button		The contents of the setting with respect to the CC-Link board selected by the channel are updated.
	Random Access Buffer Setting	Default Setting	The random access buffer area is used via default setting. (Buffer memory area: A00 _H to FFF _H)
Extension Setting		The random access buffer area is used via extension setting. (Buffer memory area: A00 _H to 2FFF _H)	

7.2.4 Operations on Network Monitor screen

This screen monitors the line status of the host.

POINT

To restart monitoring after monitoring stops due to an error, display a screen other than the "Network Monitor" screen first, and then display the "Network Monitor" screen again.

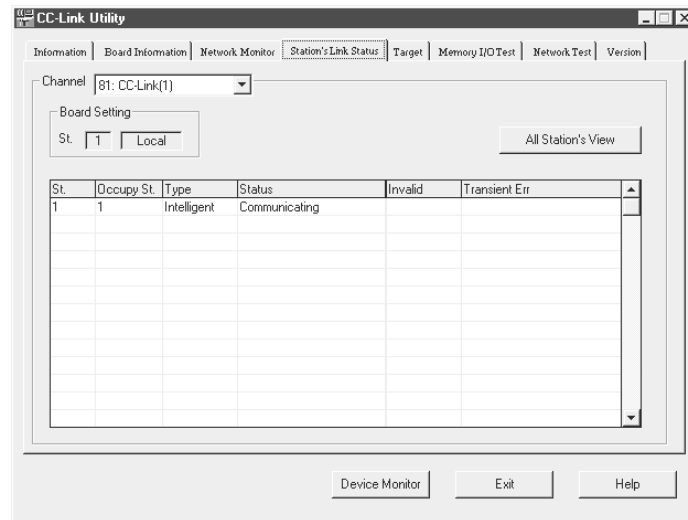


Item	Description																								
Channel	Displays the channel number.																								
St.	Displays the station number of the host.																								
Data Link Status	Monitors and displays the startup status of the data link. <table border="1" style="margin-left: 20px;"> <thead> <tr> <th>Status</th> <th>Contents</th> </tr> </thead> <tbody> <tr> <td>Initial status</td> <td>Data link is in initial status.</td> </tr> <tr> <td>No parameter</td> <td>Parameters have not been received.</td> </tr> <tr> <td>Data linking</td> <td>The data link is being executed.</td> </tr> <tr> <td>Data link stopping</td> <td>The data link has stopped.</td> </tr> <tr> <td>Disconnecting (Not poling)</td> <td>There is no inquiry from the master station and the link is disconnected.</td> </tr> <tr> <td>Disconnecting (Line Error)</td> <td>The link is disconnected due to an error in the line.</td> </tr> <tr> <td>Disconnecting (others)</td> <td>The link is disconnected due to other reasons.</td> </tr> <tr> <td>Line testing</td> <td>A line test is being performed.</td> </tr> <tr> <td>Parameter Set testing</td> <td>A test is being performed on the parameter settings from the master station.</td> </tr> <tr> <td>Automatic returning</td> <td>A return is automatically being processed.</td> </tr> <tr> <td>Resetting</td> <td>The board is being reset.</td> </tr> </tbody> </table>	Status	Contents	Initial status	Data link is in initial status.	No parameter	Parameters have not been received.	Data linking	The data link is being executed.	Data link stopping	The data link has stopped.	Disconnecting (Not poling)	There is no inquiry from the master station and the link is disconnected.	Disconnecting (Line Error)	The link is disconnected due to an error in the line.	Disconnecting (others)	The link is disconnected due to other reasons.	Line testing	A line test is being performed.	Parameter Set testing	A test is being performed on the parameter settings from the master station.	Automatic returning	A return is automatically being processed.	Resetting	The board is being reset.
Status	Contents																								
Initial status	Data link is in initial status.																								
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Disconnecting (others)	The link is disconnected due to other reasons.																								
Line testing	A line test is being performed.																								
Parameter Set testing	A test is being performed on the parameter settings from the master station.																								
Automatic returning	A return is automatically being processed.																								
Resetting	The board is being reset.																								
Error Status	Monitors and displays the error status. <table border="1" style="margin-left: 20px;"> <thead> <tr> <th>Display</th> <th>Contents</th> </tr> </thead> <tbody> <tr> <td>Normal</td> <td>Normal status</td> </tr> <tr> <td>Transmission Error</td> <td>Error in communication path was detected.</td> </tr> <tr> <td>Parameter Error</td> <td>Error in parameters was detected.</td> </tr> <tr> <td>CRC Error</td> <td>CRC error was detected.</td> </tr> <tr> <td>Time Out Error</td> <td>Timeout error was detected.</td> </tr> <tr> <td>Abort Error</td> <td>An error in the CC-Link board (gate array) was detected.</td> </tr> <tr> <td>Setting Error</td> <td>Error in the setting was detected.</td> </tr> <tr> <td>Other Error</td> <td>Error arising from some other cause was detected.</td> </tr> </tbody> </table>	Display	Contents	Normal	Normal status	Transmission Error	Error in communication path was detected.	Parameter Error	Error in parameters was detected.	CRC Error	CRC error was detected.	Time Out Error	Timeout error was detected.	Abort Error	An error in the CC-Link board (gate array) was detected.	Setting Error	Error in the setting was detected.	Other Error	Error arising from some other cause was detected.						
Display	Contents																								
Normal	Normal status																								
Transmission Error	Error in communication path was detected.																								
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Abort Error	An error in the CC-Link board (gate array) was detected.																								
Setting Error	Error in the setting was detected.																								
Other Error	Error arising from some other cause was detected.																								
Link Scan Time	Max	Displays the maximum value for the link scan time. (1 ms unit)																							
	Current	Displays the current value for the link scan time. (1 ms unit)																							
	Min	Displays the minimum value for the link scan time. (1 ms unit)																							

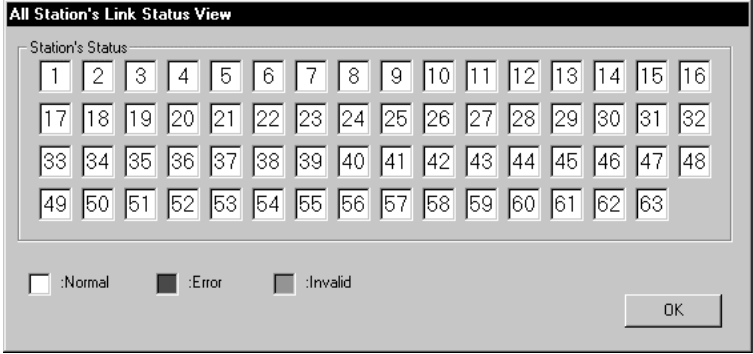
7.2.5 Operations on Station's Link Status screen

Displays the line status of another station.

POINT
(1) The Station's Link Status only monitors when the host status is "data linking."
(2) To restart monitoring after monitoring stops due to an error, display a screen other than the " Station's Link Status" screen first, and then display the "Station's Link Status" screen again.

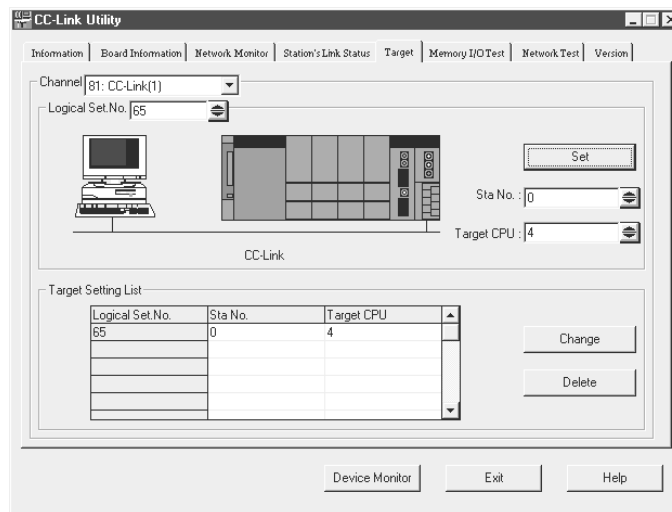


Item		Description															
Channel		Sets the channel to be used.															
Board Setting		Displays information on the host.															
Other Station Status	St.	Displays the station number that has been set.															
	Occupy St.	Displays the number of stations occupied.															
	Type	Displays the type of the station that is set. <table border="1" style="width: 100%; margin-top: 5px;"> <thead> <tr> <th>Display</th> <th>Contents</th> </tr> </thead> <tbody> <tr> <td>Remote Device</td> <td>Remote device station</td> </tr> <tr> <td>Remote I/O</td> <td>Remote I/O station</td> </tr> <tr> <td>Intelligent</td> <td>Intelligent station, local station</td> </tr> </tbody> </table>	Display	Contents	Remote Device	Remote device station	Remote I/O	Remote I/O station	Intelligent	Intelligent station, local station							
	Display	Contents															
	Remote Device	Remote device station															
Remote I/O	Remote I/O station																
Intelligent	Intelligent station, local station																
Status	Displays the status of another station. <table border="1" style="width: 100%; margin-top: 5px;"> <thead> <tr> <th>Display</th> <th>Contents</th> </tr> </thead> <tbody> <tr> <td>Communicating</td> <td>Normal</td> </tr> <tr> <td>Communication interrupted</td> <td>Communication is stopped</td> </tr> <tr> <td>Link error</td> <td>There is a link error</td> </tr> <tr> <td>WDT error</td> <td>A watchdog timer error occurred</td> </tr> <tr> <td>Fuse brake off</td> <td>A station has blown a fuse</td> </tr> <tr> <td>Repeated station</td> <td>There are duplicate station numbers</td> </tr> <tr> <td>Moved switch</td> <td>Switch was changed</td> </tr> </tbody> </table>	Display	Contents	Communicating	Normal	Communication interrupted	Communication is stopped	Link error	There is a link error	WDT error	A watchdog timer error occurred	Fuse brake off	A station has blown a fuse	Repeated station	There are duplicate station numbers	Moved switch	Switch was changed
Display	Contents																
Communicating	Normal																
Communication interrupted	Communication is stopped																
Link error	There is a link error																
WDT error	A watchdog timer error occurred																
Fuse brake off	A station has blown a fuse																
Repeated station	There are duplicate station numbers																
Moved switch	Switch was changed																
Invalid	Displays the station with an error invalid. <table border="1" style="width: 100%; margin-top: 5px;"> <thead> <tr> <th>Display</th> <th>Contents</th> </tr> </thead> <tbody> <tr> <td>Error invalid station</td> <td>There is a setting</td> </tr> <tr> <td>(Free)</td> <td>No setting</td> </tr> </tbody> </table>	Display	Contents	Error invalid station	There is a setting	(Free)	No setting										
Display	Contents																
Error invalid station	There is a setting																
(Free)	No setting																
Transient Err	Displays the status of a transient error. <table border="1" style="width: 100%; margin-top: 5px;"> <thead> <tr> <th>Display</th> <th>Contents</th> </tr> </thead> <tbody> <tr> <td>Transient Error</td> <td>There is an error</td> </tr> <tr> <td>(Free)</td> <td>No error</td> </tr> </tbody> </table>	Display	Contents	Transient Error	There is an error	(Free)	No error										
Display	Contents																
Transient Error	There is an error																
(Free)	No error																

Item	Description
<p data-bbox="360 566 592 595">All Station View button</p>	<p data-bbox="673 304 1406 427">A list of communication status for other stations is displayed. When a reserve station has been set in the data link parameter that is to set in the master station, the reserve station is displayed as a normal communication station in the following list of other station communication statuses.</p> 

7.2.6 Operations on Target screen

Set the logical station number to access a multiple PLC system.



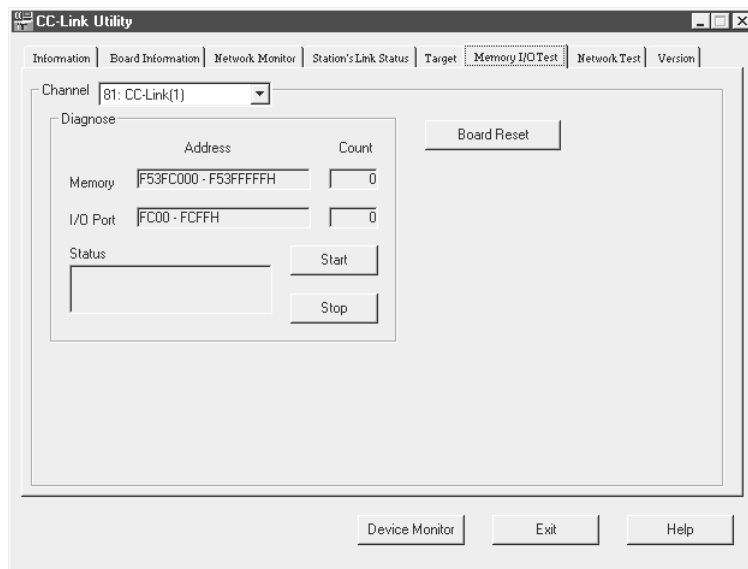
Item	Description
Channel	Select the channel for setting the destination.
Logical Set No.	Enter the logical station number to be set or modified (setting range: 65 to 239).
Sta. No.	Enter the station number of a QJ61BT11 that is controlled by a multiple PLC system.
Target CPU	Enter the target PLC to be accessed.
Set button	Register the contents of the setting to the destination list.
Change button	Select the line to be changed, then click this button to modify the registered data. (The same operation will result by double-clicking the line to be changed.)
Delete button	Select the line to be deleted, then click this button to delete the registered station number.

7.2.7 Operations on Memory I/O Test screen

Diagnoses the dual-port memory and I/O port used by the CC-Link board.

POINT

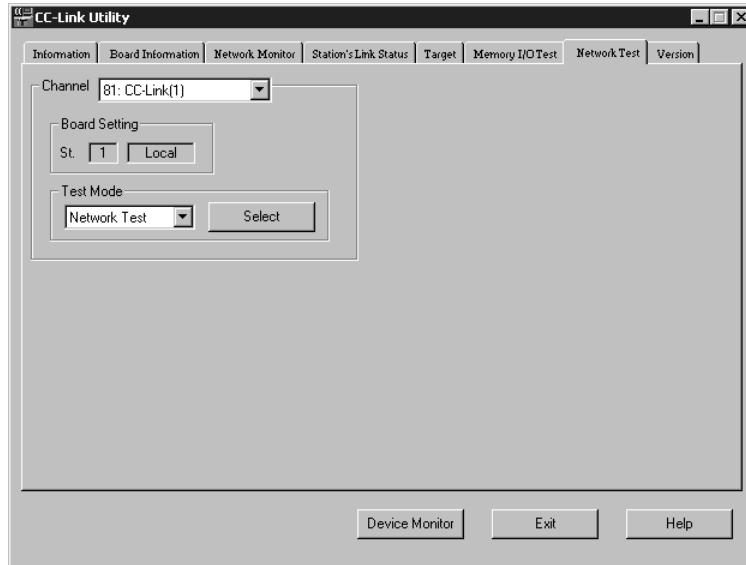
(1) Start the diagnostic operation after disconnecting the external cable.
 (2) To switch the screens during the diagnostic operation, click the **Stop** button to terminate the diagnosis and then switch screens.



Item	Description
Channel	Set the channel to be used.
Diagnose	Displays the address being diagnosed and number of the diagnosis and status.
Start button	Starts the memory and I/O diagnosis.
Stop button	Terminates the memory and I/O diagnosis.
Board Reset button	Resets the CC-Link board.

7.2.8 Operations on Network Test screen

Tests the CC-Link board that is loaded.



Item	Description				
Channel	Sets the channel to be used.				
Board Setting	Displays information on the host.				
Test Mode	<p>Sets the items to be tested.</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <thead> <tr> <th>Item</th> <th>Setting</th> </tr> </thead> <tbody> <tr> <td>Network Test</td> <td>Performs a test for data link start and stop.</td> </tr> </tbody> </table>	Item	Setting	Network Test	Performs a test for data link start and stop.
Item	Setting				
Network Test	Performs a test for data link start and stop.				
Start button	<p>The following dialog box is displayed by clicking.</p> <div style="text-align: center;"> </div> <p>Clicking this starts the test.</p> <p>Closes the dialog box without performing the test.</p>				

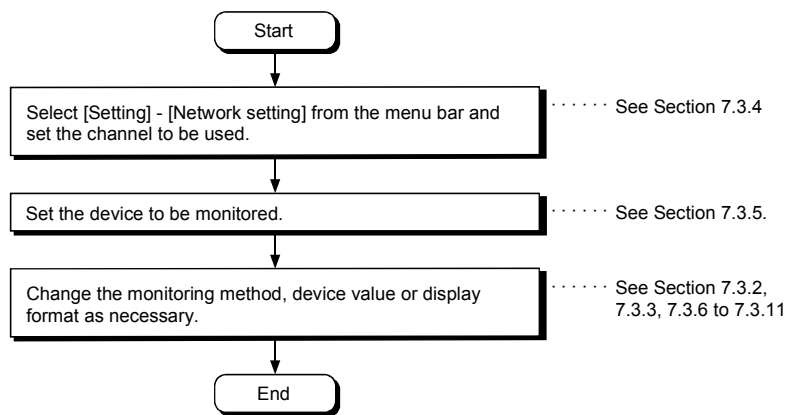
7.3 Device Monitor Utility

This section explains how to operate and set the device monitor utility.

POINT
 In the device monitor utility, SB (link special relay) and SW (link special register) are indicated as SM and SD, respectively.

7.3.1 Operation procedure

The following explains how to operate the device monitor utility.



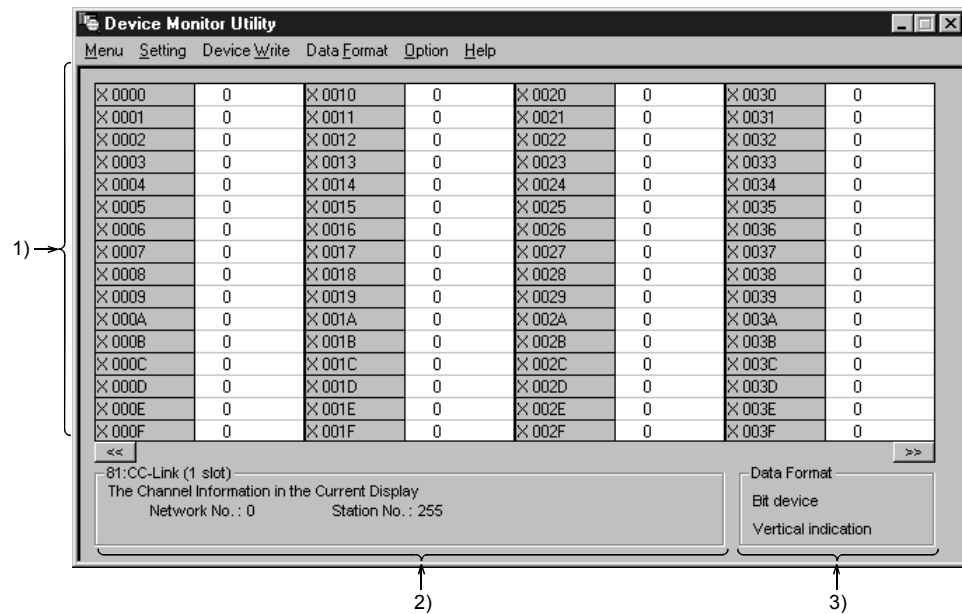
7.3.2 Setting as batch monitoring

Monitors only one device that has been specified.

(1) Selecting the menu

Select [Menu] – [Batch monitor] from the menu bar.
(Selectable for 16-point register monitor only.)

(2) Display screen



Item	Description
1) Device information	Displays the current device status. See Section 7.3.9 when the display form is changed.
2) Network status	Displays the network status currently set. See Section 7.3.4 when the network is set.
3) Data Format	Shows a display form and device types being displayed (word device and bit device). See Section 7.3.5 when the device type is changed. And, see Section 7.3.9 when the display form is changed.

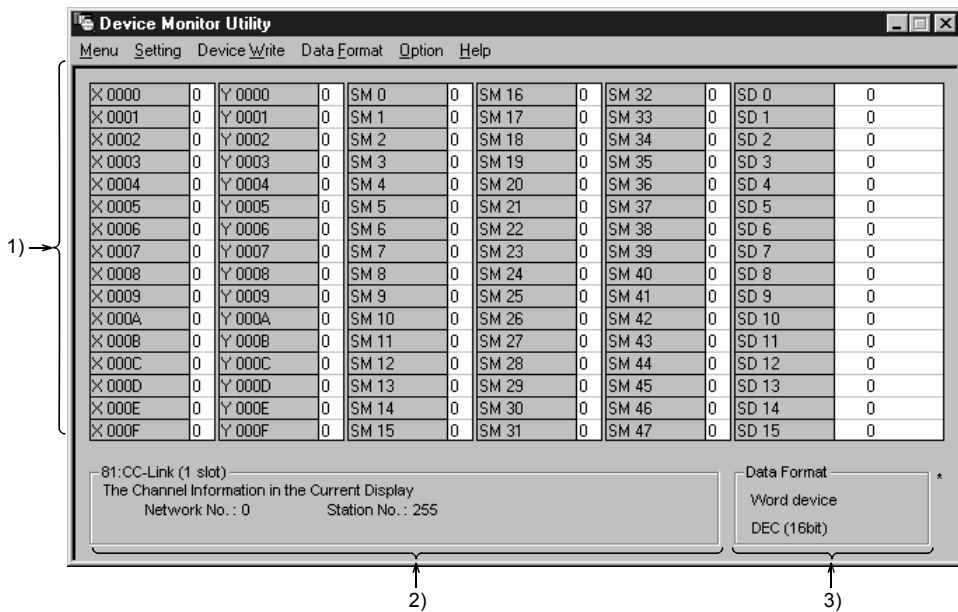
7.3.3 Setting as 16 point register monitor

Monitors up to five bit devices and one word device simultaneously.

(1) Selecting the menu

Select [Menu] – [16 point register monitor] from the menu bar.
(Selectable at batch monitoring only.)

(2) Display screen



Item	Description
1) Device information	Displays the current device status. See Section 7.3.9 when changing the display form.
2) Network status	Displays the network status currently set. See Section 7.3.4 when setting the network.
3) Data Format	Shows a display form and device types being displayed (word device and bit device). See Section 7.3.5 when changing the device type. And, see Section 7.3.9 when changing the display form.

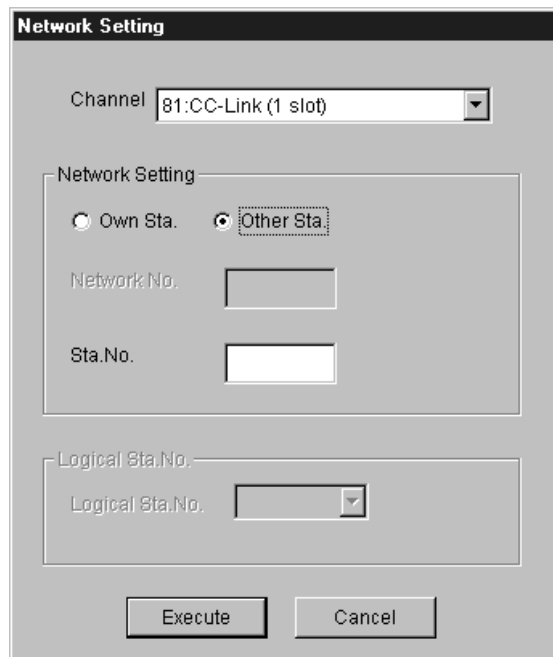
7.3.4 Setting the monitoring destination

Sets the network to be used for device monitoring.
Set this when starting the device monitor utility.

(1) Selecting the menu

Select [Setting] – [Network Setting] from the menu bar.

(2) Dialog box



Item	Description
Channel	Sets the channel to be used.
Network Setting	Sets the host and other stations along with network number and station number.

POINT
<p>(1) To access a multiple PLC system, select other station, then enter the value of the "logical station number" set with the CC-Link utility for the station number.</p> <p>(2) Do not specify a CC-Link remote I/O station or intelligent device station as the monitor destination. Specifying a remote I/O station or intelligent device station generates a corresponding error.</p> <p>(3) When own station is selected in the network setting, network No. "0" and station No. "255" are displayed as the network status.</p>

7.3.5 Setting the device to monitor

Set the device to perform monitoring.

(1) Selecting the menu

Select [Setting] – [Device Setting] from the menu bar.

(2) Dialog box

Batch monitoring

The 'Device Setting' dialog box for Batch monitoring contains the following elements:

- Device Type:** A dropdown menu with 'X(input)' selected.
- Block / Network No.:** An empty text input field.
- DeviceNo.:** Radio buttons for HEX, DEC, and OCT, with a numeric input field containing '0000'.
- Buttons:** 'Execute' and 'Cancel' buttons at the bottom.

16-points registration monitoring

The 'Device Setting' dialog box for 16-points registration monitoring contains the following elements:

- Device Type:** A dropdown menu with 'SD(special register)' selected.
- Block / Network No.:** An empty text input field.
- DeviceNo.:** Radio buttons for HEX, DEC, and OCT, with a numeric input field containing '0'.
- Setting button:** A button located below the DeviceNo. field.
- Register Device List:** A table with columns 'Bit device' and 'Word device'.

Bit device	Word device
X 0000	SD 0
Y 0000	--
SM 0	--
SM 10	--
- Buttons:** 'Change', 'Delete', 'Execute', and 'Cancel' buttons.

Item	Description																		
Device Type	<p>Sets the device type, block number, and network number to monitor. And, to monitor the host station device on the CC-Link board, set as follows.</p> <table border="1"> <thead> <tr> <th>Host station device to monitor</th> <th>Device type to specify</th> </tr> </thead> <tbody> <tr> <td>RX</td> <td>X</td> </tr> <tr> <td>RY</td> <td>Y</td> </tr> <tr> <td>SB</td> <td>SM</td> </tr> <tr> <td>SW</td> <td>SD</td> </tr> <tr> <td>RWw</td> <td>Ww</td> </tr> <tr> <td>Rwr</td> <td>Wr</td> </tr> <tr> <td>Random access buffer</td> <td>MRB</td> </tr> <tr> <td>Buffer memory</td> <td>SPB</td> </tr> </tbody> </table>	Host station device to monitor	Device type to specify	RX	X	RY	Y	SB	SM	SW	SD	RWw	Ww	Rwr	Wr	Random access buffer	MRB	Buffer memory	SPB
Host station device to monitor	Device type to specify																		
RX	X																		
RY	Y																		
SB	SM																		
SW	SD																		
RWw	Ww																		
Rwr	Wr																		
Random access buffer	MRB																		
Buffer memory	SPB																		
Device No.	Sets the head number of device to monitor. (HEX: Hexadecimal, DEC: Decimal, OCT : Octal)																		
Register Device List	Displays a list of the devices entered .																		
[Setting] button	Enters the data set in device type and device number, and adds them to register device list.																		
[Change] button	Selects the device to change, and click this button to change the entered data.																		
[Delete] button	Selects the device to be deleted, and click this button to delete from the register device list.																		

POINT

The only devices that may be monitored using the 16-point entry monitor are those that have random access capability. If a device that is not capable of random-access is specified, a device type error (-3) will occur. See Chapter 8, "ACCESSIBLE DEVICES AND RANGES," to determine whether or not a device has random-access capability.

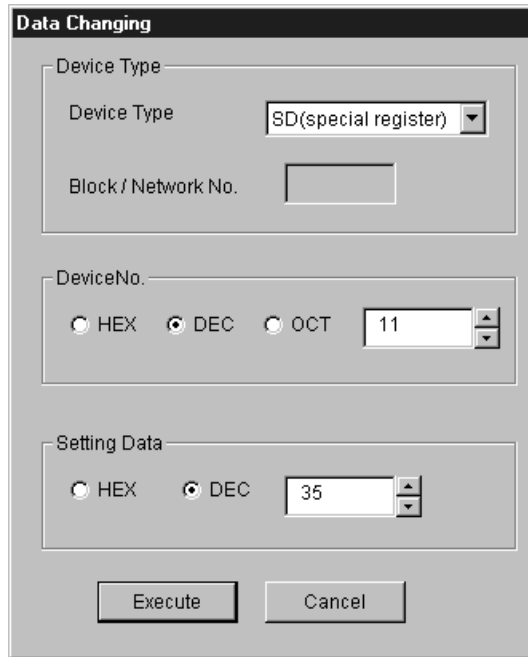
7.3.6 Changing word device values

Changes the specified word device data.

(1) Selecting the menu

Select [Device Write] – [Data Changing] from the menu bar.

(2) Dialog box



Item	Description
Device Type	Sets the device type, block number, and network number to change the data.
Device No.	Sets the device number to change the data. (HEX : Hexadecimal, DEC : Decimal, OCT : Octal)
Setting Data	Sets the data to be changed. (HEX : Hexadecimal, DEC : Decimal)



DANGER

- Configure the interlock circuit over the sequence program so that the entire system works safely at all times for data change control to the PLC in operation. Also, decide on corrective actions for an event of data communication error between the PC and PLC CPU in use.

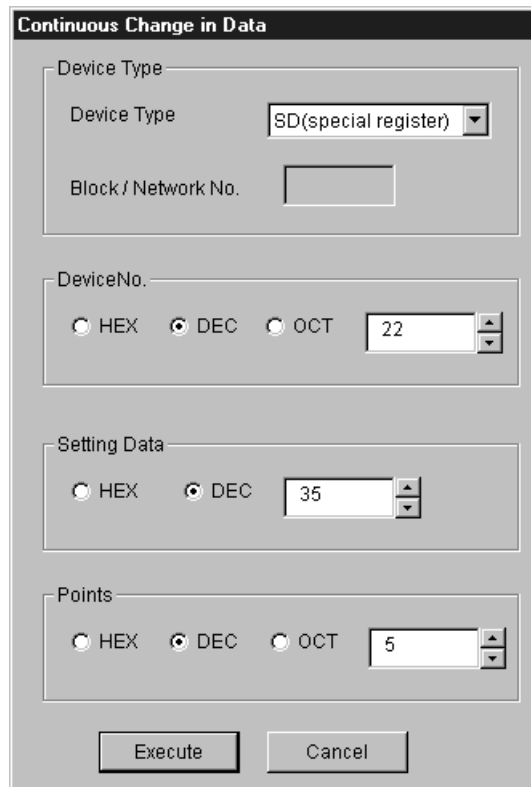
7.3.7 Changing word device values continuously

Change the specified word device data for the number of specified points being set.

(1) Selecting the menu

Select [Device Write] – [Continuous Change in Data] from the menu bar.

(2) Dialog box



Item	Description
Device Type	Sets the device type, block number, and network number to change the data.
Device No.	Sets the head address to change the data. (HEX : Hexadecimal, DEC : Decimal, OCT : Octal)
Setting Data	Sets the data to be continuously changed. (HEX : Hexadecimal, DEC : Decimal)
Points	Sets the number of points to perform continuous change of the data. (HEX : Hexadecimal, DEC : Decimal, OCT : Octal)



- Configure the interlock circuit over the sequence program so that the entire system works safely at all times for data change control to the PLC in operation. Also, decide on corrective actions for an event of data communication error between the PC and PLC CPU in use.

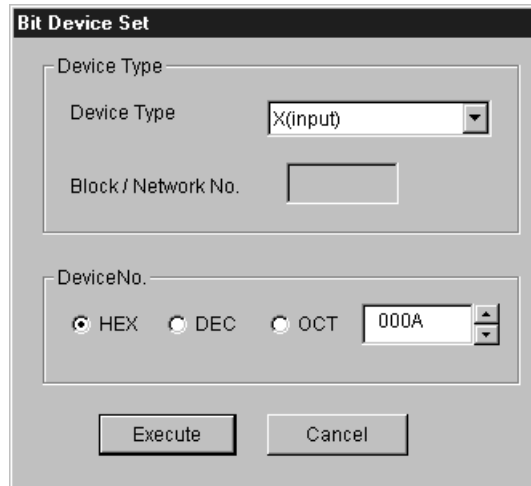
7.3.8 Tuning on/off a bit device

Turns on/off the specified bit device.

(1) Selecting the menu

Select [Device Write] – [Bit Device Setting (reset)] from the menu bar.

(2) Dialog box



Item	Description
Device Type	Sets the bit device type, block number, and network number to turn on/off.
Device No.	Sets the bit device number to turn on/off. (HEX : Hexadecimal, DEC : Decimal, OCT : Octal)

<p>DANGER</p>	<ul style="list-style-type: none"> Configure the interlock circuit over the sequence program so that the entire system works safely at all times for data change control to the PLC in operation. Also, decide on corrective actions for an event of data communication error between the PC and PLC CPU in use.
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7.3.9 Switching the display form

Switches the display form for device monitor to the selected display form. The batch monitoring and 16 point entry monitor have different sets of selectable menu.

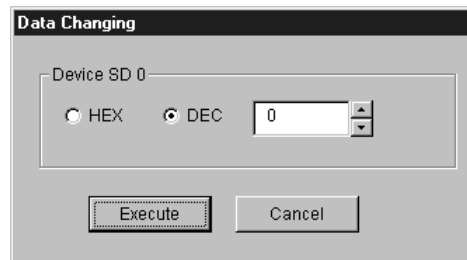
(1) Selecting the menu

Select [Display switch] – [Word (Bit) Device] from the menu bar.

7.3.10 About the Numerical Input pad

By choosing [Option]-[Numerical Pad] on the menu bar, you can use the numerical pad when setting the device value, etc.

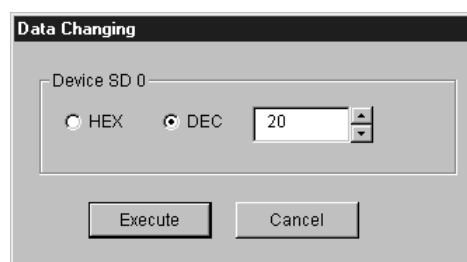
1. Click the numerical input column.



2. As the Numerical Pad appears, enter the value with the buttons. Then, click the **OK** button.



3. The value is entered.



7.3.11 Other operations

Changing data in word device and turning on/off a bit device can be performed by double-clicking the device number on the screen while monitoring.

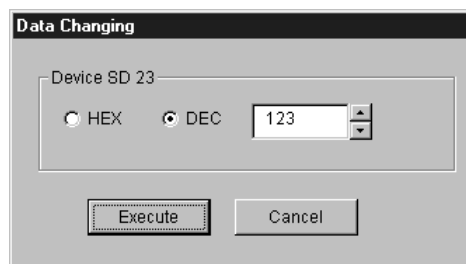
(1) Word device

The following shows the operation for changing a word device.
(Only when the display form is 16 bit.)

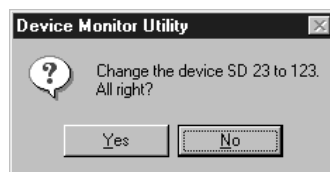
1. Double-click the number of the word device to be changed.

SD 20	0	SD 36
SD 21	0	SD 37
SD 22	0	SD 38
SD 23	0	SD 39
SD 24	0	SD 40
SD 25	0	SD 41
SD 26	0	SD 42

2. As the dialog box shown below is displayed, set any desirable value.
Then, click the **Execute** button.



3. Select **Yes** in the dialog box shown below if the change is acceptable. Select **No** to cancel it.



! DANGER

- Configure the interlock circuit over the sequence program so that the entire system works safely at all times for data change control to the PLC in operation. Also, decide on corrective actions for an event of data communication error between the PC and PLC CPU in use.

(2) Bit device

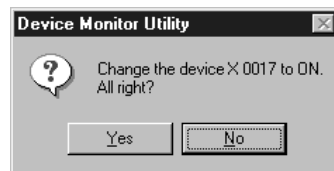
The following shows the operation for turning on/off a bit device.
However, this is operable only when the display form is "Portrait."

1. Double-click the number of the bit device to be changed.

X 0014	0	X 0024
X 0015	0	X 0025
X 0016	0	X 0026
X 0017	0	X 0027
X 0018	0	X 0028
X 0019	0	X 0029
X 001A	0	X 002A

2. Select in the dialog box shown below, if the change is acceptable.

Select to cancel it.



DANGER

- Configure the interlock circuit over the sequence program so that the entire system works safely at all times for data change control to the PLC in operation. Also, decide on corrective actions for an event of data communication error between the PC and PLC CPU in use.

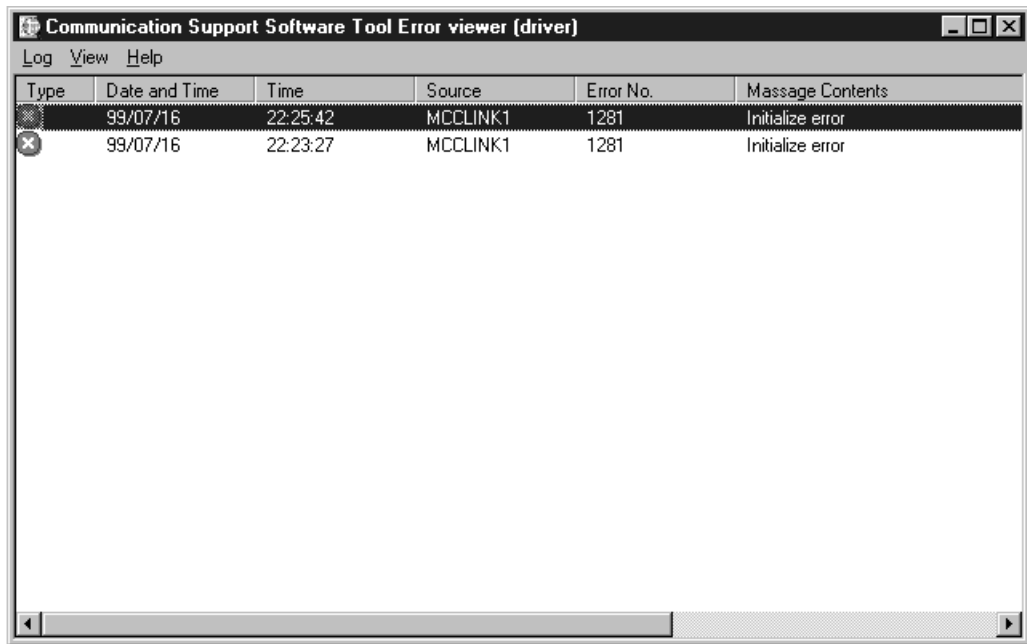
7.4 Error Viewer

This section explains how to operate or set the error viewer.

POINT
Error Viewer can be used only when the operating system (OS) is either Windows® 98 or Windows® 95.

7.4.1 Screen description

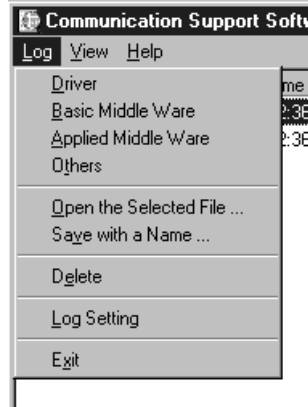
The following explains the error viewer screen.




Item	Description
Type	The error types are displayed by symbols shown below. i Normal message (Indicates comments that are generated from normal processing.) ! Warning message (Messages that are generated to elicit attention even though it is not an error.) x Error message (Displays the error contents that are generated from each module. For the lines with this symbol, double-click to see the detailed message contents, and remove the cause promptly.)
Date and Time	Displays the date an error occurred.
Time	Displays the time an error occurred.
Source	Displays the source of an error.
Error No.	Displays the number for an error.
Message Contents	Displays the content of an error.

7.4.2 Log menu

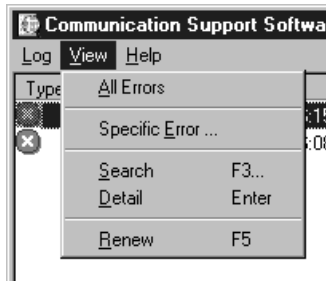
The following explains the contents of log menu.

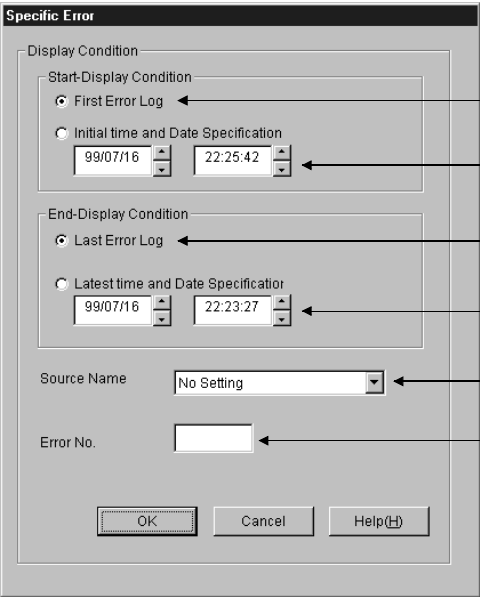
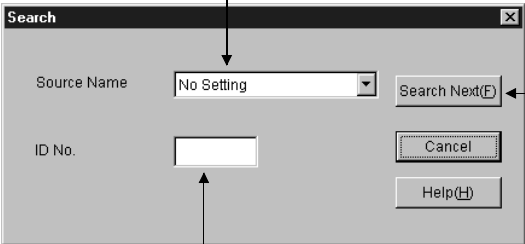


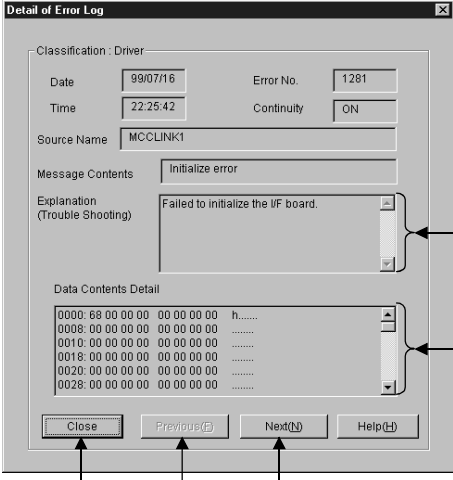
Item	Description
Selecting error-entry source type	Select the error-entry source type to be displayed in the error viewer. The currently selected items are checked. Driver ***** Displays the messages generated by drivers such as common memory device. Basic Middle Ware ***** Displays the messages generated by the common memory data server and tab control process. Applied Middle Ware ***** Displays the messages generated by MX Chart and MX Monitor. Others ***** Displays the messages generated by the application packages.
Open the Selected File	Open the error log file (*.ELF).
Save with a Name	Save the error log data of the error entry source (driver, etc. ...) currently being selected to the specified file.
Delete	Erase the error log data of the error entry source (driver, etc. ...) currently being displayed. Perform operations according to direction displayed on the dialog box.
Log Setting	Select processing method for which the number of error logs exceeds the number of maximum entry.  <div style="margin-left: 20px;"> <p>← Overwrite in history order.</p> <p>← Do not register information unless space is reserved by old information deletion.</p> </div>
Exit	End the error viewer.

7.4.3 View menu

The following explains the contents of display menu.



Item	Description
All Errors	Displays all the errors that occurred per type of error entry source.
Specific Error	<p>Sets the errors displayed on the screen according to the conditions in the dialog box shown below.</p>  <p>Start display from the first error log.</p> <p>Start error display from the specified date.</p> <p>Display log up the last error specified date.</p> <p>Display errors up to the specified date.</p> <p>Display only the errors of a specified source.</p> <p>Display only error with the specified error No.</p>
Search	<p>Search error information of the source name and error code from the error log data currently being displayed using the dialog box shown below. (pressing the F3 key will display the same.)</p> <p>Set a source file name find.</p>  <p>Find the next error information</p> <p>Input an error code to find.</p>

Item	Description
<p>Detail</p>	<p>Displays detailed information on the error log currently being selected. (pressing the Enter key after selecting a display item will display the same.)</p>  <p>Display the details of the error. No details are given according to the type of the source.</p> <p>Displays when the contents of a driver or buffer memory are referenced. No data may be displayed according to the type of the source.</p> <p>Displays the details of the next error log information.</p> <p>Display the details of next error log information.</p> <p>Close this dialogue box.</p>
<p>Renew</p>	<p>Updates the data currently being displayed.</p>

8 ACCESSIBLE DEVICES AND RANGES

This chapter describes the devices and ranges that can be accessed during CC-Link communication.

8.1 Accessible Devices

The following lists the devices that can be accessed during CC-Link communication.

POINT
The "Batch" in the following table indicates Batch Read and Batch Write. The "Random" in the table indicates Random Read, Random Write, Bit Set, or Bit Reset.

8.1.1 Host (personal computer (local station equivalent))

Device		Accessible/not accessible
X (RX)	Batch	○
	Random	
Y (RY)	Batch	○
	Random	
SB	Batch	○
	Random	
SW	Batch	○
	Random	
Ww (RWw)	Batch	○
	Random	
Wr (RWr)	Batch	○
	Random	
SPB (Host buffer memory)	Batch	○
	Random	
MRB (Host random access buffer)	Batch	○
	Random	

8.1.2 Other station

Device		Access destination							IBM PC/AT compatible PC
		A1N	A0J2H A1S(-S1) A1SH A1SJ(-S3) A1SJH(-S8) A2C(J) A2N(-S1) A2S(-S1) A2SH(-S1)	A2A(-S1) A2U(-S1) A2AS(-S1/-S30) A2USH-S1 Q02(H)-A Q06H-A	A3N A3A A3U	A4U	Q2A(-S1) Q3A Q4A Q4AR Q2AS(-S1) Q2ASH(-S1)	Q00J Q00 Q01 Q02(H) Q06H Q12H Q25H Q12PH Q25PH Q12PRH Q25PRH	
X	Batch	○	○	○	○	○	○	○	×
	Random	○	○	○	○	○	○	○	×
Y	Batch	○	○	○	○	○	○	○	×
	Random	○	○	○	○	○	○	○	×
L	Batch	○	○	○	○	○	○	○	×
	Random	○	○	○	○	○	○	○	×
M	Batch	○	○	○	○	○	○	○	×
	Random	○	○	○	○	○	○	○	×
Special M (SM), SB	Batch	○	○	○	○	○	○	○	×
	Random	○	○	○	○	○	○	○	×
F	Batch	○	○	○	○	○	○	○	×
	Random	○	○	○	○	○	○	○	×
T (contact)	Batch	○	○	○	○	○	○	○	×
	Random	○	○	○	○	○	○	○	×
T (coil)	Batch	○	○	○	○	○	○	○	×
	Random	○	○	○	○	○	○	○	×
C (contact)	Batch	○	○	○	○	○	○	○	×
	Random	○	○	○	○	○	○	○	×
C (coil)	Batch	○	○	○	○	○	○	○	×
	Random	○	○	○	○	○	○	○	×
T (present value)	Batch	○	○	○	○	○	○	○	×
	Random	○	○	○	○	○	○	○	×
C (present value)	Batch	○	○	○	○	○	○	○	×
	Random	○	○	○	○	○	○	○	×
D	Batch	○	○	○	○	○	○	○	×
	Random	○	○	○	○	○	○	○	×
Special D (SD), SW	Batch	○	○	○	○	○	○	○	×
	Random	○	○	○	○	○	○	○	×
T (set value main)	Batch	○	○	○	○	○	○	○	×
	Random	×	×	×	×	×	×	×	×
T (set value sub 1)	Batch	×	×	○ *1	○	○	○	○	×
	Random	×	×	×	×	×	×	×	×
T (set value sub 2)	Batch	×	×	×	×	○	○	○	×
	Random	×	×	×	×	×	×	×	×
T (set value sub 3)	Batch	×	×	×	×	○	○	○	×
	Random	×	×	×	×	×	×	×	×

*1 : A2ACPU(-S1) cannot be accessed.

Device		Access destination							
		A1N	A0J2H A1S(-S1) A1SH A1SJ(-S3) A1SJH(-S8) A2C(J) A2N(-S1) A2S(-S1) A2SH(-S1)	A2A(-S1) A2U(-S1) A2AS(-S1/-S30) A2USH-S1 Q02(H)-A Q06H-A	A3N A3A A3U	A4U	Q2A(-S1) Q3A Q4A Q4AR Q2AS(-S1) Q2ASH(-S1)	Q00J Q00 Q01 Q02(H) Q06H Q12H Q25H Q12PH Q25PH Q12PRH Q25PRH	IBM PC/AT compatible PC
C (set value main)	Batch	○	○	○	○	○	×	×	
	Random	×	×	×	×	×			
C (set value sub 1)	Batch	×	×	○* ¹	○	○	×	×	
	Random			×	×	×			
C (set value sub 2)	Batch	×	×	×	×	○	×	×	
	Random					×			
C (set value sub 3)	Batch	×	×	×	×	○	×	×	
	Random					×			
A	Batch	○	○	○	○	○	×	×	
	Random								
Z	Batch	○	○	○	○	○	○	×	
	Random								
V (index register)	Batch	○	○	○	○	○	×	×	
	Random								
R (file register)	Batch	×	○	○	○	○	○* ²	×	
	Random								
ER (extended file register)	Batch	×	○	○	○	○	○* ²	×	
	Random								
B	Batch	○	○	○	○	○	○	×	
	Random								
W	Batch	○	○	○	○	○	○	×	
	Random								
Q/QnA link special relay (within Q/QnA CPU)	Batch	×	×	×	×	×	○	×	
	Random								
Retentive timer (contact)	Batch	×	×	×	×	×	○	×	
	Random						×		
Retentive timer (coil)	Batch	×	×	×	×	×	○	×	
	Random						×		
Q/QnA link special register (within Q/QnA CPU)	Batch	×	×	×	×	×	○	×	
	Random								
Q/QnA edge relay (within Q/QnA CPU)	Batch	×	×	×	×	×	○	×	
	Random								
Host random-access buffer	Batch	×	×	×	×	×	×	×	
	Random								
Retentive timer (present value)	Batch	×	×	×	×	×	○	×	
	Random								
Host link register (for transmission)	Batch	×	×	×	×	×	×	×	
	Random								
Host link register (for reception)	Batch	×	×	×	×	×	×	×	
	Random								
Q/QnA SEND function (Arrival acknowledgment)	Batch	×	×	×	×	×	×	×	
	Random								

*1 : A2ACPU(-S1) cannot be accessed.

*2 : No access is allowed in the case of the Q00JCPU.

Device		Access destination							
		A1N	A0J2H A1S(-S1) A1SH A1SJ(-S3) A1SJH(-S8) A2C(J) A2N(-S1) A2S(-S1) A2SH(-S1)	A2A(-S1) A2U(-S1) A2AS(-S1/-S30) A2USH-S1 Q02(H)-A Q06H-A	A3N A3A A3U	A4U	Q2A(-S1) Q3A Q4A Q4AR Q2AS(-S1) Q2ASH(-S1)	Q00J Q00 Q01 Q02(H) Q06H Q12H Q25H Q12PH Q25PH Q12PRH Q25PRH	IBM PC/AT compatible PC
Q/QnA SEND function (Arrival acknowledgment)	Batch	×	×	×	×	×	×	×	
	Random	×	×	×	×	×	×	×	
Direct link input	Batch	×	×	×	×	×	○	×	
	Random	×	×	×	×	×	○	×	
Direct link output	Batch	×	×	×	×	×	○	×	
	Random	×	×	×	×	×	○	×	
Direct link relay	Batch	×	×	×	×	×	○	×	
	Random	×	×	×	×	×	○	×	
Direct link register	Batch	×	×	×	×	×	○	×	
	Random	×	×	×	×	×	○	×	
Direct link special relay (network module side)	Batch	×	×	×	×	×	○	×	
	Random	×	×	×	×	×	○	×	
Direct link special register (network module side)	Batch	×	×	×	×	×	○	×	
	Random	×	×	×	×	×	○	×	
Special direct buffer register	Batch	×	×	×	×	×	○	×	
	Random	×	×	×	×	×	×	×	
Other station buffer memory * ³	Batch	○	○	○	○	○	○	○	
	Random	×	×	×	×	×	×	×	
Other station random access buffer * ³	Batch	○	○	○	○	○	○	○	
	Random	×	×	×	×	×	×	×	
Other station RX * ³	Batch	○	○	○	○	○	○	○	
	Random	×	×	×	×	×	×	×	
Other station RY * ³	Batch	○	○	○	○	○	○	○	
	Random	×	×	×	×	×	×	×	
Other station link register * ³	Batch	○	○	○	○	○	○	○	
	Random	×	×	×	×	×	×	×	
Other station SB * ³	Batch	○	○	○	○	○	○	○	
	Random	×	×	×	×	×	×	×	
Other station SW * ³	Batch	○	○	○	○	○	○	○	
	Random	×	×	×	×	×	×	×	

*3 : Access to the CC-Link (intelligent device station) module buffer memory installed into each CPU.

8.2 Accessible Range

The range of access during CC-Link communication includes only the module master station, local station PLC and the intelligent device station for the CC-Link connected by the CC-Link board, and PC with CC-Link board installed.

9 MELSEC DATA LINK LIBRARY

This chapter describes the functional overview of the functions included in the library.

REMARK

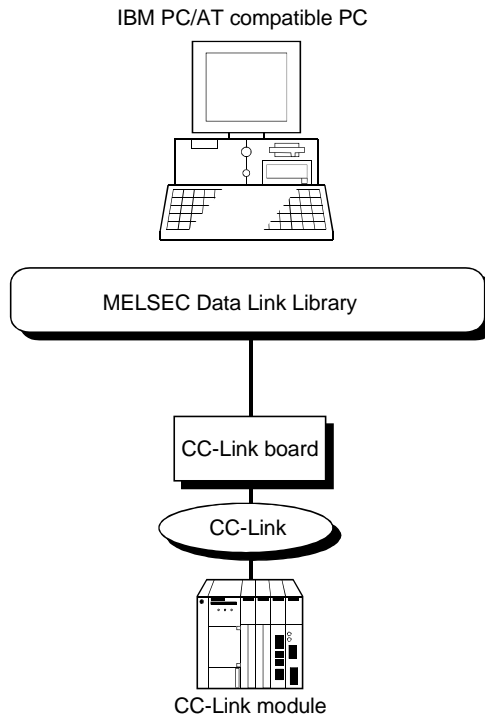
The screens of the Microsoft® Windows® 95 Operating System are used in this section.

Please note that these screens are slightly different from other Operating systems.

9.1 Overview of the MELSEC Data Link Library

These functions are used when creating a user program that communicates with a PLC CPU. With the functions, the user can perform communication without being conscious of the hardware type on the opposite side or the communication protocol.

The user can easily communicate with a designated PLC without worrying about the communication protocol.



9.2 Function List

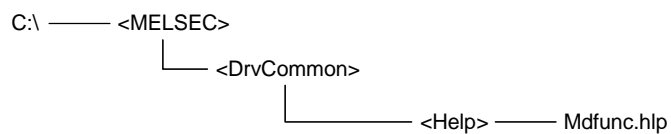
The following table lists the functions comprising the MELSEC data link library that is provided with the software package.

Function name	Description
mdOpen	Opens a communication line.
mdClose	Closes a communication line.
mdSend	Performs batch write of devices.
mdReceive	Performs batch read of devices.
mdRandW	Writes devices randomly.
mdRandR	Reads devices randomly.
mdDevSet	Sets a bit device.
mdDevRst	Resets a bit device.
mdTypeRead	Reads the type of PLC CPU.
mdControl	Remote RUN/STOP/PAUSE
mdInit	Refreshes the PLC device address.
mdBdRst	Resets the board itself.
mdBdModSet	Sets the board itself.
mdBdModRead	Reads the board itself.
mdBdLedRead	Reads the LED information of the board itself.
mdBdSwRead	Reads the switch status of the board itself.
mdBdVerRead	Reads the version information of the board itself.

POINT

For details of the functions, see HELP on MELSEC data link functions provided in the software package.

The HELP on MELSEC data link functions can be found in the following directory.



9.3 Settings for Using Functions

This section describes the setting operation in order to use functions.

POINT
<p>If Windows® 2000 Professional or Windows® XP Professional is used, Microsoft® Visual Basic® 5.0 and Microsoft® Visual C++® 5.0 cannot be used. Please use Microsoft® Visual Basic® 6.0 and Microsoft® Visual C++® 6.0.</p>

9.3.1 When using Visual Basic® 5.0 and Visual Basic® 6.0

The following describes the setting operation when using Visual Basic® 5.0 and Visual Basic® 6.0.

1. Start Visual Basic® 5.0 or Visual Basic® 6.0 and select [Project] - [Add standard module] menu.
2. Select the "Existing files" tab and select "MDFUNC.BAS. "
"MDFUNC.BAS" has been saved in the following directory during installation:
<User-specified folder>-<COMMON>-<INCLUDE>

9.3.2 When using Visual C++® 5.0 and Visual C++® 6.0

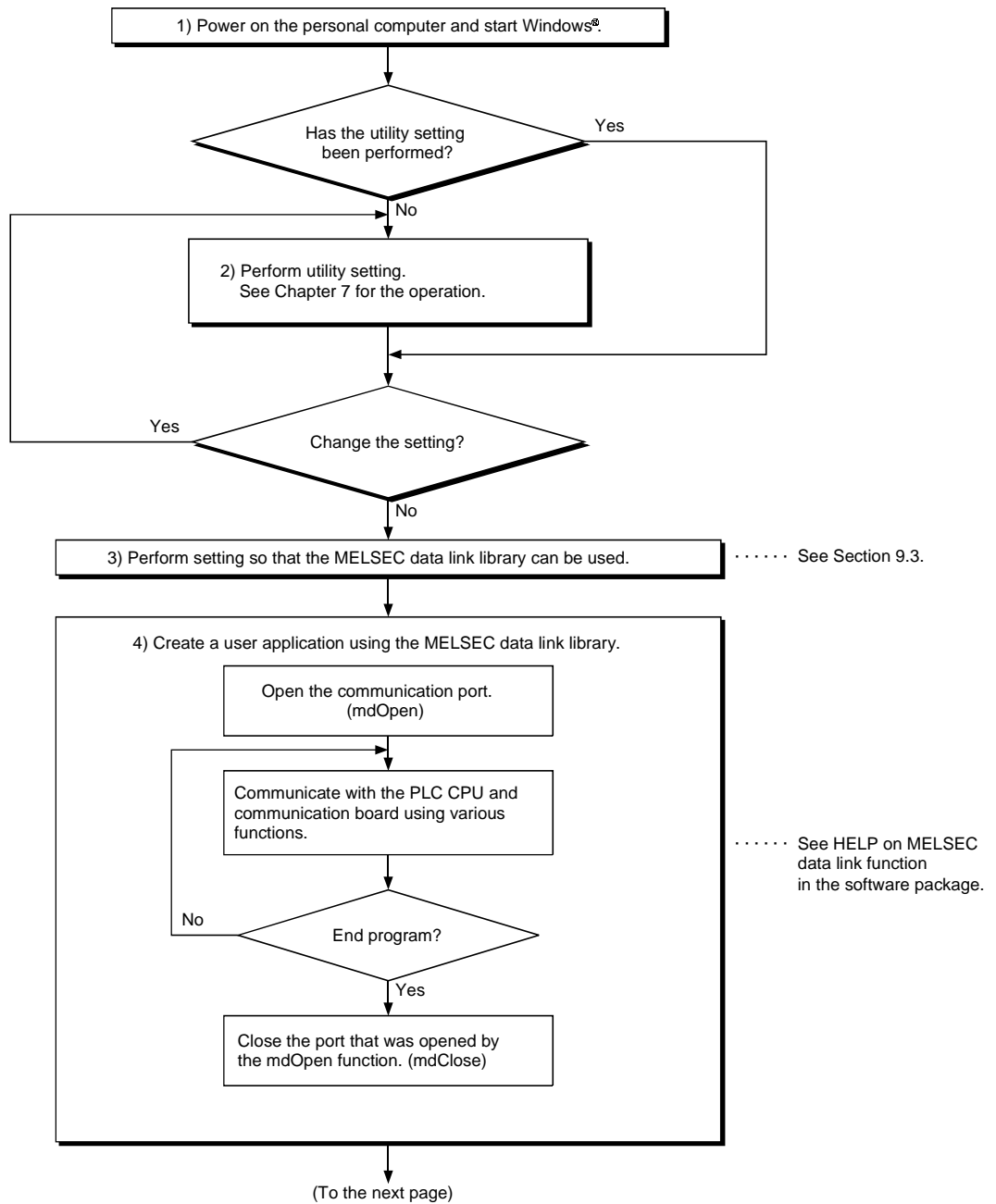
The following describes the setting operation when using Visual C++® 5.0 and Visual C++® 6.0.

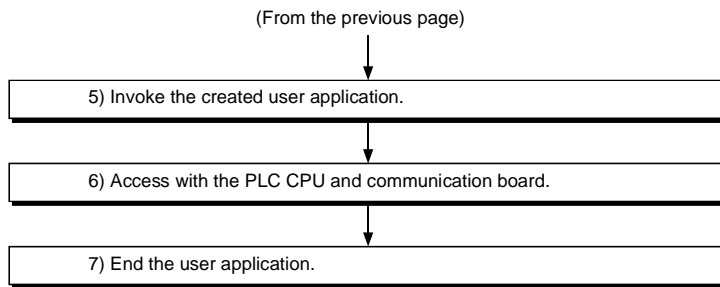
- (1) When setting an include file
 1. Start Visual C++® 5.0 or Visual C++® 6.0 and select [Tool]-[Option] menu.
 2. Select the "Directory" tab and set the directory type to "Include files. "
 3. Double-click the item to be set and reference the folder containing the include file.
MDFUN.H has been save in the following directory during installation:
<User-specified folder>-<COMMON>-<INCLUDE>
 4. Add "#include<mdfunc.h>" at the beginning of your program.
- (2) When setting a library file
 1. Start Visual C++® 5.0 or Visual C++® 6.0 and select [Tool]-[Option] menu.
 2. Select the "Directory" tab, set "Directory to be displayed" to "Library file," and reference the folder containing the library file, as in step (1) above.
"MDFUNC32.LIB" is stored in
<User-specified folder>-<COMMON>-<LIB>
during installation.
 3. Open the workspace to create and select [Project]-[Set] menu.
 4. Select the "Link" tab, set "General" as the category, then type "mdfunc32.lib" in the object/library module field.

9.4 Procedure for Programming

The following describes the procedure for programming using the MELSEC data link library.

In this section, it is assumed that the software package has already been installed.





POINT	
(1)	Perform the processing for opening and closing a communication line (mdOpen/mdClose) only once at the beginning and end of a program. Repeatedly opening and closing a communication line for each transaction will degrade the communication performance.
(2)	It is necessary to perform only steps 5) to 7) above to access the PLC CPU and communication board again using an application program that has already been created by the user.
(3)	The functions get detailed PLC information at the initial execution when the corresponding devices are added. Therefore, the initial function execution time gets longer than usual.
(4)	When accessing multiple remote stations simultaneously from the same PC using the CC-Link utility, Device Monitor utility, user application program or Mitsubishi's software package (such as MX Links), limit the number of stations to be accessed to eight or less. If nine or more remote stations are accessed simultaneously, communication performance may deteriorate.
(5)	When creating a user application program for debugging using Visual C++ [®] 6.0, do not define the buffer to be used by mdReceive in static.

9.5 Channel

The following is the channel used by the MELSEC data link library:

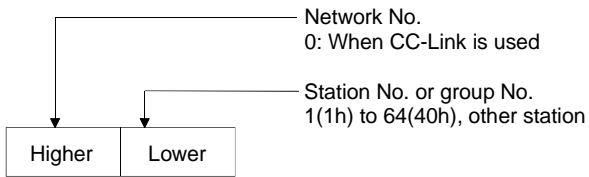
Number	Channel name	Description
81 to 84	CC-Link (1st board to 4th board)	This is used when communication via the CC-Link board. This is set using the BD No. DIP switch on the back of the CC-Link board. The following will be set using the SW1 and SW2 settings. 81: OFF, OFF 82: ON, OFF 83: OFF, ON 84: ON, ON

9.6 Station Number Settings

The following lists the station numbers specified via functions.

Communication	Station number specification
CC-Link	Host: 255 (0xFF) Other station: * ¹ , * ²

*1 :



<How to specify the logical station number>
Set "0" to the upper byte (network No.) of the station number described above, then specify the logical station number to the lower byte (station number).
The range of the logical station number specification is from 65(41H) to 239(EFH).

*2 : It is impossible to specify the station number 64 on the CC-Link communication except for the buffer memory access.

9.7 Device Types

Either code number or device name can be specified for functions as the device type.

(1) Only when via CC-Link board

The following table shows the CC-Link dedicated device type when accessing to the device via CC-Link board.

Device type		Device name specification	Device
Code specification			
Decimal	Hexadecimal		
1	1H	Dev X	Host RX
2	2H	Dev Y	Host RY
5	5H	Dev SM	Host SB (link special B for CC-Link)
14	EH	Dev SD	Host SW (link special W for CC-Link)
33	21H	Dev MRB	Host random access buffer
36	24H	Dev Ww	Host link register (for transmitting)
37	25H	Dev Wr	Host link register (for receiving)
50	32H	Dev SPB	Host buffer memory
32768	8000H	Dev RBM	Other buffer memory * ¹
32800	8020H	Dev RAB	Other random access buffer * ¹
32801	8021H	Dev RX	Other RX * ¹
32802	8022H	Dev RY	Other RY * ¹
32804	8024H	Dev RW	Other link register * ¹
32867	8063H	Dev SB	Other SB (link special; B for CC-Link) * ¹
32868	8064H	Dev SW	Other SW (link special; W for CC-Link) * ¹

*1 : Cannot use with mdRandR, mdRandW, mdDevSet and mdDevRst functions.

POINT

To access a random access buffer, a different device type must be specified depending on the random access buffer setting.

Specify a device type shown in the following table, specify an address to the device No., then access the buffer.

Setting	Device type used	Accessible range
Default setting	DevMRB	A00H to FFFH
Extension setting	DevMRB	A00H to FFFH
	DevSPB	A00H to 2FFFH

(2) Common

The following table shows the common device type for all communication course.

Device type		Device name specification	Device
Code specification			
Decimal	Hexadecimal		
1	1 _H	DevX	X
2	2 _H	DevY	Y
3	3 _H	DevL	L
4	4 _H	DevM	M
5	5 _H	DevSM	Special M (SM), SB (link special B for MELSECNET/10, MELSECNET/H and CC-Link)
6	6 _H	DevF	F
7	7 _H	DevTT	T (contact)
8	8 _H	DevTC	T (coil)
9	9 _H	DevCT	C (contact)
10	A _H	DevCC	C (coil)
11	B _H	DevTN	T (present value)
12	C _H	DevCN	C (present value)
13	D _H	DevD	D
14	E _H	DevSD	Special D (SD), SW (link special W for MELSECNET/10, MELSECNET/H and CC-Link)
15	F _H	DevTM	T (set value main)
16	10 _H	DevTS	T (set value sub 1)
16002	3E82 _H	DevTS2	T (set value sub 2)
16003	3E83 _H	DevTS3	T (set value sub 3)
17	11 _H	DevCM	C (set value main)
18	12 _H	DevCS	C (set value sub 1)
18002	4652 _H	DevCS2	C (set value sub 2)
18003	4653 _H	DevCS3	C (set value sub 3)
19	13 _H	DevA	A
20	14 _H	DevZ	Z
21	15 _H	DevV	V (index register)
22	16 _H	DevR	R (file register)
22000 to 22256	55F0 _H to 56F0 _H	DevER0 to DevER256	ER (extension file register)
23	17 _H	DevB	B
24	18 _H	DevW	W
25	19 _H	DevQSB	Q/QnA link special relay (within the Q/QnA CPU)
26	1A _H	DevSTT	Retentive timer (contact)
27	1B _H	DevSTC	Retentive timer (coil)
28	1C _H	DevQSW	Q/QnA link special register (within the Q/QnA CPU)
30	1E _H	DevQV	Q/QnA edge relay (within the Q/QnA CPU)

Device type		Device name specification	Device
Code specification			
Decimal	Hexadecimal		
33	21 _H	DevMRB	Host random access buffer * ¹
35	23 _H	DevSTN	Retentive timer (present value)
36	24 _H	DevWw	Host link register (for transmitting) * ¹
37	25 _H	DevWr	Host link register (for receiving) * ¹
40	28 _H	DevFS	FXCPU S-device
50	32 _H	DevSPB	Host buffer memory * ¹
101	65 _H	DevMAIL	Q/QnA SEND/RECV function (Arrival acknowledgment)
102	66 _H	DevMAILNC	Q/ QnA SEND/RECV function (No arrival acknowledgment)
1001 to 1255	3E9 _H to 4E7 _H	DevLX1 to DevLX255	Direct link input
2001 to 2255	7D1 _H to 8CF _H	DevLY1 to DevLY255	Direct link output
23001 to 23255	59D9 _H to 5AD7 _H	DevLB1 to DevLB255	Direct link relay
24001 to 24255	5DC1 _H to 5EBF _H	DevLW1 to DevLW255	Direct link register
25001 to 25255	61A9 _H to 62A7 _H	DevLSB1 to DevLSB255	Direct link special relay (network module side)
28001 to 28255	6D61 _H to 6E5F _H	DevLSW1 to DevLSW255	Direct link special register (network module side)
29000 to 29255	7148 _H to 7247 _H	DevSPGO to DevSPG255	Special direct buffer register
31000 to 31255	7918 _H to 7A17 _H	DevEMO to DevEM255	EM (shared device) * ²
32000 to 32255	7D00 _H to 7DFF _H	DevEDO to DevED255	ED (shared device) * ²

*1 : Dedicated device for accessing the buffer memory for the CC-Link board (host).

*2 : Access is allowed only to a remote station's PC (only if the communication destination is running MX Links (SW2D5F-CSKP-E or later) on Windows NT[®] Workstation 4.0).

9.8 Sample Programs

When SW4DNF-CCLINK-B is installed in a PC, sample programs are registered in <User-specified folder>-<Cclink>-<Sample>.

Sample programs are provided as a reference for creating user application programs. The user is solely responsible for the use of the sample programs provided.

(1) MasterStation folder

Sample programs for the A80BD-J61BT11 (cannot be used for the A80BD-J61BT13.)

(2) MDFunction folder

(a) Vb folder (for Visual Basic®)

1) Demo folder

Contains a sample program for reading D0.

2) Mtest folder

Contains a sample program for the MELSEC data link library (mdOpen, mdClose, mdSend, mdReceive).

(b) Vc folder (for Visual C++®)

1) Mtest folder

File name	Description
Mtest1.c	Sample program of the general MELSEC data link library
Netsmp1.c	Sample program to read device D of station number 0

10 ERROR CODE

An error code is returned as the return value when a function is executed.

The error definition and corrective action that correspond to each error code are described.

Return value (HEX)	Error definition	Corrective action
0	Normal completion	
1	Driver not started The driver has not been started. The interrupt number/I/O address are overlapping with other board.	Correct the error occurred during driver startup. Check the board setting.
2	Board response error Time out has occurred while waiting for a response to the corrective action.	Check the operation status of the access station(s) and loading condition of the board(s). Retry in an application program.
65 (41H)	Channel error An unregistered channel number was specified.	Check the channel number.
66 (42H)	OPEN error The specified channel has already been opened.	Open only once.
67 (43H)	CLOSE error The specified channel has already been closed.	Close only once.
68 (44H)	PATH error A path other than the opened line was set.	Specify the station with an open path.
69 (45H)	Processing code error An unsupported processing code was issued.	Use the supported processing code.
70 (46H)	Station specification error The specified station is incorrect. A process that should have been requested to other station was requested to the host. Or, the station number corresponds to the host (0xFF) but the network number is not 0.	Correct the specification of the station number in the application program.
71 (47H)	Reception data error (during RECV request) Data has not been received.	Wait until data is received.
72 (48H)	Waiting for mode setting Mode setting has not been performed.	Perform mode setting.
73 (49H)	Mode error Processing was requested to other station when the mode setting was not online.	Set the mode to online. Or, cancel the request.
	Interrupt number error The interrupt number is overlapping with other board.	Check the board setting.
	I/O address error The I/O address is overlapping with other board.	
77 (4DH)	Memory error Enough memory could not be secured.	Terminate other application(s) currently running. Check if the system is operating normally. Reboot the system. Increase the minimum working set area of the PC. *1
78 (4EH)	Time out error during mode setting Mode setting was attempted but failed due to time out.	Restart after checking that the dual-port memory is not overlapping with other board. Hardware fault.
79 (4FH)	S/W setting data error Incorrect data was found in the argument parameter when setting S/W.	Check the argument parameter of S/W setting data.
80 (50H)	Unsuccessful mapping of common memory address.	Check if the common address is overlapping with other I/F board.
81 (51H)	Channel response error at source (When a SEND request is issued) Received an abnormal response to the SEND request.	Retry. Check if the system is operating normally. Reboot the system.
85 (55H)	Channel number error (during RECV request) A channel number error.	Check the channel number used during the RECV request.
100 (64H)	Accessing host board An access request was issued to the host board while the host board is being accessed.	Retry.
101 (65H)	Routing parameter error The routing parameter is not set.	Correct the routing parameter.
102 (66H)	Data transmission error Data transmission has failed.	Retry. Check if the system is operating normally. Reboot the system.

Return value (HEX)	Error definition	Corrective action
103 (67 _H)	Data receiving error Data receiving has failed.	Retry. Check if the system is operating normally. Reboot the system.
129 (81 _H)	Device type error The specified device type is invalid.	Check the device type.
130 (82 _H)	Device number error The specified device number is out of range. When specifying the bit device, the device number is not a multiple of 8.	Check the device number.
131 (83 _H)	Device points error The specified number of points is out of device range. When specifying the bit device, the device number is not a multiple of 8.	Check the size.
132 (84 _H)	Number of bytes written error The specified number of bytes written is out of range.	Set a number of bytes written that is within the range.
133 (85 _H)	Link parameter error The link parameter is corrupt. The total number of slave station is 0.	Reset the link parameter.
136 (88 _H)	Random write specification error A value other than 0 through 2 was specified for random write.	Set a new value between 0 and 2.
215 (D7 _H)	Reception data length error The length of reception data or byte length is out of range.	Retry. Check the cable.
	Request data buffer length over The length of request data is out of request data area.	Reduce the request data size.
216 (D8 _H)	Protocol error The communication procedure is abnormal. The requested code does not exist.	Check the cable.
217 (D9 _H)	Address error The address is out of access range.	Check the request data.
219 (DB _H)	Write error Unable to write.	
224 (E0 _H)	PC number error The destination station does not exist.	Correct the station number.
225 (E1 _H)	Processing mode error A processing code that cannot be processed by the destination ACPU was set. (It is checked by the destination ACPU.)	Check the destination ACPU and processing code.
226 (E2 _H)	Special module specification error The specified special module is not a module that can be processed.	Correct the Y number.
227 (E3 _H)	Other data error Incorrect data was found in the address, head step or shift value of the request data.	Correct the request data.
228 (E4 _H)	Link specification error A processing code that cannot be processed by the destination station was set. (It is checked by the destination link module.)	Check the destination station number and processing code.
232 (E8 _H)	Remote error The keyword did not match for the remote RUN/STOP/PAUSE request. Check the destination station number and processing code.	Check the destination station number and processing code.
233 (E9 _H)	Link time over The destination disconnected the link while processing.	Check the hardware of the special module.
234 (EA _H)	Special module BUSY Either the receive buffer is full at the destination due to transmission of general data, or preparation for receiving data has not been completed.	
236 (EC _H)	Destination BUSY Either the receive buffer is full at the destination due to transmission of general data, or preparation for receiving data has not been completed.	Execute the request when the destination can receive data.
240 (F0 _H)	Link error A request was issued to a disconnected link station.	Return the link.
241 (F1 _H)	Special module bus error Processing preparation has not been completed for the specified special module.	Check the hardware of the special module.

Return value (HEX)	Error definition	Corrective action
242 (F2 _H)	Special module time over No response from the specified special module.	Check the hardware of the special module.
	No response from the MELSECNET (II) board.	Check the hardware of the MELSECNET (II) board.
1280 (500 _H)	Host board memory access error	Check the switch setting on the host board and move the memory address to the area that is not effected by other board. Change the memory access setting to 16 bit if it is set to 8 bit.
1281 (501 _H)	Unable to access I/O port	Check the I/O port address setting. Perform a board self-loopback test and check the hardware.
4110 (100E _H)	DLL non-load error	Exit the program and restart the PC. Setup the package again. Consult with the dealer regarding the problem.
8204 (200C _H)	Request cancel	
8205 (200D _H)	Drive name error	
8206 (200E _H)	First step error	
8207 (200F _H)	Parameter type error	
8208 (2010 _H)	File name error	
8209 (2011 _H)	Registering/release/set status error	
8210 (2012 _H)	Detailed condition division error	
8211 (2013 _H)	Step condition error	
8212 (2014 _H)	Bit device condition error	
8213 (2015 _H)	Parameter setting error	
8215 (2017 _H)	Keyword error	
8216 (2018 _H)	Read/write flag error	
8217 (2019 _H)	Refresh method error	
8218 (201A _H)	Buffer access method error	
8219 (201B _H)	Start mode/stop mode error	
8220 (201C _H)	Written clock data error	
8221 (201D _H)	Online data write error	
8223 (201F _H)	Trace time error	
8224 (2020 _H)	First I/O number error	
8225 (2021 _H)	First address error	
8226 (2022 _H)	Pattern error	
8227 (2023 _H)	SFC block number error	
8228 (2024 _H)	SFC step number error	
8229 (2025 _H)	Step number error	

Return value (HEX)	Error definition	Corrective action
8230 (2026 _H)	Data error	Exit the program and restart the PC. Setup the package again. Consult with the dealer regarding the problem.
8231 (2027 _H)	System data error	
8232 (2028 _H)	TC set value number error	
8233 (2029 _H)	Clear mode error	
8234 (202A _H)	Signal flow error	
8235 (202B _H)	Version administration error	
8236 (202C _H)	Module has been registered	
8237 (202D _H)	PI type error	
8238 (202E _H)	PI No error	
8239 (202F _H)	PI number error	
8240 (2030 _H)	Shift error	
8241 (2031 _H)	File type error	
8242 (2032 _H)	Specified module error	
8243 (2033 _H)	Error check flag error	
8244 (2034 _H)	Step RUN-operation error	
8245 (2035 _H)	Step RUN data error	
8246 (2036 _H)	Step RUN-time error	
8247 (2037 _H)	Program RUN inside writing error to E ² ROM	
8248 (2038 _H)	Clock data read/write error	
8249 (2039 _H)	Trace non-completion	
8250 (203A _H)	Registration clearness flag error	
8251 (203B _H)	Operation error	
8252 (203C _H)	The number of station error	
8253 (203D _H)	The number of repeat error	
8254 (203E _H)	The acquisition data selection error	
8255 (203F _H)	The number of SFC cycle error	
8258 (2042 _H)	The scheduled time setting error	
8259 (2043 _H)	Function count error	
8260 (2044 _H)	System information error	
8262 (2046 _H)	Function number error	
8263 (2047 _H)	RAM operation error	

Return value (HEX)	Error definition	Corrective action
8264 (2048 _H)	Boot former ROM forwarding failure	Exit the program and restart the PC. Setup the package again. Consult with the dealer regarding the problem.
8265 (2049 _H)	Boot former transfer mode specification error	
8266 (204A _H)	Not enough memory	
8267 (204B _H)	Backup drive (former boot drive) ROM error	
8268 (204C _H)	Block size error	
8269 (204D _H)	RUN-time detaching error	
8270 (204E _H)	Module has already registered	
8271 (204F _H)	Password registration data full error	
8272 (2050 _H)	Password unregistration error	
8273 (2051 _H)	Remote password error	
8274 (2052 _H)	IP address error	
8275 (2053 _H)	Error (argument when requesting) outside time-out value range	
8276 (2054 _H)	Instruction cast undetection	
8277 (2055 _H)	Trace execution type error	
8278 (2056 _H)	Version error	
16384 to 20479 (4000 _H to 4FFF _H)	Errors detected by the access target CPU.	Refer to the user's manual of the access target CPU module.
16386 (4002 _H)	A request that cannot be processed was received.	Change the request destination.
16432 (4030 _H)	The specified device type does not exist.	Check the specified device type.
16433 (4031 _H)	The specified device number is out of range	Check the specified device number.
16448 (4040 _H)	The module does not exist.	Do not issue a request that generated an error to the specified special module.
16449 (4041 _H)	The number of device points is out of range.	Check the head address and number of access points and access within the existing range.
16450 (4042 _H)	Corresponding module error	Check if the specified module is operating normally
16451 (4043 _H)	The module does not exist at the specified location.	Check the head I/O number of the specified module.
28672 to 32767 (7000 _H to 7FFF _H)	Errors detected by intelligent function modules such as the serial communication module.	Refer to the user's manual of the access target intelligent function module.
40577 (9E81 _H)	Device type error The device type specified for the destination station is invalid. (It is checked by the destination link module).	Check the device type.
40578 (9E82 _H)	Device number error The device number specified for the destination station is out of range. When specifying the bit device, the device number is not a multiple of 8. (It is checked by the destination link module).	Check the device number.
40579 (9E83 _H)	Devices points error The number of points specified for the destination station is out of range. When specifying the bit device, the device number is not a multiple of 8. (It is checked by the destination link module).	Check the size.

Return value (HEX)	Error definition	Corrective action
-1 (FFFF _H)	Path error The specified path is invalid.	Check the bus that was returned by the mdOpen function.
-2 (FFFE _H)	Device number error The specified device number is out of range. When specifying the bit device, the device number is not a multiple of 8.	Check the head device number for the specified device.
-3 (FFFD _H)	Device type error The specified device type is invalid.	Check if the device type used is in the device list.
-4 (FFFC _H)	CPU error An invalid station was specified.	Check the status of the communication station. Check the specified station number.
-5 (FFFB _H)	Size error The device number and size are over the device range. Access was attempted using an odd device. The device number and size are over the range for the same block.	Check the specified device size. Check the device number and size.
-6 (FFFA _H)	Number of block error The number of blocks specified in dev[0] for device random read/write is out of range.	Check the number of blocks specified in dev [0].
-8 (FFF8 _H)	Channel number error The channel number specified in the mdOpen function is invalid.	Check the specified channel number.
-11 (FFF5 _H)	Insufficient buffer area The read area size of the read data storage array variable is too small.	Check the read size and read data destination size.
-12 (FFF4 _H)	Block error The specified block number of the extension file register is invalid.	Check the block number (device type) of the extension file register.
-13 (FFF3 _H)	Write protect error The specified block number of the extension file register is overlapping with the write protect area of the memory cassette.	Check the block number (device type) of the extension file register. Check the write protect DIP switch of the accessed memory cassette.
-14 (FFF2 _H)	Memory cassette error No memory cassette is loaded to the accessed CPU, or an incorrect memory cassette is loaded.	Check the accessed memory cassette.
-15 (FFF1 _H)	Read area length error The read area size of the read data storage array variable is too small.	Check the read size and read data destination size.
-16 (FFF0 _H)	Station number/network number error The station number/network number is out of range.	Check the specified station number/network number
-17 (FFEF _H)	All-station/group number specification error A function that does not support all-station specification/group-number specification was specified.	Check if all-station specification/group number specification is enabled for the function.
-18 (FFEE _H)	Remote instruction error A code that is not designated was specified.	Check the specified code.
-19 (FFED _H)	SEND/RECV channel number error The channel number specified with the SEND/RECV function is out of range.	Check the specified channel number.
-21 (FFEB _H)	Error in gethostbyname () An error occurred in the function, gethostbyname ().	Check if the specified host name exists in the HOSTS file.
-24 (FFE8 _H)	Time out error in select () A time out error occurred in the function, select ().	Check if MGW server service has been started on the server machine.
-25 (FFE7 _H)	Error in sendto () An error occurred in the function, sendto ().	Check if normal Ethernet communication can be performed with the server machine.
-26 (FFE6 _H)	Error in recvfrom () An error occurred in the function, recvfrom ().	
-28 (FFE4 _H)	Error response reception An error response was received.	
-29 (FFE3 _H)	Reception data length over Too much data was received.	

Return value (HEX)	Error definition	Corrective action
-30 (FFE2 _H)	Sequence number error The received sequence number is abnormal.	Check if normal Ethernet communication can be performed with the server machine.
-31 (FFE1 _H)	DLL load error An attempt to load a DLL, which is necessary to execute the function, has failed.	Setup the package again.
-32 (FFE0 _H)	Other task/thread is occupying the resource and the resource is not released within 30 seconds.	Retry. There may be a problem of insufficient memory. Terminate other application(s) currently running. Check if the system is operating normally. Reboot the system.
-33 (FFDF _H)	Incorrect access destination The setting for the communication destination is incorrect.	Check if the communication destination is correctly set by the utility.
-34 (FFDE _H)	Registry error An attempt to open the registry has failed.	
-35 (FFDD _H)	Registry read error An attempt to read from the registry has failed.	
-36 (FFDC _H)	Registry write error An attempt to write to the registry has failed.	Check if the communication destination is correctly set by the utility.
-37 (FFDB _H)	Communication initialization setting error An attempt to perform initial setting for communication has failed.	Retry. There may be a problem of insufficient memory. Terminate other application(s) currently running. Check if the system is operating normally. Reboot the system.
-38 (FFDA _H)	Ethernet communication error An attempt to set for Ethernet communication has failed.	Retry. Check if the communication destination is correctly set by the utility.
-39 (FFD9 _H)	COM communication setting error An attempt to set for COM communication has failed.	There may be a problem of insufficient memory. Terminate other application(s) currently running. Check if the system is operating normally. Reboot the system.
-41 (FFD7 _H)	COM control error Control cannot be performed properly during COM communication.	Retry. Check if the system is operating normally. Reboot the system.
-42 (FFD6 _H)	Close error Communication cannot be closed.	Change the TC setting value during RAM operation.
-43 (FFD5 _H)	ROM operation error A TC setting value was written to the CPU during ROM operation.	
-44 (FFD4 _H)	LLT communication setting error An attempt to set for LLT communication has failed.	
-45 (FFD3 _H)	Ethernet control error Control cannot be performed properly during Ethernet communication.	Retry. Check if the communication destination is correctly set by the utility. There may be a problem of insufficient memory. Terminate other application(s) currently running.
-46 (FFD2 _H)	USB open error Failed to initialize and open the USB port.	Retry. Check if the system is operating normally.
-47 (FFD1 _H)	Random read condition disable error The random read condition is not enabled and random read cannot be performed.	There may be a problem of insufficient memory. Terminate other application (s) currently running. Check if the system is operating normally. Reboot the system.
-48 (FFD0 _H)	TEL error.	A conditional random read has been set via a switch such as GX Developer. Wait until the condition is enabled. Alternatively, cancel the condition.
-50 (FFCE _H)	Opened path maximum value over The number of open paths exceeds the maximum value (32).	Exit the program and restart the PC. Setup the package again. Consult with the dealer regarding the problem.
-51 (FFCD _H)	Exclusive control error An error occurred in the exclusive control.	Close several paths.
-2174 (F782 _H)	Destination station number specification error The destination station number for the processing request is specifying the host.	Retry. Check if the system is operating normally.
-4096 to -257 (F000 _H to FFFF _H)	Errors detected in the MELSECNET/H, MELSECNET/10 network system.	Check the destination station number.
		MELSECNET/10 network system Refer to the MELSECNET/H, MELSECNET/10 network system reference manual.

Return value (HEX)	Error definition	Corrective action
-16384 to -12289 (C000 _H to CFFF _H)	Errors detected by the Ethernet interface module	Refer to the user's manual of the Ethernet interface module.
-20480 to -16385 (B000 _H to BFFF _H)	Errors detected in the CC-Link system.	Refer to the CC-Link system master/local module user's manual. * Refer to the QJ61BT11N User's Manual for whether the cyclic data can be transmitted to/from stations compatible with CC-Link Ver.2.
-18558 (B782 _H)	Request destination station number specification error The local station number was specified as the station number of the processing request destination station.	Review the correct request destination station number.
-18560 (B780 _H)	Transient was issued to the remove I/O.	Check the destination station to request.
-18575 (B771 _H)	A device for other station only was accessed to the host.	Check the device type.
-24957 (9E83 _H)	Device points error The number of points specified for the destination station is out of device range. When specifying the bit device, the device number is not a multiple of 8. (It is checked by the destination link module.)	Check the size.
-24958 (9E82 _H)	Device number error The device number specified for the destination station is out of range. When specifying the bit device, the device number is not a multiple of 8. (It is checked by the destination link module.)	Check the device number.
-24959 (9E81 _H)	Device type error The device type specified for the destination station is invalid. (It is checked by the destination link module.)	Check the device type.
-25056 (9E20 _H)	Processing code error A processing code that cannot be processed by the destination station was set. (It is checked by the destination link module.)	Check the destination station number and processing code.
-26333 (9923 _H)	The ROM version of the CC-Link board does not match the QCPU (Q mode).	Access a CPU other than the QCPU (Q mode). Use the CC-Link board supplied with the module (ROM version: "W" or later) after the SW3DNF-CCLINK.
-26334 (9922 _H)	Board reset error Other process has executed a board reset using the same channel while other station is being accessed.	Retry.
-26336 (9920 _H)	Request error for other loop Routing to other loop was performed.	Change the routing destination to AnUCPU or QnACPU.
-28150 (920A _H)	Data link disconnecting error	A host link device was accessed while the data link is being disconnected.
-28151 (9209 _H)	APS No. error. An incorrect response data was received.	Change the equipment at the process request destination.
-28156 (9204 _H)	Dual-port hand-shake error	Remove other optional board.
-28158 (9202 _H)	WDT error	Reset the board. Reboot the PC. Take the measures for WDT error occurrence. (Refer to Section 11.6.)

- *1: Procedures and sample program for increasing the minimum working set area of the PC
 The following provides measures for increasing the minimum working set area of the PC when an error of error code 77 occurs due to MD function execution, and its sample program.
 The PC board driver runs using the minimum working set area in the memory area reserved in the application program. Some application program may use a large area of the minimum working set area. In such a case, when the minimum working set area for the PC board driver cannot be reserved, an error code 77 is returned.
 If this situation occurs, increase the minimum working set area in the application program before executing the MD function. (See the following sample program.)
 The minimum working set area of 200KB is reserved at startup of the personal computer.

Sample program

This section gives a processing overview for setting a greater size to the minimum working set and provides sample programs.

(a) Processing overview of sample program

- 1) Obtain the application program ID by the GetCurrentProcessID function.
- 2) Using the ID obtained in step 1), obtain the application program handle by the OpenProcess function.
- 3) The current minimum and maximum working set sizes can be obtained by executing the GetProcessWorkingSetSize function.
- 4) Set a size greater than the minimum working set obtained in step 3) and execute the SetProcessWorkingSetSize.
- 5) Release the application program handle by the CloseHandle function.

(b) Sample program: When setting by VB

(Example of min. working set size 1MB and max. working set size 3MB)

```
Dim id As Long      'Application program ID variable
Dim ph As Long     'Application program handle variable
Dim wkmin As Long  'Minimum working set variable
Dim wkmax As Long  'Maximum working set variable

'Obtain the application program ID
id = GetCurrentProcessID()
'Open the application program handle
PROCESS_SET_QUOTA = 256, PROCESS_QUERY_INFORMATION = 1024
ph = OpenProcess(256 + 1024, False, id)
'Obtain the maximum working set size and minimum working set size of the application program
bret = GetProcessWorkingSetSize(ph, wkmin, wkmax)
'Set the minimum working set size to 1MB
wkmin = 1 * 1024 * 1024
'Set the maximum working set size to 3MB
wkmax = 3 * 1024 * 1024
'Change the maximum working set size and minimum working set size of the application program
bret = SetProcessWorkingSetSize(ph, wkmin, wkmax)
'Close the application program handle
bret = CloseHandle(ph)
```

The set sizes shown here are reference sizes. Adjust the sizes in accordance with your system.

(c) Sample program: When setting by VC
 (Example of min. working set size 1MB and max. working set size 3MB)

```
#define ERROR -1
short ChangeWorkingSetSize()
{
    DWORD    dwProcessId;           /*Application program ID variable*/
    HANDLE   hProcess;             /*Application program handle variable*/
    DWORD    dwMinimumWorkingSetSize; /*Minimum working set variable*/
    DWORD    dwMaximumWorkingSetSize; /*Maximum working set variable*/

    /*Obtain the application program ID*/
    dwProcessId = GetCurrentProcessId();

    /*Open the application program handle*/
    hProcess =
    OpenProcess(PROCESS_SET_QUOTA+PROCESS_QUERY_INFORMATION,FALSE,dwProcessId);
    if(hProcess == NULL){
        /*Error end*/
        return(ERROR);
    }

    /*Obtain the maximum working set size and minimum working set size of the application program */
    if(GetProcessWorkingSetSize(hProcess,&dwMinimumWorkingSetSize,&dwMaximumWorkingSetSize)==0){
        /*Error end*/
        CloseHandle(hProcess);
        return(ERROR);
    }

    /*Set the minimum working set size to 1MB*/
    dwMinimumWorkingSetSize = 1 * 1024 * 1024;
    /*Set the maximum working set size to 3MB*/
    dwMaximumWorkingSetSize = 3 * 1024 * 1024;

    /*Change the maximum working set size and minimum working set size of the application program */
    if(SetProcessWorkingSetSize(hProcess,dwMinimumWorkingSetSize,dwMaximumWorkingSetSize)==0){
        /*Error end*/
        CloseHandle(hProcess);
        return(ERROR);
    }

    /*Close the application program handle*/
    CloseHandle(hProcess);

    /*Normal return*/
    return(0);
}
```

The set sizes shown here are reference sizes. Adjust the sizes according to your system.

11 TROUBLESHOOTING

This chapter describes how to determine the cause of trouble that may occur during system construction as well as appropriate corrective actions.

11.1 When Performing Troubleshooting

Ideally occurrence of trouble should be kept to a minimum in order to startup the system effectively. However, once an error occurs, it is important that we identify the cause as quickly as possible.

The followings are the three basic points that must be kept in mind when performing troubleshooting.

(1) Visual check

Check the following points.

- 1) Movement of the external device (status when stopped or during operation)
- 2) On/off status of power supply
- 3) Wiring condition (cable)
- 4) LED display status (power supply display LED)
- 5) Checks whether the PC is one suitable for the operating environment

After checking 1) through 5), connect the external device and check the operation of the user program.

(2) Confirming the error

Examine how the error status changes by the following operation.

- 1) Change the input status and check if the change can be read correctly using the test program.
- 2) Repeat on/off of output and check if the status of the external device changes accordingly.

(3) Narrowing the range

Based on the steps 1) and 2) above, deduce the range of error location as one of the following.

- 1) PC side or external device side
- 2) PC main body or board
- 3) Cable
- 4) User program

11.2 Troubleshooting Table by the Type of Error Occurring

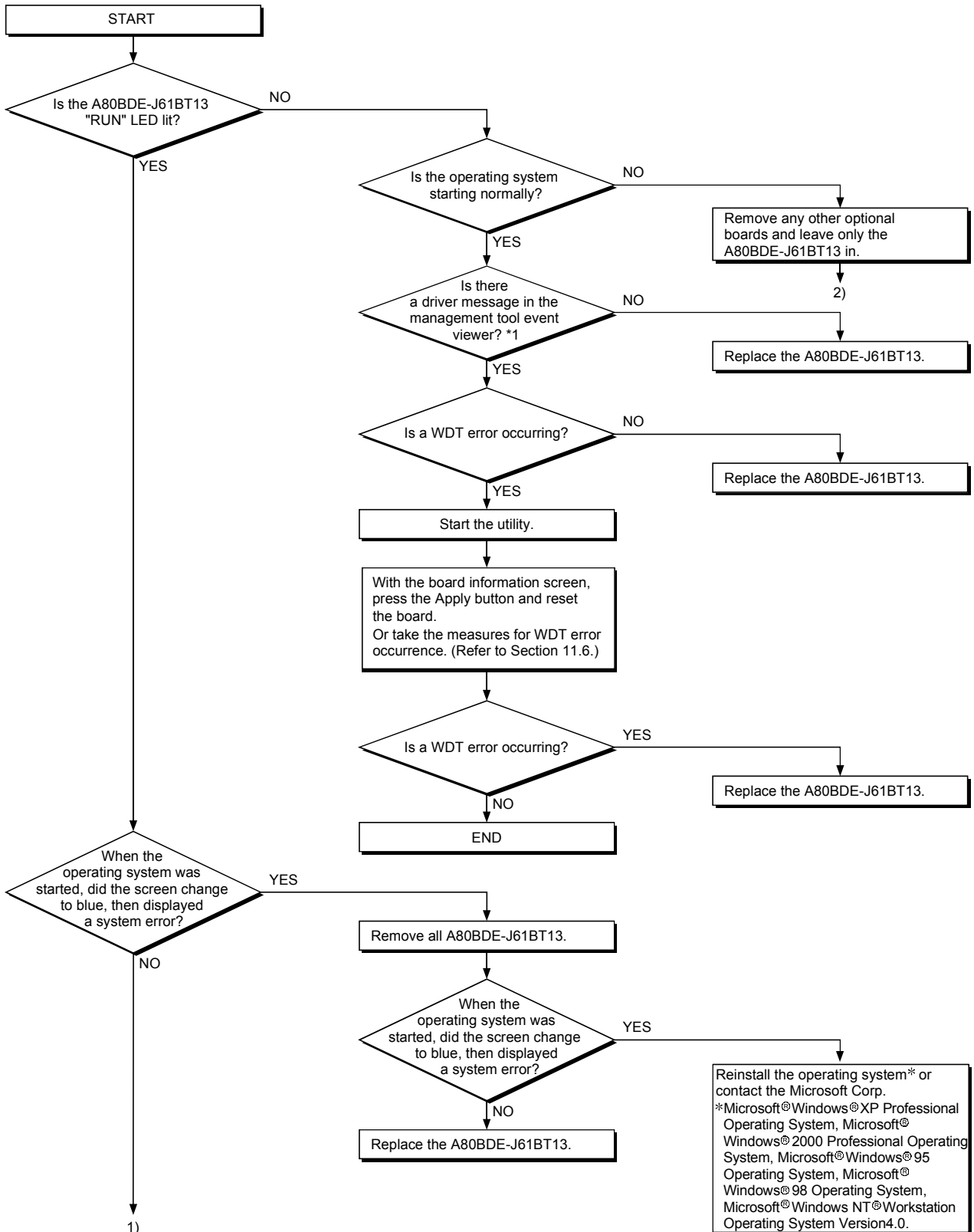
When trouble occurs, refer to the methods in Table 11.1 for determining the cause of the trouble.

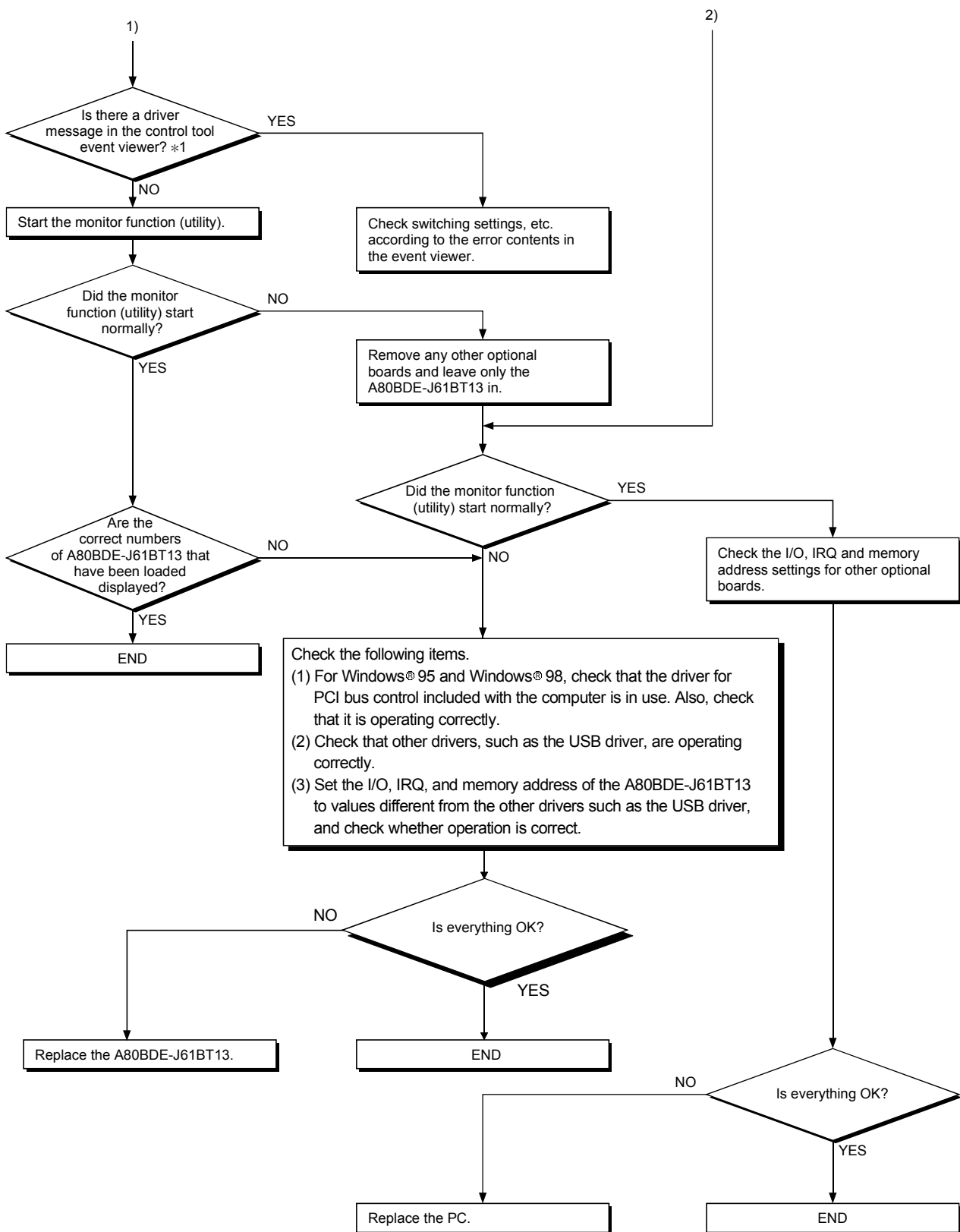
Table 11.1 Troubleshooting table by the type of error occurring

No.	Error detail	Cause determination method/Action
1	A CC-Link board did not operate normally upon startup.	Refer to the flowchart found in Section 11.3 for when the board and PC do not operate.
2	There was no data linking although the master station and other station were connected to the CC-Link board.	Refer to the flowchart found in Section 11.4 for when the data link could be completed.
3	When an error occurs during the data link 1) An unexpected value is entered in the special device. 2) The device is being accessed using a function in the user program, but data cannot be read or written. 3) Communication stops occasionally while the user program is executing. 4) The system goes down (blue screen) or resets while the user program is executing in operating system.	Refer to the flowchart found in Section 11.5 for when an error occurs during data linking.
4	Uninstallation is not executed normally. 1) Although the message "SW□DNC-CCLINK-B has been successfully uninstalled from your machine" is displayed on the screen, the uninstallation is not complete.	Logon as a user with administrator authority and execute the uninstallation. (Refer to POINT in Subsection 8.4.3)
5	An error message is displayed in utility. 1) "Device Monitor Utility is not registered." is displayed. 2) "There is no Help file of CC-Link Utility." is displayed. 3) "Error going in loading Version information." is displayed. 4) "Error going in writing CC-Link board information." is displayed.	Logon as a user with administrator authority and execute utility (Refer to POINT in Chapter 9) or reinstall the operating system.

11.3 Flowchart to Use when the Board or PC do not Operate

The following indicates a check procedure in the PC unit when the CC-Link board does not run normally during startup.





*1 : With Windows® 95 and Windows® 98, check the driver message in the error viewer.

11.3.1 Table of error event messages that may occur during driver startup

The table below lists the errors displayed in the event viewer/error viewer.

Event ID (HEX)	Error content	Corrective action
256 (100H)	The driver could not be executed because an error occurred during driver startup.	Reinstall the driver package. If the error occurs again, reinstall operating system.
257 (101H)	The CC-Link board could not be detected.	Check the installation status of the CC-Link board.
258 (102H)	No response from hardware.	Replace the CC-Link board.
259 (103H)	The number of boards detected exceeds the maximum number that can be loaded.	Remove boards until the number falls within the maximum limit.
262 (106H)	An attempt to link the device name has failed.	Reinstall operating system.
268 (10CH)	An error occurred during receiving process. (The request packet is incorrect).	Check the PC and PLC program for which the processing is being requested to this PC.
269 (10DH)	An error occurred during transmission process.	
279 (117H)	An error occurred when writing to the registry.	1) This error occurs when the CC-Link board driver is installed first. Install SW4DNF-CCLINK-B, then restart the PC to confirm that this error does not occur. 2) Increase the system memory and disk capacities.
280 (118H)	A request that cannot be processed was received from other station. (A request for which a response request cannot be processed was received)	Check the PC and PLC program for which the processing is being requested to this PC.
282 (11AH)	Mapping of the I/O port has failed.	The I/O port is overlapping with another resource. Remove other optional boards.
283 (11BH)	The shared memory area of the CC-Link board is overlapping with other hardware.	Remove other optional boards.
284 (11CH)	The CC-Link board IRQ is overlapping with other hardware.	Remove other optional boards.
285 (11DH)	It is possible the CC-Link board will not operate normally, since it detected a temperature abnormality.	Install the PC in a location with a suitable temperature.
286 (11EH)	Failed to secure the memory area required to start the driver.	Increase system memory.
288 (120H)	A WDT error occurred.	Remove other optional boards. Take the measures for WDT error occurrence. (Refer to Section 11.6.)
289 (121H)	Handshaking with the shared memory area has failed.	Reset the board. If the error occurs again, replace the board.
290 (122H)	The board number of the CC-Link board is a duplicate.	Reset so there are no duplicate board numbers.
291 (123H)	Failed in mapping the shared memory area.	Remove other optional boards.
293 (125H)	Interrupt registration has failed.	Remove other optional boards.
294 (126H)	The I/O port for the CC-Link board is overlapping with other hardware.	Remove other optional boards. * ¹

Event ID (HEX)	Error content		Corrective action	
1281 (501H)	Initiali- zation of the CC-Link board has failed.	DUMP value	Error contents (details)	_____
		01h	There is no response from the hardware.	Replace the CC-Link board.
		02h	The IRQ or memory is overlapping. * ²	Remove other optional boards.
		03h	There is no response from the hardware.	Replace the CC-Link board.
		04h	Handshaking with the shared memory area has failed.	Restart. If the error occurs again, replace the board.
		66h	There is no response from the hardware.	Replace the CC-Link board.

DUMP value ••• Value of the 1 byte at the head of the data contents details area

*1 : If this event error occurs in the Windows® 2000 Professional, Windows® XP Professional or Windows NT® Workstation 4.0 event viewer, restart the PC that has the BIOS setup shown below after setting the "Plug & Play O/S" in [No] and "Reset Configuration Data" in [Yes] as in the following example.

Example)

BIOS Setup Utility

Set Plug & Play O/S : [YES] → [No]

Reset Configuration Data : [No] → [YES]

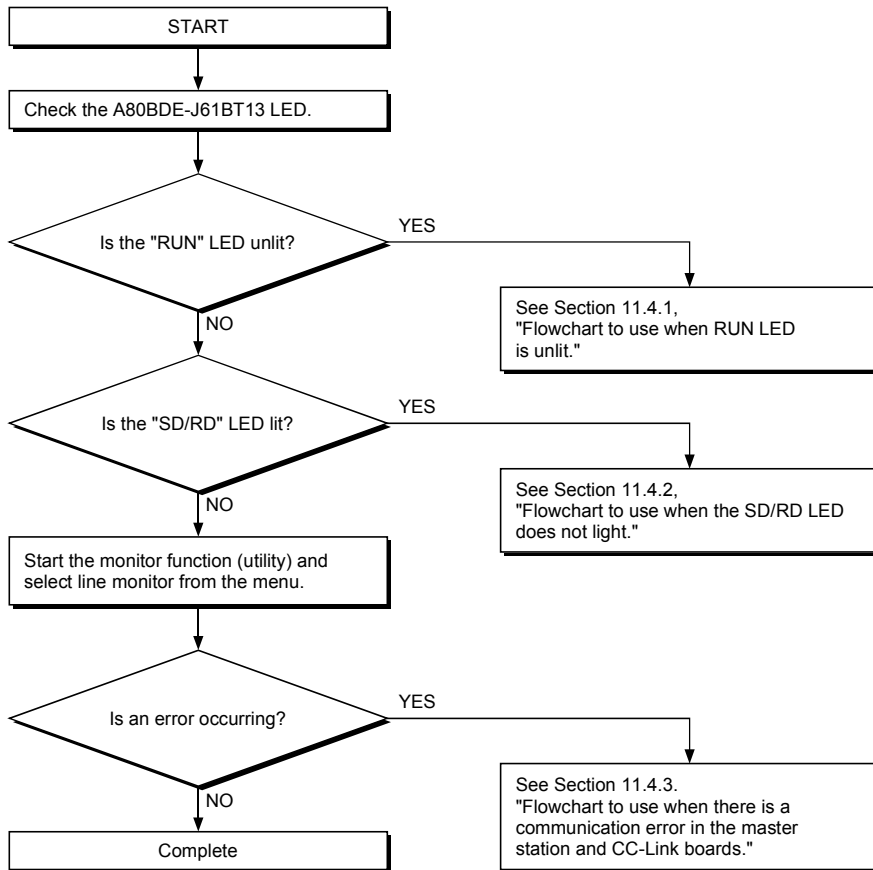
Then restart.

*2 : This event error may occur when the PCI bus controller is not operating correctly. When the PC being used comes pre-installed with Windows® 95, Windows® 98, use the drivers for Windows 95/98 and the PCI bus controller that come in the PC unit.

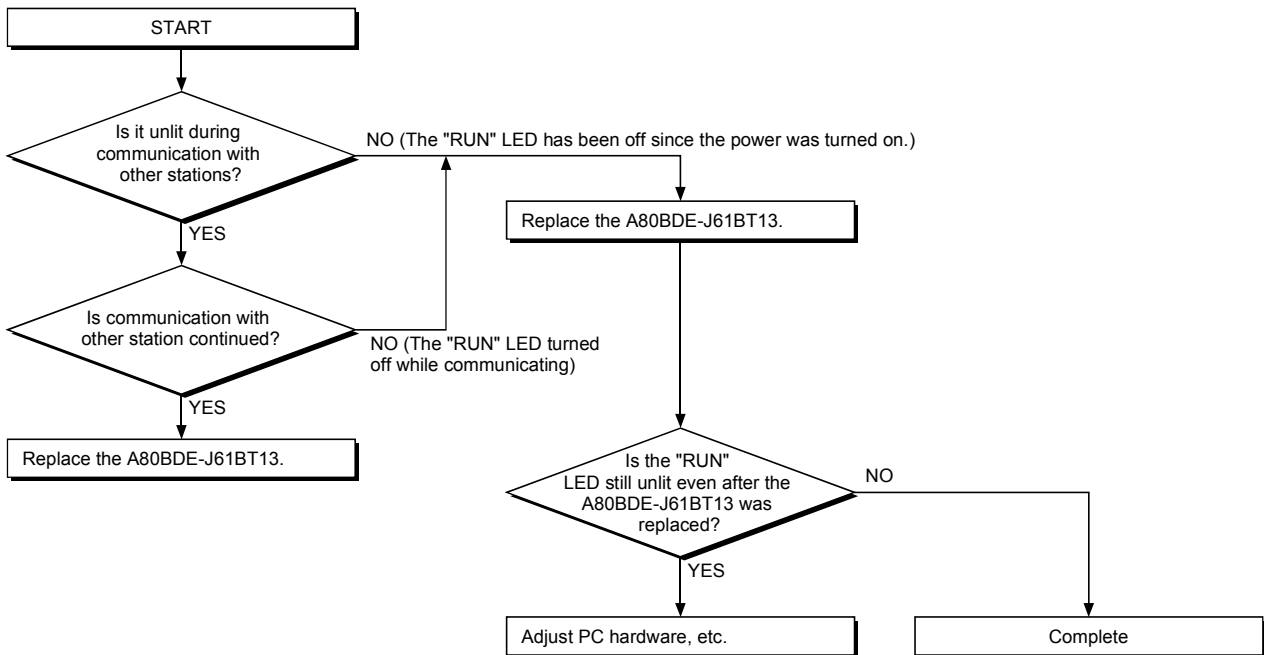
If Windows® 95, Windows® 98 have been purchased separately, obtain the drivers for the PCI bus controller suggested by the PC manufacturer and install.

11.4 Flowchart to Use when the Data Link could not be Completed

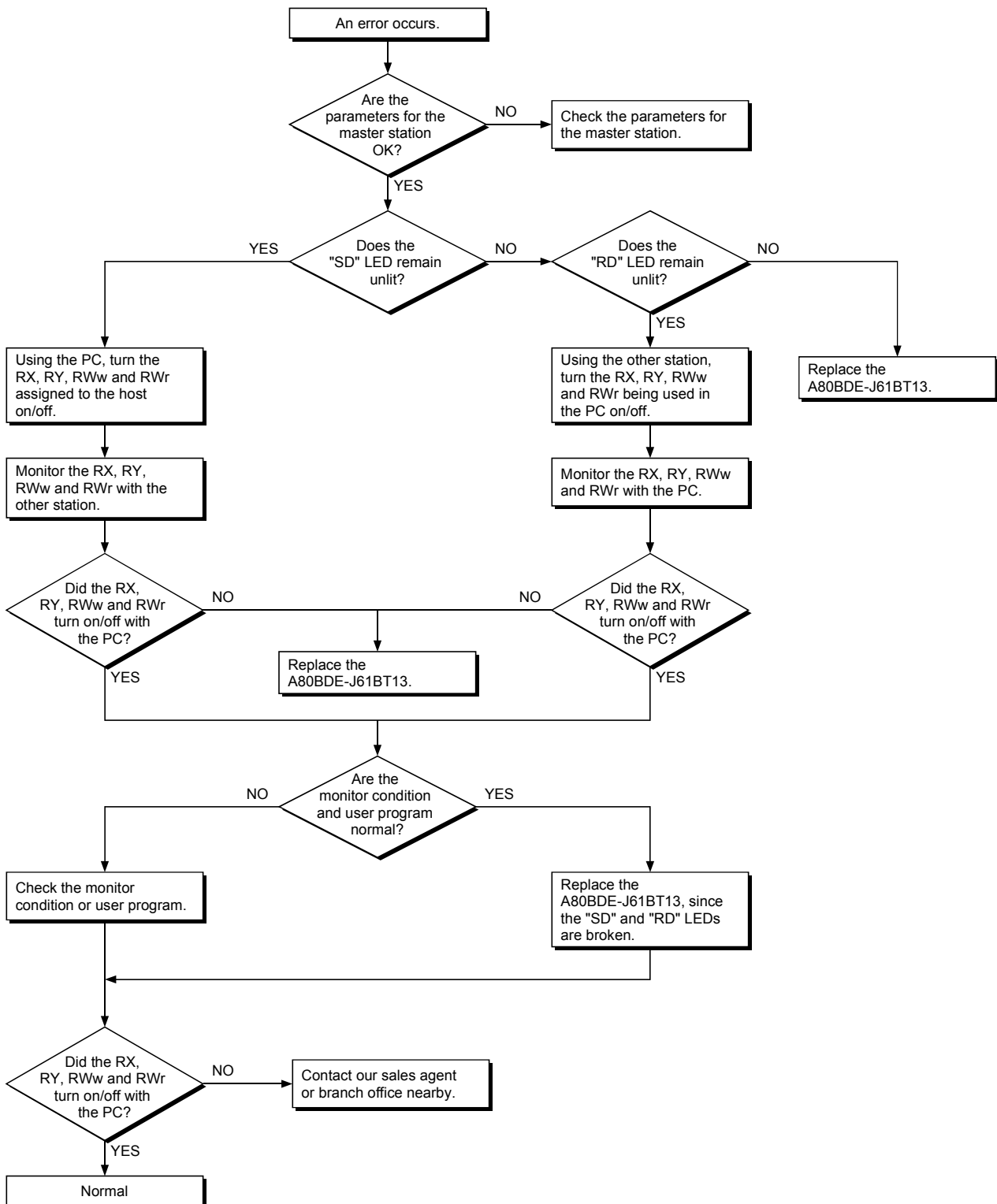
The following flowchart indicates when the data link could not be completed even though the CC-Link board was connected to another station.



11.4.1 Flowchart to use when RUN LED is unlit



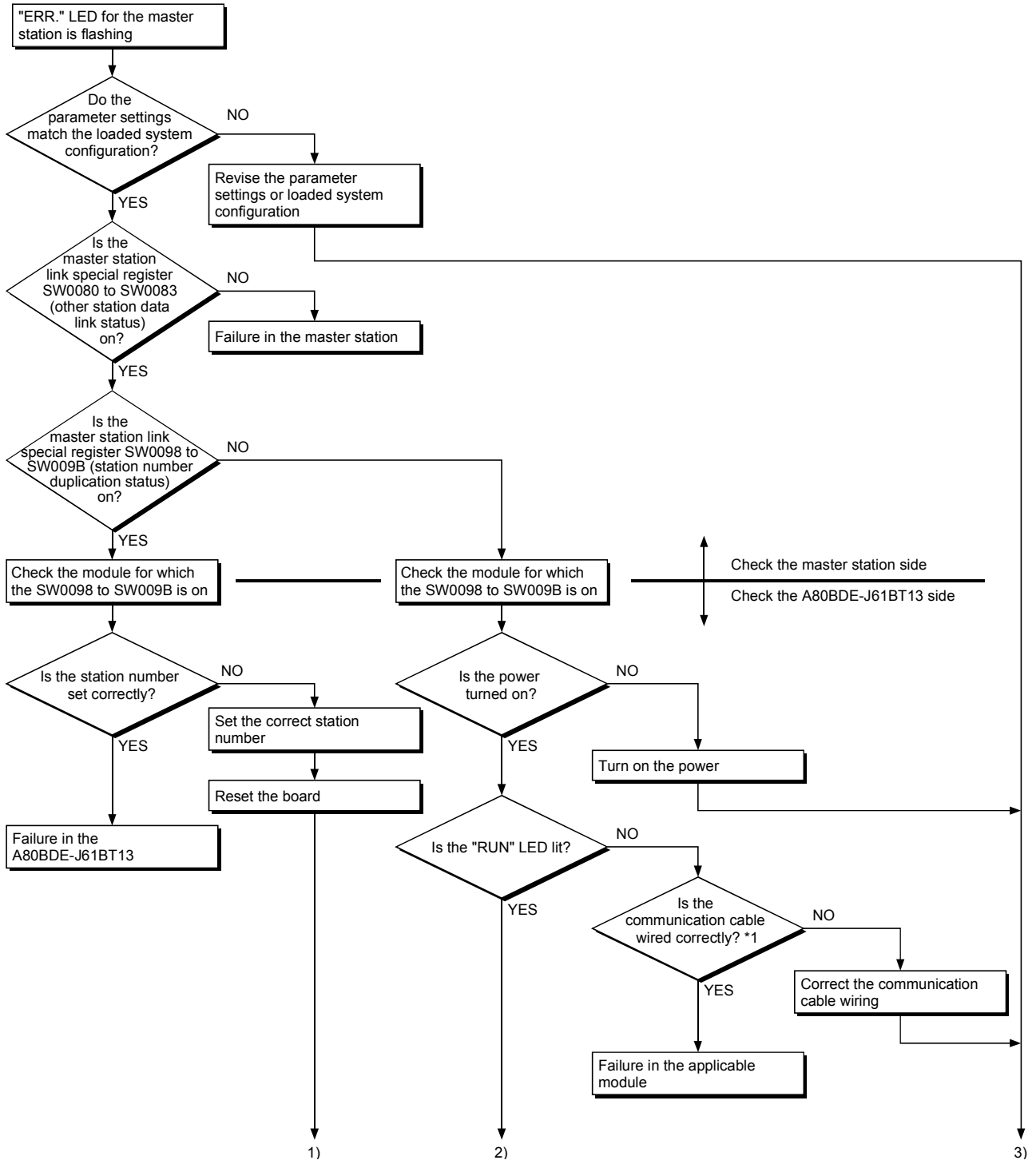
11.4.2 Flowchart to use when SD/RD LED does not turn on

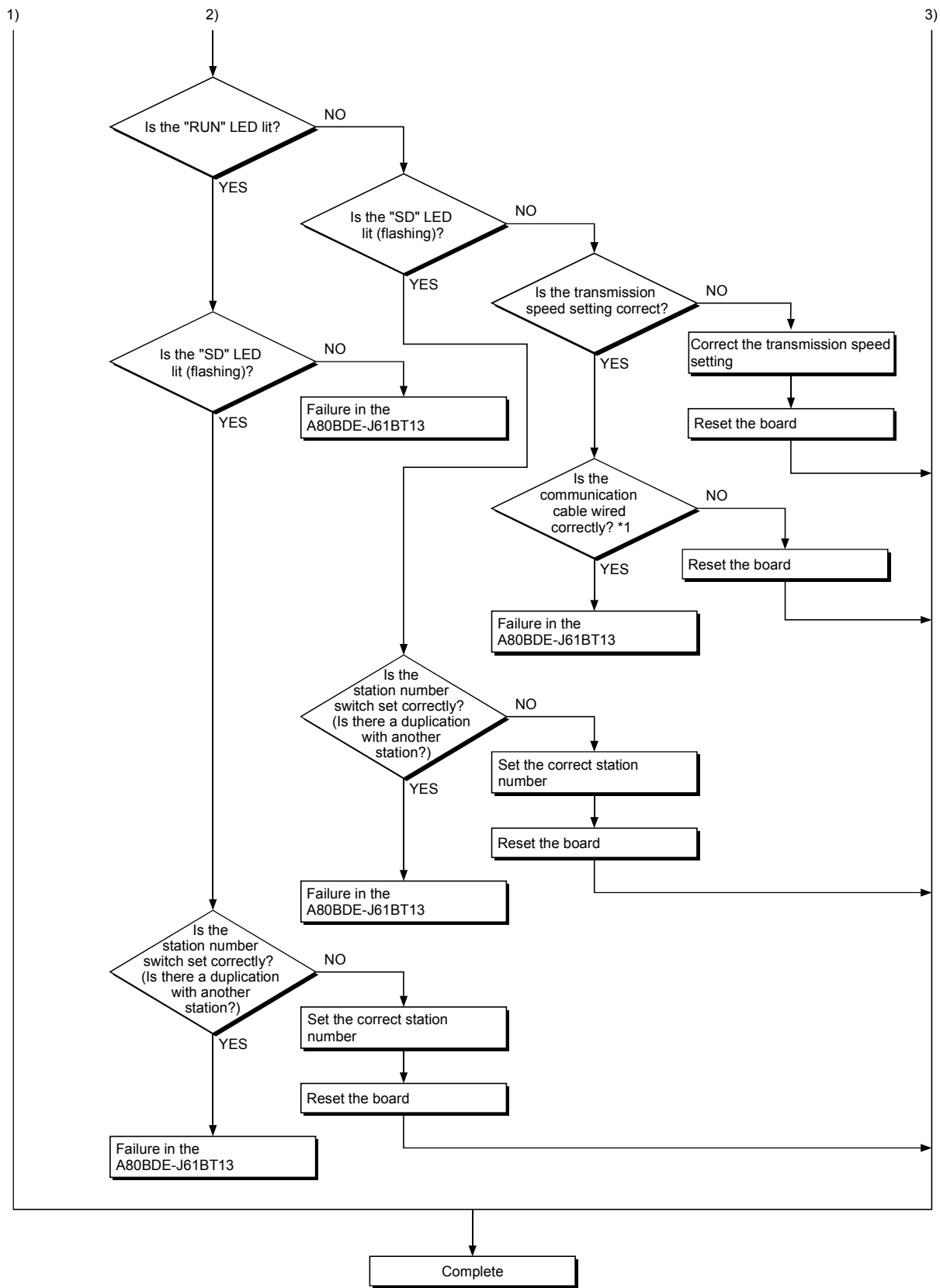


11.4.3 Flowchart to use when there is a communication error between the master station and CC-Link board

When a station number duplicate bit turns on in the link special register SW0098 to SW009B (station number duplicate status), check the CC-Link board of the relevant station number using the following procedure.

Troubleshooting flowchart when the "ERR." LED for the master station is flashing

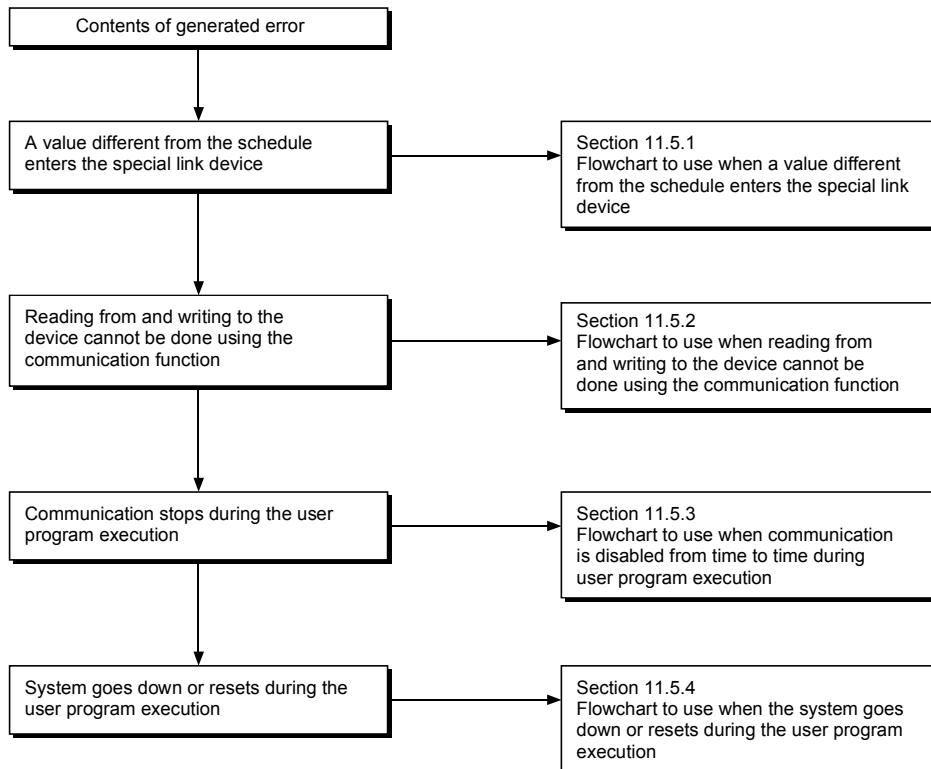




*1 : Check for shorts, reversed connection, broken connection, terminal resistor, FG connection, total extended distance, and distance between stations

11.5 Flowchart to Use when an Error Occurs During Data Linking

The following flowchart indicates when an error occurs during data linking is shown.

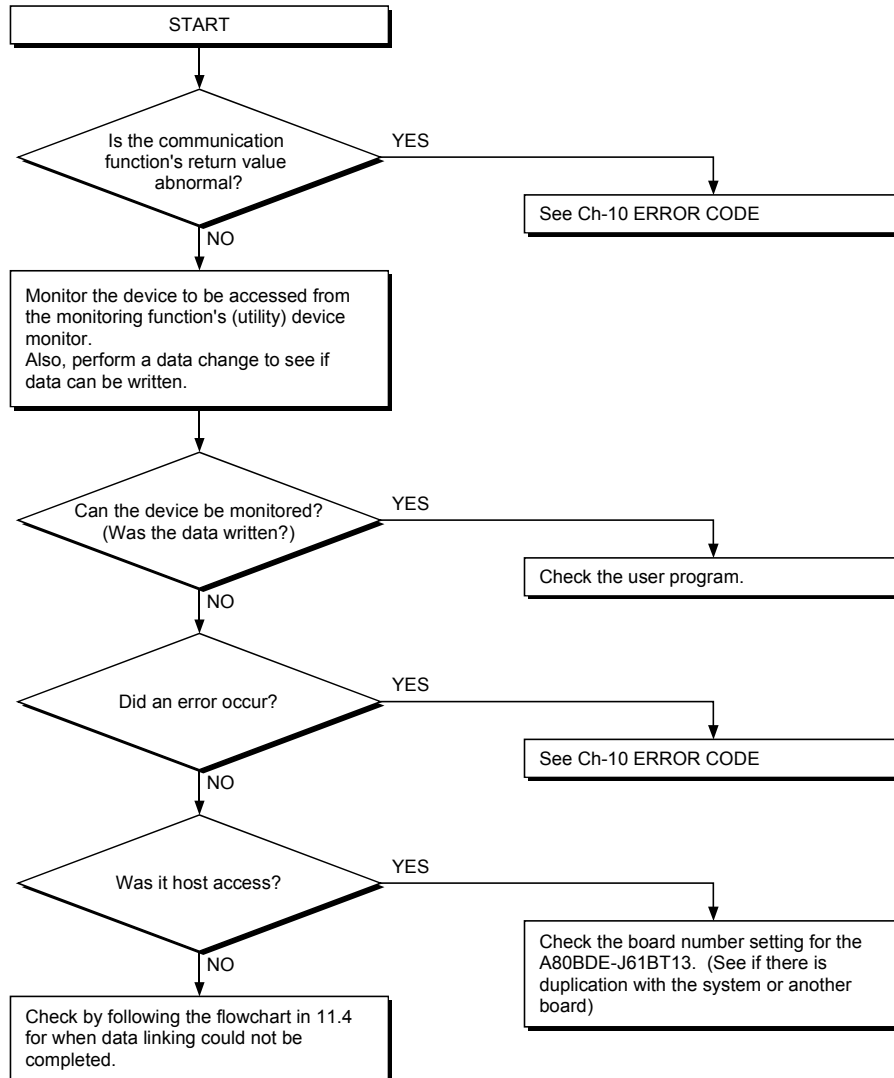


11.5.1 Flowchart to use when unexpected value is input to specific link device

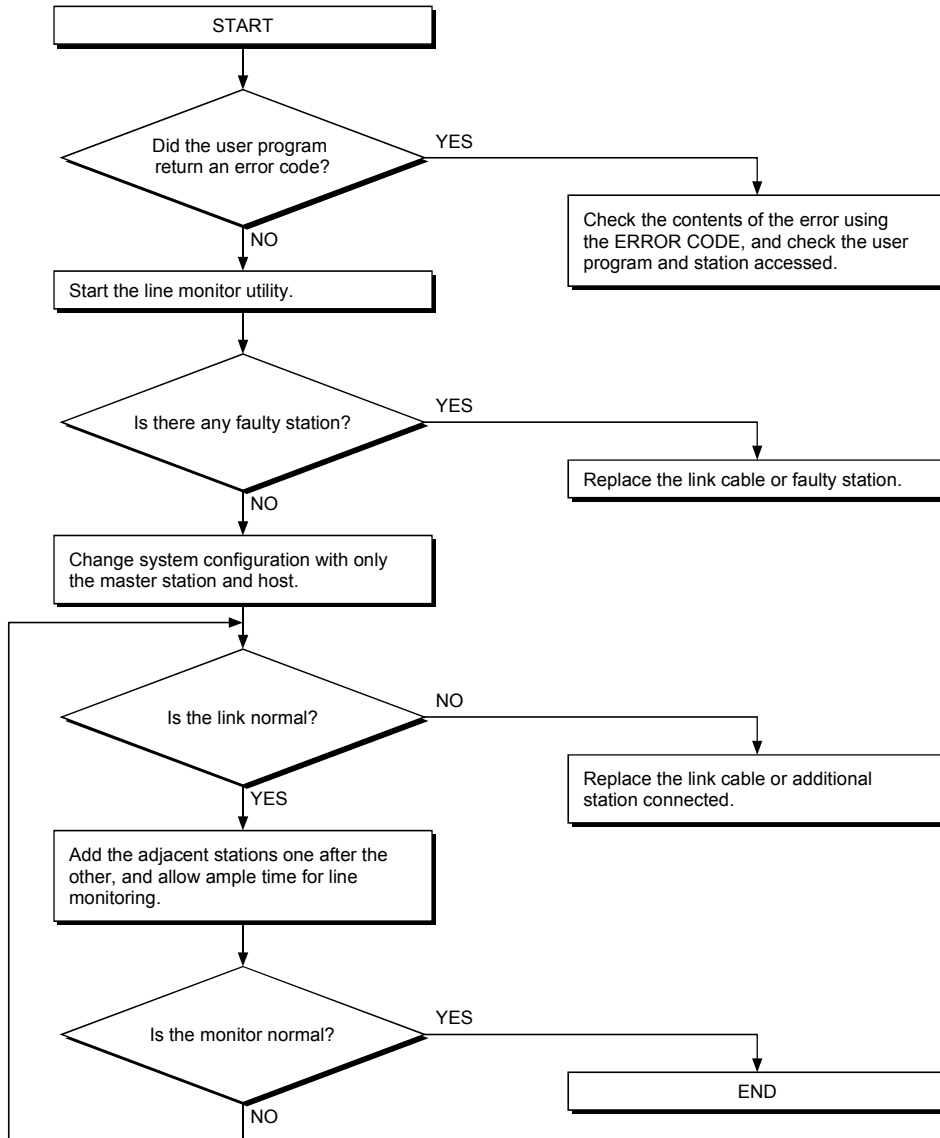
Check the following items.

- 1) Check for a station with link error using the network monitor in the monitoring function.
- 2) Check the link parameter assignment range at the master station.
- 3) Check the device range used in the PLC program at the PLC.
- 4) Check, in the user program, argument data for the communication function accessing the specific link device.

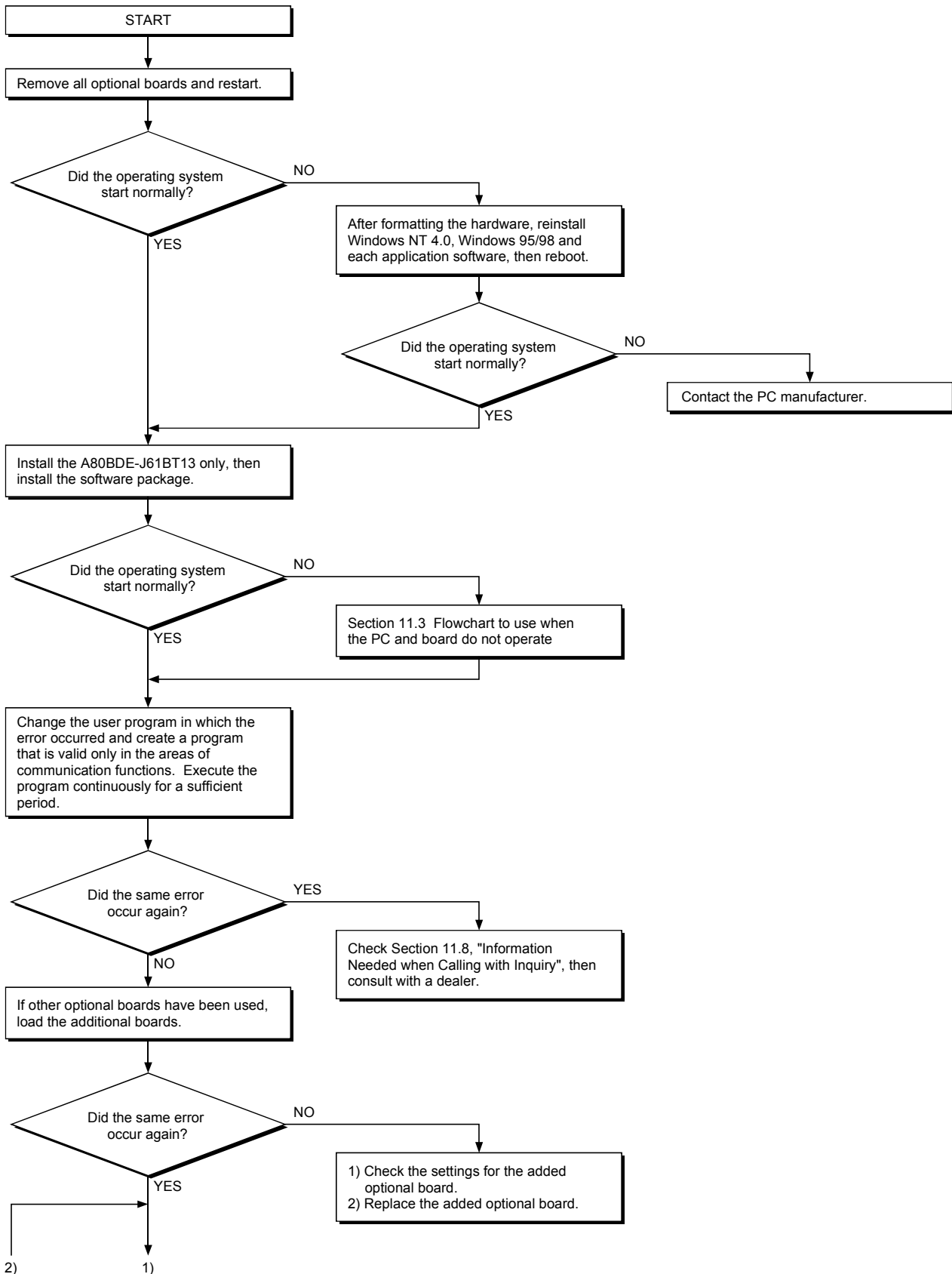
11.5.2 Flowchart to use when reading from and writing to the device cannot be done using the communication function

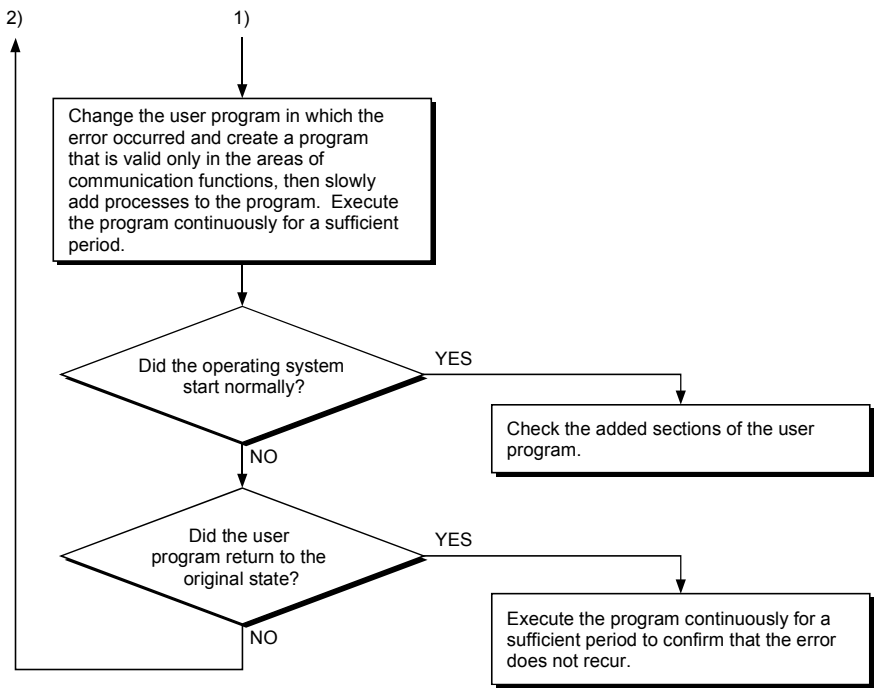


11.5.3 Flowchart to use when communication is disabled from time to time during user program execution



11.5.4 Flowchart to use when the system goes down or resets during the user program execution





11.6 Measures for WDT error occurrence

The following explains the causes of WDT error occurrence in CC-Link board and measures for them.

(1) Cause of WDT error occurrence

The WDT error occurs in CC-Link board as follows:

- 1) CC-Link driver cannot operate because the PC or OS is hang up.
- 2) The CPU cannot start to control the CC-Link driver within the WDT time, as the other drive has occupied the CPU processing.

In case 2), the WDT time has to be adjusted, as affected by the operation of the PC or other driver.

For details, refer to (2).

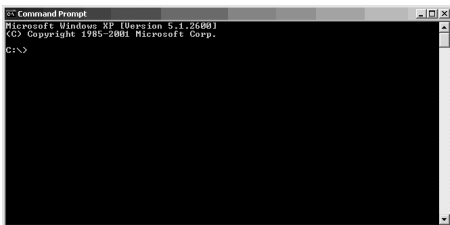
(2) Adjusting WDT Time

The following explains adjusting the WDT time.

The screens of Windows® XP Professional are used in the explanation. Therefore, the screens and file names to be executed are slightly different from those of other operating systems. Adjust the WDT time with reference to

REMARK.

- 1) Insert Disk 6 into the floppy disk drive.



- 2) Open [Start] → [All Programs] → [Accessories] → [Command Prompt].

REMARK

When Windows® 95, Windows® 98 or Windows NT® Workstation 4.0 is used, open [Start] → [Programs] → [MS-DOS Prompt].
When Windows® 2000 Professional is used, open [Start] → [Programs] → [Command Prompt].

↓
(To the next page)

(From the previous page)

```
C:\>A:\Tools\WDTSETNT.exe
```

- 3) Execute WDTSETNE.exe.
Enter "A:\Tools\WDTSETNT.exe", and then press the key.

REMARK

Above enter example is relevant to Windows NT® Workstation 4.0 and Windows® 2000 Professional or Windows® XP Professional. When Windows® 95 or Windows® 98 is used, enter "A:\Tools\WDTSET95.exe", and then press the key.

```
C:\>A:\Tools\WDTSETNT.exe
WDT Setting Value(0,1-32767) =
```

- 4) As the message shown left is displayed, enter in "WDT Setting Value" the value large enough to avoid WDT error, and then press the key. (Setting range: 1 to 32767)

WDT time is defined by the value set to "WDT Setting Value" as shown below.

$$(WDT\ time) = (Value\ set\ as\ "WDT\ Setting\ Value") \times 8ms.$$

"WDT Setting Value" is factory-set to "300".

If "WDT Setting Value" is set to "0" and the key is pressed, the currently set value will be displayed.

```
C:\>A:\Tools\WDTSETNT.exe
WDT Setting Value(0,1-32767) = 500
done
C:\>
```

- 5) When "done" is displayed after the above setting, this means the setting operation is completed. End the command prompt and restart the personal computer.

REMARK

If "ERROR" is displayed, reinstall the software package or operating system.

(Complete)

POINT

If WDT error still occurs after the above operations reset "WDT Setting Value". (Enter the value larger than previous setting.)

11.7 Precautions for installing other optional board

Executing user applications (including the device monitor utility) for each board simultaneously under the following condition may cause an error.

When an error occurs in the user application, take the action shown below.

<Condition>

A personal computer into which the CC-Link board and other optional board are installed and where the resources were allocated automatically by Plug-and-Play is used.

<Action>

- (1) Change the positions where the CC-Link board and other optional board are installed.
- (2) In the BIOS setup, exchange the IRQs between the CC-Link board and other optional board or change their IRQs.

11.8 Information Needed when Calling with Inquiry

The following conditions and status must be reported when calling us with an inquiry regarding a damaged board.

- (1) Error state (be specific)
Example) The system does not start during the startup process after turning on the power, displaying a "board Not response" message.
- (2) PC manufacturer, PC name/model
- (3) Main memory capacity, hard disk capacity, CPU model
- (4) OS name : Windows® XP Professional, Windows® 2000 Professional or other
- (5) Position of installation slot, number of boards installed
- (6) Use of optional boards made by other companies.
- (7) When optional boards made by other companies are installed, have the following items for each board available.
 - Board model
 - Board manufacturer
 - Memory address (head address and occupied size)
 - I/O address (head address and occupied size)
 - IRQ number, DMA number
- (8) Whether a comparison check in another PC has been done
- (9) Switch setting
- (10) Details of the CC-Link driver error registered in the event viewer (for Windows® XP Professional, Windows® 2000 Professional, Windows NT® Workstation 4.0) or the error viewer (for Windows® 95, Windows® 98)

APPENDIX

Appendix 1 Communication with the Redundant CPU

This section explains communication with the Redundant CPU when the CC-Link board is used.



(1) Access to the Redundant CPU

(a) Redundant CPU specify

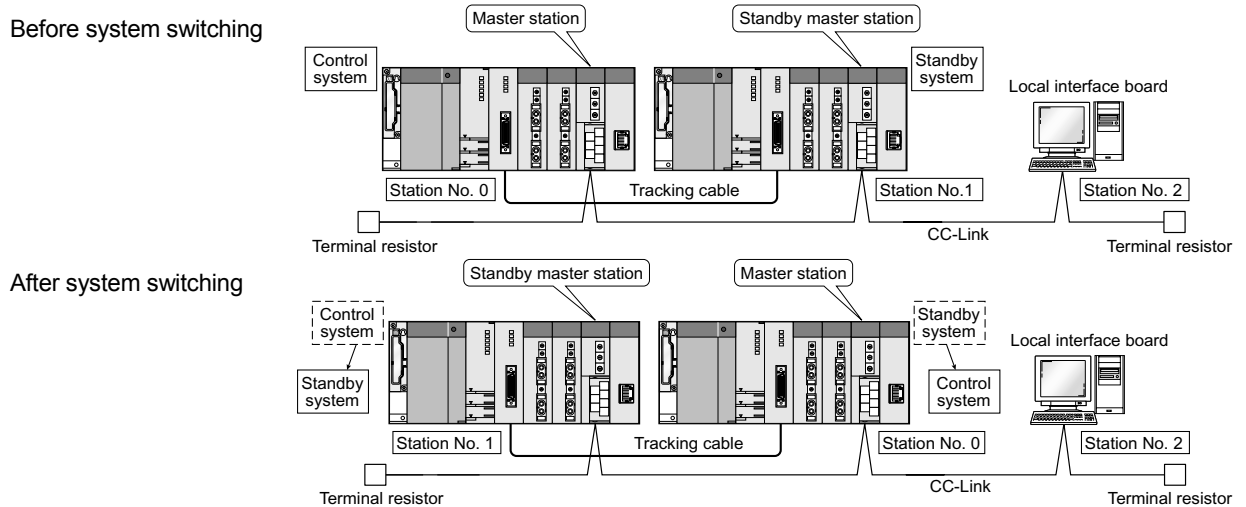
To access the Redundant CPU, directly specify the station number of the CC-Link module mounted on the station of the target Redundant CPU.

(b) Action to be taken at occurrence of system switching

After system switching, the Redundant CPU in the same system (control system or standby system) can also be accessed by directly specifying the station number that was specified before system switching. *1

*1: When system switching occurs in the Redundant CPU system to be accessed, the station number of the CC-Link module mounted on the station of each Redundant CPU is also changed internally.

(Example) When the Redundant CPU in the control system is accessed



POINT													
Create a program to monitor which system in the redundant CPU system is accessed from the CC-Link board.													
SM1515	Control/Standby system status • Indicates the CPU module operation status • Remains ON/OFF even if the tracking cable is disconnected while the redundant system is running.												
SM1516													
	<table border="1"> <thead> <tr> <th></th> <th>Control system</th> <th>Standby system</th> <th>At the time of TRK.CABLE ERR.(Error code: 6120) occurrence (System not determined.)</th> </tr> </thead> <tbody> <tr> <td>SM1515</td> <td>ON</td> <td>OFF</td> <td>OFF</td> </tr> <tr> <td>SM1516</td> <td>OFF</td> <td>ON</td> <td>OFF</td> </tr> </tbody> </table>		Control system	Standby system	At the time of TRK.CABLE ERR.(Error code: 6120) occurrence (System not determined.)	SM1515	ON	OFF	OFF	SM1516	OFF	ON	OFF
	Control system	Standby system	At the time of TRK.CABLE ERR.(Error code: 6120) occurrence (System not determined.)										
SM1515	ON	OFF	OFF										
SM1516	OFF	ON	OFF										

(2) Retry processing for error that will occur during system switching processing

Any of the following errors will occur when the MELSEC data link library is used to access the Redundant CPU during system switching processing.

Examples of errors that will occur in redundant CPU

- A system switching error (Error code 4248H)
- CPU starting error (Error code 4004H)
- Other system CPU module error (Error code 4245H)
- Access destination illegal error (Error code FFDFH)

Examples of errors that will occur in CC-Link board or module

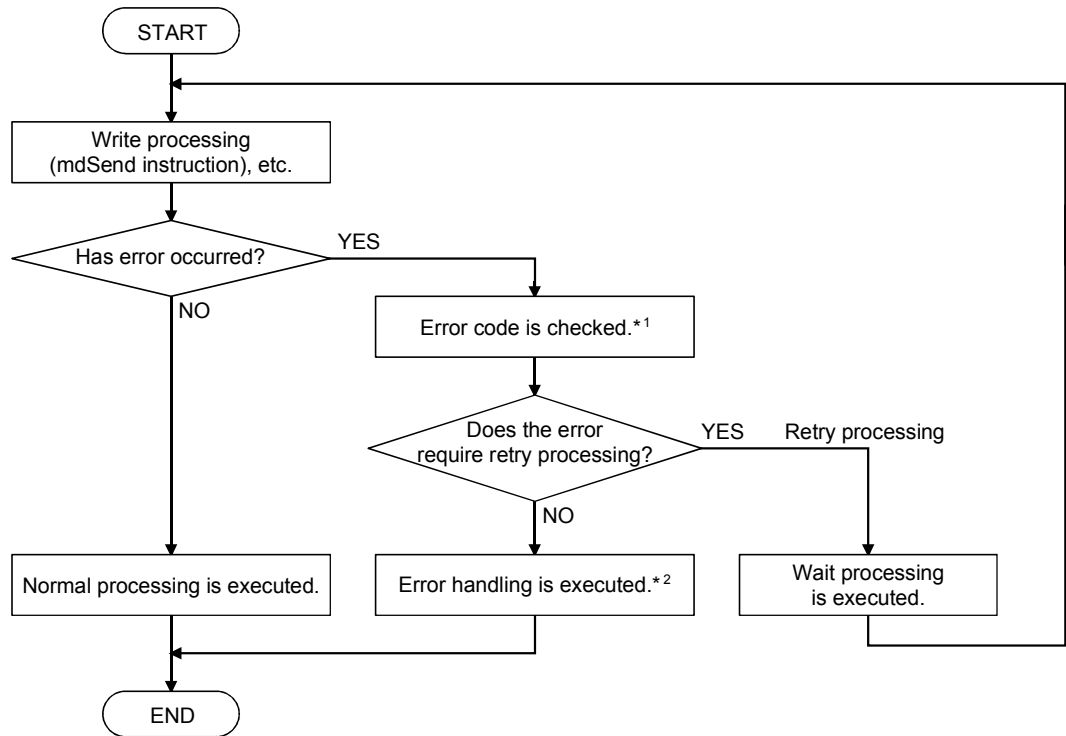
- Response timeout (Error code B778h)
- Corresponding station error during sending (Error code B201h)
- Transient target station error (Error code B205h)

When an error has occurred, confirm the error code, and create a user program for retry processing as necessary.

(a) The following indicates the functions that will result in error if executed during system switching.

	Functions that will result in error by system switching
MELSEC data link library	mdControl,mdDevRst,mdDevSet,mdRandR,mdRandW,mdReceive,mdSend,mdTypeRead

(b) The following example gives a flowchart for error occurrence at batch write.



*1: Refer to the following manual for the details of and corrective action for the error code.

When a Redundant CPU error occurs

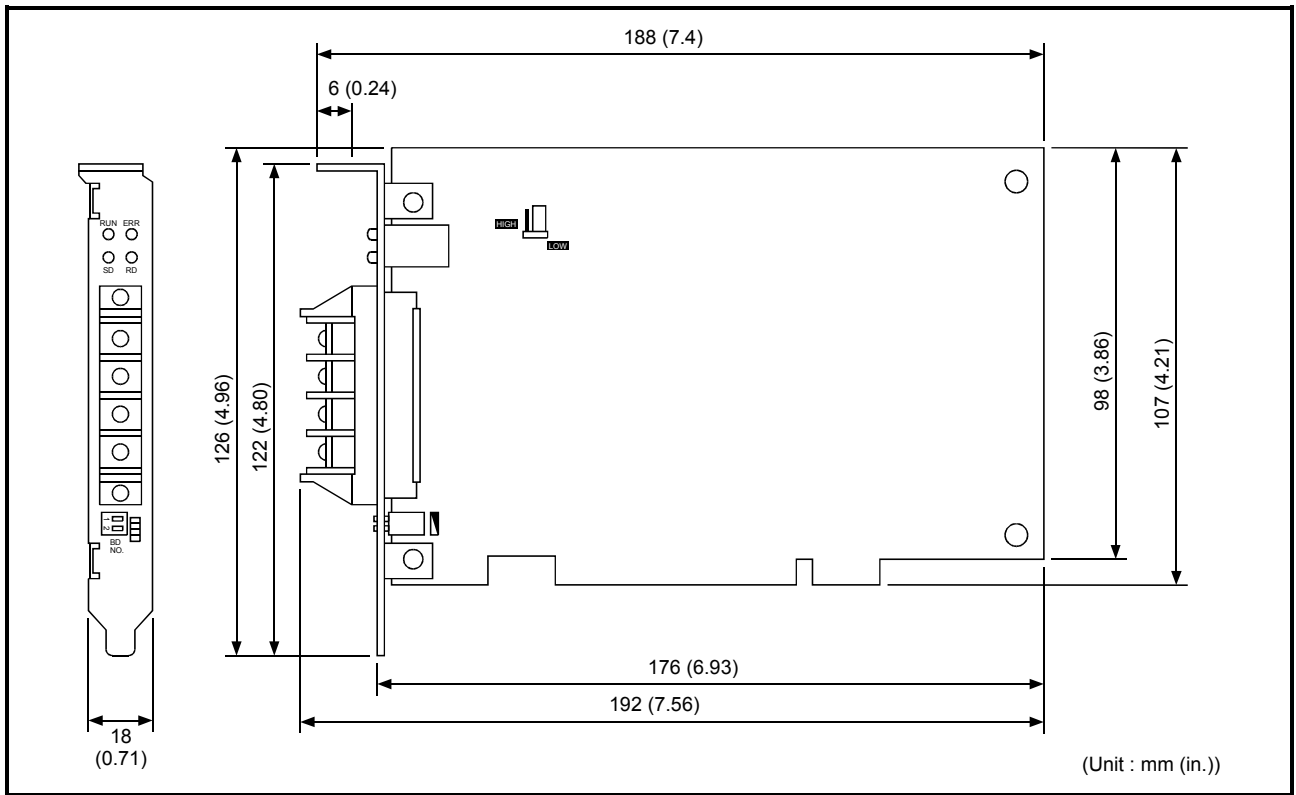
- "Error code returned to request source during communication with CPU module" in the QCPU User's Manual (Hardware Design, Maintenance and Inspection).

When a CC-Link board error or module error occurs

- Type A80BD-J61BT11 CC-Link System Master/Local Interface Board User's Manual (For SW4DNF-CCLINK-B)
- CC-Link System Master/Local Module User's Manual

*2: Perform retry processing as necessary according to the system specifications.

Appendix 2 External Dimensions



WARRANTY

Please confirm the following product warranty details before using this product.

1. Gratis Warranty Term and Gratis Warranty Range

If any faults or defects (hereinafter "Failure") found to be the responsibility of Mitsubishi occurs during use of the product within the gratis warranty term, the product shall be repaired at no cost via the sales representative or Mitsubishi Service Company.

However, if repairs are required onsite at domestic or overseas location, expenses to send an engineer will be solely at the customer's discretion. Mitsubishi shall not be held responsible for any re-commissioning, maintenance, or testing on-site that involves replacement of the failed module.

[Gratis Warranty Term]

The gratis warranty term of the product shall be for one year after the date of purchase or delivery to a designated place.

Note that after manufacture and shipment from Mitsubishi, the maximum distribution period shall be six (6) months, and the longest gratis warranty term after manufacturing shall be eighteen (18) months. The gratis warranty term of repair parts shall not exceed the gratis warranty term before repairs.

[Gratis Warranty Range]

- (1) The range shall be limited to normal use within the usage state, usage methods and usage environment, etc., which follow the conditions and precautions, etc., given in the instruction manual, user's manual and caution labels on the product.
- (2) Even within the gratis warranty term, repairs shall be charged for in the following cases.
 1. Failure occurring from inappropriate storage or handling, carelessness or negligence by the user. Failure caused by the user's hardware or software design.
 2. Failure caused by unapproved modifications, etc., to the product by the user.
 3. When the Mitsubishi product is assembled into a user's device, Failure that could have been avoided if functions or structures, judged as necessary in the legal safety measures the user's device is subject to or as necessary by industry standards, had been provided.
 4. Failure that could have been avoided if consumable parts (battery, backlight, fuse, etc.) designated in the instruction manual had been correctly serviced or replaced.
 5. Failure caused by external irresistible forces such as fires or abnormal voltages, and Failure caused by force majeure such as earthquakes, lightning, wind and water damage.
 6. Failure caused by reasons unpredictable by scientific technology standards at time of shipment from Mitsubishi.
 7. Any other failure found not to be the responsibility of Mitsubishi or that admitted not to be so by the user.

2. Onerous repair term after discontinuation of production

(1) Mitsubishi shall accept onerous product repairs for seven (7) years after production of the product is discontinued.

Discontinuation of production shall be notified with Mitsubishi Technical Bulletins, etc.

(2) Product supply (including repair parts) is not available after production is discontinued.

3. Overseas service

Overseas, repairs shall be accepted by Mitsubishi's local overseas FA Center. Note that the repair conditions at each FA Center may differ.

4. Exclusion of loss in opportunity and secondary loss from warranty liability

Regardless of the gratis warranty term, Mitsubishi shall not be liable for compensation of damages caused by any cause found not to be the responsibility of Mitsubishi, loss in opportunity, lost profits incurred to the user by Failures of Mitsubishi products, special damages and secondary damages whether foreseeable or not, compensation for accidents, and compensation for damages to products other than Mitsubishi products, replacement by the user, maintenance of on-site equipment, start-up test run and other tasks.

5. Changes in product specifications

The specifications given in the catalogs, manuals or technical documents are subject to change without prior notice.

6. Product application

- (1) In using the Mitsubishi MELSEC programmable logic controller, the usage conditions shall be that the application will not lead to a major accident even if any problem or fault should occur in the programmable logic controller device, and that backup and fail-safe functions are systematically provided outside of the device for any problem or fault.
- (2) The Mitsubishi programmable logic controller has been designed and manufactured for applications in general industries, etc. Thus, applications in which the public could be affected such as in nuclear power plants and other power plants operated by respective power companies, and applications in which a special quality assurance system is required, such as for Railway companies or Public service purposes shall be excluded from the programmable logic controller applications.

In addition, applications in which human life or property that could be greatly affected, such as in aircraft, medical applications, incineration and fuel devices, manned transportation, equipment for recreation and amusement, and safety devices, shall also be excluded from the programmable logic controller range of applications.

However, in certain cases, some applications may be possible, providing the user consults their local Mitsubishi representative outlining the special requirements of the project, and providing that all parties concerned agree to the special circumstances, solely at the users discretion.

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Type A80BDE-J61BT13 CC-Link System
Local Interface Board

User's Manual (For SW4DNF-CCLINK-B)

MODEL	A80BDBT13-SW4-U-E
MODEL CODE	13JR29
IB(NA)-0800176-H(0606)MEE	

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Specifications subject to change without notice.