

# Programmable Controller



# MELSEC iQ-F FX5 User's Manual (SLMP)

Ethernet module

-FX5-ENET

-FX5-ENET/IP

CC-Link IE TSN master/local module

-FX5-CCLGN-MS

CC-Link IE Field Network module

-FX5-CCLIEF

Motion module

-FX5-40SSC-G

-FX5-80SSC-G

## SAFETY PRECAUTIONS

(Read these precautions before use.)

Before using this product, please read this manual and the relevant manuals introduced in this manual carefully and pay full attention to safety in order to handle the product correctly.

This manual classifies the safety precautions into two categories: [ WARNING] and [ CAUTION].

# **WARNING**

Indicates that incorrect handling may cause hazardous conditions, resulting in death or severe injury.

# **A** CAUTION

Indicates that incorrect handling may cause hazardous conditions, resulting in minor or moderate injury or property damage.

Depending on the circumstances, procedures indicated by [ ( CAUTION] may also cause severe injury. It is important to follow all precautions for personal safety.

Store this manual in a safe place so that it can be read whenever necessary. Always forward it to the end user.

## [DESIGN PRECAUTIONS]

# **MARNING**

- Make sure to set up the following safety circuits outside the PLC to ensure safe system operation
  even during external power supply problems or PLC failure. Otherwise, malfunctions may cause
  serious accidents.
  - (1) Note that when the CPU module detects an error, such as a watchdog timer error, during self-diagnosis, all outputs are turned off. Also, when an error that cannot be detected by the CPU module occurs in an input/output control block, output control may be disabled. External circuits and mechanisms should be designed to ensure safe machinery operation in such a case.
- Do not write any data to the "system area" of the buffer memory in an intelligent function module.
   Doing so may cause malfunction of the programmable controller system.
- When executing control (data change) to a running other station programmable controller by connecting the external device to the SLMP compatible device, configure interlock circuits in the program of the other station programmable controller to ensure that the entire system operates safely at any time.
  - For other controls to a running other station programmable controller (such as program modification or operating status change), read relevant manuals carefully and ensure the safety before the operation. Especially, in the case of a control from an external device to a remote other station programmable controller, immediate action cannot be taken for a problem on the programmable controller due to a communication failure.
  - Determine the handling method as a system when communication failure occurs along with configuration of interlock circuit on other station PLC program, by considering external equipment and other station PLC.
- Do not write any data into the "system area" or "write protect area" of the buffer memory in the SLMP compatible device or intelligent function module. Also, do not output (ON) any "use prohibited" signals among the signals which are output to the SLMP compatible device and intelligent function device. Executing data writing to the "system area" or "write protect area", or outputting "use prohibited" signals may cause malfunction of the programmable controller alarm.

## [SECURITY PRECAUTIONS]

# **!** WARNING

To maintain the security (confidentiality, integrity, and availability) of the programmable controller and the system against unauthorized access, denial-of-service (DoS) attacks, computer viruses, and other cyberattacks from unreliable networks and devices via network, take appropriate measures such as firewalls, virtual private networks (VPNs), and antivirus solutions.

## [STARTUP AND MAINTENANCE PRECAUTIONS]

# **!** WARNING

- Before modifying the program in operation, forcible output, running or stopping the PLC, read through this manual carefully, and ensure complete safety. An operation error may damage the machinery or cause accidents.
- Do not change the program in the PLC from two or more peripheral equipment devices at the same time. (i.e. from an engineering tool and a GOT)
   Doing so may cause destruction or malfunction of the PLC program.

## [STARTUP AND MAINTENANCE PRECAUTIONS]

# **CAUTION**

 Read relevant manuals carefully and ensure the safety before performing online operations (operation status change) with peripheral devices connected to the running SLMP compatible device or CPU modules of other stations. Improper operation may damage machines or cause accidents.

# INTRODUCTION

This manual explains the specifications and settings related to the SLMP function of the MELSEC iQ-F Series. It should be read and understood before attempting to install or use the module. Always forward it to the end user.

#### Regarding use of this product

- This product has been manufactured as a general-purpose part for general industries, and has not been designed or manufactured to be incorporated in a device or system used in purposes related to human life.
- Before using the product for special purposes such as nuclear power, electric power, aerospace, medicine or passenger movement vehicles, consult Mitsubishi Electric.
- This product has been manufactured under strict quality control. However when installing the product where major accidents or losses could occur if the product fails, install appropriate backup or failsafe functions in the system.

#### Note

- If in doubt at any stage during the installation of the product, always consult a professional electrical engineer who is qualified and trained to the local and national standards. If in doubt about the operation or use, please consult the nearest Mitsubishi Electric representative.
- Since the examples indicated by this manual, technical bulletin, catalog, etc. are used as a reference, please use it after
  confirming the function and safety of the equipment and system. Mitsubishi Electric will accept no responsibility for actual
  use of the product based on these illustrative examples.
- · This manual content, specification etc. may be changed without a notice for improvement.
- The information in this manual has been carefully checked and is believed to be accurate; however, if you notice a doubtful point, an error, etc., please contact the nearest Mitsubishi Electric representative. When doing so, please provide the manual number given at the end of this manual.

# **CONTENTS**

SAFE	ETY PRECAUTIONS	
	RODUCTION	
	EVANT MANUALS	
	MS	
	NERIC TERMS AND ABBREVIATIONS	
<b>-</b>		
CHA	APTER 1 OUTLINE	8
1.1	Outline of SLMP	
1.2	Features of SLMP	10
CHA	APTER 2 SLMP DATA COMMUNICATION	12
2.1	Type and Application of the Data Communication Frame	12
2.2	Allowable Access Range of Each Data Communication Frame	13
	SLMP frame	
	Access range	13
2.3	Concept of Control Procedure of SLMP	13
2.4	Access Timing of the Ethernet-equipped Module Side	14
2.5	Transfer Time	15
CHA	APTER 3 MESSAGE FORMAT	16
3.1	3E Frame	16
	Message format and control procedure	16
	Application data specification items.	23
	Transfer data in character area	29
	Character areas	34
3.2	1E Frame	41
	Message format and control procedure	
	Application data specification items.	
	Transfer data in character area	48
	Character areas	
CHA	APTER 4 3E FRAME COMMANDS	57
4.1	List of Commands and Functions	
4.2	Device Access	
	Commands	
	Device range	
	Device Read (Batch)	
	Device Write (Batch)	73
	Device Read Random	76
	Device Write Random	
	Device Read Block	89
	Device Write Block	
4.3	Remote Control	104
	Before the remote operation	
	Remote RUN	
	Remote STOP	106
	Remote PAUSE	106
	Remote latch clear	

	Remote RESET	108
	Processor type read	109
4.4	Clear Error	112
4.5	Self-Test	
4.6	Remote Password Unlock or Lock	115
	Lock	116
	Unlock	117
CHA	APTER 5 1E FRAME COMMANDS	119
5.1	List of Commands and Functions	119
5.2	Device Access	
	Commands	120
	Device range	121
	Batch Reading	122
	Batch Writing	125
	Test (Random Write)	127
5.3	Remote Control	132
	Before the remote operation	132
	Remote RUN	132
	Remote STOP	133
5.4	Read PC Type Name	134
5.5	Loopback Test	135
CHA	APTER 6 TROUBLESHOOTING	137
APF	PENDIX	139
Appe	endix 1 Device Memory Extension Specification	139
	Access to module access device	139
	Access with indirect specification of the device No. by using index register or long index regis	ter 142
	Access with indirect specification of the device No. by using the values stored in word device	147
Appe	endix 2 Command Comparison between MC Protocol and SLMP	150
Appe	endix 3 CPU Module Processing Time of SLMP	151
Appe	endix 4 Added and Enhanced Functions	
IND	EX	156
DE\/	ISIONS	150
	RRANTY	
	DEMARKS	
	<del>&gt; = 171/1 11 11 12</del>	

# **RELEVANT MANUALS**

Manual name <manual number=""></manual>	Description
MELSEC iQ-F FX5S/FX5UJ/FX5U/FX5UC User's Manual (Hardware) <sh-082452eng></sh-082452eng>	Describes the details of hardware of the FX5 CPU module, including performance specifications, wiring, installation, and maintenance.
MELSEC iQ-F FX5 User's Manual (Application) <jy997d55401></jy997d55401>	Describes the basic knowledge required for program design, functions of the CPU module, devices/labels, and parameters.
MELSEC iQ-F FX5 Programming Manual (Program Design) <jy997d55701></jy997d55701>	Describes the specifications of ladder, ST, FBD/LD, and SFC programs, and labels.
MELSEC iQ-F FX5 Programming Manual (Instructions, Standard Functions/Function Blocks) <jy997d55801></jy997d55801>	Describes the specifications of instructions and functions that can be used in programs.
MELSEC iQ-F FX5 User's Manual (Ethernet Communication) <jy997d56201></jy997d56201>	Describes the Ethernet communication function of the CPU module built-in and the Ethernet module.
MELSEC iQ-F FX5 User's Manual (SLMP) <jy997d56001> (This manual)</jy997d56001>	Explains methods for the device that is communicating with the CPU module by SLMP to read and write the data of the CPU module.
GX Works3 Operating Manual <sh-081215eng></sh-081215eng>	Describes the system configuration, parameter settings, and online operations of GX Works3.

# **TERMS**

Unless otherwise specified, this manual uses the following terms.

For details on the FX3 devices that can be connected with the FX5, refer to the User's Manual (Hardware) of the CPU module to be used.

Term	Description				
Engineering tool	The product name of the software package for the MELSEC programmable controllers				
Own station	own station indicates the station directly connected to external device.  Own station indicates a station connected to the own station on the network.				
Other station	External device Other station				
	Own station Networks Other station				
Relay station	A station that includes two or more network modules. Transient transmission is performed through this station to stations on other networks.				
Buffer memory	Memory areas of intelligent function modules and SLMP-compatible devices for storing setting values and monitor values.				

# **GENERIC TERMS AND ABBREVIATIONS**

Unless otherwise specified, this manual uses the following generic terms and abbreviations.

Generic term/abbreviation	Description
Ethernet-equipped module	A generic term for the following modules when the Ethernet function is used:  • CPU module  • FX5-ENET  • FX5-ENET/IP
Ethernet module	A generic term for FX5-ENET and FX5-ENET/IP
FX5	A generic term for FX5S, FX5UJ, FX5U, and FX5UC programmable controllers
FX3	A generic term for FX3S, FX3G, FX3GC, FX3U, and FX3UC programmable controllers
FX5 CPU module	A generic term for FX5S CPU module, FX5UJ CPU module, FX5U CPU module, and FX5UC CPU module
FX5S CPU module	A generic term for FX5S-30MR/ES, FX5S-40MR/ES, FX5S-60MR/ES, FX5S-80MR/ES*1, FX5S-30MT/ES, FX5S-40MT/ES, FX5S-60MT/ES, FX5S-80MT/ESS, FX5S-80MT/ESS, FX5S-60MT/ESS, FX5S-60MT/ESS, FX5S-80MT/ESS*1
FX5UJ CPU module	A generic term for FX5UJ-24MR/ES, FX5UJ-24MT/ES, FX5UJ-24MT/ESS, FX5UJ-40MR/ES, FX5UJ-40MT/ESS, FX5UJ-60MR/ES, FX5UJ-60MT/ESS, FX5UJ-60MT/ESS, FX5UJ-60MT/ESS
FX5U CPU module	A generic term for FX5U-32MR/ES, FX5U-32MT/ES, FX5U-32MT/ESS, FX5U-64MR/ES, FX5U-64MT/ES, FX5U-64MT/ESS, FX5U-80MR/ES, FX5U-80MT/ES, FX5U-80MT/ESS, FX5U-32MT/DS, FX5U-32MT/DSS, FX5U-64MR/DS, FX5U-64MT/DS, FX5U-64MT/DSS, FX5U-80MT/DS, FX5U-80MT/DSS, FX5U-80MT/DSS
FX5UC CPU module	A generic term for FX5UC-32MT/D, FX5UC-32MT/DSS, FX5UC-64MT/D, FX5UC-64MT/DSS, FX5UC-96MT/D, FX5UC-96MT/DSS, FX5UC-32MT/DS-TS, FX5UC-32MT/DS-TS, and FX5UC-32MR/DS-TS
GX Works3	The product name of the software package, SWnDND-GXW3, for the MELSEC programmable controllers (The 'n' represents a version.)
MC protocol	The abbreviation for the MELSEC communication protocol.  A protocol for accessing MC protocol-compatible devices and programmable controllers that are connected to MC protocol-compatible devices from external devices.
SLMP	The abbreviation for Seamless Message Protocol.  A protocol for accessing SLMP-compatible devices and programmable controllers that are connected to SLMP-compatible devices from external devices.
SLMP-compatible device	A generic term for devices that can receive SLMP messages
Intelligent module	The abbreviation for intelligent function modules
Intelligent function module	A generic term for FX5 intelligent function modules and FX3 intelligent function modules
External device	A generic term for devices of communication target (such as personal computer, HMI)
Module access device	A generic term for the module access devices of the MELSEC iQ-R series/MELSEC iQ-F series and intelligent function module devices of the MELSEC-Q/L series

<sup>\*1</sup> Area-specific model

# 1 OUTLINE

This manual describes the compatible devices, access ranges, communication procedures, and message formats of the SLMP.

When transferring data using SLMP, always refer to Page 12 SLMP DATA COMMUNICATION.

# 1.1 Outline of SLMP

SLMP is a protocol used for access from a Ethernet-equipped module or an external device (such as a personal computer or an HMI) to an SLMP compatible device through Ethernet.

SLMP communications are available among devices that can transfer messages by SLMP.

The Ethernet port of the Ethernet-equipped module can be used as a server of SLMP. The Ethernet port of the CPU module can be used as a client of SLMP.

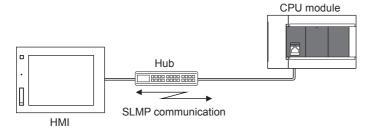
The message format of SLMP is 3E/1E frames.

For the versions of modules that are compatible with 1E frames, refer to the following. Fage 153 Added and Enhanced Functions

[Server function]

The CPU module performs data processing and data transfer based on a request message (command) from external devices. [Client function]

Request messages can be sent to external devices and response messages from external devices can be received by dedicated instructions. The SLMP client function is supported only for the CPU module, and the SLMP frame transmission is supported only for the 3E frame.





The message format of each SLMP is the same as that of the following MC protocols frames.

- 3E frame: QnA compatible 3E frame of MC protocol
- 1E frame: A compatible 1E frame of MC protocol

The external devices used with the above MC protocols can be connected to SLMP compatible devices.

For details on MC protocol, refer to the following manual.

MELSEC Communication Protocol Reference Manual

#### **Applications**

- · Device data in a Ethernet-equipped module can be written or read from a personal computer or an HMI by using SLMP.
- Writing and reading the device allows operation monitoring, data analyzing, and production managing of a Ethernetequipped module by a personal computer or an HMI.
- External illegal access can be prevented by the remote password function.

#### **Data communication procedures**

The following shows the flow for starting SLMP communication. For details, refer to MELSEC iQ-F FX5 User's Manual (Ethernet Communication).

1. Connecting cables and external devices

Make the connections for SLMP communication.

2. Setting parameters

Configure the module parameters with the engineering tool.

**3.** Writing to the Ethernet-equipped module

Write the parameters set in the Ethernet-equipped module. Turn power OFF  $\rightarrow$  ON or perform reset to enable the parameters.

**4.** Initial process state check

After setting the module parameter, check if initial process of the Ethernet-equipped module is completed normally.

**5.** SLMP communication\*1

[Server function]

SLMP messages from external devices are received.

[Client function]\*2

SLMP messages are sent to external devices.

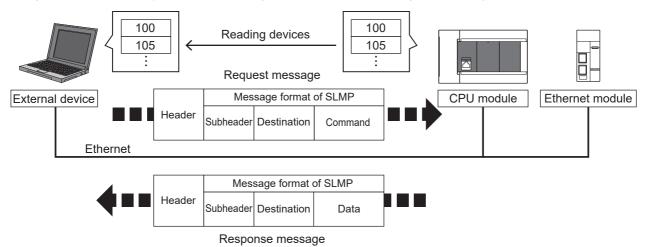
- \*1 The connection is established/disconnected by the system.
- \*2 Only 3E frame of the CPU module is supported.

## 1.2 Features of SLMP

#### System monitoring from an external device (such as personal computer, HMI)

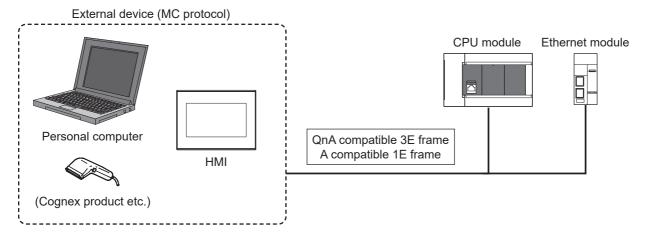
An external device can send a request message in SLMP message format to an Ethernet-equipped module to enable device read, allowing system monitoring.

Using SLMP allows not only device data reading but also device data writing and resetting an Ethernet-equipped module.



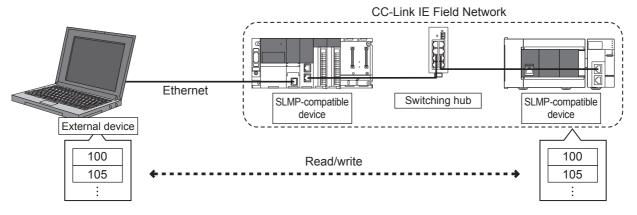
#### Connecting an external device used with MC protocol

An external device that uses the QnA compatible 3E frame of MC protocol and A compatible 1E frame of MC protocol can be connected to an Ethernet-equipped module directly.



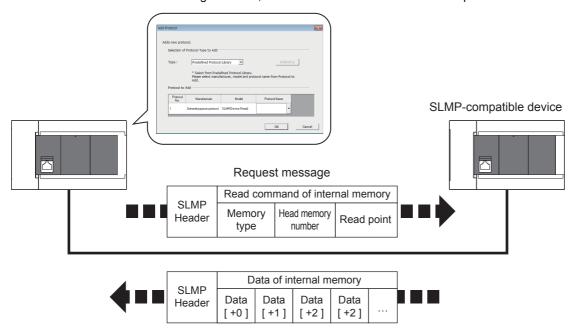
#### Access via network

SLMP allows an external device to access modules in the same network and other networks seamlessly via an SLMP compatible device.



#### Easy SLMP communication with the predefined protocol support function

SLMP communication can be easily used with the predefined protocol support function of the engineering tool. Like external devices communicating on SLMP, CPU modules can control SLMP-compatible devices.



# 2 SLMP DATA COMMUNICATION

This chapter describes the SLMP data communication by which the external equipment reads or writes data to a Ethernet-equipped module.

# 2.1 Type and Application of the Data Communication Frame

This section describes the type and application of the frame (data communication message) by which the external equipment accesses a Ethernet-equipped module with SLMP.

When the external equipment accesses a Ethernet-equipped module using Ethernet, the data communication is executed by sending or receiving a command message (access request) and response message (response) of the following frame.

Target communication method	Applicable communication frames	Communication data code	Section of control procedure	
Ethernet	• 3E frame • 1E frame	ASCII code or binary code	Page 16 MESSAGE FORMAT	



There are 2 types of ASCII code: ASCII code (X, Y OCT) and ASCII code (X, Y HEX).

The specification method of the device number for the X (input) and Y (output) to be accessed is different from each other. ( Page 65 Device Access, Page 120 Device Access)

- ASCII code (X, Y OCT): octal
- ASCII code (X, Y HEX): hexadecimal

Unless otherwise specified, the both of them are described as ASCII code.

For supported versions of ASCII code (X, Y HEX) for the FX5U/FX5UC CPU module, refer to Fage 153 Added and Enhanced Functions.

#### 3E frame

- The message format is the same as the QnA compatible 3E frame of MC protocol.
- The main purpose of the frame is to access all the devices of the Ethernet-equipped module from the external equipment.
- The frame enables access to CC-Link IE controller network and CC-Link IE field network.



When using binary codes, the communication time will decrease since the amount of communication data is reduced by approximately half comparing to using ASCII codes.

#### 1E frame

- The message format is the same as the A compatible 1E frame of MC protocol.
- · This frame is designed mainly to facilitate access to Ethernet-equipped module devices from the external equipment.



The communication time of 1E frame is shorter than 3E frame because the amount of communication data by the 1E frame is smaller compared to 3E frame.

# 2.2 Allowable Access Range of Each Data Communication Frame

The following shows the frame and access range of a message used in SLMP.

#### **SLMP** frame

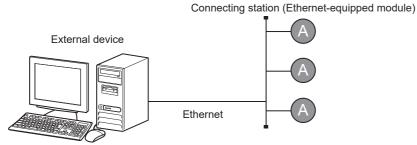
Frame	Type of the network which connects the external device with the connecting stations	Reference
Ethernet communication frame (3E/1E frame)	Ethernet	Page 16 MESSAGE FORMAT

### Access range

#### **Ethernet communication frame**

#### ■When the external device is connected directly with the Ethernet-equipped module via Ethernet

In the following system configuration, communication with the Ethernet-equipped module is possible using the Ethernet communication frame from the external device.



Assigned symbol	Description
A	Station directly connected to the external device

# 2.3 Concept of Control Procedure of SLMP

This section describes the concept of the procedure (control procedure) when the external equipment accesses a Ethernetequipped module with SLMP.

#### Sending a command message

Data communication using SLMP communication is executed in half-duplex communication.

To access the Ethernet-equipped module, send the next command message after receiving a response message for the preceding command message from the Ethernet-equipped module.

(Until the receiving of the response message is completed, the next command message cannot be sent.)



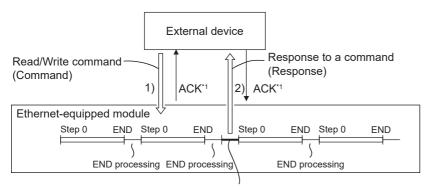
#### When a response message of completion for a command message cannot be received

When a response message of completion with an error is received, take corrective actions depending on the error code in the response message.

# 2.4 Access Timing of the Ethernet-equipped Module Side

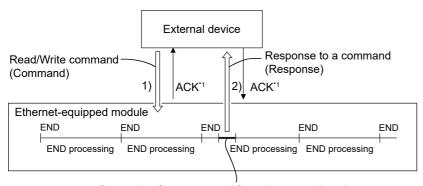
The following shows the access timing of the Ethernet-equipped module side when the Ethernet port of the Ethernet-equipped module is accessed from the external device.

RUN



Processing for a command from the external equipment

STOP



Processing for a command from the external equipment

- \*1 ACK shown in the figure is a response which is sent or received between the Ethernet-equipped module and external equipment (a response for receiving a massage) when the Ethernet-equipped module is accessed from the external equipment using TCP/IP communication.
  - This response is not the same as the one for the processing requested from the external equipment by a command message (processing result).
  - When access is executed using UDP/IP communication via the Ethernet port, an ACK response is not sent.
- **1.** To send a read request or a write request to the Ethernet-equipped module side from the external equipment, a command message is sent.
- 2. The Ethernet-equipped module reads or writes the data according to the description requested from the external equipment when the END instruction of the CPU module is executed and sends a response message (response) including the processing result to the external equipment of the request source.



- Access between the external equipment and Ethernet-equipped module is processed at each END
  processing when the Ethernet-equipped module is running for a command request. (The scan time
  becomes longer by the processing time of the command request.)
- When accesses are requested simultaneously to the Ethernet-equipped module from multiple external equipment, the processing requested from the external device may be on hold until several END processings take place depending on the request timing.

# 2.5 Transfer Time

This section describes the method for calculating the link time of the CPU module.



The link time of the Ethernet module varies depending on the usage of other intelligent function modules.

#### Link time

#### **■**Calculation method

Calculate the minimum processing time of the SLMP communication by the following calculation formula.

However, the processing time may become longer depending on the load of the network (how much a line is crowded), window size of each connecting device, number of connections to be used simultaneously, and system configuration. As a guideline, recognize the value calculated by the following calculation formula as the processing time when a communication is executed by only one connection.

• Minimum processing time of the SLMP communication (for batch read or batch write)

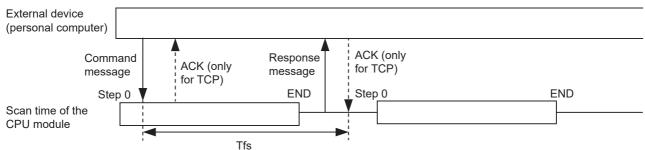
Tfs = Ke + (Kdt  $\times$  Df) + Scr  $\times$  Number of scans required for processing + ACK processing time of external equipment Tfs: Time from when the request data of a personal computer is received until the CPU module completes the processing (Unit: ms)<sup>\*1</sup>

Ke, Kdt: Constant (Refer to the following table.)

Df: Number of words of the request data + Number of words of the response data (application data part)

Scr: Scan time

\*1 The following shows the timing from when the request data of a personal computer is received until the CPU module completes the processing.



Communication description	TCP/IP communication	UDP/IP communication			
	Ke	Kdt	Ke	Kdt	
Batch read	1	0.001	1	0.001	
Batch write	1	0.001	1	0.001	



[Calculation example 1]

Time from when the request data of a personal computer is received until the processing is completed, when a TCP/IP communication is executed between personal computers and 32 points data read from the data register (D) of own station by the SLMP communication in binary code (Unit: ms)

The scan time of the mounted station is 40 ms.

Tfs = 1 +  $(0.001 \times 32)$ +40 × 1 + ACK processing time of external equipment

[Calculation example 2]

Time from when the request data of a personal computer is received until the processing is completed, when a TCP/IP communication is executed between personal computers and 32 points data written to the data register (D) of own station by the SLMP communication in binary code (Unit: ms)

The scan time of the mounted station is 40 ms.

Tfs = 1 +  $(0.001 \times 32)+40 \times 1$  + ACK processing time of external equipment

# **3** MESSAGE FORMAT

This chapter describes the message data format, the data specification method, and limitations etc. when performing SLMP data communication using the 3E frame to the Ethernet port.

Frame type	Ethernet port	Remark
3E frame	Communicable	The message format is the same as the QnA compatible 3E frame
1E frame	Communicable	The message format is the same as the A compatible 1E frame

# **3.1** 3E Frame

This section describes the message format for each command when performing the data communication using the 3E frame.

## Message format and control procedure

This section describes the message format and the control procedures when performing the data communication using the 3E frame.

#### **Data format**

The data format for communicating between the built-in Ethernet port and the external device consists of header and application data.

#### ■Request message

Header		Application data								
	Subheader	Request	Request	Request	Request	Request	Monitoring	Command	Subcommand	Request
		destination	destination	destination	destination	data	timer			data
		network	station No.	module I/O	multidrop	length				
		No.		No.	station No.					

#### **■**Response message

Header				Application	on data			
	Subheader	- 1			Request			Response
					destination	data length	code	data
		network	station No.	module I/O	multidrop			
		No.		No.	station No.			

#### Header

This header is for TCP/IP and UDP/IP.

Add the header for external equipment to Ethernet-equipped module (command message) at the external equipment side before sending the message (normally the header is added automatically).

It is not necessary to set the header for Ethernet-equipped module to external equipment (response message) by the user because the header is added by the Ethernet-equipped module automatically.

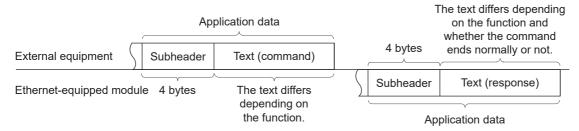
#### **Application data**

Application data is divided into subheader and text.

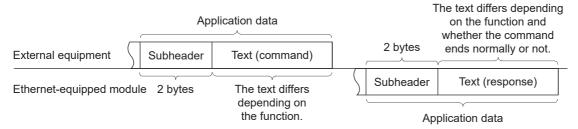
The subheader indicates whether a message is a command message or a response message. ( Page 18 Subheader configuration)

Text is the request data (command) and the response date (response) in each function. ( Page 57 3E FRAME COMMANDS)

#### **■When communicating data in ASCII code**



#### ■When communicating data in binary code





It is not necessary to set the response to a command from the external equipment by the user because the response is created and sent by the Ethernet-equipped module.

#### Subheader configuration

This section describes the subheader configuration.

#### **■**When communicating data in ASCII code

Com	mano	d me	ssag	e	Resp	onse	mes	ssage
5	0	0	0		D	0	0	0
35H	30H	30H	30H		44H	30H	30H	30H

#### ■When communicating data in binary code



#### **Control procedure**

This section describes the control procedures and the format of the application data when performing the data communication.

The  $\square$  (Thick line) part shown in the message explanation diagram (  $\square$  Page 65 Device Access) of this section are items common to all commands and correspond to the \* portion of the message explanation diagrams indicated in this chapter. For the data contents and the data specification method of the  $\square$  (Thick line) part, refer to  $\square$  Page 23 Application data specification items.



Data code (ASCII/binary) to be used when communicating, it is determined by the parameters of the GX Works3.

[CPU module]

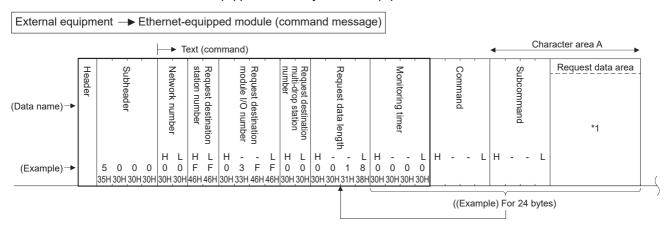
Navigation window ⇒ [Parameter] ⇒ Module model ⇒ [Module Parameter] ⇒ [Ethernet Port] ⇒ [Basic Settings] ⇒ [Own Node Settings] ⇒ "Communication Data Code"

[Ethernet module]

Navigation window ⇒ [Parameter] ⇒ [Module Information] ⇒ [FX5-ENET] or [FX5-ENET/IP] ⇒ [Basic Settings] ⇒ [Own Node Settings] ⇒ "Communication Data Code"

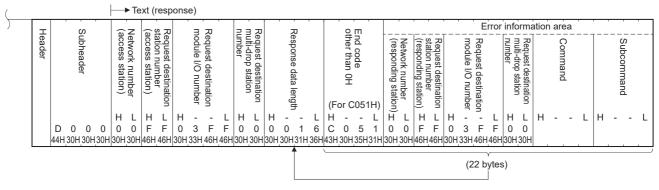
#### **■When communicating data in ASCII code**

• When data is read from a Ethernet-equipped module by external equipment



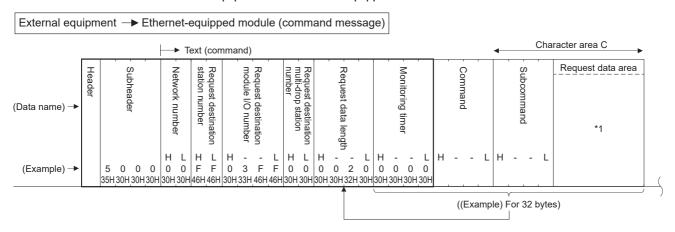
Ethernet-equipped module → External equipment (response message) (When completed normally) Character area B Text (response) Request destination multi-drop station number Response data area End code Heade module I/O number Request destination Response data length Subheader Network number Request destination station number \*1 L 0 H F L F H 0 3 -F L F H 0 L 0 H 0 0 0 L C H - -0 0 0 0 D 0 0 0 30H 33H 46H 46H 30H 30H 30H 30H 30H 43H 30H 30H 30H 30H ((Example) For 12 bytes)

(When completed with error)



<sup>\*1</sup> The order of data items differs depending on the command or subcommand. For details, refer to 🖙 Page 65 Device Access.

• When data is written from external equipment to a Ethernet-equipped module



(Whe	en c	omp	lete	ed no	rm ⊢—	•	,	(res	pons	se)												
	Header	·	Subheader		Network Hallinger	Plotopric pumphor	station number	Request destination		module I/O number	Request destination			Request destination		Nesponse data length			,	End code	, i i i i	
			•	0 0 0H <u>,</u> 30H	H 0 30H	0 30H	H F 46H	F 46H	0 30H	- 3 33H	- F 46H	F 46H	H 0 30H	0 30H	H 0 30H	- 0 30H	- 0 30H	4 34H	H 0 30H	- 0 30H;	- 0 30H	0 30H
(4													t by	tes	)							

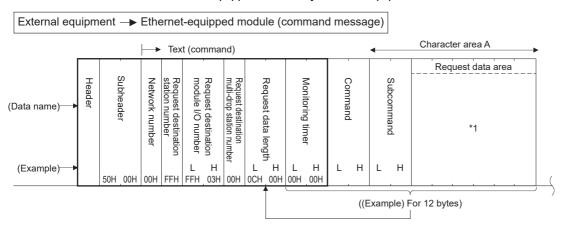
(When comp	letec	with	error)	)
------------	-------	------	--------	---

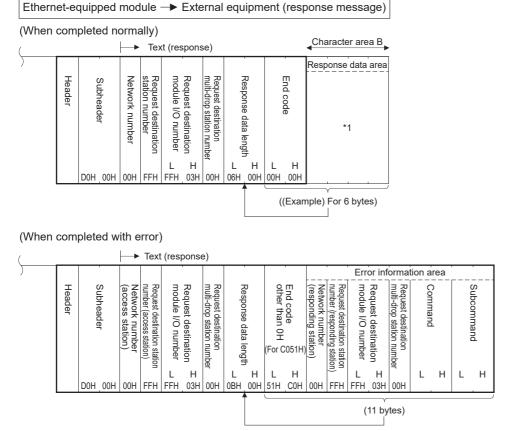
(					ŀ	-	• Te	ext (	resp	ons	e)																															
)	He		O	n .		3)	N	(a St	R		В	Z Z		ΞΞ.	Z.		٠,	ZD			0	ш								Err	or ii	nfoi	rma	tion	are	ea						
	eader		Oubileduei			(access station)	×	(access station)	Request destination		0	Request destination		number	Request destination		9	Resnonse data length		(Fo	other than 0H C	ode	H)	Request destination module I/O number Request destination station number (responding station)  Network number (responding station)				number	Request destination			Command				Subcommand						
						Н	L	Н	L	Н	-	-	L	Н	L	Н	-	-	L	Н	-	-	L	H	L	Н	L	Н	-	_	L	Н	L	Н	-	-	L	H	1 .		-	L
		D	0	0	0	0	0	F	F	0	3	F	F	0	0	0	0	1	6	С	0	5	1	0	0	F	F	0	3	F	F	0	0									
		44H	30H	30H <sub>.</sub> 3	30H	30H	30H	46H,	46H	30H	33H	46H	46H	30H	30H	30H	30H	1,31H	1,36H	43H	30H <sub>,</sub> 3	35H	1H	30H,3	30H	46H,4	16H	30H,3	33H <sub>4</sub>	16H	46H	30F	1,30H									
																													(2	2 b	ytes	s)										$\supset$

<sup>\*1</sup> The order of data items differs depending on the command or subcommand. For details, refer to 🖙 Page 65 Device Access.

#### **■When communicating data in binary code**

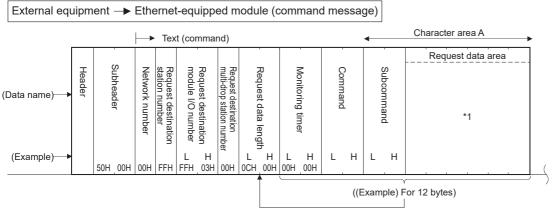
• When data is read from a Ethernet-equipped module by external equipment

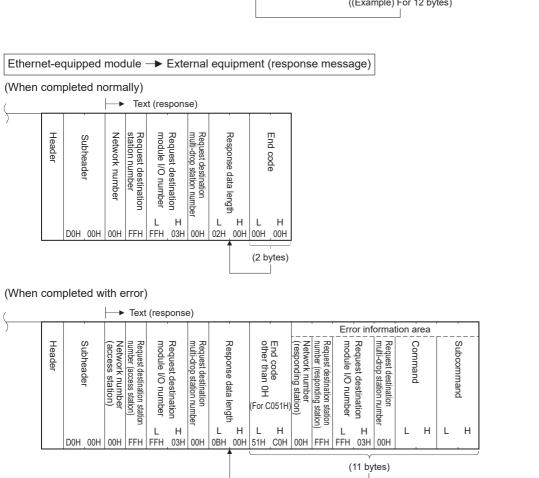




<sup>\*1</sup> The order of data items differs depending on the command or subcommand. For details, refer to 🖙 Page 65 Device Access.

• When data is written from external equipment to a Ethernet-equipped module





<sup>\*1</sup> The order of data items differs depending on the command or subcommand. For details, refer to 🖙 Page 65 Device Access.

# **Application data specification items**

This section describes the data contents and the specification method of common data items in the application data in each message when performing the data communication using the 3E frame.

#### Request destination network number and request destination station number

#### **■**Request message

Header					Applicatio	n data				
	Subheader	Request	Request	Request	Request	Request	Monitoring	Command	Subcommand	Request
		destination	destination	destination	destination	data	timer			data
		network	station No.	module I/O	multidrop	length				
		No.		No.	station No.					

#### **■**Response message

Header				Application	on data			
	Subheader	Request	Request	Request	Request	Response	End	Response
		destination	destination	destination	destination	data length	code	data
		network	station No.	module I/O	multidrop			
		No.		No.	station No.			

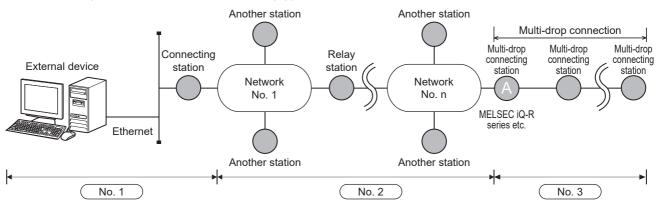
Specify the request destination network number and request destination station number to be used as an access destination in hexadecimal.

Specify the request destination network number and request destination station number according to installation conditions of access destination stations based on the following table.

Data of the response message is a value set in the request message.

No.	Access destination	Station to be specified	Request destination network number	Request destination station number
1*1	Connecting station (Within the range indicated in No. 1 in the figure below)	(Specify the fixed value indicated on the right)	00Н	FFH
2	Other stations or relay station (Within the range indicated in No. 2 in the figure below)	Access destination station	01 to EFH (1 to 239)	01 to 78H (1 to 120): Station number 7DH: Assigned control station/ Master station 7EH: Present control station/ Master station
3	Multi-drop connecting station via network (Within the range indicated in No. 3 in the figure below)	A station on the network where multi-drop connecting stations are connected (In the figure below, [A] is specified)	01 to EFH (1 to 239)	01 to 78H (1 to 120): Station number 7DH: Assigned control station/ Master station 7EH: Present control station/ Master station

<sup>\*1</sup> Please use specification No.1 to access Ethernet-equipped module.





When specifying the connecting station (network No.00H, station number FFH)



#### **Precautions**

The stations of network number 240 to 255 cannot be accessed.

Ethernet-equipped module cannot perform multi-drop connection.

Ethernet-equipped module cannot perform connection via network.

#### Request destination module I/O number

#### **■**Request message

Н	eader					Applicatio	n data		-		
		Subheader	Request	Request	Request	Request	Request	Monitoring	Command	Subcommand	Request
			destination	destination	destination	destination	data	timer			data
			network	station No.	module I/O	multidrop	length				
			No.		No.	station No.					

#### **■**Response message

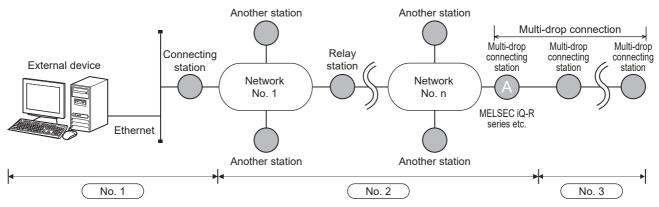
Header				Application	on data			
	Subheader	Request	Request	Request	Request	Response	End	Response
		destination	destination	destination	destination	data length	code	data
		network	station No.	module I/O	multidrop			
		No.		No.	station No.			

Select the module number of the access destination from the table below.

When the send destination of the request message is a multi-drop connecting station that is connected to the request destination station, set the I/O number (upper 3-digits) of the serial communication module which is performing the multi-drop connection.

No.	Module to be accessed*1	Request destination station Request destination module I/O number
1 <sup>*2</sup>	Own station	03FFH
2	Other station (control CPU)	03FFH
3	The module which is performing multi-drop connection with serial communication module ("A" in the figure below), which is connected to the network	0000H to 01FFH

- \*1 Ethernet-equipped module cannot perform multi-drop connection.
- \*2 Please use specification No.1 to access Ethernet-equipped module.





When specifying the own station (03FFH) as the request destination module I/O number



Request destination module I/O No.



#### Request destination multi-drop station number

#### ■Request message

Header					Applicatio	n data				
	Subheader	Request	Request	Request	Request	Request	Monitoring	Command	Subcommand	Request
		destination	destination	destination	destination	data	timer			data
		network	station No.	module I/O	multidrop	length				
		No.		No.	station No.					

#### ■Response message

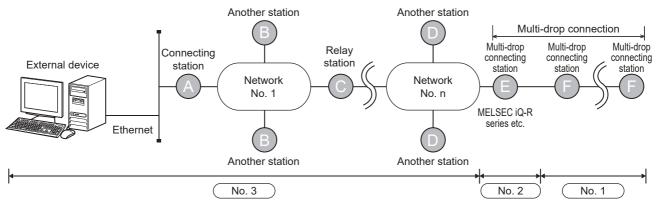
Header				Application	on data			
	Subheader	Request	Request	Request	Request	Response	End	Response
		destination d		destination	destination	data length	code	data
		network		module I/O	multidrop			
		No.		No.	station No.			

Specify the station number of the SLMP compatible device linked by the multi-drop connection in the access destination, within the range shown in the table below.

When not specifying the SLMP compatible device linked by the multi-drop connection, set 00H.

No.	Access station of external equipment	Request destination multi-drop station number
1	Stations on the multi-drop connection ("F" in the figure below)	Set the station number (00H to 1FH (0 to 31)) ("F" in the figure below)
2	A station that relays the network and the multi-drop connection ("E" in the figure below)	00H (0)
3 <sup>*1</sup>	Other than above	00H (0)

\*1 Please use specification No.3 to access Ethernet-equipped module.



When specifying 00H as the requested multi-drop station number



#### Request data length

#### **■**Request message

Head	er	Application data									
	Subheader	Request	Request	Request	Request	Request	Monitoring	Command	Subcommand	Request	
		destination	destination	destination	destination	data	timer			data	
		network	station No.	module I/O	multidrop	length					
		No.		No.	station No.						
	•		,	,		1			Υ		

Specify the total data size from the Monitoring timer to the request data in hexadecimal. (Unit: byte)



When the request data length is 24 (18H) bytes



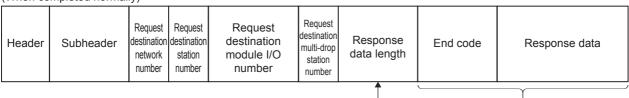


#### Response data length

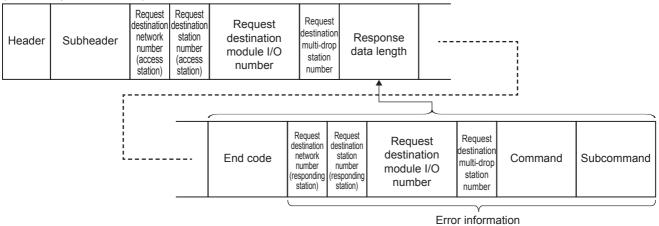
#### **■**Response message

When normally completed, the total data size from the end code to the response data is set in hexadecimal. When completed with error, the total data size from the end code to the error information is set in hexadecimal. (Unit: byte)

(When completed normally)



(When completed with error)



#### Monitoring timer

#### **■**Request message

Header		Application data										
	Subheader	Request	Request	Request	Request	Request	Monitoring	Command	Subcommand	Request		
		destination	destination	destination	destination	data	timer			data		
		network	station No.	module I/O	multidrop	length						
		No.		No.	station No.							

This timer is used to set the wait time until a response is returned after the SLMP-compatible device that has received a request message from an external device sends a processing request to the accessed device.

- 0000H (0): Indefinitely waiting (waiting until the processing is completed)
- 0001H to FFFFH (1 to 65535)\*1: Wait time (unit: 250 ms)
- \*1 Supported only for Ethernet modules.

For normal data communication, it is recommended to use this message within the setting range shown in the following table depending on the communication destination.

Access destination	Monitoring timer
Other station	01H to 28H (0.25 sec to 10 sec)



ASCII code





#### ■When communicating data in ASCII code

Sending from the upper byte to the lower byte.

#### **■**When communicating data in binary code

Sending from the lower byte to the upper byte.

#### **Precautions**

Specify "0000H" (indefinite wait) for the CPU module.

#### End code

#### **■**Response message

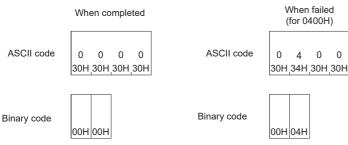
Header				Application	on data		
	Subheader	destination	destination	Request destination module I/O multidrop		End code	Response data
		No.		No.	station No.		

The command processing result is stored.

When normally completed, "0000H" is stored. When completed with error, an error code set at the request destination is stored.

(For the set error code and corresponding error contents, refer to FP Page 137 TROUBLESHOOTING and manuals of the SLMP compatible device of the response station.)





#### Request data

#### **■**Request message

Header		Application data										
	Subheader	Request	Request	Request	Request	Request	Monitoring	Command	Subcommand	Request		
		destination	destination	destination	destination	data	timer			data		
		network	station No.	module I/O	multidrop	length						
		No.		No.	station No.							

Set a command to be executed and data for the argument of the subcommand.

(Some commands and subcommands do not require the request data specification.)

For details of the request data, refer to the paragraph relating to the command to be executed. ( Page 65 Device Access)

#### Response data

#### **■**Response message

Header				Application	on data			
	Subheader	Request	Request	Request	Request	Response	End	Response
		destination		destination	destination	data length	code	data
		network	station No.	module I/O	multidrop			
		No.		No.	station No.			

The processing result of the request data is stored.

(Some commands do not return response messages.)

For details of the response data, refer to the paragraph relating to the command to be executed. (Fig. Page 65 Device Access)

#### **Error information**

The request destination network number, request destination station number, request destination module I/O number, and request destination multi-drop station number of the station which responded with errors are stored.

Numbers which differ from the requested station specified by the request message may be stored because the information of the station which responded with errors is stored.

The command and the subcommand specified by the request message of the request data are stored.

## Transfer data in character area

This section describes how to transfer bit device data and word device data and data alignment in the character area sent and received between the external equipment and the Ethernet-equipped module by using each command.

The transfer data explained below is handled as the character area A for reading and monitoring and the character area C for writing, testing, and registering the monitor data are stored.

#### **Character area**

#### **■**Request message

Header		Application data									
	Subheader	destination		destination module I/O	destination	data length	Monitoring timer	Command	Subcommand	Request data	
									Character A and		

#### **■**Response message

Header				Application	on data			
	Subheader	Request	Request	Request	Request	Response	End	Response
		destination				data length	code	data
			station No.	module I/O				
		No.		No.	station No.			
			Charac	ter area B				

#### Communicating data (when communicating in ASCII code)

#### ■When bit device memory is read or written

The bit device memory is handled in 1-bit (1-point) units or in 1-word (16-point) units.

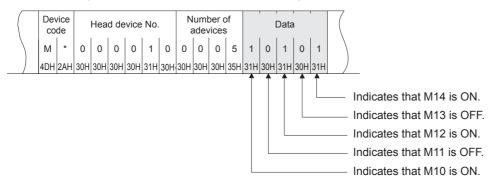
The transfer data in each case is described below.

• In 1-bit (1-point) units

When the bit device memory is handled in 1-bit units, specify 1-point (1-byte) with an ASCII code, and express "1" (31H) for ON and "0" (30H) for OFF. Specify for the number of devices starting from the head device in the order of device numbers.



When indicating the on/off status of five devices starting from M10

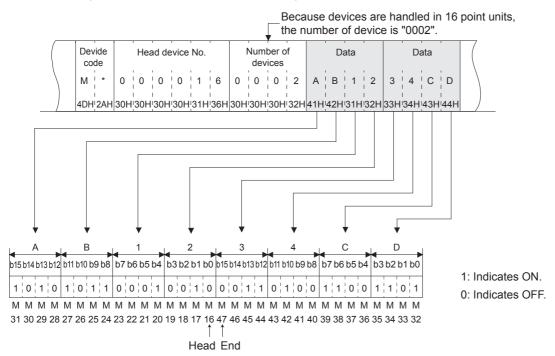


#### • In 1-word (16-point) units

When the bit device memory is handled in 1-word units, specify one word (16 bits) with a 4-digit ASCII code, and express 1-point with 1-bit ON/OFF. Specify for the number of devices starting from the head device in 1-word units in the order from the most significant bit to the least significant bit (b15 to b0).



When indicating the on/off status of 32 devices starting from M16

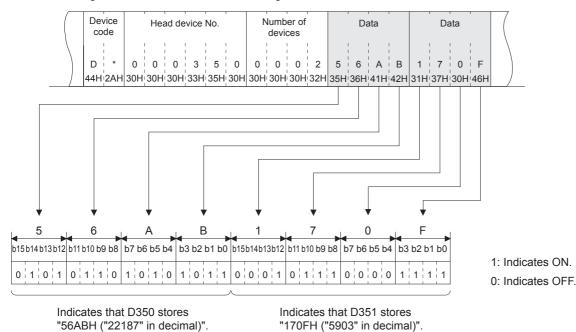


#### ■When word device memory is read or written

One word device is expressed with a 1-word (4-byte) 4-digit ASCII code (hexadecimal). Specify for the number of devices starting from the head device in 1-word units in the order from the most significant byte to the least significant byte (b15 to b0).



When indicating the contents stored in the data registers D350 and D351





Use capitalized code for alphabetical letter.

When data other than integer value (real number, character string), is stored in the word device memory for reading data, the stored value are read as integer value.

(Example 1) When a real number (0.75) is stored in D0 and D1, the value is read as the following integer value.

• D0 = 0000H, D1 = 3F40H

(Example 2) When a character string (12AB) is stored in D2 and D3, the character string is read as the following

integer value.

• D2 = 3231H, D3 = 4241H

Data in word units handled when reading and writing buffer memory areas is expressed in the same way as the word device memory.

#### Communicating data (When communicating data in binary code)

#### ■When bit device memory is read or written

The bit device memory is handled in 1-bit (1-point) units or in 1-word (16-point) units.

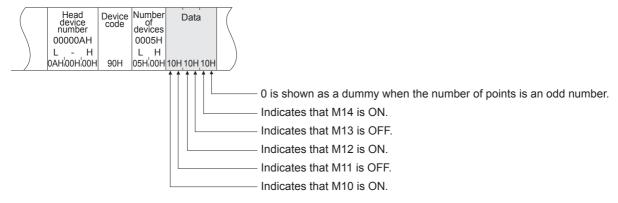
The transfer data in each case is described below.

• In 1-bit (1-point) units

When the bit device memory is handled in 1-bit units, specify 1-point, 4 bits, (two points, 1 byte) with a binary code, "1" for ON and "0" for OFF. Specify for the number of devices starting from the head device in the order of device numbers from the most significant bit.



When indicating the on/off status of five devices starting from M10

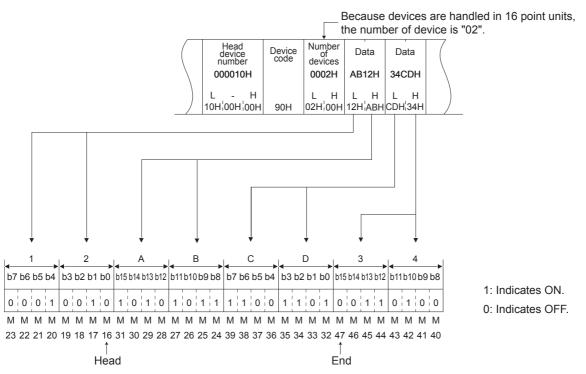


#### • In 1-word (16-point) units

When the bit device memory is handled in 1-word units, specify one word (2 bytes) with a binary code, and express 1-point with 1-bit ON/OFF. Specify for the number of devices starting from the head device in 1-word units in the order from the least significant bytes (b7 to b0) to the most significant bytes (b15 to b8).



When indicating the on/off status of 32 devices starting from M16

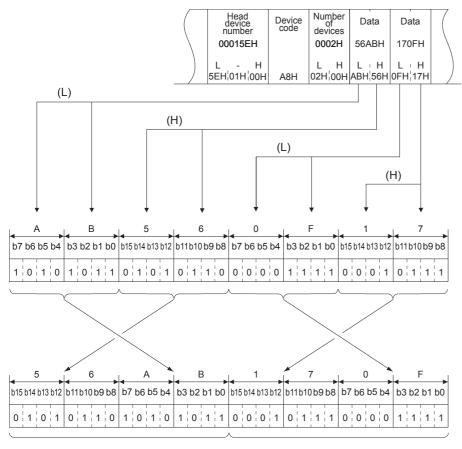


#### ■When word device memory is read or written

One word device memory is expressed with a 1-word (2-byte) 4-digit binary code (hexadecimal). Specify for the number of devices starting from the head device in 1-word units in the order from the least significant bytes (b7 to b0) to the most significant bytes (b15 to b8).



When indicating the contents stored in the data registers D350 and D351



- 1: Indicates ON.
- 0: Indicates OFF.

Indicates that D350 stores "56ABH ("22187" in decimal)".

Indicates that D351 stores "170FH ("5903" in decimal)".



When data other than integer value (real number, character string), is stored in the word device memory for reading data, the stored value are read as integer value.

(Example 1) When a real number (0.75) is stored in D0 and D1, the value is read as the following integer value.

• D0 = 0000H, D1 = 3F40H

(Example 2) When a character string (12AB) is stored in D2 and D3, the character string is read as the following integer value.

• D2 = 3231H, D3 = 4241H

Reading and writing extension file registers and buffer memory areas are performed in the same way as those of the word device memory.

## **Character areas**

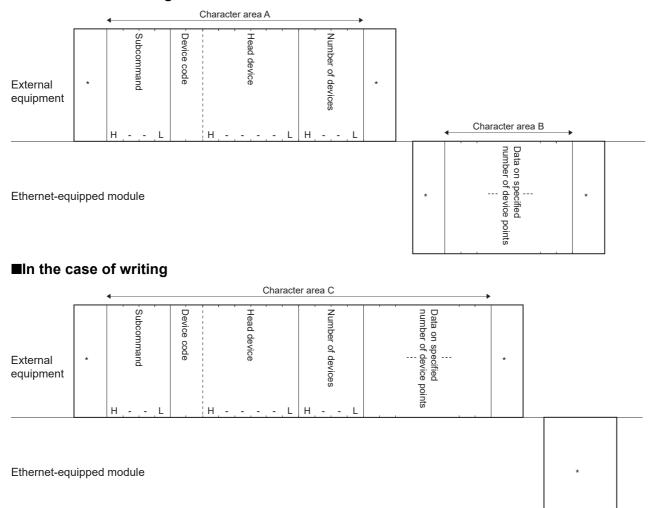
This section explains character areas in the control procedure (data area when communicating in binary code).

- Character areas differ depending on command to be used and contents to be specified. This section explains the data common to the character area when the device memory to be read or written is specified directly.
- Character area data handled only by a certain command and not by others, is explained in the section that explains the corresponding command.

#### Data of character area (when communicating in ASCII code)

The data order and contents of character areas A, B, and C are identical when the same command is used under the same conditions in the control procedure when communicating using ASCII code.

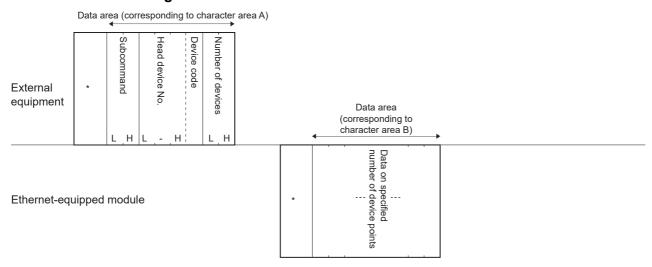
#### ■In the case of reading



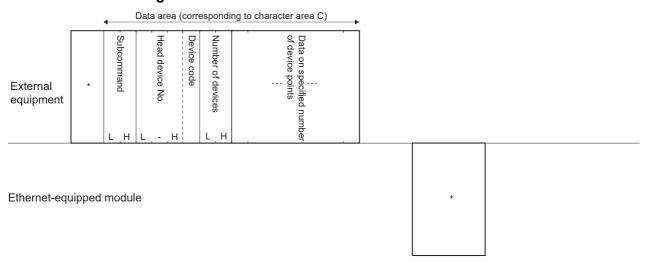
The data array and the data contents marked with \* are shown in Page 16 Message format and control procedure.

#### Data of data area (when communicating in binary code)

#### ■In the case of reading



#### ■In the case of writing



The data array and the data contents marked with \* are shown in Page 16 Message format and control procedure.

#### Data contents common to character areas

#### **■Subcommand**

Subcommands are data for specifying the unit for reading and writing, device type to be specified, and the data reading condition.

The following table shows the details of setting items.

Setting item		Description	
Data size specification	Word units	The target data is read or written in word units. Select "0" even when the reading data or writing data does not exist in arguments of the command.	
	Bit units	The target data is read or written in bit units.	
Device specification format	2 digit code/6 digit number specification	Data or items related to the address specifications are expressed in the following sizes, which are the same as the existing setting.  • Device code: 1 byte in binary  • Device number: 3 bytes in binary	
	4 digit code/8 digit number specification	Data or items related to the address specifications are extended to the following size.  • Device code: 2 byte in binary  • Device number: 4 bytes in binary	
Device memory extension specification	Not specified	Set this when specifying devices of a Ethernet-equipped module.  * Set this when not using the device memory extension specification.	
	Specified	Set this for the buffer memory specification of the intelligent function module.     This setting corresponds to the buffer memory indirect specification with index register.	

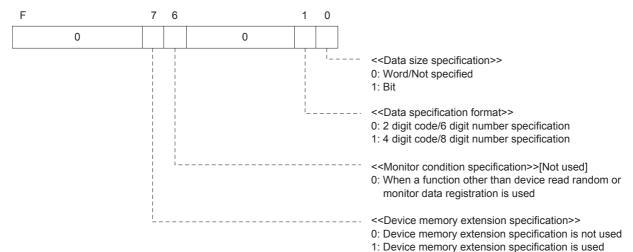
When communicating data in ASCII code

The value 0000H(0), or the following value, is converted to a 4 digit (hexadecimal) ASCII code and sequentially transmitted beginning from the most significant digit ("0").

When communicating data in binary code

The value 0000H, or the following 2-byte value, is used for transmission.

The following figure shows the specification contents of the subcommand.



- In the following cases, the subcommand is 0000H or 0001H.
- When neither monitor condition nor device memory extension is specified.
- When using a command that cannot select monitor condition specification and device memory extension specification.

#### **■**Device code

Device codes are data for identifying the device memory to be read or written.

Device codes are shown in Page 66 Device range.

When communicating data in ASCII code

Device codes are converted into 2-digit ASCII code (when word device is specified) or 4-digit ASCII code (when long device is specified), and the device codes are sequentially sent beginning from the most significant digit. Use capitalized code for alphabetical letter in ASCII code.



In the case of input (X)



The input relay device code "X\*" is sequentially sent from "X".

The second character "\*" can be specified by a space (code: 20H).

When communicating data in binary code

The data is sent with the binary codes.



#### ■Head device No. (device No.)

Data for specifying the number of the device to read data from or write data to. When specifying continuous device areas, specify the head number of the device range. Specify the head device number by the expressing method for the relevant device (octal, decimal or hexadecimal number).

For the device number and expressing method, refer to Page 66 Device range.

2 3

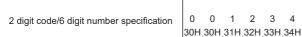
#### When communicating data in ASCII code

The device number is converted to a 6-digit ASCII code (when word device is specified) or 8-digit ASCII code (when long device is specified), and sequentially sent beginning from the most significant digit.

The "0" column of the most significant digit (in for example "001234", this refers to "0" of the first two characters) can also be specified by a space (code: 20H).



In the case of the device number is "1234"



4 digit code/8 digit number specification

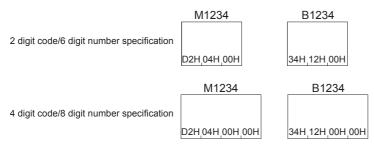


#### When communicating data in binary code

The 3-byte (2 digit code/6 digit number specification) or 4-byte (4 digit code/8 digit number specification) binary code with the device number specified by the device specification format is sequentially sent starting from the low byte. The device with decimal device number is sent after converting to hexadecimal device number.



In case of internal relay M1234 and link relay B1234



Internal relay M1234 becomes 0004D2H and is sent in the order of D2H, 04H, and 00H.

Link relay B1234 becomes 001234H and is sent in the order of 34H, 12H, and 00H.

#### **■**Number of devices

This data is for specifying the number of points to be read or written when each command is executed. It must be specified within the limits of the number of points that can be processed per communication. (Fig. Page 65 Commands)

#### When communicating data in ASCII code

Points are converted into 4-digit hexadecimal ASCII code (when word device is specified) or 8-digits ASCII code (when long device is specified) with the device number that specified by the device specification format and sequentially sent beginning from the most significant digit. Use capitalized code for alphabetical letter in ASCII code.



In the case of 5 points and 20 points



2When communicating data in binary code

Use numerical values in 2 bytes which indicate the number of points to be processed, and send them in order from the lower byte to the upper byte.



In the case of 5 points and 20 points



#### ■Data on specified number of device points

This field holds the contents of the data written to the specified device, or the contents of the data read from the specified device. The data order changes depending on the processing units (words or bits).

For the data contents and order (transmission order), refer to Fage 29 Transfer data in character area.

#### **■**Bit access points

This data is for specifying the number of points to be accessed in units of bits. It must be specified within the limits of the number of points processed per communication. ( Page 65 Commands)

When communicating data in ASCII code

The number of the bytes is converted into 2-digit ASCII code (hexadecimal) and sequentially sent beginning from the most significant digit. Use capitalized code for alphabetical letter in ASCII code.



In the case of 5 points and 20 points



When communicating data in binary code

The 1-byte value (hexadecimal), which indicates the number of the points, is used for transmission.



In the case of 5 points and 20 points



#### ■Device memory extension specification (subcommand: bit7)

For details, refer to Page 139 Device Memory Extension Specification.

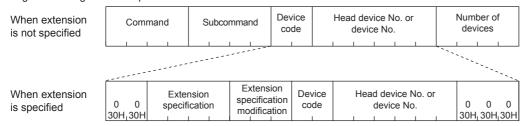
This section explains how to read or write from/to a device to/from module access device areas and how to specify a device indirectly by using index register.

#### Message format

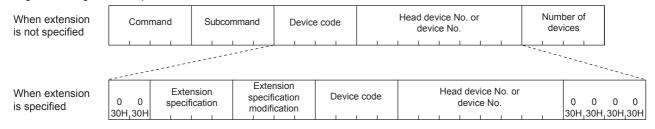
Response messages are extended as well.

#### ■When communicating data in ASCII code

#### 2 digit code/6 digit number specification

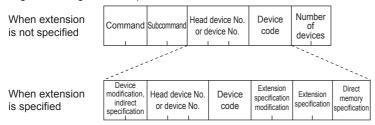


#### 4 digit code/8 digit number specification

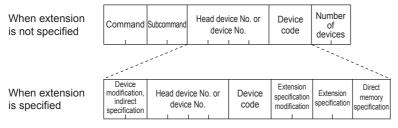


#### ■When communicating data in binary code

#### 2 digit code/6 digit number specification

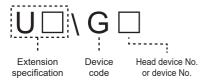


#### 4 digit code/8 digit number specification



#### 2 Module access device specification

The following shows the approach for module access device specification in programming and request data.



#### ■Extension specification

Specify the module number of intelligent function modules.

ASCII code	Binary code	
Specify the start I/O number in hexadecimal (3-digit ASCII code). When described with 4-digits, specify the start I/O number with the upper 3-digits.	Specify the module number in hexadecimal (2 bytes). When described with 4-digits, specify the module number with the upper 3-digits.	
Example 001  U	Example 001	

#### ■Device code

Specify the module access device. ( Page 66 Device range)

■Head device No. or device No.

The format is the same as the message when extension is not specified.

## 3.2 1E Frame

This section describes the message format for each command when performing the data communication using the 1E frame.

## Message format and control procedure

This section describes the message format and the control procedures when performing the data communication using the 1E frame.

#### **Data format**

The data format consists of header and application data.

#### **■**Request message

Header		Application data			
	Subheader	PC No.	Monitoring timer	Request data	

#### **■**Response message

Header	Application data			
	Subheader	End code	Response data	

#### Header

This header is for TCP/IP and UDP/IP.

Add the header for external equipment to Ethernet-equipped module (command message) at the external equipment side before sending the message (normally the header is added automatically).

It is not necessary to set the header for Ethernet-equipped module to external equipment (response message) by the user because the header is added by the Ethernet-equipped module automatically.

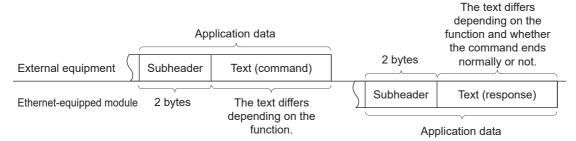
#### **Application data**

Application data is divided into subheader and text.

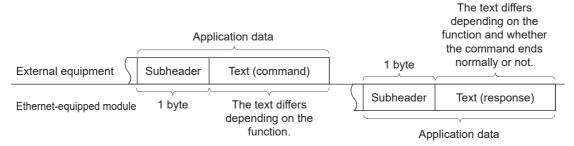
The subheader indicates whether a message is a command message or a response message. ( Page 42 Subheader configuration)

Text is the request data (command) and the response date (response) in each function. (Fig. Page 119 1E FRAME COMMANDS)

#### ■When communicating data in ASCII code



#### ■When communicating data in binary code





It is not necessary to set the response to a command from the external equipment by the user because the response is created and sent by the Ethernet-equipped module.

#### Subheader configuration

This section describes the subheader configuration.

#### ■When communicating data in ASCII code





[Command message]

Specify the command with a 2-digit ASCII code in the order from the most significant byte to the least significant byte.

[Response message]

A 2-digit ASCII code obtained by adding 8H to the most significant byte of the command from the requesting station is sent in the order from the most significant byte to the least significant byte.

#### **■**When communicating data in binary code



[Command message]

Specify the command with a 1-byte binary code.

[Response message]

A 1-byte binary code obtained by adding 80H to the command from the requesting station is cont.

#### **Precautions**

When the communication data code is an ASCII code, if data that cannot be binary converted into a subheader is specified, the data cannot be recognized as a 1E frame message, and no response message is returned.

#### Control procedure

This section describes the control procedures and the format of the application data when performing the data communication.

The  $\square$  (Thick line) part shown in the message explanation diagram of this section are items common to all commands. For the data contents and the data specification method of the  $\square$  (Thick line) part, refer to  $\square$  Page 46 Application data specification items.



Data code (ASCII/binary) to be used when communicating, it is determined by the parameters of the GX Works3.

[CPU module]

Navigation window ⇔ [Parameter] ⇔ Module model ⇔ [Module Parameter] ⇔ [Ethernet Port] ⇔ [Basic Settings] ⇔ [Own Node Settings] ⇔ "Communication Data Code"

[Ethernet module]

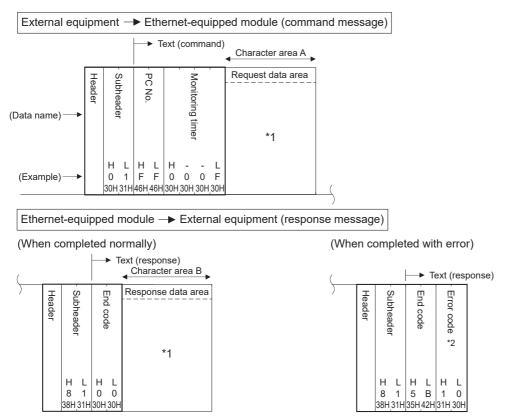
Navigation window 

□ [Parameter] 

□ [Module Information] 
□ [FX5-ENET] or [FX5-ENET/IP] 
□ [Basic Settings] 
□ [Own Node Settings] 
□ "Communication Data Code"

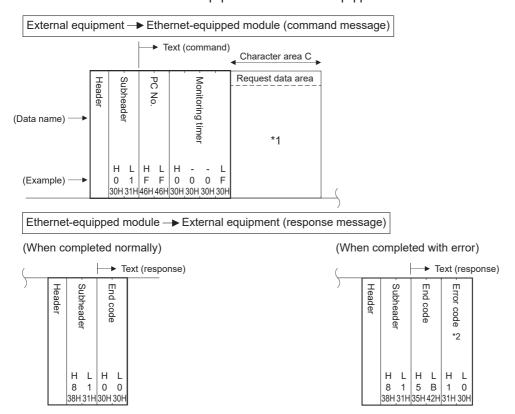
#### ■When communicating data in ASCII code

• When data is read from a Ethernet-equipped module by external equipment



- \*1 The order of data items differs depending on the command. For details, refer to 🖙 Page 120 Device Access.
- \*2 The error code is stored when the end code is "5BH."

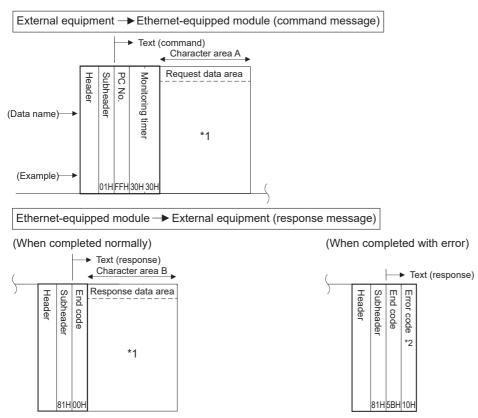
· When data is written from external equipment to a Ethernet-equipped module



- \*1 The order of data items differs depending on the command. For details, refer to 🖙 Page 120 Device Access.
- \*2 The error code is stored when the end code is "5BH."

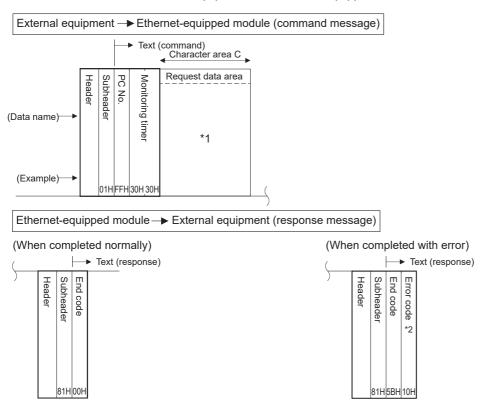
#### **■**When communicating data in binary code

• When data is read from a Ethernet-equipped module by external equipment



- \*1 The order of data items differs depending on the command. For details, refer to 🖙 Page 120 Device Access.
- \*2 The error code is stored when the end code is "5BH."

• When data is written from external equipment to a Ethernet-equipped module



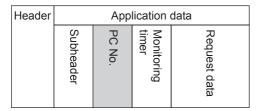
- \*1 The order of data items differs depending on the command. For details, refer to Fage 120 Device Access.
- \*2 The error code is stored when the end code is "5BH."

## **Application data specification items**

This section describes the data contents and the specification method of common data items in the application data in each message when performing the data communication using the 1E frame.

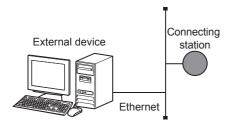
#### PC No.

#### **■**Request message



Specify the request destination PC No. to be used as an access destination in hexadecimal.

Only the connecting station (FFH) can be specified as the access destination.





When specifying the connecting station (PC No. FFH)



#### **Precautions**

When the communication data code is an ASCII code, if data that cannot be binary converted into a PC number is specified, the data cannot be recognized as a 1E frame message, and no response message is returned.

#### **Monitoring timer**

#### ■Request message

Header	Application data					
	Subheader	PC No.	Monitoring timer	Request data		

This timer is used to set the wait time until a response is returned after the SLMP-compatible device that has received a request message from an external device sends a processing request to the accessed device.

- 0000H (0): Indefinitely waiting (waiting until the processing is completed)
- 0001H to FFFFH (1 to 65535)\*1: Wait time (unit: 250 ms)
- \*1 Supported only for Ethernet modules.

For normal data communication, it is recommended to use this message within the setting range shown in the following table depending on the communication destination.

Access destination	Monitoring timer
Other station	01H to 28H (0.25 sec to 10 sec)

#### ■When communicating data in ASCII code

Sending from the upper byte to the lower byte.

#### **■When communicating data in binary code**

Sending from the lower byte to the upper byte.

#### Precautions

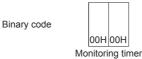
Specify "0000H" (indefinite wait) for the CPU module.



When specifying the 0000H (Unlimited wait)







#### **End code**

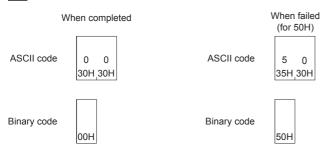
#### **■**Response message

Header	Application data			
	Subheader	End code	Response data	

The command processing result is stored.

When normally completed, "00H" is stored. When completed with error, an error code set at the request destination is stored. (For the set error code and corresponding error contents, refer to Page 137 TROUBLESHOOTING and manuals of the SLMP compatible device of the response station.)





#### Request data

#### **■**Request message

Header	Application data				
	Subheader	PC No.	Monitoring timer	Request data	

Set the data that is the argument of the command to be executed.

(Some commands do not require the request data specification.)

For details of the request data, refer to the paragraph relating to the command to be executed. ( Fage 120 Device Access)

#### Response data

#### **■**Response message

Header	Application data				
	Subheader	End code	Response data		

The processing result of the request data is stored

(Some commands do not return response messages.)

For details of the response data, refer to the paragraph relating to the command to be executed. ( Page 120 Device Access)

## Transfer data in character area

This section describes how to transfer bit device data and word device data and data alignment in the character area sent and received between the external equipment and the Ethernet-equipped module by using each command.

The transfer data explained below is handled as the character area A for reading and monitoring and the character area C for writing, testing, and registering the monitor data are stored.

#### Character area

#### **■**Request message

Header	Application data			
	Subheader	PC No.	Monitoring timer	Request data
				Character area A and C

#### **■**Response message

Header	Application data			
	End code Subheader		Response data	
			Character area B	

### Communicating data (when communicating in ASCII code)

#### ■When bit device memory is read or written

The bit device memory is handled in 1-bit (1-point) units or in 1-word (16-point) units.

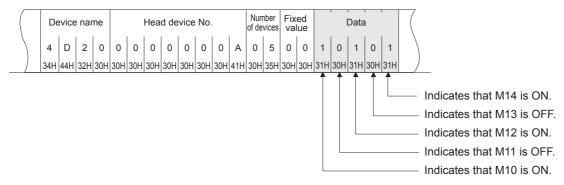
The transfer data in each case is described below.

• In 1-bit (1-point) units

When the bit device memory is handled in 1-bit units, specify 1-point (1-byte) with an ASCII code, and express "1" (31H) for ON and "0" (30H) for OFF. Specify for the number of devices starting from the head device in the order of device numbers.

Ex.

When indicating the on/off status of five devices starting from M10

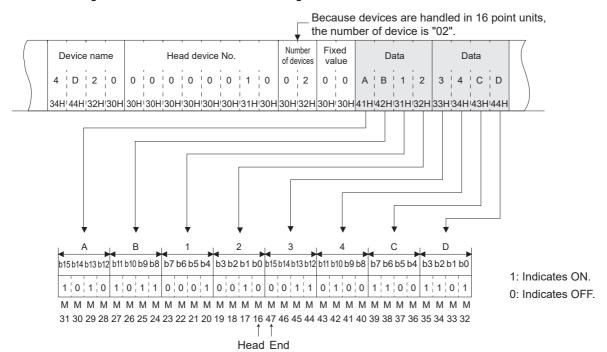


#### • In 1-word (16-point) units

When the bit device memory is handled in 1-word units, specify one word (16 bits) with a 4-digit ASCII code, and express 1-point with 1-bit ON/OFF. Specify for the number of devices starting from the head device in 1-word units in the order from the most significant bit to the least significant bit (b15 to b0).

Ex.

When indicating the on/off status of 32 devices starting from M16

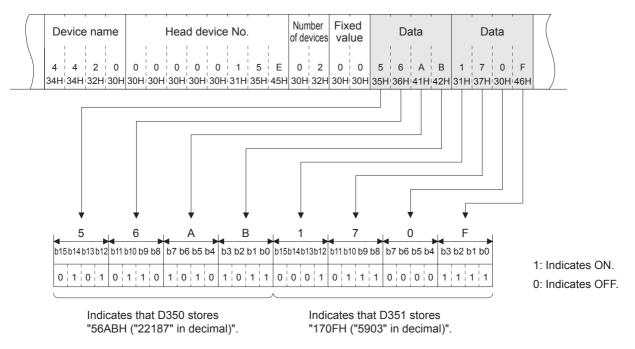


#### ■When word device memory is read or written

One word device is expressed with a 1-word (4-byte) 4-digit ASCII code (hexadecimal). Specify for the number of devices starting from the head device in 1-word units in the order from the most significant byte to the least significant byte (b15 to b0).



When indicating the contents stored in the data registers D350 and D351





Use capitalized code for alphabetical letter.

When data other than integer value (real number, character string), is stored in the word device memory for reading data, the stored value are read as integer value.

(Example 1) When a real number (0.75) is stored in D0 and D1, the value is read as the following integer value.

• D0 = 0000H, D1 = 3F40H

(Example 2) When a character string (12AB) is stored in D2 and D3, the character string is read as the following integer value.

• D2 = 3231H, D3 = 4241H

### Communicating data (When communicating data in binary code)

#### ■When bit device memory is read or written

The bit device memory is handled in 1-bit (1-point) units or in 1-word (16-point) units.

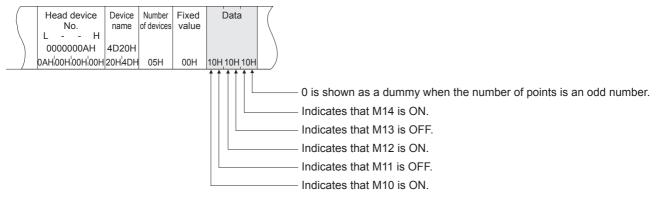
The transfer data in each case is described below.

• In 1-bit (1-point) units

When the bit device memory is handled in 1-bit units, specify 1-point, 4 bits, (two points, 1 byte) with a binary code, "1" for ON and "0" for OFF. Specify for the number of devices starting from the head device in the order of device numbers from the most significant bit.



When indicating the on/off status of five devices starting from M10

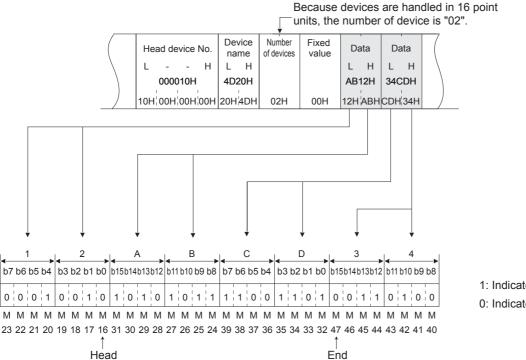


#### • In 1-word (16-point) units

When the bit device memory is handled in 1-word units, specify one word (2 bytes) with a binary code, and express 1-point with 1-bit ON/OFF. Specify for the number of devices starting from the head device in 1-word units in the order from the least significant bytes (b7 to b0) to the most significant bytes (b15 to b8).

Ex.

When indicating the on/off status of 32 devices starting from M16



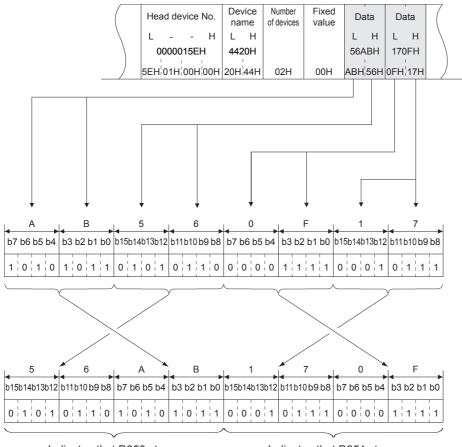
- 1: Indicates ON.
- 0: Indicates OFF.

#### ■When word device memory is read or written

One word device memory is expressed with a 1-word (2-byte) 4-digit binary code (hexadecimal). Specify for the number of devices starting from the head device in 1-word units in the order from the least significant bytes (b7 to b0) to the most significant bytes (b15 to b8).



When indicating the contents stored in the data registers D350 and D351



- 1: Indicates ON.
- 0: Indicates OFF.

Indicates that D350 stores "56ABH ("22187" in decimal)".

Indicates that D351 stores "170FH ("5903" in decimal)".



When data other than integer value (real number, character string), is stored in the word device memory for reading data, the stored value are read as integer value.

(Example 1) When a real number (0.75) is stored in D0 and D1, the value is read as the following integer value.

• D0 = 0000H, D1 = 3F40H

(Example 2) When a character string (12AB) is stored in D2 and D3, the character string is read as the following integer value.

• D2 = 3231H, D3 = 4241H

## **Character areas**

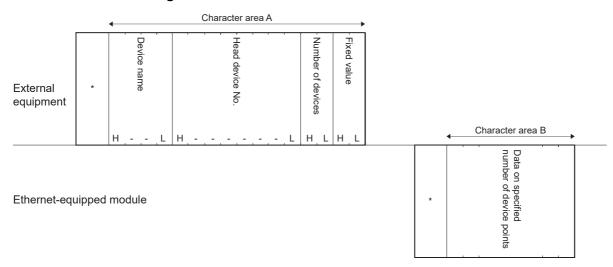
This section explains character areas in the control procedure (data area when communicating in binary code).

- Character areas differ depending on command to be used and contents to be specified. This section explains the data common to the character area when the device memory to be read or written is specified directly.
- Character area data handled only by a certain command and not by others, is explained in the section that explains the corresponding command.

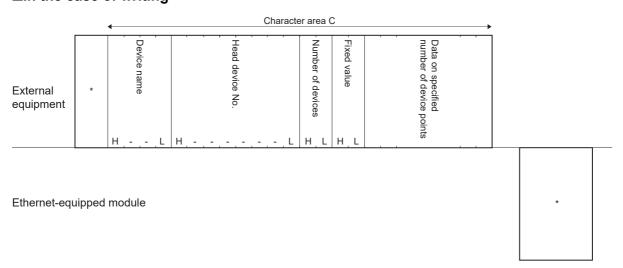
### Data of character area (when communicating in ASCII code)

The data order and contents of character areas A, B, and C are identical when the same command is used under the same conditions in the control procedure when communicating using ASCII code.

#### ■In the case of reading



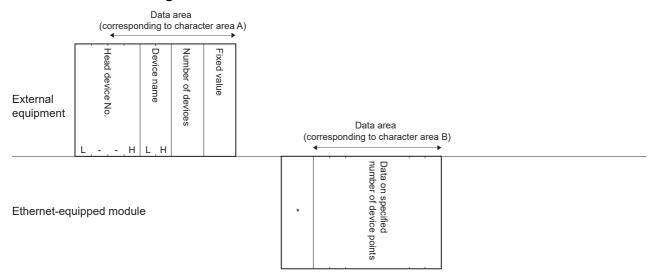
#### ■In the case of writing



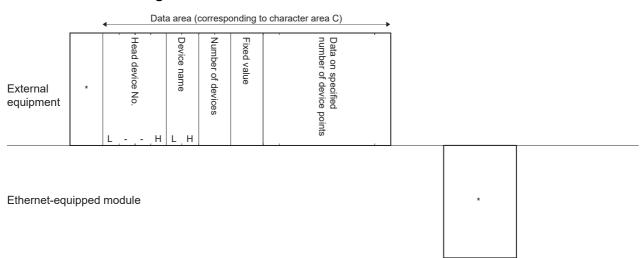
The data array and the data contents marked with \* are shown in Page 41 Message format and control procedure.

## Data of data area (when communicating in binary code)

#### ■In the case of reading



#### ■In the case of writing



The data array and the data contents marked with \* are shown in Page 41 Message format and control procedure.

#### Data contents common to character areas

#### **■**Device name (Device code)

Device codes are data for identifying the device memory to be read or written.

Device codes are shown in Page 120 Device Access.

When communicating data in ASCII code

Device codes are converted into 4-digit ASCII code (hexadecimal), and the device codes are sequentially sent beginning from the most significant digit. Use capitalized code for alphabetical letter in ASCII code.



In the case of input (X)



When communicating data in binary code

Specify the device code with a 2-byte binary code in the order from the least significant byte to the most significant byte.



In the case of input (X)

5820H 20H 58H

#### ■Head device No. (device No.)

Data for specifying the number of the device to read data from or write data to. When specifying continuous device areas, specify the head number of the device range. The method for specifying the head device number varies depending on the expressing method for the relevant device.

- · Octal: Specify in octal notation.
- · Decimal: Specify after converting into hexadecimal.
- · Hexadecimal: Specify in hexadecimal notation.

Use capitalized code for alphabetical letter.

For the device number and expressing method, refer to Page 120 Device Access.

When communicating data in ASCII code

Device codes are converted into 8-digit ASCII code, and the device codes are sequentially sent beginning from the most significant digit.



In the case of the device number is "1234 (4D2H)"



When communicating data in binary code

Specify the device number as a 4-byte binary code in the specified device specification format in the order from the least significant byte to the most significant byte after converting into hexadecimal.



In the case of the device number is "1234 (4D2H)"

4D2H D2H<sub>,</sub>04H<sub>,</sub>00H<sub>,</sub>00H

#### **■**Number of devices

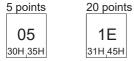
This data is for specifying the number of points to be read or written when each command is executed. It must be specified within the limits of the number of points that can be processed per communication. ( Page 120 Commands)

When communicating data in ASCII code

Device codes are converted into 4-digit ASCII code (hexadecimal), and the device codes are sequentially sent beginning from the most significant digit. Use capitalized code for alphabetical letter.



In the case of 5 points and 20 points



2When communicating data in binary code

Specify the number of points with a 1-byte binary code after converting into hexadecimal.



In the case of 5 points and 20 points



#### **■**Fixed value

A fixed value (00H) must be specified after the number of device points.

When communicating data in ASCII code

Specify the fixed value after converting into a 2-digit ASCII code.



30H,30H

When communicating data in binary code

Specify the fixed value with a 1-byte binary code.



# 4 3E FRAME COMMANDS

This chapter explains 3E frame commands of SLMP.

For parts of the transmission message other than the command part, refer to 🖙 Page 16 3E Frame

## 4.1 List of Commands and Functions

This section describes commands and functions when accessing from the external equipment to the Ethernet-equipped module.

#### **CPU** module

Name	Command	Sub- commands	Processing content	Number of points processed per communication
Device Read (Batch)	0401H	0001H	This command reads data from a bit device or word device in units of 1 bit.	ASCII: 1792 points BIN: 3584 points
		0000H	This command reads data from bit devices in units of 16 bits.  This command reads data from word devices in units of 1 word.	ASCII: 480 words (7680 points) BIN: 960 words (15360 points)
		0081H	This command reads data from the buffer memory in intelligent function modules in units of 1 bit. This command reads data from devices indirectly specified by index registers in units of 1 bit.	ASCII: 1792 points BIN: 3584 points
		0080H	This command reads data from the buffer memory in intelligent function modules in units of 1 word. This command reads data from devices indirectly specified by index registers in units of 1 word.	ASCII: 480 words (7680 points) BIN: 960 words (15360 points)
		0083H	This command reads data from the buffer memory in intelligent function modules in units of 1 bit. This command reads data from devices indirectly specified by index registers in units of 1 bit.	ASCII: 1792 points BIN: 3584 points
		0082H	This command reads data from the buffer memory in intelligent function modules in units of 1 word. This command reads data from devices indirectly specified by index registers in units of 1 word.	ASCII: 480 words (7680 points) BIN: 960 words (15360 points)
Device Write (Batch)	1401H	0001H	This command writes data to bit devices in units of 1 bit.	ASCII: 1792 points BIN: 3584 points
		0000H	This command writes data to bit devices in units of 16 bits.  This command writes data to word devices in units of 1 word.	ASCII: 480 words (7680 points) BIN: 960 words (15360 points)
		0081H	This command writes data to the buffer memory in intelligent function modules and SLMP-compatible devices in units of 1 bit. Bit devices, word devices, and buffer memory are indirectly specified by index registers.	ASCII: 1792 points BIN: 3584 points
		0080H	This command writes data to the buffer memory in intelligent function modules and SLMP-compatible devices in units of 1 word (16 bits).	ASCII: 480 words (7680 points) BIN: 960 words (15360 points)
		0083H	This command writes data to the buffer memory in intelligent function modules and SLMP-compatible devices in units of 1 bit.	ASCII: 1972 points BIN: 3584 points
		0082H	This command writes data to the buffer memory in intelligent function modules and SLMP-compatible devices in units of 1 word (16 bits).	ASCII: 480 words (7680 points) BIN: 960 words (15360 points)
Device Read Random	0403H	0000Н	This command reads data from word devices in units of 1 word or 2 words by randomly specifying device numbers.	ASCII: (Word access points + double- word access points) ×2 ≤192 BIN: Word access points + double- word access points ≤192

Name	Command Sub- commands Processing content			Number of points processed per communication
Device Read 0403H Random		0080Н	This command reads data from the buffer memory in intelligent function modules and SLMP-compatible devices in units of 1 word (16 bits).	ASCII: (Word access points + doubleword access points) ×4 ≤192 BIN: (Word access points + doubleword access points) ×2 ≤192
		0082Н	This command reads data from the buffer memory in intelligent function modules and SLMP-compatible devices in units of 1 word (16 bits).	ASCII: (Word access points + doubleword access points) ×4 ≤192 BIN: (Word access points + doubleword access points) ×2 ≤192
Device Write Random	1402H	0001H	This command writes data to bit devices in units of 1 bit by randomly specifying device numbers.	ASCII: 94 points BIN: 188 points
		O000H     This command writes data to bit devices in units of 16 by randomly specifying device numbers.     This command writes data to word devices in units of 1 words by randomly specifying device numbers.		ASCII: ((Word access points)×12+ (double-word access points) ×14) ×2 ≤1920 BIN: (Word access points)×12+ (double-word access points) ×14 ≤1920
		0081H	This command writes data to the buffer memory in intelligent function modules and SLMP-compatible devices in units of 1 bit.  Buffer memory is indirectly specified by index registers.	ASCII: 47 points BIN: 94 points
	0080Н	This command writes data to the buffer memory in intelligent function modules and SLMP-compatible devices in units of 1 word (16 bits) or 2 words.	ASCII: ((Word access points) ×12+ (double-word access points) ×14) ×4 ≤1920 BIN: ((Word access points)×12+ (double-word access points) ×14) ×2 ≤1920	
		0083H	This command writes data to the buffer memory in intelligent function modules and SLMP-compatible devices in units of 1 bit.	ASCII: 47 points BIN: 94 points
		0082H	This command writes data to the buffer memory in intelligent function modules and SLMP-compatible devices in units of 1 word (16 bits) or 2 words.	ASCII: ((Word access points) ×12+ (double-word access points) ×14) ×4 ≤1920 BIN: ((Word access points)×12+ (double-word access points) ×14) ×2 ≤1920
Device Read 0406H 0000H Block		0000H	With n points of bit devices and word devices as 1 block, this command reads data by randomly specifying multiple blocks. (When bit devices are specified, 1 point is 16 bits.)	ASCII: (Number of word device blocks) + number of bit device blocks) ×2 ≤120 and (Total points of each blocks of word device + total points of each blocks of bit device) ×2 ≤960 BIN: Number of word device blocks + number of bit device blocks ≤120 and Total points of each blocks of word device + total points of each blocks of bit device ≤960

Name	Command	Sub- commands	Processing content	Number of points processed per communication
Device Read Block	0406H	0080H	With n points of buffer memory in intelligent function modules and SLMP-compatible devices as 1 block, this command reads data by randomly specifying multiple blocks. (When bit devices are specified, 1 point is 16 bits.)	ASCII: (Number of word device blocks + number of bit device blocks) ×4 ≤120 and (Total points of each blocks of word device + total points of each blocks of bit device) ×2 ≤960 BIN: (Number of word device blocks + number of bit device blocks) ×2 ≤120 and Total points of each blocks of word device + total points of each blocks of bit device ≤960
		0082H	With n points of buffer memory in intelligent function modules and SLMP-compatible devices as 1 block, this command reads data by randomly specifying multiple blocks.	ASCII: (Number of word device blocks + number of bit device blocks) ×4 ≤120 and (Total points of each blocks of word device + total points of each blocks of bit device) ×2 ≤960 BIN: (Number of word device blocks + number of bit device blocks) ×2 ≤120 and Total points of each blocks of word device + total points of each blocks of bit device ≤960
Device Write Block			With n points of bit devices and word devices as 1 block, this command writes data by randomly specifying multiple blocks. (When bit devices are specified, 1 point is 16 bits.)	ASCII:  (Number of word device blocks + number of bit device blocks) ×2 ≤120 and ((Number of word device blocks + number of bit device blocks) ×4 + Total points of each blocks of word device + total points of each blocks of bit device) ×2 ≤760 BIN: Number of word device blocks + number of bit device blocks ≤120 and (Number of word device blocks + number of bit device blocks) ×4 + Total points of each blocks of word device + total points of each blocks of bit device ≤760
		0080H	With n points of buffer memory in intelligent function modules and SLMP-compatible devices as 1 block, this command writes data by randomly specifying multiple blocks.  (When bit devices are specified, 1 point is 16 bits.)	ASCII:  (Number of word device blocks)  + number of bit device blocks)  ×4 ≤120 and ((Number of word device blocks + number of bit device blocks) ×4 + Total points of each blocks of word device + total points of each blocks of bit device) ×2 ≤760  BIN:  (Number of word device blocks + number of bit device blocks) ×2 ≤120 and (Number of word device blocks + number of bit device blocks) ×4 + Total points of each blocks of word device + total points of each blocks of bit device ≤760

Name	Command	Sub- commands	Processing content	Number of points processed per communication
Device Write Block	1406H	0082H	With n points of buffer memory in intelligent function modules and SLMP-compatible devices as 1 block, this command writes data by randomly specifying multiple blocks.	ASCII: (Number of word device blocks + number of bit device blocks) ×4 ≤120 and ((Number of word device blocks + number of bit device blocks) ×4 + Total points of each blocks of word device + total points of each blocks of bit device) ×2 ≤760 BIN: (Number of word device blocks + number of bit device blocks) ×2 ≤120 and (Number of word device blocks + number of bit device blocks) ×4 + Total points of each blocks of word device + total points of each blocks of bit device ≤760
Remote Run	1001H	0000H	This command performs a remote RUN request for a device.	_
Remote Stop	1002H	0000H	This command performs a remote STOP request for a device.	_
Remote Pause	1003H	0000H	This command performs a remote PAUSE request for a device.	_
Remote Latch Clear	1005H	0000H	This command performs a remote latch clear request when the device is in the STOP state.	_
Remote Reset	1006H	0000H	This command performs a remote reset request to reset the device error stop state.	_
Read Type Name	0101H	0000H	This command reads the processor module name code (processor type) of a device.	_
Self-Test	0619H	0000H	This command checks if normal communication is possible.	_
Clear Error	1617H	0001H	This command batch clears all errors and turns off the LED.	_
Password Lock	1631H	0000Н	This command sets to the locked status from the unlocked status by specifying the remote password. (Sets the device to the state where communication is not possible.)	_
Password Unlock	1630H	0000Н	This command sets to the unlocked status from the locked status by specifying the remote password. (Sets the device to the state where communication is possible.)	_

## Ethernet module, FX5-CCLGN-MS, FX5-CCLIEF, FX5-40SSC-G, FX5-80SSC-G

Name	Command	Sub- commands	Processing content	Number of points processed per communication
Device Read 0401H (Batch)		0001H	This command reads data from a bit device in units of 1 bit.	ASCII: 1792 points BIN: 3584 points
		0000H	This command reads data from bit devices in units of 16 bits.  This command reads data from word devices in units of 1 word.	ASCII: 480 words (7680 points) BIN: 960 words (15360 points)
		0081H	The CPU devices (bit devices) can be directly accessed. This command performs the same processing as the batch read (command: 0401H) and subcommand: 0001H.	ASCII: 1792 points BIN: 3584 points
		0080H	This command reads data from the buffer memory in intelligent function modules in units of 1 word.  The CPU devices (bit devices and word devices) can be directly accessed. This command performs the same processing as the batch read (command: 0401) and subcommand: 0000H.	ASCII: 480 words (7680 points) BIN: 960 words (15360 points)
		0083H	The CPU devices (bit devices) can be directly accessed. This command performs the same processing as the batch read (command: 0401H) and subcommand: 0001H.	ASCII: 1792 points BIN: 3584 points
		0082H	This command reads data from the buffer memory in intelligent function modules in units of 1 word.  The CPU devices (bit devices and word devices) can be directly accessed. This command performs the same processing as the batch read (command: 0401) and subcommand: 0000H.	ASCII: 480 words (7680 points) BIN: 960 words (15360 points)
Device Write (Batch)	1401H	0001H	This command writes data to bit devices in units of 1 bit.	ASCII: 1792 points BIN: 3584 points
		0000H	This command writes data to bit devices in units of 16 bits.  This command writes data to word devices in units of 1 word.	ASCII: 480 words (7680 points) BIN: 949 words (15184 points)
		0081H	The CPU devices (bit devices) can be directly accessed. This command performs the same processing as the batch write (command: 1401H) and subcommand: 0001H.	ASCII: 1792 points BIN: 3584 points
		0080Н	This command writes data to the buffer memory in intelligent function modules and SLMP-compatible devices in units of 1 word (16 bits).  The CPU devices (bit devices and word devices) can be directly accessed. This command performs the same processing as the batch write (command: 1401H) and subcommand: 0000H.	ASCII: 480 words (7680 points) BIN: 949 words (15184 points)
		0083H	The CPU devices (bit devices) can be directly accessed. This command performs the same processing as the batch write (command: 1401H) and subcommand: 0001H.	ASCII: 1972 points BIN: 3584 points
		0082H	This command writes data to the buffer memory in intelligent function modules and SLMP-compatible devices in units of 1 word (16 bits).  The CPU devices (bit devices and word devices) can be directly accessed. This command performs the same processing as the batch write (command: 1401H) and subcommand: 0000H.	ASCII: 480 words (7680 points) BIN: 949 words (15184 points)
Device Read Random*1	0403H	0000Н	This command reads data from bit devices and word devices in units of 1 word or 2 words by randomly specifying device numbers.	ASCII: (Word access points + doubleword access points) ×2 ≤192 BIN: Word access points + doubleword access points ≤123

Name	Command	Sub- commands	Processing content	Number of points processed per communication		
Device Read Random*1	· ·		This command reads data from the buffer memory in intelligent function modules in units of 1 word (16 bits) or 2 words.  This command reads data from devices indirectly specified by index registers in units of 1 word or 2 words. The CPU devices (bit devices and word devices) can be directly accessed.  This command performs the same processing as the random read (command: 0403H) and subcommand: 0000H.	ASCII: (Word access points + doubleword access points) ×4 ≤192 BIN: (Word access points + doubleword access points) ×2 ≤192		
		0082H	This command reads data from the buffer memory in intelligent function modules in units of 1 word (16 bits) or 2 words.  This command reads data from devices indirectly specified by index registers in units of 1 word or 2 words. The CPU devices (bit devices and word devices) can be directly accessed.  This command performs the same processing as the random read (command: 0403H) and subcommand: 0000H.	ASCII: (Word access points + doubleword access points) ×4 ≤192 BIN: (Word access points + doubleword access points) ×2 ≤192		
Device Write Random*2	1402H	0001H	This command writes data to bit devices in units of 1 bit by randomly specifying device numbers.	ASCII: 94 points BIN: 188 points		
	0000H		This command writes data to bit devices in units of 16 bits by randomly specifying device numbers. This command writes data to word devices in units of 1 word or 2 words by randomly specifying device numbers.	ASCII: ((Word access points)×12+ (double-word access points) ×14) ×2 ≤1920 BIN: (Word access points)×18+ (double-word access points) ×20 ≤1920		
		0081H	The CPU devices (bit devices) can be directly accessed. This command performs the same processing as the random write (command: 1402H) and subcommand: 0001H.	ASCII: 47 points BIN: 94 points		
		0080Н	This command writes data to the buffer memory in intelligent function modules in units of 1 word (16 bits) or 2 words.  This command writes data from devices indirectly specified by index registers in units of 1 word or 2 words. The CPU devices (bit devices and word devices) can be directly accessed.  This command performs the same processing as the random write (command: 1402H) and subcommand: 0000H.	ASCII: ((Word access points) ×12+ (double-word access points) ×14) ×4 ≤1920 BIN: ((Word access points)×12+ (double-word access points) ×14) ×2 ≤1920		
		0083H	The CPU devices (bit devices) can be directly accessed. This command performs the same processing as the random write (command: 1402H) and subcommand: 0001H.	ASCII: 47 points BIN: 94 points		
		0082H	This command writes data to the buffer memory in intelligent function modules in units of 1 word (16 bits) or 2 words.  This command writes data from devices indirectly specified by index registers in units of 1 word or 2 words. The CPU devices (bit devices and word devices) can be directly accessed.  This command performs the same processing as the random write (command: 1402H) and subcommand: 0000H.	ASCII: ((Word access points) ×12+ (double-word access points) ×14) ×4 ≤1920 BIN: ((Word access points)×12+ (double-word access points) ×14) ×2 ≤1920		
Device Read Block* <sup>3</sup>	0406H	0000Н	With n points of bit devices and word devices as 1 block, this command reads data by randomly specifying multiple blocks. (When bit devices are specified, 1 point is 16 bits.)	ASCII:  (Number of word device blocks) + number of bit device blocks) ×2 ≤120 and (Total points of each blocks of word device + total points of each blocks of bit device) ×2 ≤960 BIN: Number of word device blocks + number of bit device blocks ≤120 and Total points of each blocks of word device + total points of each blocks of bit device ≤960		

Name	Command	Sub- commands	Processing content	Number of points processed per communication
Device Read Block*3			With n points of buffer memory in intelligent function modules as 1 block, this command reads data by randomly specifying multiple blocks.  (When bit devices are specified, 1 point is 16 bits.) This command performs the same processing as the multiple block batch read (command: 0406H) and subcommand: 0000H.	ASCII: (Number of word device blocks + number of bit device blocks) ×4 ≤120 and (Total points of each blocks of word device + total points of each blocks of bit device) ×2 ≤960 BIN: (Number of word device blocks + number of bit device blocks) ×2 ≤120 and Total points of each blocks of word device + total points of each blocks of bit device ≤960
		0082H	With n points of buffer memory in intelligent function modules as 1 block, this command reads data by randomly specifying multiple blocks.     This command performs the same processing as the multiple block batch read (command: 0406H) and subcommand: 0000H.	ASCII: (Number of word device blocks) + number of bit device blocks) ×4 ≤120 and (Total points of each blocks of word device + total points of each blocks of bit device) ×2 ≤960 BIN: (Number of word device blocks + number of bit device blocks) ×2 ≤120 and Total points of each blocks of word device + total points of each blocks of bit device ≤960
Device Write Block*3			With n points of bit devices and word devices as 1 block, this command writes data by randomly specifying multiple blocks. (When bit devices are specified, 1 point is 16 bits.)	ASCII: (Number of word device blocks + number of bit device blocks) ×2 ≤120 and ((Number of word device blocks + number of bit device blocks) ×4 + Total points of each blocks of word device + total points of each blocks of bit device) ×2 ≤770 BIN: Number of word device blocks + number of bit device blocks ≤120 and (Number of word device blocks + number of bit device blocks) ×4 + Total points of each blocks of word device + total points of each blocks of bit device ≤770
		0080Н	With n points of buffer memory in intelligent function modules as 1 block, this command writes data by randomly specifying multiple blocks. (When bit devices are specified, 1 point is 16 bits.) This command performs the same processing as the multiple block batch write (command: 1406H) and subcommand: 0000H	ASCII: (Number of word device blocks) + number of bit device blocks) ×4 ≤120 and ((Number of word device blocks + number of bit device blocks) ×4 + Total points of each blocks of word device + total points of each blocks of bit device) ×2 ≤770 BIN: (Number of word device blocks + number of bit device blocks) ×2 ≤120 and (Number of word device blocks + number of bit device blocks) ×4 + Total points of each blocks of word device + total points of each blocks of bit device ≤770

Name	Command	Sub- commands	Processing content	Number of points processed per communication
Device Write Block*3	1406H	0082H	With n points of buffer memory in intelligent function modules as 1 block, this command writes data by randomly specifying multiple blocks.     This command performs the same processing as the multiple block batch write (command: 1406H) and subcommand: 0000H	ASCII: (Number of word device blocks) + number of bit device blocks) ×4 ≤120 and ((Number of word device blocks + number of bit device blocks) ×4 + Total points of each blocks of word device + total points of each blocks of bit device) ×2 ≤770 BIN: (Number of word device blocks + number of bit device blocks) ×2 ≤120 and (Number of word device blocks + number of bit device blocks) ×4 + Total points of each blocks of word device + total points of each blocks of bit device ≤770
Remote Run	1001H	0000H	This command performs a remote RUN request for a device.	_
Remote Stop	1002H	0000H	This command performs a remote STOP request for a device.	_
Remote Pause	1003H	0000H	This command performs a remote PAUSE request for a device.	_
Remote Latch Clear	1005H	0000H	This command performs a remote latch clear request when the device is in the STOP state.	_
Remote Reset	1006H	0000H	This command performs a remote reset request to reset the device error stop state.	_
Read Type Name	0101H	0000H	This command reads the processor module name code (processor type) of a device.	_
Self-Test	0619H	0000H	This command checks if normal communication is possible.	_

<sup>\*1</sup> The following devices (contacts and coils) cannot be specified.

- Timers (TS and TC)
- Retentive timers (STS and STC)
- Counters (CS and CC)
- Long counters (LCS and LCC)
- \*2 The following devices (contacts and coils) cannot be specified.
  - Timers (TS and TC)
  - Retentive timers (STS and STC)
  - Counters (CS and CC)
- \*3 Double-word devices cannot be accessed.

## 4.2 Device Access

This section explains the control procedure specification method and shows a specification example when the device memory is read and written.

## **Commands**

This section explains commands when the device memory is read or written.

#### **Commands**

Function		Command (Subcommand)	Processing content			
Device Read (Batch)	Bit units	0401 (00□1)	Reads bit devices in 1 point units.			
	Word units	0401	Reads bit devices in 16 point units.			
		(00□0)	Reads word devices in 1 point units.			
Device Write (Batch)	Bit units	1401 (00□1)	Writes bit devices in 1-point units.			
	Word units	1401	Writes bit devices in 16-point units.			
		(00□0)	Writes word devices in 1-point units.			
Device Read Random	Word units	0403	Reads bit devices specified randomly in 16-point units or 32-point units.			
		(00□0)	Reads word devices specified randomly in 1-point units or 2-point units.			
Device Write Random	Bit units	1402 (00□1)	Sets or resets device memory to bit devices specified randomly in 1-point units.			
	Word units	1402 (00□0)	Sets or resets device memory to bit devices specified randomly in 16-point units or 32-point units			
			Writes device memory to word devices specified randomly in 1-point units or 2-point units.			
Device Read Block	Word units	0406 (00□0)	Sets n point(s) in the word device or bit device (one point is specified by 16-bit) as 1 block, specifies multiple blocks randomly and reads the device memory.			
Device Write Block	Word units	1406 (00□0)	Sets n point(s) in the word device or bit device (one point is specified by 16-bit) as 1 block, specifies multiple blocks randomly and writes the device memory.			

## **Device range**

This section shows accessible CPU module device.

Specify the device and device number range that exist in the module targeted for data read or write.

## In the case of Ethernet-equipped module

Classification	Device		Type Device co (Device s <sub>l</sub> Long)		cation format:	Device No.		Device compatibil ity*2
				ASCII code	Binary code			
Internal user device	Input		Bit	X* (X***)	9CH (9C00H)	Specify in the range of device numbers of the	*3	0
	Output			Y* (Y***)	9DH (9D00H)	module to access.	*3	0
	Internal relay		-	M* (M***)	90H (9000H)		Decimal	0
	Latching relay			L* (L***)	92H (9200H)		Decimal	0
	Annunciator		-	F* (F***)	93H (9300H)		Decimal	0
	Edge relay			V* (V***)	94H (9400H)		Decimal	_
	Link relay  Step relay  Data register  Link register			B* (B***)	A0H (A000H)	_	Hexade cimal	0
				S* (S***)	98H		Decimal	0
			Word	D*	(9800H) A8H		Decimal	0
				(D***) W* (W***)	(A800H) B4H (B400H)		Hexade cimal	0
	Timer	Contact	Bit	TS (TS**)	C1H (C100H)		Decimal	0
		Coil	Bit	TC (TC**)	C0H (C000H)			0
		Current value	Word	TN (TN**)	C2H (C200H)			0
	Long timer	Contact	Bit	(ITV ) — (LTS*)	51H (5100H)		Decimal	_
		Coil	Bit	(LTC*)	50H (5000H)	_		_
		Current value	Double Word	(LTN*)	52H (5200H)			_
	Retentive timer	Contact	Bit	SS (STS*)	C7H (C700H)		Decimal	0
		Coil	Bit	SC (STC*)	C6H (C600H)			0
		Current value	Word	SN (STN*)	C8H (C800H)			0
	Long retentive timer	Contact	Bit	(LSTS)	59H (5900H)	-	Decimal	_
		Coil	Bit	(LSTC)	58H (5800H)			_
		Current value	Double Word	(LSTO)	5AH (5A00H)	-		_
	Counter	Contact	Bit	CS (CS**)	C4H (C400H)		Decimal	0
		Coil	Bit	CC (CC**)	C3H (C300H)	_		0
		Current value	Word	CN (CN**)	C5H (C500H)			0

Classification	Device		Type Device code*1 (Device specification forma Long)			Device No.		Device compatibil ity*2
				ASCII code	Binary code			
Internal user device	Long counter	Contact	Bit	 (LCS*)	55H (5500H)	Specify in the range of device numbers of the	Decimal	0
		Coil	Bit	— (LCC*)	54H (5400H)	module to access.		0
		Current value	Double Word	— (LCN*)	56H (5600H)			0
	Link special rela	у	Bit	SB (SB**)	A1H (A100H)		Hexade cimal	0
	Link special regi	ster	Word	SW (SW**)	B5H (B500H)		Hexade cimal	0
System device	Special relay		Bit	SM (SM**)	91H (9100H)		Decimal	0
	Special register		Word	SD (SD**)	A9H (A900H)		Decimal	0
	Function input		Bit	_	_	-	Hexade cimal	_
	Function output			_	_		Hexade cimal	_
	Function registe	r	Word	_	_		Decimal	_
Index register			Word	Z* (Z***)	CCH (CC00H)	Specify in the range of device numbers of the	Decimal	0
Long index regist	Long index register		Double Word	LZ (LZ***)	62H (6200H)	module to access.	Decimal	0
File register			Word	R* (R***)	AFH (AF00H)		Decimal	0
				ZR (ZR**)	B0H (B000H)		Decimal	_
Link direct device*4	Link input		Bit	X* (X***)	9CH (9C00H)		Hexade cimal	_
	Link output			Y* (Y***)	9DH (9D00H)		Hexade cimal	_
	Link relay		-	B* (B***)	A0H (A000H)		Hexade cimal	_
	Link special rela	у		SB (SB**)	A1H (A100H)		Hexade cimal	_
	Link register		Word	W* (W***)	B4H (B400H)		Hexade cimal	_
	Link special regi	ster		SW (SW**)	B5H (B500H)		Hexade cimal	_
Module access device*4	Link register		Word	W* (W***)	B4H (B400H)		Hexade cimal	_
	Link special regi	ster		SW (SW**)	B5H (B500H)	1	Hexade cimal	_
	Module access	Module access device		G* (G***)	ABH (AB00H)	-	Decimal	0
Other devices	SFC block device	ce	Bit	BL (BL**)	DCH (DC00H)	_	Decimal	×

<sup>\*1 [</sup>ASCII code]

If the device code is less than the specified character number, add "\*" (ASCII code: 2AH) or a space (ASCII code: 20H) after the device code.

[Binary code]

When "Device code" is less than the size specified add "00H" to the end of the device code.

- \*2 O: SLMP-compatible device
  - —: FX5-incompatible device
  - $\times$ : SLMP-incompatible device
- \*3 Depends on the communication data code. See below.

ASCII code (X, Y OCT): octal

ASCII code (X, Y HEX), binary code: hexadecimal

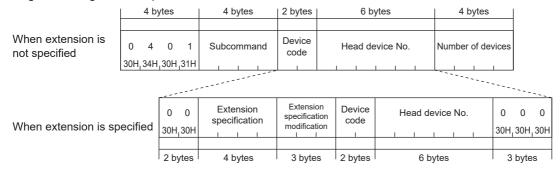
## **Device Read (Batch)**

Data in devices are read in a batch.

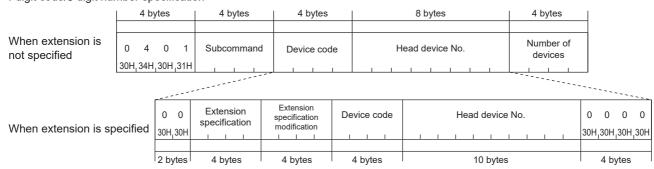
#### Request data

#### **■When communicating data in ASCII code**

2 digit code/6 digit number specification

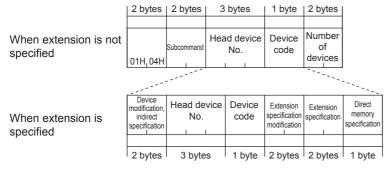


4 digit code/8 digit number specification

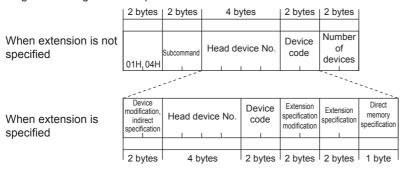


#### **■When communicating data in binary code**

2 digit code/6 digit number specification



4 digit code/8 digit number specification



#### **■**Subcommand

Specify the subcommand selected from the item.

Item				Subcommand				
Data size specification	Device specification format	Device memory extension specification	ASCII code (Upper column: characters, lower column: character code)				Binary code	
Bit units	2 digit code/6 digit number	Not specified	0	0	0	1	01H	00H
specification	specification		30H	30H	30H	31H	1	
		Specified	0	0	8	1	81H	00H
			30H	30H	38H	31H		
	4 digit code/8 digit number	Specified	0	0	8	3	83H	00H
	specification		30H	30H	38H	33H	1	
Word units	2 digit code/6 digit number	Not specified	0	0	0	0	00H	00H
	specification		30H	30H	30H	30H	1	
		Specified	0	0	8	0	80H	00H
			30H	30H	30H	30H	7	
	4 digit code/8 digit number	Specified	0	0	8	2	82H	00H
	specification		30H	30H	38H	32H	1	

#### **■**Device code

Specify the device code that corresponds to the device type to be read. ( Page 66 Device range)

### Precautions

Batch Read (0401H) is not applicable to double word devices or long index registers (LZ).

#### **■**Device No.

Specify the head number of target device of reading.

#### **■**Number of devices

Specify the number of target device points of reading.

Item	Number of devices				
	ASCII code	Binary code			
When reading data in bit units	1 to 1792 points	1 to 3584 points			
When reading data in word units	1 to 480 points	1 to 960 points			

#### Response data

The read device value is stored in hexadecimal. The data order differs depending on the type of code, ASCII code or binary code.

Read data

### **Communication example**

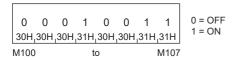
#### **■**When reading data in bit units

M100 to M107 are read.

• When communicating data in ASCII code (Request data)

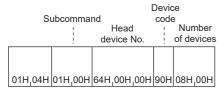
				Sı	ubcor	nmar	nd		vice ode	Head device No.						Number of devices			
0	4	0	1	0	0	0	1	М	*	0	0	0	1	0	0	0	0	0	8
30H	34H	,30H	31H	30H	,30H	<sub>1</sub> 30H	<sub>1</sub> 31H	4DH	<sub>I</sub> 2AH	30H	,30H	,30H	31H	,30H	<sub>1</sub> 30H	30H	,30H	,30H	<sub>1</sub> 38H

(Response data)

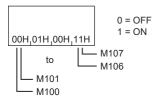


When communicating data in binary code

(Request data)



(Response data)



## ■When reading data in word units (bit device)

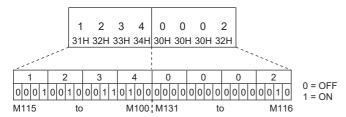
M100 to M131 (2-word) are read.

· When communicating data in ASCII code

(Request data)

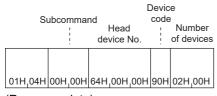
				Sı	ıbcon	nmar	nd		vice de		Hea	nd de	vice l	No.		Num	ber c	of dev	/ices
0	4	0	1	0	0	0	0	М	*	0	0	0	1	0	0	0	0	0	2
30H	34H	30H	31H	30H	30H	30H	30H	4DH	2AH	30H	,30H	30H	31H	30H	30H	30H	30H	,30H	,32H

#### (Response data)

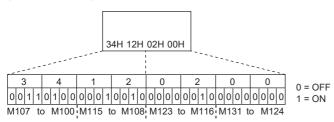


• When communicating data in binary code

#### (Request data)



#### (Response data)



## ■When reading data in word units (word device)

Values in T100 to T102 are read.

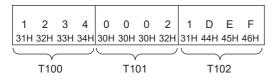
It is supposed that 4660 (1234H) is stored in T100, 2 (2H) is stored in T101, and 7663 (1DEFH) is stored T102.

• When communicating data in ASCII code

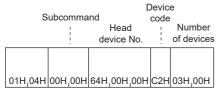
#### (Request data)

				Sı	ıbcon	nman	nd		vice de		Hea	ad de	vice l	No.		Num	nber c	of dev	/ices
0	4	0	1	0	0	0	0	Т	N	0	0	0	1	0	0	0	0	0	3
30H	,34H	30H	31H	30H	30H	30H	30H	54H	4EH	30H	30H	30H	31H	30H	30H	30H	30H	30H	33H

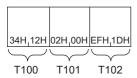
#### (Response data)



• When communicating data in binary code (Request data)



#### (Response data)



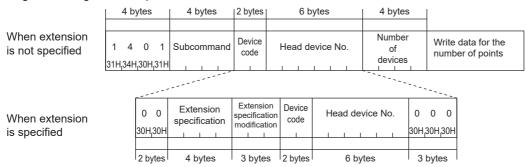
## **Device Write (Batch)**

Data in devices are written in a batch.

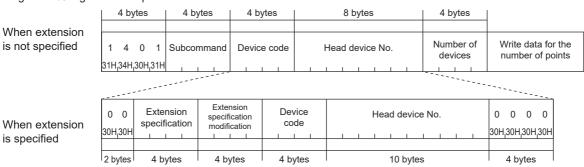
## Request data

#### ■When communicating data in ASCII code

2 digit code/6 digit number specification

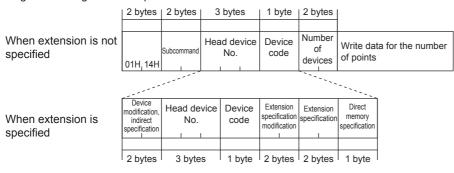


4 digit code/8 digit number specification

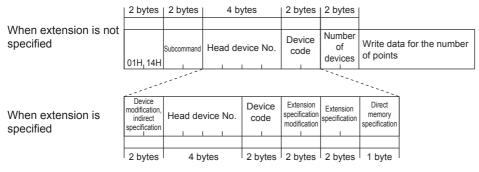


#### **■**When communicating data in binary code

2 digit code/6 digit number specification



4 digit code/8 digit number specification



#### **■**Subcommand

Specify the subcommand selected from the item.

Item			Subcom	mand				
Data size specification	Device specification format	Device memory extension specification	ASCII co (Upper o	olumn: ch	aracters, lo	wer column:	Binary	code
Bit units	2 digit code/6 digit number	Not specified	0	0	0	1	01H	00H
	specification		30H	30H	30H	31H		
		Specified	0	0	8	1	81H	00H
			30H	30H	38H	31H		
	4 digit code/8 digit number	Specified	0	0	8	3	83H	00H
	specification		30H	30H	38H	33H	1	
Word units	2 digit code/6 digit number	Not specified	0	0	0	0	00H	00H
	specification		30H	30H	30H	30H	1	
		Specified	0	0	8	0	80H	00H
			30H	30H	38H	30H	1	
	4 digit code/8 digit number	Specified	0	0	8	2	82H	00H
	specification		30H	30H	38H	32H	]	

### **■**Device code

Specify the device code that corresponds to the device type to be written. ( Page 66 Device range)

#### **Precautions**

Batch Write (1401H) is not applicable to double word devices or long index registers (LZ).

#### **■**Device No.

Specify the head number of target device of writing.

#### ■Number of devices

Specify the number of target device points of writing.

Item	Number of devices		
	ASCII code	Binary code	
		CPU module	Ethernet module, FX5- CCLGNMS, FX5-CCLIEF, FX5- 40SSCG, FX5-80SSC-G
When writing data in bit units	1 to 1792 points	1 to 3584 points	
When writing data in word units	1 to 480 points	1 to 960 points	1 to 949 points

#### **■**Write data

Specify value to be written to a device for the number of points specified in "Device point".

#### Response data

There is no response data for the Device Write command.

## **Communication example**

#### ■When writing data in bit units

Values are written to M100 to M107.

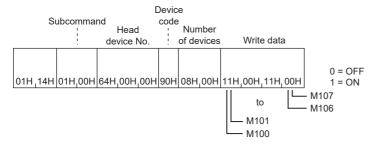
When communicating data in ASCII code

(Request data)

				Sı	ubcoı	mma	nd		vice de		He	ad de	evice	No.		Num	ber c	of dev	rices			١	Vrite	data			
1	4	0	1	0	0	0	1	М	*	0	0	0	1	0	0	0	0	0	8	1	1	0	0	1	1	0	0
31H	<sub>1</sub> 34H	30H	,31H	30H	30H	,30H	31H	4DH	2AH	30H	,30H	,30H	,31H	30H	,30H	30H	30H	,30H	38H	31H	,31H	,30H	30H	31H	,31H	30H	,30H

M100 to M107 0 = OFF

 When communicating data in binary code (Request data)



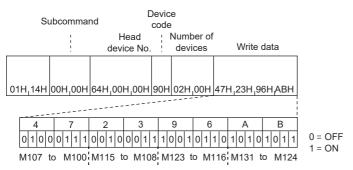
## ■When writing data in word units (bit device)

Values are written to M100 to M131 (2-word).

• When communicating data in ASCII code (Reguest data)

								De	vice																		
				Sı	ubco	mma	nd	CC	de		Hea	ad de	vice	No.		Num	iber c	of dev	vices			١	Write	data			
1	4	0	1	0	0	0	0	М	*	0	0	0	1	0	0	0	0	0	2	2	3	4	7	Α	В	9	6
31H	,34H	,30H	31H	30H	30H	,30H	30H	4DH	2AH	30H	,30H	30H	31H	30H	30H	30H	30H	,30H	,32H	32H	,33H	34H	37H	41H	42H	39H	,36H
														•													
																											!
															2	;	3	4		7	.	A	В		9		6
														0	0 1 0	000	1 1	0 1 0	000	1 1	1 1 0	1 0	10	1 1 1	00	1 0	1 1 0
															115					M100				to			M116

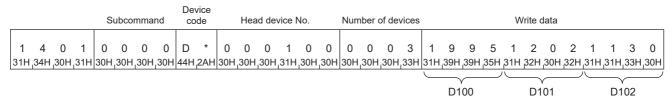
 When communicating data in binary code (Request data)



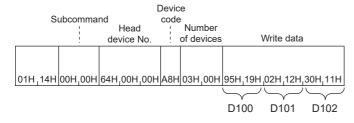
#### ■When writing data in word units (word device)

6549 (1995H) is written in D100, 4610 (1202H) is written in D101, and 4400 (1130H) is written in D102.

 When communicating data in ASCII code (Request data)



 When communicating data in binary code (Request data)

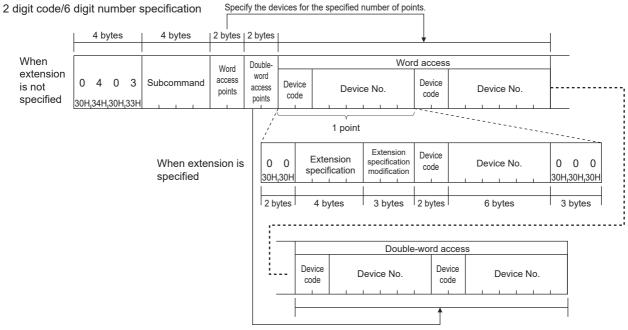


## **Device Read Random**

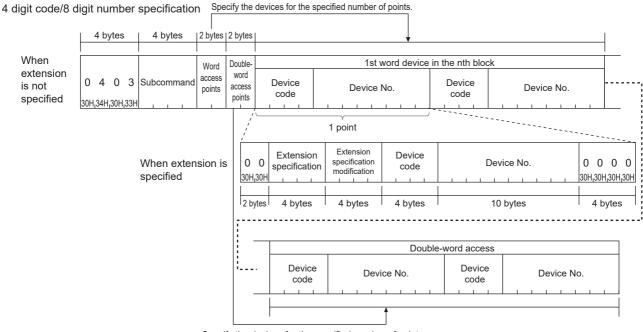
This command specifies the device No. randomly and reads the device value.

## Request data

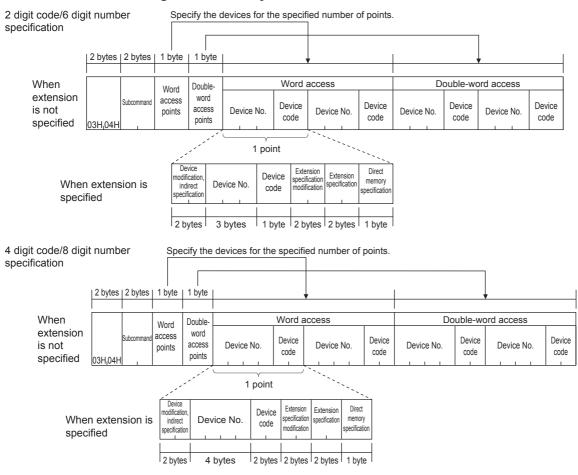
## ■When communicating data in ASCII code



Specify the devices for the specified number of points.



## **■**When communicating data in binary code



#### **■**Subcommand

Specify the subcommand selected from the item.

Item			Subcomm	nand				
Data size specification	Device specification format	Device memory extension specification	ASCII cod (Upper co character	lumn: chara	acters, lowe	r column:	Binary co	de
Word units	2 digit code/6 digit number	Not specified	0	0	0	0	00H	00H
	specification		30H	30H	30H	30H		
		Specified	0	0	8	0	80H	00H
			30H	30H	38H	30H		
	4 digit code/8 digit number	Specified	0	0	8	2	82H	00H
	specification		30H	30H	38H	32H		

## ■Word access points, double-word access points

Specify the number of target device points of reading.

Item	Description	Number of points	
		ASCII code	Binary code
Word access points	Specify the number of points to be accessed in one- word units.  The bit device is 16-point units, the word device is one- word units.	1 ≤ (word access points + double- word access points) ×2 ≤ 192 When device memory extension specification is used, double the	$1 \le$ word access points + doubleword access points $\le 192^{*1}$ When device memory extension specification is used, double the
Double-word access points	Specify the number of points to be accessed in two- word units.  The bit device is 32-point units, the word device is two- word units.	number of the access points.	number of the access points.

 $<sup>^{\</sup>star}1$  123 points when the subcommand 0000H is specified in the Ethernet module.

## **■**Device code, device No.

Specify the target device of reading.

Item	Description
Word access	Specify the device points specified as word access points. The specification is not necessary when the word access points are zero.
Double-word access	Specify the device points specified as double-word access points. The specification is not necessary when the double-word access points are zero.

Set up in order of word access device  $\rightarrow$  double word access device.

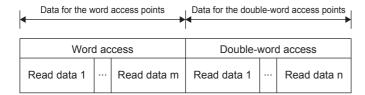
## Precautions

Random Read (0403H) is not applicable to the following devices (contacts and coils).

- Timers (TS and TC)
- Accumulated timers (STS and STC)
- · Counters (CS and CC)
- Long counters (LCS and LCC)

## Response data

The read device value is stored in hexadecimal. The data order differs depending on the type of code, ASCII code or binary code.



## **Communication example**

44H,2AH,30H,30H,30H,30H,30H

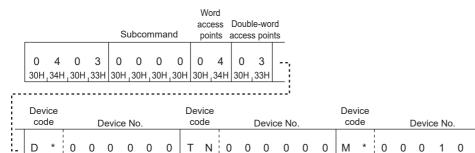
Read D0, T0, M100 to M115, X20 to X37 by word access, and D1500 to D1501, Y160 to Y217, M1111 to M1142 by doubleword access.

It is supposed that 6549 (1995H) is stored in D0, 4610 (1202H) is stored in T0, 20302 (4F4EH) is stored in D1500, 19540 (4C54H) is stored in D1501.

54H,4EH,30H,30H,30H,30H,30H,30H,4DH,2AH,30H,30H,30H,31H,30H,30H

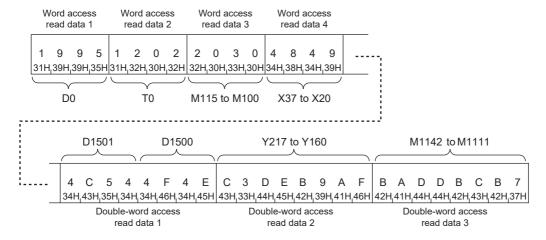
#### ■When communicating data in ASCII code (X, Y OCT)

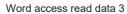
· Request data



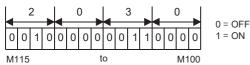
Dev				Devic	e No	).		Dev	/ice de		[	Devid	ce No	).	Dev			[	Devic	e No	).	
D 44H2	* 2AH	0 30H.	0 30H	1 .31H	5 .35H	0 .30H	0 .30H	Y 59H		0 30H	0 .30H	0 .30H		6 .36H	M 4DH.	* 2AH	0 30H	0 30H	1 .31H.	1 31H	1 .31H	1 .31H

#### · Response data





X37

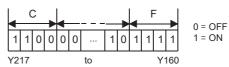


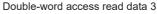


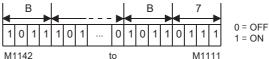
to

X20

#### Double-word access read data 2







Device

code

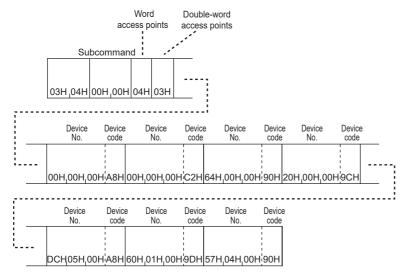
Device No.

0 0 0 2

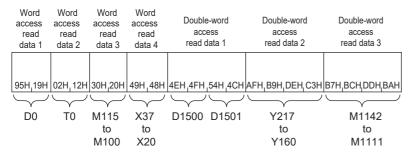
58H,2AH,30H,30H,30H,30H,32H,30H

## **■**When communicating data in binary code

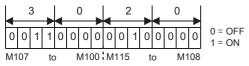
#### · Request data



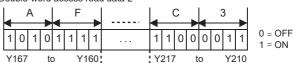
#### · Response data



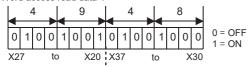




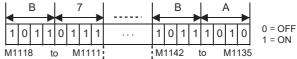
#### Double-word access read data 2



## Word access read data 4



#### Double-word access read data 3



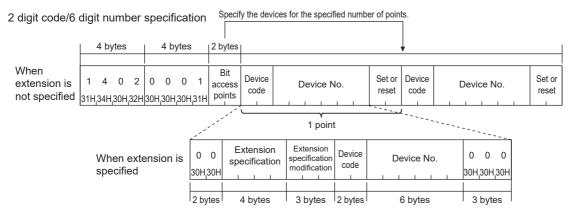
## **Device Write Random**

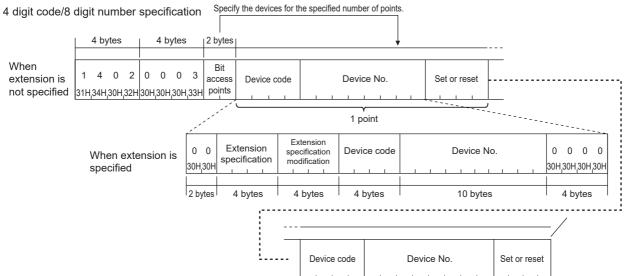
This command specifies the device No. randomly and writes the data.

## Request data

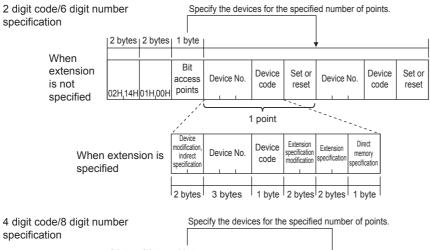
#### ■When writing data in bit units

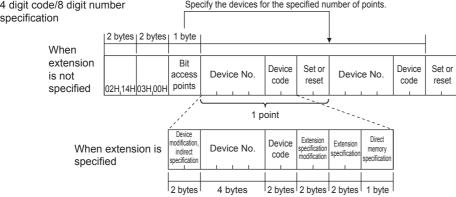
· When communicating data in ASCII code





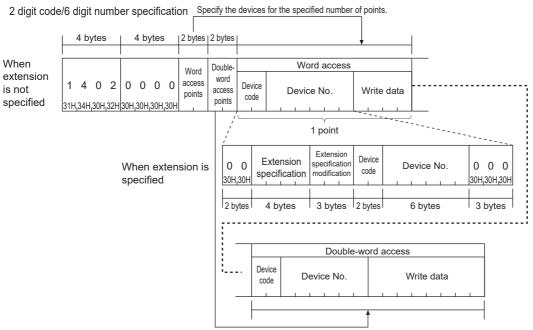
#### · When communicating data in binary code



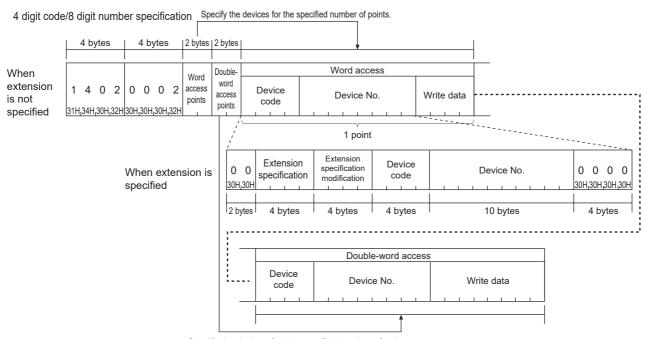


## **■**When writing data in word units

· When communicating data in ASCII code

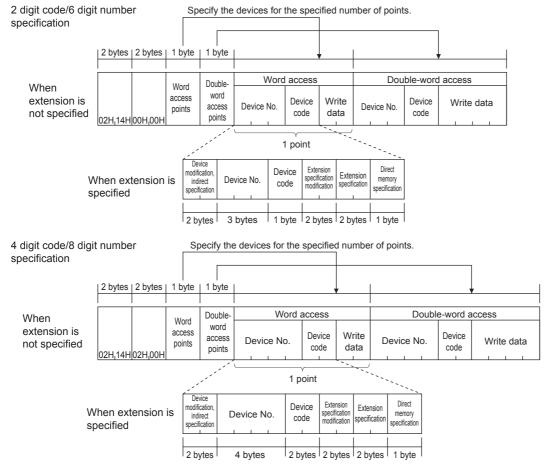


Specify the devices for the specified number of points.



Specify the devices for the specified number of points.

#### · When communicating data in binary code



#### **■**Subcommand

Specify the subcommand selected from the item.

Item			Subcomm	nand				
Data size specification	Device specification format	Device memory extension specification	ASCII cod (Upper co character	lumn: chara	acters, lowe	er column:	Binary co	de
Bit units	2 digit code/6 digit number	Not specified	0	0	0	1	01H	00H
	specification		30H	30H	30H	31H		
		Specified	0	0	8	1	81H	00H
-			30H	30H	38H	31H		
	4 digit code/8 digit number	Specified	0	0	8	3	83H	00H
	specification		30H	30H	38H	33H		
Word units	2 digit code/6 digit number	Not specified	0	0	0	0	00H	00H
	specification		30H	30H	30H	30H		
		Specified	0	0	8	0	80H	00H
			30H	30H	38H	30H	1	
	4 digit code/8 digit number	Specified	0	0	8	2	82H	00H
	specification		30H	30H	38H	32H	1	

## ■Bit access points, word access points, double-word access points

Item	Description	Number of points	
		ASCII code	Binary code
Bit access points	Specify the number of bit device points in one-point units.	1 to 94  When device memory extension specification is used 1 to 47	1 to 188  When device memory extension specification is used 1 to 94
Word access points	Specify the number of points to be accessed in one-word units.  The bit device is 16-point units, the word device is one-word units.	$1 \le$ (word access points $\times$ 12 + double-word access points $\times$ 14) $\times$ 2 $\le$ 1920 When device memory extension	$1 \le$ word access points $\times$ 12 + double-word access points $\times$ 14 $\le$ 1920*1 When device memory extension
Double-word access points	Specify the number of points to be accessed in two-word units.  The bit device is 32-point units, the word device is two-word units.	specification is used, double the number of the access points.	specification is used, double the number of the access points.

<sup>\*1</sup> When the subcommand 0000H is specified in the Ethernet module, the number of points is: 1 ≤ (number of word access points) × 18 + (number of double-word access points) × 20 ≤ 1962 points.

## ■Device code, device No., write data

Specify the target device of writing.

The data is specified in hexadecimal number.

Item	Description
Word access	Specify the device points specified as word access points. The specification is not necessary when the word access points are zero.
Double-word access	Specify the device points specified as double-word access points. The specification is not necessary when the double-word access points are zero.

## Precautions

Random Write (1402H) is not applicable to the following devices (contacts and coils).

- Timers (TS and TC)
- · Accumulated timers (STS and STC)
- Counters (CS and CC)

#### **■**Set or reset

Specify ON/OFF of the bit device.

• 2 digit code/6 digit number specification

Item	Data to write		Remark
	ON	OFF	
ASCII code	"01"	"00"	Two characters will be sent in order from "0".
Binary code	01H	00H	The one-byte numerical value shown left will be sent.

#### • 4 digit code/8 digit number specification

Item	Data to write		Remark
	ON	OFF	
ASCII code	"0001"	"0000"	Four characters will be sent in order from "0".
Binary code	0001H	0000H	The two-byte numerical value shown left will be sent.

## Response data

There is no response data for the Write Random command.

## **Communication example**

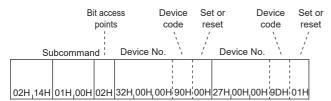
## **■**When writing data in bit units

Turn off M50 and turn on Y27.

• When communicating data in ASCII code (X, Y OCT) (Request data)

								E	3it																				
				Sı	ıbcor	nmar	nd		cess ints		vice de			Devic	e No	).		Set res		Dev co	/ice de		[	Devic	e No	١.			t or set
1	4	0	2	0	0	0	1	0	2	М	*	0	0	0	0	5	0	0	0	Υ	*	0	0	0	0	2	7	0	1
31F	1 <sub>1</sub> 34H	,30H	<sub>1</sub> 32H	30H	30H	,30H	31H	30H	32H	4DH	2AH	30H	,30H	,30H	30H	,35H	,30H	30H	30H	59H	2AH	30H	30F	I <sub>I</sub> 30H	,30H	32H	37H	30H	31H

• When communicating data in binary code (Request data)



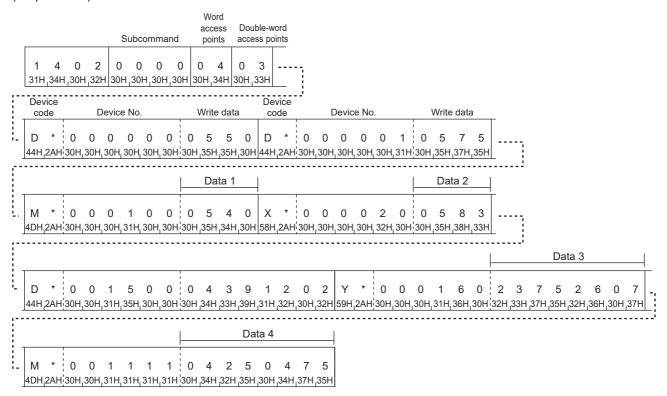
## **■**When writing data in word units

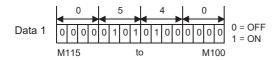
Write the value in a device as follows.

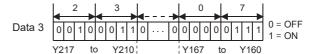
Item	Target device
Word access	D0, D1, M100 to M115, X20 to X37
Double-word access	D1500 to D1501, Y160 to Y217, M1111 to M1142

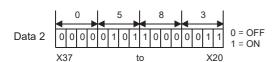
When communicating data in ASCII code (X, Y OCT)

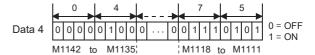
(Request data)



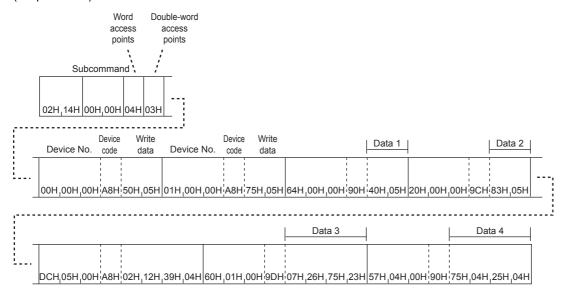


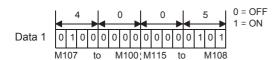


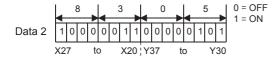


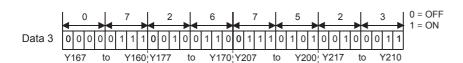


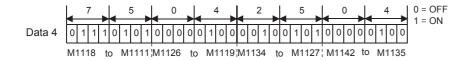
# • When communicating data in binary code (Request data)











## **Device Read Block**

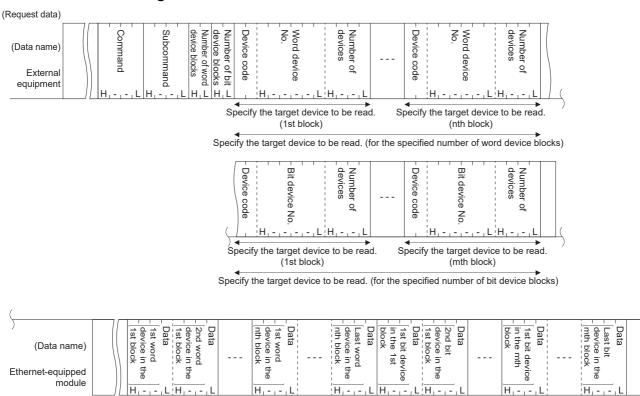
The examples shown in this section explain the control procedure for reading by randomly specifying multiple blocks, where 1 block consists of n point(s) of a bit device memory (one point is specified by 16-bit) and a word device memory (one point is specified by 1-word).

## Data array in the character area during the device read block

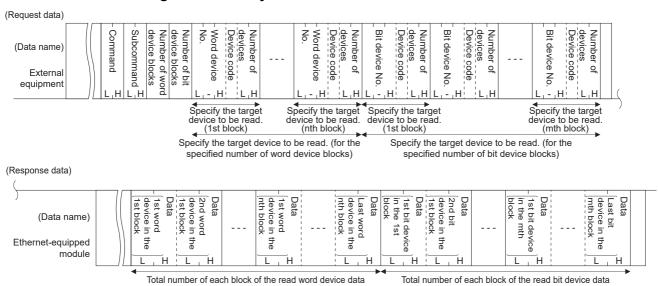
This section explains how data is ordered in the character areas during device read block.

Total number of each block of the read word device data

#### ■When communicating data in ASCII code



## ■When communicating data in binary code



Total number of each block of the read bit device data

## Contents of the character areas during device read block

This section explains what is in the character area when a device read block function is performed.

#### ■Number of word device blocks and number of bit device blocks

This data is for specifying the number of word device blocks or bit device blocks to be sent directly after this data field in the batch read to the word device or bit device, respectively.

· When communicating data in ASCII code

Each number of blocks are converted to 2-digit ASCII code (hexadecimal) and sent.



For 5 blocks: Converted to "05", and sent sequentially from "0".

For 20 blocks: Converted to "14", and sent sequentially from "1".

· When communicating data in binary code

1-byte numeric value indicating the number of blocks is transmitted.



For 5 blocks: 05H is sent. For 20 blocks: 14H is sent.

· Specify the number of blocks so the following condition is satisfied:

120 ≥ number of word device blocks + number of bit device blocks

• When setting either number of blocks to 0, the corresponding device number, device code, number of device points, and data specification are not necessary.

#### **■**Word device number and bit device number

This data is for specifying the head word device or bit device for each block to which batch read is performed, where continuous word or bit devices are considered one block.

· When communicating data in ASCII code

The head device number of each block is converted to 6-digit ASCII code and sent.



Internal relay M1234 and link register W1234:

The internal relay M1234 is converted to "001234" or " 1234", and the link register W1234 is converted to "001234" or " \_\_1234". In both cases, the transmission starts from "0" or " " (space).

· When communicating data in binary code

The head device number of each block is indicated in a 3-byte numeric value and sent.



Internal relay M1234 and link register W1234:

Internal relay M1234 becomes 0004D2H and is sent in the order of D2H, 04H, and 00H.

The link register W1234 is converted to 001234H and sent in the order of 34H, 12H, and 00H.

#### **■**Device code

This data is for identifying the head device memory for each block for which batch read is performed.

The device code for each device is shown in Page 66 Device range.

#### **Precautions**

Double word devices and long index registers (LZ) cannot be used in the multiple block batch read (0406H).

· When communicating data in ASCII code

Each device code is converted to 2-digit ASCII code (hexadecimal) and sent.



Internal relay (M) and link register (W):

The internal relay (M) is converted to "M\*" and link register (W) is converted to "W\*", and sent from "M" and "W" respectively.

· When communicating data in binary code

1-byte numeric value indicating each device code is sent.



Internal relay (M) and link register (W):

90H is transmitted for the internal relay (M) and B4H is sent for the link register (W).

#### **■**Number of devices

This data is for specifying the number of points in the continuous device range of each block for which batch read is performed (1 point = 16 bits for bit device memory and 1 point = 1 word for word device memory), where one block consists of continuous word or bit devices.

• When communicating data in ASCII code

The number of points for each block is converted to a 4-digit ASCII code (hexadecimal) and sent.



For 5 points: Converted to "0005", and sent sequentially from "0".

For 20 points: Converted to "0014", and sent sequentially from "0".

• When communicating data in binary code

2-byte numeric value indicating the number of points for each block is sent.



For 5 points: Converted to 0005H, and sent sequentially from 05H.

For 20 points: Converted to 0014H, and sent sequentially from 14H.

· Specify number of devices so that the appropriate condition is satisfied

960 ≥ total number of points for all word device blocks + total number of points for all bit device blocks



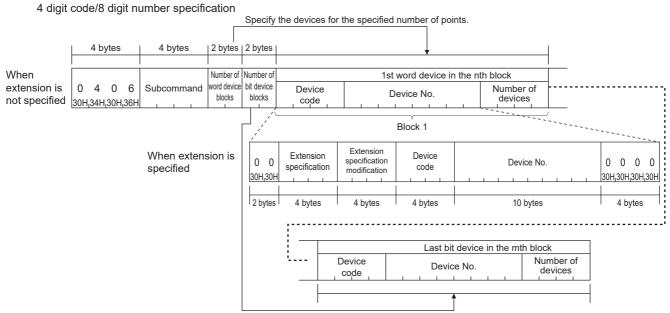
The extension specification is allowed for the device memory being read using the device read block functions.

## Request data

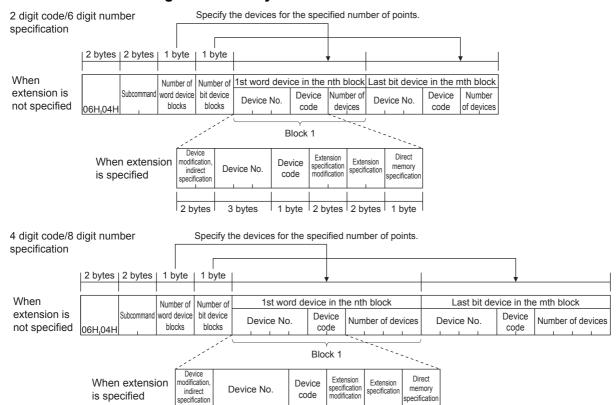
## **■When communicating data in ASCII code**

2 digit code/6 digit number specification Specify the devices for the specified number of points. 4 bytes 4 bytes 2 bytes | 2 bytes When 1st word device in the nth block Number of Number of bit device extension is 4 0 Subcommand word device Device Device No. Number of devices not specified 30H,34H,30H,36H blocks blocks code Block 1 Extension specification When extension is Extension Device 0 0 0 Device No. 0 specified specification code modification 30H,30H 30H,30H,30H 2 bytes 6 bytes 4 bytes 3 bytes 2 bytes 3 bytes Last bit device in the mth block Device Device No. Number of devices code

Specify the devices for the specified number of points.



## **■**When communicating data in binary code



#### Subcommand

Specify the subcommand selected from the item.

Item	Item				Subcommand								
Data size specification	Device specification format	Device memory extension specification	xtension (Upper column: characters, lower column:										
Word units	2 digit code/6 digit number	Not specified	0	0	0	0	00H	00H					
	specification		30H	30H	30H	30H							
		Specified	0	0	8	0	80H	00H					
			30H	30H	38H	30H							
	4 digit code/8 digit number specification		0	0	8	2	82H	00H					
			30H	30H	38H	32H							

2 bytes 2 bytes 2 bytes 1 byte

#### 2 Number of word device blocks and number of bit device blocks

Specify the number of blocks of the device to be read in hexadecimal.

2 bytes

4 bytes

Item	Description	Number of points						
		ASCII code	Binary code					
Number of word device blocks	Specify the number of blocks of the word device to be read.	(Number of word device blocks + number of bit device blocks) ×2	Number of word device blocks + number of bit device blocks ≤120					
Number of bit device blocks	Specify the number of blocks of the bit device to be read.	≤120 and (Total points of each blocks of word device + total points of each blocks of bit device) ×2 ≤960	and Total points of each blocks of word device + total points of each blocks of bit device ≤960					
		When device memory extension specification is used (Number of word device blocks + number of bit device blocks) ×4 ≤120 and (Total points of each blocks of word device + total points of each blocks of bit device) ×2 ≤960	When device memory extension specification is used (Number of word device blocks + number of bit device blocks) ×2 ≤120 and Total points of each blocks of word device + total points of each blocks of bit device ≤960					

3 Device code, device No., number of device points

Specify the device points while satisfying the following conditions:

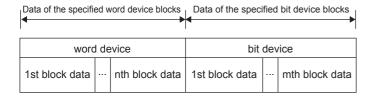
Total number of points for all word device blocks + total number of points for all bit device blocks ≤ 960

Item	Description
Word device	Specify the device points specified in "Number of word device blocks". When "Number of word device blocks" is set to 0, this specification is unnecessary.
Bit device	Specify the device points specified in "Number of bit device blocks". When "Number of bit device blocks" is set to 0, this specification is unnecessary.



When specifying a contact and a coil of a timer, retentive timer, and counter, use the bit device block. Set up in order of word device  $\rightarrow$  bit device.

## Response data



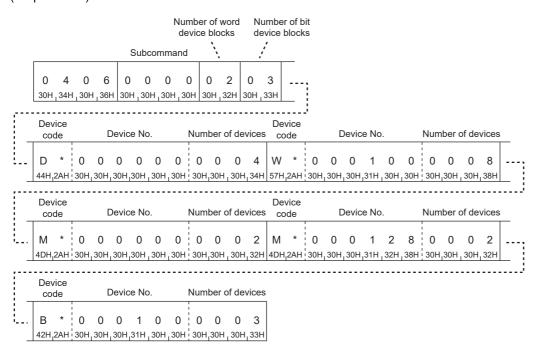
## Communication example

Values are read from devices as follows.

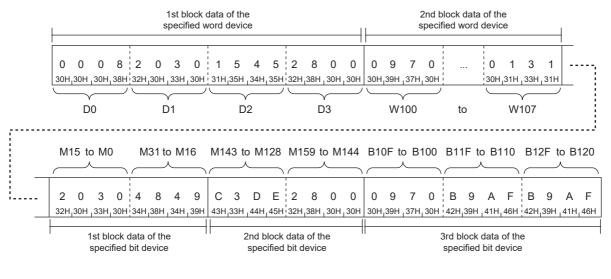
Item	Read contents
Word device	Block 1: D0 to D3 (4 points)     Block 2: W100 to W107 (8 points)
Bit device	Block 1: M0 to M31 (2 points)     Block 2: M128 to M159 (2 points)     Block 3: B100 to B12F (3 points)

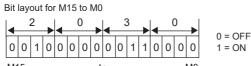
#### ■When communicating data in ASCII code

(Request data)



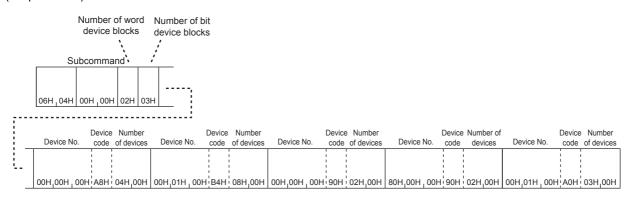
#### (Response data)



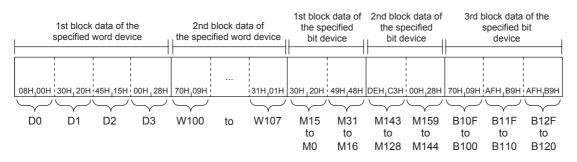


#### ■When communicating data in binary code

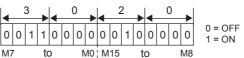
(Request data)



#### (Response data)



Bit layout for M15 to M0



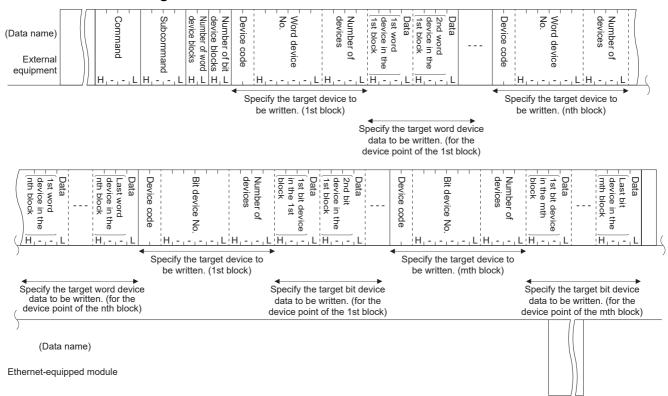
## **Device Write Block**

The examples shown in this section explain the control procedure for writing by randomly specifying multiple blocks, where 1 block consists of n point(s) of a bit device memory (one point is specified by 16-bit) and a word device memory (one point is specified by 1-word).

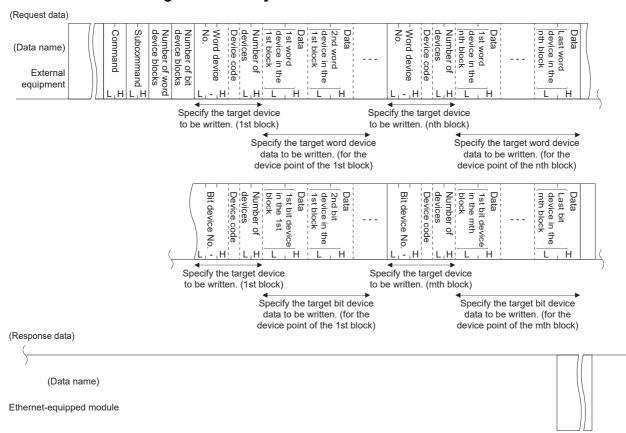
## Data array in the character area during the device write block

This section explains how data is ordered in the character areas during device write block

#### ■When communicating data in ASCII code



## **■When communicating data in binary code**



## Contents of the character areas during device write block

This section explains what is in the character area when a device write block function is performed.

#### ■Number of word device blocks and number of bit device blocks

This data is for specifying the number of word device blocks or bit device blocks to be sent directly after this data field in the batch write to the word device or bit device, respectively.

· When communicating data in ASCII code

Each number of blocks are converted to 2-digit ASCII code (hexadecimal) and sent.



For 5 blocks: Converted to "05", and sent sequentially from "0".

For 20 blocks: Converted to "14", and sent sequentially from "1".

· When communicating data in binary code

1-byte numeric value indicating the number of blocks is transmitted.



For 5 blocks: 05H is sent. For 20 blocks: 14H is sent.

• Specify the number of blocks so the following condition is satisfied:

120 ≥ number of word device blocks + number of bit device blocks

• When setting either number of blocks to 0, the corresponding device number, device code, number of device points, and data specification are not necessary.

#### **■**Word device number and bit device number

This data is for specifying the head word device or bit device for each block to which batch write is performed, where continuous word or bit devices are considered one block.

· When communicating data in ASCII code

The head device number of each block is converted to 6-digit ASCII code and sent.



Internal relay M1234 and link register W1234:

The internal relay M1234 is converted to "001234" or " 1234", and the link register W1234 is converted to "001234" or " 1234". In both cases, the transmission starts from "0" or " " (space).

· When communicating data in binary code

The head device number of each block is indicated in a 3-byte numeric value and sent.



Internal relay M1234 and link register W1234:

Internal relay M1234 becomes 0004D2H and is sent in the order of D2H, 04H, and 00H.

The link register W1234 is converted to 001234H and sent in the order of 34H, 12H, and 00H.

#### **■**Device code

This data is for identifying the head device memory for each block for which batch write is performed.

The device code for each device is shown in Page 66 Device range.

#### Precautions

Double word devices and long index registers (LZ) cannot be used in the multiple block batch write (1406H).

· When communicating data in ASCII code

Each device code is converted to 2-digit ASCII code (hexadecimal) and sent.



Internal relay (M) and link register (W):

The internal relay (M) is converted to "M\*" and link register (W) is converted to "W\*", and sent from "M" and "W" respectively.

· When communicating data in binary code

1-byte numeric value indicating each device code is sent.



Internal relay (M) and link register (W):

90H is transmitted for the internal relay (M) and B4H is sent for the link register (W).

#### **■**Number of devices

This data is for specifying the number of points in the continuous device range of each block for which batch write is performed (1 point = 16 bits for bit device memory and 1 point = 1 word for word device memory), where one block consists of continuous word or bit devices.

· When communicating data in ASCII code

The number of points for each block is converted to a 4-digit ASCII code (hexadecimal) and sent.



For 5 points: Converted to "0005", and sent sequentially from "0".

For 20 points: Converted to "0014", and sent sequentially from "0".

· When communicating data in binary code

2-byte numeric value indicating the number of points for each block is sent.



For 5 points: Converted to 0005H, and sent sequentially from 05H.

For 20 points: Converted to 0014H, and sent sequentially from 14H.

· Specify number of devices so that the appropriate condition is satisfied

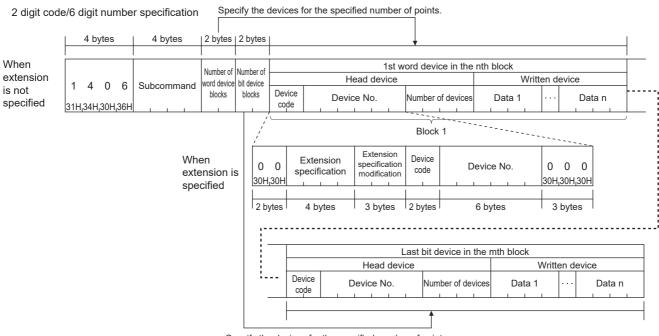
 $760 \ge 4 \times \text{(number of word device blocks + number of bit device blocks)} + \text{total number of points for all word device blocks} + \text{total number of points for all bit device blocks}$ 



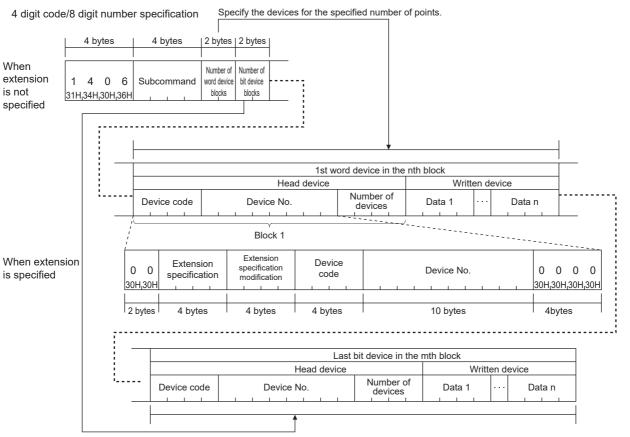
The extension specification is allowed for the device memory being written to using the device write block functions.

## Request data

#### ■When communicating data in ASCII code

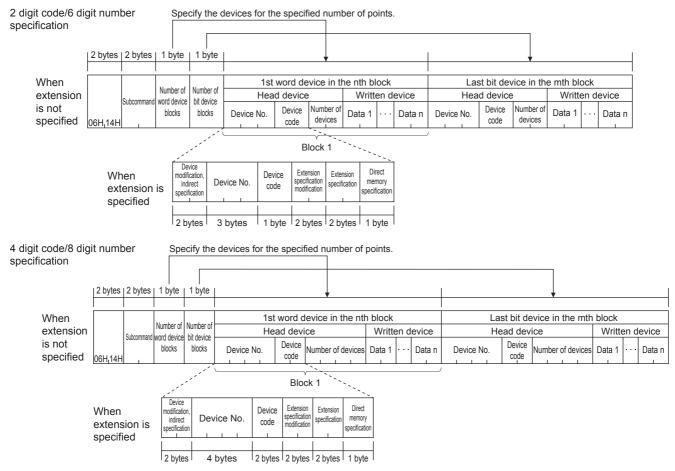


Specify the devices for the specified number of points.



Specify the devices for the specified number of points.

## **■**When communicating data in binary code



#### **1**Subcommand

Specify the subcommand selected from the item.

Item	Item				Subcommand								
Data size specification	Device specification format	Device memory extension specification	(Upper co	ASCII code (Upper column: characters, lower column: character code)									
Word units	2 digit code/6 digit number	Not specified	0	0	0	0	00H	00H					
	specification		30H	30H	30H	30H	]						
		Specified	0	0	8	0	80H	00H					
			30H	30H	38H	30H							
	4 digit code/8 digit number specification		0	0	8	2	82H	00H					
			30H	30H	38H	32H	1						

②Number of word device blocks and number of bit device blocks Specify the number of blocks of the device to be write in hexadecimal.

Item	Description	Number of points	Number of points						
		ASCII code	Binary co	ode					
			CPU module	Ethernet module, FX5-CCLGN-MS, FX5-CCLIEF, FX5-40SSC-G, FX5-80SSC-G					
Number of word device blocks	Specify the number of blocks of the word device to be write.	(Number of word device blocks + number of bit device blocks) ×2	number of	word device blocks + bit device blocks ≤120					
Number of bit device blocks	Specify the number of blocks of the bit device to be write.	≤120 and ((Number of word device blocks + number of bit device blocks) ×4 + Total points of each blocks of word device + total points of each blocks of bit device) ×2 ≤760	and (Number of word device blocks + number of bit device blocks) ×4 + Total points of each blocks of word device + total points of each blocks of bit device ≤760						
		When device memory extension specification is used (Number of word device blocks + number of bit device blocks) ×4 ≤120 and ((Number of word device blocks + number of bit device blocks) ×4 + Total points of each blocks of word device + total points of each blocks of bit device) ×2 ≤760	When device memory extension specification is used (Number of word device blocks + number of bit device blocks) ×2 ≤120 and (Number of word device blocks + number of bit device blocks) ×4 + Total points of each blocks of word device + total points of each blocks of bit device ≤760						

3 Device code, device No., number of device points

Specify the device points while satisfying the following conditions:

(number of word device blocks + number of bit device blocks)  $\times$  4 + total number of points for all word device blocks + total number of points for all bit device blocks  $\leq$  760

Item	Description
Word device	Specify the device points specified in "Number of word device blocks". When "Number of word device blocks" is set to 0, this specification is unnecessary.
Bit device	Specify the device points specified in "Number of bit device blocks". When "Number of bit device blocks" is set to 0, this specification is unnecessary.



When specifying a contact and a coil of a timer, retentive timer, and counter, use the bit device block. Set up in order of word device  $\rightarrow$  bit device.

## Response data

There is no response data for the device write block command.

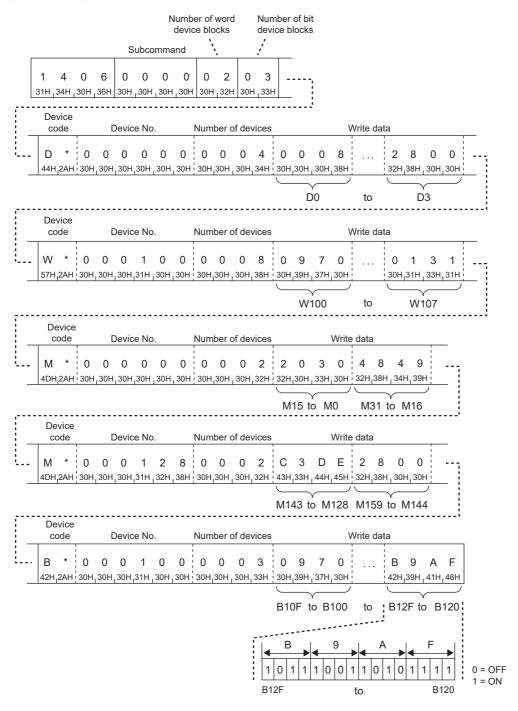
## Communication example

Write values from devices as follows.

Item	Write contents		
Word device	Block 1: D0 to D3 (4 points)     Block 2: W100 to W107 (8 points)		
Bit device	Block 1: M0 to M31 (2 points)     Block 2: M128 to M159 (2 points)     Block 3: B100 to B12F (3 points)		

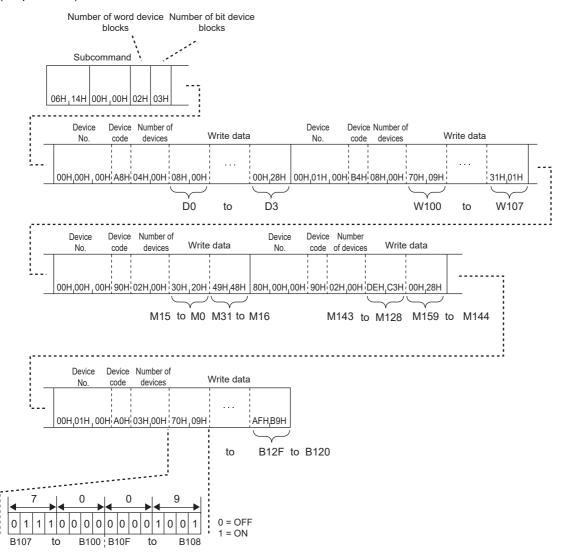
#### ■When communicating data in ASCII code

(Request data)



## **■**When communicating data in binary code

(Request data)



## 4.3 Remote Control

This section describes the command to set the SLMP compatible device or Ethernet-equipped module to the RUN status or STOP status by a message from the external device.

## Before the remote operation

# When the accessed device or module is turned from off to on or reset after the remote operation

The information about the remote operation will be deleted.



Even if the Remote STOP is executed when the switch of the Ethernet-equipped module is in the RUN status, the switch will return to the RUN status after resetting the module.

# When a remote password of the Ethernet-equipped module of the access destination is enabled

Remote operation from the external device is not available. An error will occur at the access destination, and an abnormal response will be sent back to the external device. Unlock the remote password of the Ethernet-equipped module side, and resend the request message.

## Operable station in one command

Only one station can be operated remotely by one command.

## When executing the remote operation to SLMP compatible device

It is recommended to use the UDP protocol for the remote operation. If TCP is used, the connection will be terminated when resetting. Therefore, reestablishing of connection is necessary.

## Remote RUN

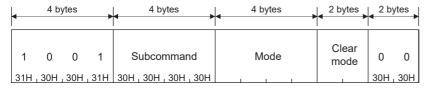
This command executes Remote RUN to the access destination module.



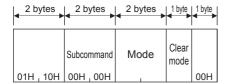
Remote RUN can be executed when the switch of the access destination module is in the RUN status. Even if the switch is in the STOP status, Remote RUN (command: 1001H) will be completed normally. However, the access destination does not change to the RUN status.

## Request data

#### ■When communicating data in ASCII code



## **■When communicating data in binary code**



#### ■Mode

This mode specifies whether Remote RUN can be executed forcibly by a device other than the external device which performed Remote STOP or Remote PAUSE. If forced execution is not allowed, Remote RUN can be executed only by the external device which performed Remote STOP or Remote PAUSE.

Forced execution is used when the external device which performed the remote operation cannot execute Remote RUN because of a problem with the device.

Item	Mode				
	ASCII code	Binary code			
Forced execution not allowed (Remote RUN cannot be executed when other device executes Remote STOP or Remote PAUSE.)	0 0 0 1 30H,30H,30H,31H	01H,00H			
Forced execution allowed (Remote RUN can be executed when other device executes Remote STOP or Remote PAUSE.)	0 0 0 3 30H,30H,30H,33H	03Н,00Н			

#### **■Clear mode**

This mode specifies whether the clear (initialization) processing of device is executed when starting the calculation for the Remote RUN.

Only 00H is valid.

Item	Mode		
	ASCII code	Binary code	
Do not clear the device	0 0 30H,30H	ООН	

## Response data

There is no response data for the Remote RUN command.

## Communication example

Set mode to "Forced execution not allowed.", and set clear mode to "Clear all devices including that in the latch range" when executing Remote RUN.

 When communicating data in ASCII code (Request data)

	Clea Mode mode														
1	0	0	1	0	0	0	0	0	0	0	1	0	2	0	0
31H	,30H	30H	31H	30H	30H	,30H	,30H	30H	30H	30H	31H	30H	32H	30H	30H

 When communicating data in binary code (Request data)

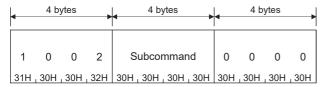
				Мо	de	Clear mode	
01H	10H	00H	00H	01H	00H	02H	00H

## **Remote STOP**

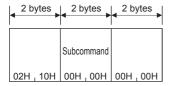
This command executes Remote STOP to the access destination module.

## Request data

#### ■When communicating data in ASCII code



#### ■When communicating data in binary code



## Response data

There is no response data for the Remote STOP command.

## Communication example

Send request messages from the external device by using the message format shown in the request data above.

## Remote PAUSE

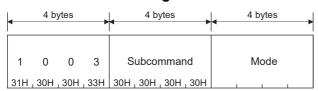
This command executes Remote PAUSE to the access destination module.



Remote PAUSE can be executed when the switch of the access destination module is in the RUN status. Even if the switch is in the STOP status, Remote PAUSE (command: 1003H) will be completed normally. However, the access destination does not change to the PAUSE status.

## Request data

#### ■When communicating data in ASCII code



#### ■When communicating data in binary code

2 bytes	2 bytes	2 bytes
	Subcommand	Mode
03H , 10H	00H , 00H	

#### **■**Mode

This mode specifies whether Remote PAUSE can be executed forcibly by a device other than the external device which performed Remote STOP or Remote PAUSE. If forced execution is not allowed, Remote PAUSE can be executed only by the external device which performed Remote STOP or Remote PAUSE.

Forced execution is used when the external device which performed the remote operation cannot execute Remote PAUSE because of a problem with the device.

Item	Mode					
	ASCII code	Binary code				
Forced execution not allowed (Remote RUN cannot be executed when other device executes Remote STOP or Remote PAUSE.)	0 0 0 1 30H,30H,30H,31H	01H,00H				
Forced execution allowed (Remote RUN can be executed when other device executes Remote STOP or Remote PAUSE.)	0 0 0 3 30H,30H,30H,33H	03Н,00Н				

# Response data

There is no response data for the Remote PAUSE command.

### Communication example

Set mode to "Forced execution not allowed" when executing Remote PAUSE.

#### ■When communicating data in ASCII code

(Request data)

									Mc	ode	
1	0	0	3	0	0	0	0	0	0	0	1
31H	30H	30H	,33H	30H	30H	30H	30H	30H	30H	,30H	,31H

#### **■**When communicating data in binary code

(Request data)



# Remote latch clear

This command executes remote latch clear to the access destination module.

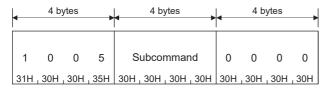


Before executing the remote latch clear, set the status of the access destination module to STOP. While the access destination is stopped or paused remotely by request from another external device:

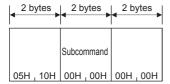
- The remote latch clear cannot be executed. Abnormal completion of the command will occur.
- Cancel the Remote STOP or Remote PAUSE before executing the command.

# Request data

# ■When communicating data in ASCII code



#### **■When communicating data in binary code**



#### Response data

There is no response data for remote latch clear command.

# Communication example

Send request messages from the external device by using the message format shown in the request data above.

# Remote RESET

This command executes Remote RESET to the access destination module. Remote RESET is used to restore when an error occurred in the SLMP compatible device.



Before executing Remote RESET, perform the following.

- When the access destination module has a Remote RESET enable/disable setting, go to GX Works3

  Navigation window ⇒ [Parameter] ⇒ Module model ⇒ [CPU Parameter] ⇒ [Operation Related Setting] ⇒

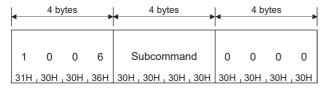
  [Remote Reset Setting], and select "Enable" for "Remote Reset". (Default: Disable)
- Set the status of the access destination module to STOP.

#### Precautions

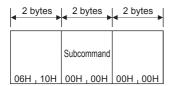
- In some cases, Remote RESET cannot be executed because of hardware error, etc.
- The response message when Remote RESET is executed may not be sent back to the external device since the access destination is reset.

# Request data

#### ■When communicating data in ASCII code



#### ■When communicating data in binary code



#### Response data

There is no response data for the Remote RESET command.

#### Communication example

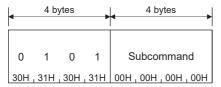
Send request messages from the external device by using the message format shown in the request data above.

# **Processor type read**

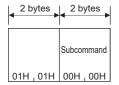
This command reads the processor module name code (processor type) of the access destination module.

# Request data

#### ■When communicating data in ASCII code

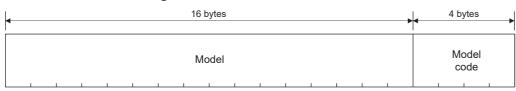


# ■When communicating data in binary code

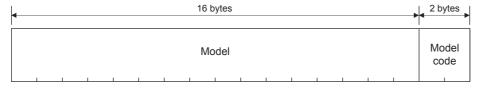


# Response data

# ■When communicating data in ASCII code



#### ■When communicating data in binary code



#### ■Model

The characters of the module model are stored for 16 characters from the upper byte.

If the model to be read is less than 16 characters, space (20H) is stored for the remaining characters. Even when communicating data in binary code, the module model is stored in ASCII code.

# **■**Model code

The following model codes will be stored.

When communicating in binary code, the data is stored in order from the lower byte to the upper byte.

Model	Model code (hexadecimal)
FX5U-32MR/ES	4A21H
FX5U-64MR/ES	4A23H
FX5U-80MR/ES	4A24H
FX5U-32MT/ES	4A29H
FX5U-64MT/ES	4A2BH
FX5U-80MT/ES	4A2CH
FX5U-32MT/ESS	4A31H
FX5U-64MT/ESS	4A33H
FX5U-80MT/ESS	4A34H
FX5U-32MR/DS	4A41H
FX5U-64MR/DS	4A43H
FX5U-80MR/DS	4A44H
FX5U-32MT/DS	4A49H
FX5U-64MT/DS	4A4BH
FX5U-80MT/DS	4A4CH
FX5U-32MT/DSS	4A51H
FX5U-64MT/DSS	4A53H
FX5U-80MT/DSS	4A54H
FX5UC-32MT/D	4A91H
FX5UC-64MT/D	4A92H
FX5UC-96MT/D	4A93H
FX5UC-32MT/DSS	4A99H
FX5UC-64MT/DSS	
FX5UC-96MT/DSS	4A9BH
FX5UC-32MR/DS-TS	4AA9H
FX5UC-32MT/DS-TS	4AB1H
FX5UC-32MT/DSS-TS	4AB9H
FX5UJ-24MR/ES	480DH
FX5UJ-40MR/ES	480EH
FX5UJ-60MR/ES	480FH
FX5UJ-24MT/ES	4B14H
FX5UJ-40MT/ES	4B15H
FX5UJ-60MT/ES	4B16H
FX5UJ-24MT/ESS	4B1BH
FX5UJ-40MT/ESS	4B1CH
FX5UJ-60MT/ESS	4B1DH
FX5S-30MR/ES	484EH
FX5S-40MR/ES	484FH
FX5S-60MR/ES	4B50H
FX5S-80MR/ES*1	4B51H
FX5S-30MT/ES	4855H
FX5S-40MT/ES	4B56H
FX5S-60MT/ES	4857H
FX5S-80MT/ESS*1	4B58H
FX5S-30MT/ESS	485CH
FX5S-40MT/ESS	4B5DH
FX5S-60MT/ESS	485EH
FX5S-80MT/ESS*1	485FH
1700 0017200	150111

<sup>\*1</sup> Area-specific model



- The model of the CPU module is identified by the model code.
- When the Ethernet module is used, the model code of the connected CPU module is stored.

# Communication example

# **■When communicating data in ASCII code**

(Request data)

0	1	0	1	0	0	0	0
30H	31H	30H	31H	30H	30H	30H	30H

(Response data)

F	Χ	5	U	-	3	2	M	R	/	Ε	S					4	Α	2	1
46H	58H	35H	55H	2DH	33H	32H	4DH	52H	2FH	45H	53H	20H,	20H,	20H,	20H	34H	41H	32H	31H

# ■When communicating data in binary code

(Request data)



(Response data)

F X 5 U - 3 2 M R / E S 46H,58H,35H,55H,2DH,33H,32H,4DH,52H,2FH,45H,53H,20H,20H,20H,20H,20H

# 4.4 Clear Error

This function turns off ERR LED of the CPU module from the external equipment and/or initializes the communication error information or error code stored in the buffer memory.

This function is used to initialize the current error information due to an abnormal response for a command message and return it to the normal state or initialize the error code storage area of the buffer memory.

The order and description of the data item with \* shown in the figure of the control procedure differ depending on the frame and pattern in a communication.



This function can be used only for the CPU module which is connected with the external equipment. This function cannot be used for the CPU module of another station via the network system.

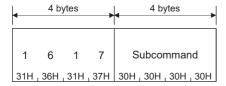
The data part of the command and control procedure when the display LEDs of the CPU module are turned off and the communication error information is initialized from the external equipment is described.

#### Command

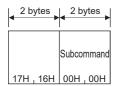
Function	Command (Subcommand)	Processing content
Clear Error	1617(0000)	Turns off the display LEDs, initializes the error code, and others.

# Request data

# ■When communicating data in ASCII code



# ■When communicating data in binary code



#### Response data

There is no response data for the Clear Error command.

#### Communication example

Send request messages from the external device by using the message format shown in the request data above.

# 4.5 Self-Test

This function tests whether the communication function between the external equipment and Ethernet-equipped module operates normally or not. The control procedure when this function is used is described with examples.



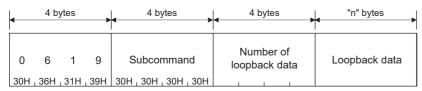
- At the startup of the Ethernet-equipped module or when trouble occurs, this function can check whether the connection between the external equipment and Ethernet-equipped module is correct and/or whether the data communication function operates normally.
- This function can be used only for the Ethernet-equipped module which is connected with the external equipment (including a multi-drop connecting station). This function cannot be used for the Ethernet-equipped module of another station via the network system.

# Command

Function	Command (Subcommand)	Processing content
Self-Test	0619(0000)	Checks whether a data communication is executed normally.

# Request data

#### ■When communicating data in ASCII code



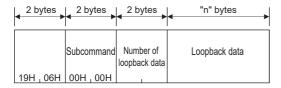
· Number of loopback data (number of bytes)

The number of the bytes is converted into a four-digit ASCII code (hexadecimal) and data is sent from the upper digit ("0").

· Loopback data (user data)

The order of character strings for up to 960 1-byte characters ("0" to "9", "A" to "F") is sent from the head.

#### **■When communicating data in binary code**



· Number of loopback data (number of bytes)

The two-byte numerical value which indicates the number of the bytes is used and data is sent from the low byte (L: bit 0 to 7).

· Loopback data (user data)

Data is sent for up to 960 bytes from the head by treating each character code ("0" to "9", "A" to "F") as a 1 byte value.

#### Response data

The same number of the loopback data and loopback data which the external equipment sent are sent back to the external equipment.

# **Communication example**

Send request messages from the external device by using the message format in the request data. ( Page 113 Request data)

Examples of test with loopback data "ABCDE" are given below.

# ■When executing the Self-Test by communicating in ASCII code

(Request data)

	Com	man	d	Su	Number of Subcommand loopback data Loopback data							a				
0	6	1	9	0	0	0	0	0	0	0	5	Α	В	С	D	Е
30H	,36H	,31H	,39H	30H	30H	,30H	,30H	30H	30H	,30H	35H	41H	42H	<sub>1</sub> 43H	44H	,45H

#### (Response data)

١	Numl	oer c	of					
loc	pba	ck da	ata	L	oopt	ack	data	a
	_	•	_		1	_	1	_
0	U	U	5	Α	В	C	D	Ε
30H	,30H	30H	<sub>1</sub> 35H	41H	42H	43H	<sub>1</sub> 44H	<sub>-</sub> 45⊦

# ■When executing the Self-Test by communicating in binary code

(Request data)

#### (Response data)

Number of loopback data Loopback data

A B C D E

05H,00H 41H,42H,43H,44H,45H

# 4.6 Remote Password Unlock or Lock

A remote password prevents illegal access from a user who is not allowed to operate the SLMP compatible device. The following modules support this function.

- FX5 CPU module
- FX5-CCLGN-MS
- FX5-CCLIEF
- FX5-40SSC-G, FX5-80SSC-G

If a remote password is set to the SLMP compatible device, the remote password is checked when the SLMP compatible device is accessed.

The following shows how to use a command to lock or unlock the remote password by the SLMP.

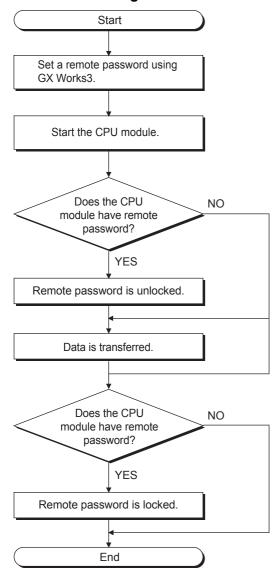
# Target of the remote password checking function

When a remote password is set to the SLMP compatible device, unlock the remote password using a command in this section. Then execute data communication.

#### Control procedure

The following shows the control procedure when a remote password is set to the SLMP compatible device.

#### ■When accessing the FX5CPU





- When the FX5CPU communicating data is set with a remote password, communication is enabled after the completion of the unlock process until the lock process.
- All commands received while the remote password is in locked status will generate an error response. (Execute communication after executing the remote password unlock process.)
- The remote password lock process is automatically performed when the line is disconnected.

# Lock

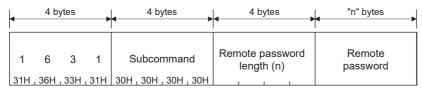
This command changes the remote password from unlocked status to locked status. (Communication to the device is disabled.)

#### Command

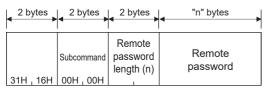
Function		Command (Subcommand)	Processing content
Remote password	. ,		Specifies a remote password and changes the unlock status to the lock status.  (Communication to the CPU module is disabled.)

# Request data

# ■When communicating data in ASCII code



# ■When communicating data in binary code



#### **■**Subcommand

Item		Subcommand								
				Binary code						
Default	Characters	0	0	0	0	_	_			
	Character code	30H	30H	30H	30H	00H	00H			

#### ■Remote password length

Remote password length is not used.

#### **■**Remote password

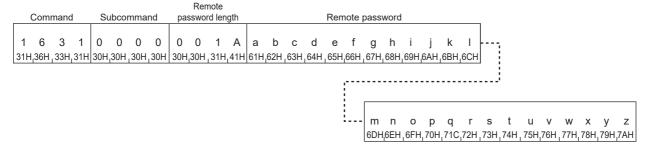
Remote password is not used.

# Response data

There is no response data for the lock command of the remote password.

# Communication example

### ■When performing the lock process in communication using ASCII code



#### ■When performing the lock process in communication using binary code



# **Unlock**

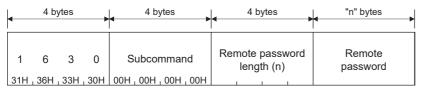
This command changes the remote password from locked status to unlocked status. (Enables communication to the device.)

#### Command

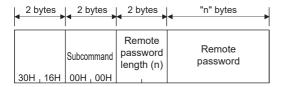
Function		Command (Subcommand)	Processing content
Remote password	, , ,		Specifies a remote password and changes the lock status to the unlock status.  (Communication to the CPU module is enabled.)

# Request data

#### ■When communicating data in ASCII code



#### **■When communicating data in binary code**



#### **■**Subcommand

Item		Subcommand									
		ASCII code				Binary code					
Default	Characters	0	0	0	0	_	_				
	Character code	30H	30H	30H	30H	00H	00H				

# **■**Remote password length

Specify the remote password length.

The password length is the specified characters (6 to 32 characters).

Item	Remote password length (when the number of remote password characters is 32)								
		ASCII code		Binary code					
6 to 32 characters	Characters	0	0	2	0	_	_		
	Character code	30H	30H	32H	30H	20H	00H		

#### **■**Remote password

Specify the remote password set for the SLMP compatible device, CPU module or intelligent function module using GX Works3.

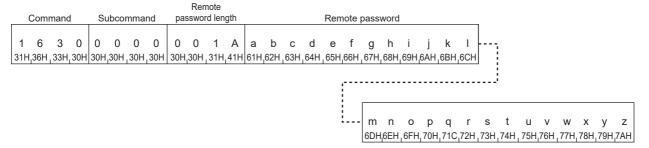
Specify the remote password using ASCII code also when communicating using binary code.

# Response data

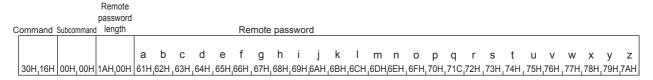
There is no response data for the unlock command of the remote password.

# Communication example

#### ■When performing the unlock process in communication using ASCII code



#### ■When performing the unlock process in communication using binary code



# 5 1E FRAME COMMANDS

This chapter explains 1E frame commands of SLMP.

For parts of the transmission message other than the command part, refer to F Page 41 1E Frame.

# **5.1** List of Commands and Functions

This section describes commands and functions when accessing from the external equipment to the Ethernet-equipped module.

Name	Command	Processing content	Number of points processed per communication
Batch Reading	00H	Reads in 1-bit units from bit devices.	256 points
	01H	Reads in 16-bit units from bit devices.*1	32 words (512 points)
		Reads in 1-word units from word devices.*2	64 points
Batch Writing	02H	Writes data in 1-bit units to bit devices.	160 points
	03H	Writes data in 16-bit units to bit devices.*1	10 words (160 points)
		Writes data in 1-word units to bit devices.*2*3	64 points
Test (Random Write)	04H	Writes data in 1-bit units to a bit device by randomly specifying the device number.	80 points
	05H <sup>*4</sup>	Writes data in 16-bit units to a bit device by randomly specifying the device number.	10 words (160 points)
		Writes data in 1-word units to a word device by randomly specifying the device number.	10 points
Remote RUN	13H	Requests remote RUN/STOP to a device.*5	_
Remote STOP	14H		
Read PC Type Name	15H	Reads Ethernet-equipped module model code.	_
Loopback Test	16H	Returns received characters back to the computer as they are.	254 bytes

<sup>\*1</sup> The head bit device number must be a multiple of 16.

<sup>\*2</sup> When reading double word data by user program or the like, read/write 32 bits of data at a time. Specification across C199 and C200 is not allowed.

<sup>\*3</sup> Long counters cannot be specified.

<sup>\*4</sup> TS (timer (contact)), CS (counter (contact)) and LCS (long timer (contact)) cannot be specified in the Ethernet module.

<sup>\*5</sup> When the Remote STOP operation is performed, another communication requesting station cannot perform the remote RUN/STOP operation until the communication requesting station that performed the remote STOP operation performs the remote RUN operation. When the power to the CPU module is turned on, off and on in the remote RUN/STOP state, the remote RUN/STOP state is disabled. When the remote RUN/STOP state is disabled, the RUN/STOP switch setting of the Ethernet-equipped module is enabled.

# 5.2 Device Access

This section explains the control procedure specification method and shows a specification example when the device memory is read and written.

# **Commands**

This section explains commands when the device memory is read or written.

_							
r	^	m	m	2	n	М	0

Name		Command	Processing content					
Batch Reading	Bit units	00H	Reads bit devices in 1 point units.					
	Word units	01H	Reads bit devices in 16 point units.					
			Reads word devices in 1 point units.					
Batch Writing	Bit units	02H	Writes bit devices in 1-point units.					
	Word units	03H	Writes bit devices in 16-point units.					
			Writes word devices in 1-point units.					
Test (Random Write)	Bit units	04H	Sets or resets device memory to bit devices specified randomly in 1-point units.					
	Word units	05H	Sets or resets device memory to bit devices specified randomly in 16-point units.					
			Writes device memory to word devices specified randomly in 1-point units.					

# **Device range**

This section shows accessible CPU module device.

Specify the device and device number range that exist in the module targeted for data read or write.

# In the case of Ethernet-equipped module

Classification	Device		Туре	Symbol	Device c	ode <sup>*1</sup>	Device No.		Access*2	
					ASCII	Binary				
					code	code				
Internal user	Input		Bit	Х	X*	5820H	0 to 377	*3	0	
device	Output		1	Υ	Y*	5920H	0 to 377	*3	0	
	Internal relay		1	М	M*	4D20H	0 to 7679	Decimal	0	
	Latching relay		1	L	L*	4C20H	_	Decimal	_	
	Annunciator		1	F	F*	4620H	_	Decimal	_	
	Link relay		1	В	B*	4220H	_	Hexadecimal	_	
	Step relay		1	S	S*	5320H	0 to 4095	Decimal	0	
	Data register		Word	D	D*	4420H	0 to 7999	Decimal	0	
	Link register		1	W	W*	5720H	_	Hexadecimal	_	
	Timer	Contact	Bit	TS	TS	5453H	0 to 511	Decimal	0	
		Coil	Bit	TC	TC	5443H	_		_	
		Current value	Word	TN	TN	544EH	0 to 511		0	
	Retentive	Contact	Bit	STS	SS	5353H	_	Decimal	_	
	timer	Coil	Bit	STC	sc	5343H	_		_	
		Current value	Word	STN	SN	534EH	_		_	
	Counter	Contact	Bit	CS	CS	4353H	0 to 255	Decimal	0	
		Coil	Bit	СС	СС	4343H	_		_	
		Current value	Word	CN	CN	434EH	0 to 255		0	
	Long counter	Contact	Bit	LCS	LS	4C53H	*4	Decimal	Δ	
		Coil	Bit	LCC	LC	4C43H	_		_	
		Current value	Double Word	LCN	LN	4C4EH	*5		Δ	
	Link special rel	lay	Bit	SB	SB	5342H	_	Hexadecimal	_	
	Link special re	gister	Word	SW	SW	5357H	_	Hexadecimal	_	
System device	Special relay		Bit	SM	SM	534DH	*6	Decimal	Δ	
	Special registe	r	Word	SD	SD	5344H	*7	Decimal	Δ	
Index register			Word	Z	Z*	5A20H	_	Decimal	_	
Long index registe	r		Double Word	LZ	LZ	4C5AH	_	Decimal	_	
File register			Word	R	R*	5220H	0 to 32767	Decimal	0	
Link direct device	Link input		Bit	DX	DX	4458H	_	Hexadecimal	_	
	Link output		1	DY	DY	4459H	_	Hexadecimal	_	
Module access de	vice		Word	G	_	_	_	Decimal	_	

<sup>\*1 [</sup>ASCII code]

If the device code is less than the specified character number, add a space (ASCII code: 20H) after the device code. [Binary code]

When "Device code" is less than the size specified add "20H" to the end of the device code.

- \*2 O: Accessible to the FX5 CPU module devices
  - —: Inaccessible to the FX5 CPU module devices
  - $\triangle$ : Accessible to a specific device of FX5 CPU module (cannot be directly specified)
- \*3 Depends on the communication data code. See below.

ASCII code (X, Y OCT): octal

 ${\sf ASCII}\ {\sf code}\ ({\sf X},\,{\sf Y}\,{\sf HEX}),\, {\sf binary}\ {\sf code};\, {\sf hexadecimal}$ 

- \*4 Access LCS0 to LCS55 by specifying CS200 to CS255.
- \*5 Access LCN0 to LCN55 by specifying CN200 to CN255.
- $^{*}6$  Access SM8000 to SM8511 by specifying M8000 to M8511.
- \*7 Access SD8000 to SD8511 by specifying D8000 to D8511.

# **Batch Reading**

Data in devices are read in a batch.

# Request data

# ■When communicating data in ASCII code

2 b	oyt	es	2 bytes	4 bytes	4 bytes			8 by	rtes			2 by	/tes	2 by	tes
0		0	PC No.	Monitoring timer	Device name		Hea	ad de	vice	No.		Num of de		Fixe val	
30F	30H, 30H				1 1 1 1	١,					 ı				

# ■When communicating data in binary code

1 byte	1 byte	2 bytes	4 bytes	2 bytes	1 byte	1 byte
	PC No.	Monitoring timer	Head device No.	Device name	Number of devices	Fixed value
00H						

#### **■Subheader**

Specify the command selected from the data size.

Data size	Command							
	ASCII code (Upper colur character co	nn: characters, lower column de)	Binary code					
Bit devices in 1 point units	0	0	00H					
	30H	30H						
Bit devices in 16 point units	0	1	01H					
Word devices in 1 point units	30H	31H						

#### **■PC No.**

Specify the "FFH".

# **■**Monitoring timer

Specify the "0000H".

#### **■**Device name

Specify the device code that corresponds to the device type to be read. ( Page 121 Device range)

#### ■Head device No.

Specify the head number of target device of reading.

#### **■**Number of devices

Specify the number of devices of reading.

Item	Number of devices
When reading data in 1-bit units	1 to 256 points
When reading data in 16-bit units	1 to 32 words (16 to 512 points)
When reading data in 1-word units	1 to 64 points



To specify 256 for the number of device points, specify "00H."

#### **■**Fixed value

Specify the "00H".

# Response data

The read device value is stored in hexadecimal. The data order differs depending on the ASCII code or binary code.

Read data

# Communication example

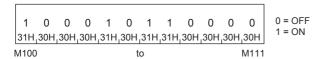
# **■When reading data in bit units**

M100 to M111 are read.

• When communicating data in ASCII code (Request data)

Su	ıbhe	eader	РС	No.	Мо	nitori	ing tii	mer	D	evice	nan	ne	Head device No.					Num of de		Fix val				
- 1					1			0	1				l											
30	OH,	30H	46H	<sub>4</sub> 6H	30H	,30H	<sub>1</sub> 30H	1,30H	34H	44H	,32H	,30H	30H	,30H	,30H	,30H	,30H	,30H	,36H	<sub>1</sub> 34H	30H	43H	30H	,30H

#### (Response data)

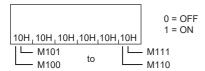


When communicating data in binary code

(Request data)

Subheader		Monitoring timer	Head devic	e No.	Device name	Number of devices	Fixed value
00H	FFH	00Н.00Н	64H.00H.00	H.00H	20H.4DH	0CH	00H

#### (Response data)



#### ■When reading data in word units (bit device)

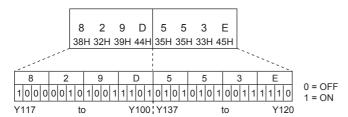
Y100 to Y137 (2-word) are read.

· When communicating data in ASCII code (X, Y HEX)

(Request data)

Subh	eader	РС	No.	Мо	nitori	ng tir	ner	D	evice	e nam	ne			Hea	ad de	vice	No.			Nun of de	nber vices	Fix va	ed lue
0	1	F	F	0	0	0	0	5	9	2	0	0	0	0	0	0	0	4	0	0	2	0	0
30H	,30H	46H	46H	30H	,30H	,30H	,30H	35H	39H	32H	,30H	30H	,30H	,30H	30H	,30H	30H	34H	30H	30H	<sub>1</sub> 32H	30H	,30H

#### (Response data)

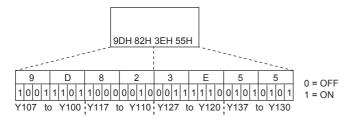


• When communicating data in binary code

#### (Request data)

	I	Monitoring		Device	Number	Fixed		
Subheader	PC No.	timer	Head	device	No.	name	of devices	value
01H	FFH	00H <sub>1</sub> 00H	40H,00	H <sub>1</sub> 00H	H00	20H <sub>1</sub> 59H	02H	00H

#### (Response data)



# ■When reading data in word units (word device)

Values in D100 to D102 are read.

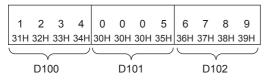
It is supposed that 4660 (1234H) is stored in D100, 5 (5H) is stored in D101, and 26505 (6789H) is stored D102.

• When communicating data in ASCII code

(Request data)

Subh	eader	РС	No.	Мо	nitori	ng tir	ner	D	evice	nam	ne			Hea	ad de	vice	No.			Num of de		Fix val	
0	1	F	F	0	0	0	0	4	4	2	0	0	0	0	0	0	0	6	4	0	3	0	0
30H	,30H	46H	46H	30H	,30H	,30H	30H	34H	34H	32H	30H	30H	,30H	30H	30H	30H	30H	,36H	34H	30H	33H	30H	,30H

#### (Response data)



· When communicating data in binary code

#### (Request data)

Subheader		Monitoring timer	Head device No.	Device name	Number of devices	Fixed value
01H	FFH	00Н,00Н	64H,00H,00H,00H	20H <sub>1</sub> 44H	03H	00H

### (Response data)



# **Batch Writing**

Data in devices are written in a batch.

# Request data

#### ■When communicating data in ASCII code

2 by	2 bytes   2 bytes		4 bytes	4 bytes	8 bytes	2 bytes	2 bytes	
0	2 PC No. Monitoring timer		Device name	Head device No.	Number of devices	Fixed value		
30H, 32H		l 1				1 1	1 1	

# ■When communicating data in binary code

1 byte	1 byte	2 bytes	4 bytes	2 bytes	1 byte	1 byte
	PC No.	Monitoring timer	Head device No.	Device name	Number of devices	Fixed value
02H				l i		

#### **■**Subheader

Specify the command selected based on the data size.

Data size	Command			
	ASCII code (Upper column: chara character code)	(Upper column: characters, lower column:		
Bit devices in 1 point units	0	2	02H	
	30H	32H		
Bit devices in 16 point units	0	3	03H	
Word devices in 1 point units	30H	33H		

#### **■PC No.**

Specify the "FFH".

# **■**Monitoring timer

Specify the "0000H".

#### **■**Device name

Specify the device code that corresponds to the device type to be read. ( Page 121 Device range)

#### Precautions

When specifying the command 03H, observe the following instructions.

- When the CPU module uses long counters, specify the number of long counter points × 2 for the number of device points.
- The Ethernet module cannot use long counters.

#### ■Head device No.

Specify the head number of target device of reading.

#### **■**Number of devices

Specify the number of devices of reading.

Item	Number of devices
When reading data in 1-bit units	1 to 160 points
When reading data in 16-bit units	1 to 10 words (16 to 160 points)
When reading data in 1-word units	1 to 64 points

#### **■**Fixed value

Specify the "00H".

#### Response data

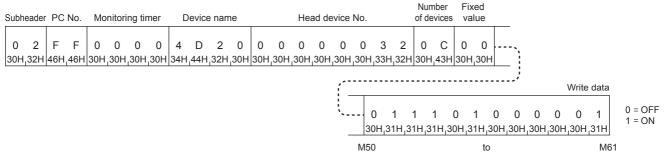
There is no response data for the Batch Writing command.

### Communication example

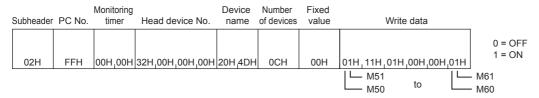
#### **■When writing data in bit units**

Values are written to M50 to M61.

 When communicating data in ASCII code (Request data)



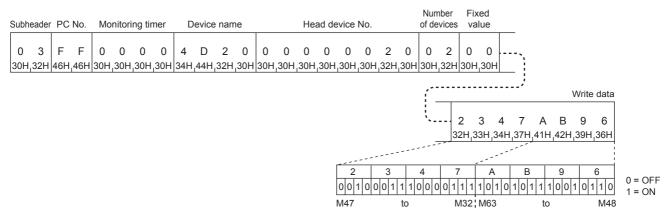
 When communicating data in binary code (Request data)



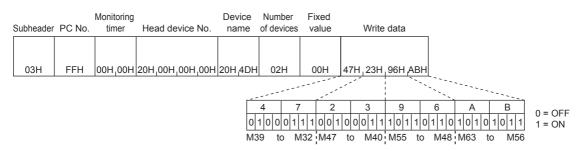
#### ■When writing data in word units (bit device)

Values are written to M32 to M63 (2-word).

 When communicating data in ASCII code (Request data)



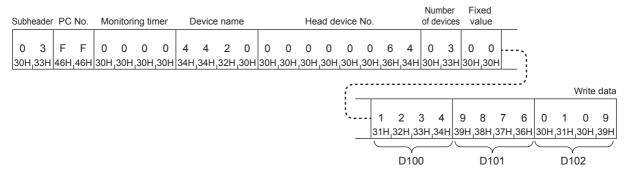
 When communicating data in binary code (Request data)



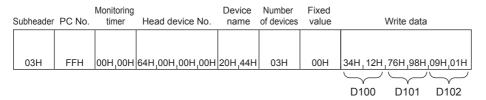
# ■When writing data in word units (word device)

4660 (1234H) is written in D100, 39030 (9876H) is written in D101, and 265 (109H) is written in D102.

 When communicating data in ASCII code (Request data)



 When communicating data in binary code (Request data)



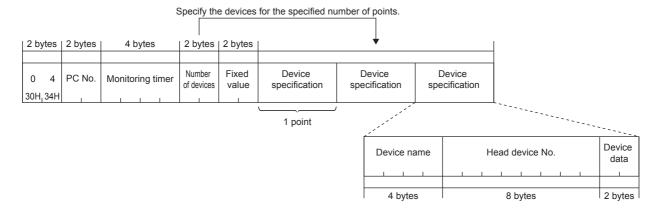
# **Test (Random Write)**

This command specifies the device No. randomly and writes the data.

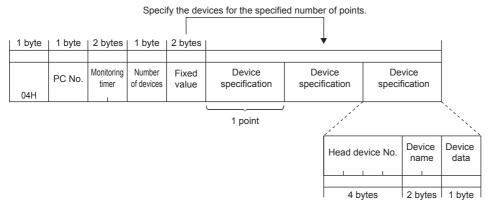
# Request data

#### ■When writing data in bit units

· When communicating data in ASCII code

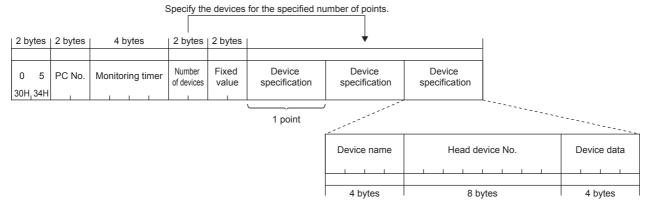


· When communicating data in binary code

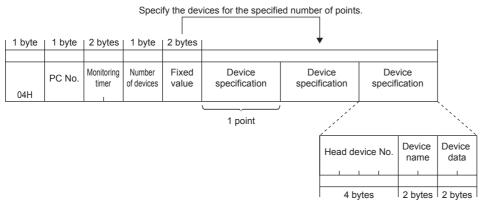


# **■**When writing data in word units

· When communicating data in ASCII code



• When communicating data in binary code



### **■**Subheader

Specify the command selected from the data size.

Data size	Command			
		ASCII code (Upper column: characters, lower column: character code)		
Bit devices in 1 point units	0	4	04H	
	30H	34H		
Bit devices in 16 point units	0	5	05H	
Word devices in 1 point units	30H	35H		

#### **■PC No.**

Specify the "FFH".

# **■**Monitoring timer

Specify the "0000H".

#### **■**Device name

Specify the device code that corresponds to the device type to be read. ( Page 121 Device range)

#### Precautions

When the command 05H is specified in the Ethernet module, TS (timer (contact)), CS (counter (contact)) and LCS (long timer (contact)) cannot be used.

#### ■Head device No.

Specify the head number of target device of reading.

#### **■**Number of devices

Specify the number of devices of reading.

Item	Number of devices
When reading data in 1-bit units	1 to 80 points
When reading data in 16-bit units	1 to 10 words (16 to 160 points)
When reading data in 1-word units	1 to 10 points

#### **■**Fixed value

Specify the "00H".

#### **■**Device data

Specify the value to be written to the device.

Device units	Communicating data	
	ASCII code	Binary code
Bit units (Bit 1-point units)	If the specified device is ON, express it as "01." If it is OFF, express it as "00." Convert the code into a 2-digit ASCII code, and specify in the order from the most significant byte to the least significant byte.	If the specified device is ON, express it as "01." If it is OFF, express it as "00." Specify with a 1-byte binary code.
Word units (Bit 16-point units)	Specify one word (16 bits) with a 4-digit ASCII code, and express 1-point with 1-bit ON/OFF. Specify in 1-word units in the order from the most significant bit to the least significant bit (b15 to b0).	Specify one word (2 bytes) with a binary code, and express 1-point with 1-bit ON/OFF. Specify in 1-word units in the order from the least significant byte (b7 to b0) to the least significant byte (b15 to b8).
Word units (Word 1-point units)	Express the value to be written with a 1-word (4-byte) 4-digit ASCII code (hexadecimal). Specify in 1-word units in the order from the most significant byte to the least significant byte.	Express the value to be written with a 1-word (2-byte) 4-digit binary code (hexadecimal). Specify in 1-word units in the order from the least significant byte to the most significant byte.

# Response data

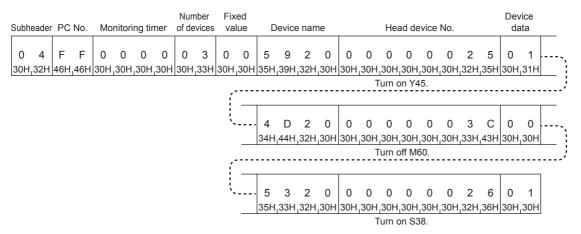
There is no response data for the Test (Random Write) command.

# **Communication example**

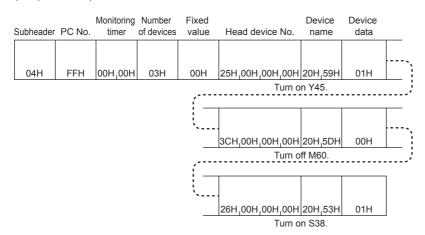
#### **■**When writing data in bit units

Turn on Y45, turn off M60 and turn on S38.

• When communicating data in ASCII code (X, Y HEX) (Request data)



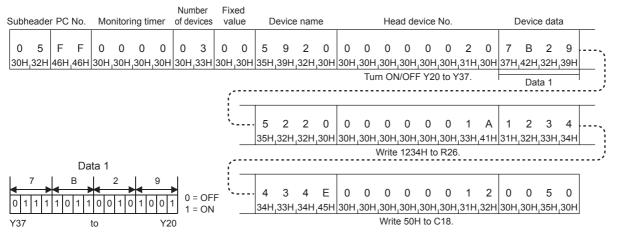
 When communicating data in binary code (Request data)



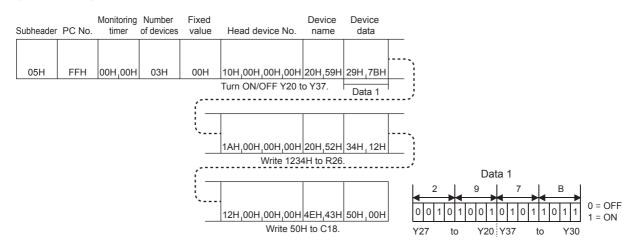
# **■**When writing data in word units

Turn ON/OFF Y20 to Y37, and write 4660 (1234H) to R26 and 80 (50H) to C18.

• When communicating data in ASCII code (X, Y HEX) (Request data)



• When communicating data in binary code (Request data)



# **5.3** Remote Control

This section describes the command to set the SLMP compatible device or Ethernet-equipped module to the RUN status or STOP status by a message from the external device.

# Before the remote operation

# When the Remote STOP operation is performed

Unless the Remote RUN operation is performed by the external device that performed the Remote STOP operation, the Remote RUN/STOP operation by other external devices is invalid.

# When the accessed device or module is turned from off to on or reset after the remote operation

The information about the remote operation will be deleted.



The Remote STOP is executed when the switch of the Ethernet-equipped module is in the RUN status, and the switch will return to the RUN status when the Ethernet-equipped module power is turned from OFF to ON.

# When a remote password (3E frame) of the CPU module of the access destination is enabled

Remote operation from the external device is not available. An error will occur at the access destination, and an abnormal response will be sent back to the external device. Unlock the remote password of the CPU module side, and resend the request message.

# Remote RUN

External equipment executes the Remote RUN operation for the Ethernet-equipped module.



The Remote RUN for the CPU module can be used when the switch of the accessed CPU module is set to RUN. Even if the switch is in the STOP status, Remote RUN (command: 13H) will be completed normally. However, the access destination does not change to the RUN status.

# Request data

#### ■When communicating data in ASCII code

2 by	/tes	2 bytes	4 bytes
1	3	PC No.	Monitoring timer
31H.	33H		

#### ■When communicating data in binary code

C No.	Monitoring timer
	C No.

#### **■**Subheader

Specify the command.

Data size	Command			
	ASCII code (Upper column: characters, lower column: character code)		Binary code	
Remote RUN	1	3	13H	
	31H	33H		

#### **■PC No.**

Specify the "FFH".

# **■**Monitoring timer

Specify the "0000H".

# Response data

There is no response data for the Remote RUN command.

# **Remote STOP**

External equipment executes the Remote STOP operation for the Ethernet-equipped module.

# Request data

# **■When communicating data in ASCII code**

2 bytes		2 bytes	4 bytes
1	4	PC No.	Monitoring timer
31H	34H		

# ■When communicating data in binary code

1 byte	1 byte	2 bytes
14H	PC No.	Monitoring time

# **■Subheader**

Specify the command.

Data size	Command	Command		
	, · · ·	ASCII code (Upper column: characters, lower column: character code)		
Remote STOP	1	4	14H	
	31H	34H		

#### **■PC No.**

Specify the "FFH".

# **■**Monitoring timer

Specify the "0000H".

# Response data

There is no response data for the Remote STOP command.

# **5.4** Read PC Type Name

This command reads the type name code of Ethernet-equipped module.

# Request data

# ■When communicating data in ASCII code

2 bytes		2 bytes	4 bytes
1	5	PC No.	Monitoring timer
31H, 35H			

# ■When communicating data in binary code

1 byte	1 byte	2 bytes
15H	PC No.	Monitoring timer

#### **■**Subheader

Specify the command.

Data size	Command		
	ASCII code (Upper column: chara character code)	Binary code	
Read PC Type Name	1	5	15H
	31H	35H	

#### **■PC No.**

Specify the "FFH".

#### **■**Monitoring timer

Specify the "0000H".

# Response data

The model code "F3H" is stored.

# ■When communicating data in ASCII code

2 bytes					
F	3				
46H	33H				

# ■When communicating data in binary code

L	1 byte
	F3H

# 5.5 Loopback Test

This function tests whether the communication function between the external equipment and Ethernet-equipped module operates normally or not. The control procedure when this function is used is described with examples.



At the startup of the Ethernet-equipped module or when trouble occurs, this function can check whether the connection between the external equipment and Ethernet-equipped module is correct and/or whether the data communication function operates normally.

# Request data

# **■When communicating data in ASCII code**

(Specified byte length × 2) + 10 bytes								
	1 31H,			Monitoring timer	Data length (1 to 254 bytes)	Head transmission data	to	End transmission data

· Data length

Convert the data length to a 2-digit ASCII code (hexadecimal), and specify in the order from the most significant byte.

· Transmission data

Each character code with a sequence of 1-byte characters ("0" to "9" and "A" to "F") is set as a 2-byte value, and up to 254 characters are sent starting from the head.

#### **■When communicating data in binary code**

l	1 byte	1 byte	2 bytes	Specified byte length + 5 bytes				
	16H	PC No.	Monitoring timer	Data length (1 to 254 bytes)	Head transmission data	to	End transmission data	

Data length

Specify the data length by 1-byte.

· Transmission data

Data is sent for up to 254 bytes from the head by treating each character code ("0" to "9", "A" to "F") as a 1-byte value.

#### **■Subheader**

Specify the command.

Data size	Command	Command			
	ASCII code (Upper column character code	: characters, lower column: )	Binary code		
Loopback Test	1	6	16H		
	31H	36H			

#### **■PC No.**

Specify the "FFH".

#### **■**Monitoring timer

Specify the "0000H".

#### Response data

The same data length and data as those sent by the external equipment are returned to the external equipment from the Ethernet-equipped module.

# **Communication example**

"ABCDE" is sent.

# ■When communicating data in ASCII code

(Request data)

Subheader PC No. Monitoring timer length Transmission data															
	1	6	F	F	0	0	0	0	0	5	А	В	С	D	E
	30H	32H	46H	46H	30H	<sub>1</sub> 30H	<sub>1</sub> 30H	,30H	30H	<sub>1</sub> 35H	34H <sub>1</sub> 31H	34H <sub>1</sub> 32H	34H <sub>1</sub> 33H	34H <sub>1</sub> 34H	34H <sub>1</sub> 35H

# (Response data)

Da len	ata igth	Transmission data							
0	5	А	В	С	D	Е			
30H	35H	34H <sub>1</sub> 31H	34H <sub>1</sub> 32H	34H <sub>1</sub> 33H	34H <sub>1</sub> 34H	34H <sub>1</sub> 35H			

# ■When communicating data in binary code

(Request data)

;	Subheader		Monitoring timer	Data length	Ti	ansn	nissic	n da	ta
					1	_	С	_	
	16H	FFH	00H <sub>1</sub> 00H	05H	41H	42H	43H	44H	<sub>1</sub> 45H

# (Response data)

Data length	Tı	ransn	nissio	on da	ta
05H	A 41H	B 42H	C ,43H	D 44H	E ,45H

# 6 TROUBLESHOOTING

Error codes stored when communication ends in error during SLMP are as provided in the following table. For the troubleshooting on the SLMP-compatible device side, refer to the SLMP-compatible device manual.

# **CPU** module

3E: 3E frame, 1E: 1E frame, ○: Supported, —: Not supported

Error code	Error details and causes	Action	SLN	IP
(Hexadecimal)			3E	1E
C035H	The existence of the external device could not be confirmed within the response monitoring timer value.	Check the movement of the other party equipment.     Check whether the connecting cable has come off.	0	0
C050H	When the communication data code is set to "ASCII", ASCII code data which cannot be converted to binary is received.	For communication, set to "Binary" in the communication data code and restart the CPU module.     Correct the send data from the target device and send it.	0	0
C051H	Maximum number of bit devices for which data can be read/written all at once is outside the allowable range.	Correct number of bit devices that can be read or written all at once, and send to CPU module again.	0	0
C052H	Maximum number of word devices for which data can be read/written all at once is outside the allowable range.	Correct number of word devices that can read or write all at once, and send to CPU module again.	0	0
C053H	Maximum number of bit devices for which data can be random read/written all at once is outside the allowable range.	Correct number of bit devices that can be random read or written all at once, and send to CPU module again.	0	0
Maximum number of word devices for which data can be random read/written all at once is outside the allowable range.		Correct number of word devices that can be random read or written all at once, and send to CPU module again.	0	0
C056H Read or write request exceeds maximum address.		Correct starting address or number of read and write points, and send to CPU module again. (Be careful not to exceed the maximum address.)	0	0
C058H	Request data length after ASCII-to-binary conversion does not match the number of data in the character section (part of text).	After reviewing and correcting content of text or length of request data in the header, send to CPU module again.	0	_
С059Н	Error in command or subcommand specification.     There is a command or subcommand that cannot be used by the CPU module.	Reconsider request contents.     Send command or subcommand that can be used by the CPU module.	0	0
C05BH	CPU module cannot read or write from/to specified device.	Reconsider device to read or write.		0
C05CH	Error in request contents. (Reading or writing by bit unit for word device, etc.)	Correct request content, and send to CPU module again. (Subcommand correction, etc.)	0	0
C05FH	There is a request that cannot be executed for the target CPU module.	Correct network No., request station No., request destination module I/O No., or request destination module station No. Correct contents of write request and/or read request.	0	0
C060H	Error in request contents. (Error in specification of data for bit device, etc.)	Correct request content, and send to CPU module again. (Data correction, etc.)	0	0
C061H	Request data length does not match the number of data in the character section (part of text).	After reconsidering and correcting content of text or length of request data in the header, send to CPU module again.	0	0
C06FH	When the communication data code is set to "Binary", a request message of ASCII is received. (Error history of this error code is registered but no error response is sent.)	Sent a request message which matches the setting of the communication data code.     Change the communication data code to match the request message.	0	_
C0D8H	The number of specified blocks exceeds the range.	Correct the specified value of for the number of blocks.	0	-
C200H	Error in remote password.	Correct remote password, and re-execute remote password lock and unlock.	0	_
C201H	Locked status of the remote password of the port which is used for communication.	Unlock the remote password before data communication.	0	0
C204H	Different device requested remote password to be unlocked.	Request remote password lock from device that requested unlock of remote password.	0	_
C810H	Error in remote password. (Authentication failure count is 9 or less.)	Correct remote password, and re-execute remote password unlock.	0	_
C815H	Error in remote password. (Authentication failure count is 10.)	Re-execute remote password unlock after the specified time elapses.	0	_

Error code	Error details and causes	Action	SLM	ЛP	
(Hexadecimal)			3E	1E	
C816H	Remote password authentication is locked out.	Re-execute remote password unlock after the specified time elapses.	0	_	

# **Ethernet module**

3E: 3E frame, 1E: 1E frame,  $\bigcirc$ : Supported,  $\longrightarrow$ : Not supported

Error code	Error details and causes	Action	SLN	/IP
(Hexadecimal)			3E	1E
C035H	The existence of the external device could not be confirmed within the response monitoring timer value.	Check the movement of the other party equipment. Reconsider and change the set values for confirmation of the existence. Check whether the connecting cable has come off.	0	0
C050H	When the communication data code is set to "ASCII", ASCII code data which cannot be converted to binary is received.	For communication, set to "Binary" in the communication data code and restart the CPU module.     Correct the send data from the target device and send it.	0	0
C051H	Maximum number of bit devices for which data can be read/written all at once is outside the allowable range.	Correct number of bit devices that can be read or written all at once, and send to Ethernet module again.	0	0
C052H	Maximum number of word devices for which data can be read/written all at once is outside the allowable range.	Correct number of word devices that can read or write all at once, and send to Ethernet module again.	0	0
C053H	Maximum number of bit devices for which data can be random read/written all at once is outside the allowable range.	Correct number of bit devices that can be random read or written all at once, and send to Ethernet module again.	0	0
C054H	Maximum number of word devices for which data can be random read/written all at once is outside the allowable range.  Correct number of word devices that can be random read or written all at once, and send to Ethernet module again.		0	0
C056H	Read or write request exceeds maximum address.	Correct starting address or number of read and write points, and send to Ethernet module again. (Be careful not to exceed the maximum address.)	0	0
C057H	The request data length in the SLMP message does not match the number of data in the character section (part of the test).  After reexamining and correcting the content of the trequest data length in the header, resend the message does not match the number of data in the character section (part of the test).  Ethernet module.		0	0
C058H	Request data length after ASCII-to-binary conversion does not match the number of data in the character section (part of text).	After reviewing and correcting content of text or length of request data in the header, send to Ethernet module again.	0	_
C059H	Error in command or subcommand specification.     There is a command or subcommand that cannot be used by the CPU module.	Reconsider request contents.     Send command or subcommand that can be used by the Ethernet module.	0	0
C05BH	CPU module cannot read or write from/to specified device.	Reconsider device to read or write.	0	0
C05CH	Error in request contents. (Error related to device specification, such as reading or writing by bit unit for word device, etc.)	Correct request content, and send to Ethernet module again. (Subcommand correction, etc.)	0	0
C05EH	The communication time between the Ethernet module and PLC CPU exceeds the Ethernet monitor timer setting.	Increase the monitor timer setting.     Check the connection between the CPU and Ethernet module.	0	0
C05FH	There is a request that cannot be executed for the target CPU module.	Correct network No., request station No., request destination module I/O No., or request destination module station No. Correct contents of write request and/or read request.	0	0
C060H	Error in request contents. (Error in specification of data for bit device, etc.)	Correct request content, and send to Ethernet module again. (Data correction, etc.)	0	0
C061H	Request data length does not match the number of data in the character section (part of text).	After reconsidering and correcting content of text or length of request data in the header, send to Ethernet module again.	0	0
C06FH	When the communication data code is set to "Binary", a request message of ASCII is received. (Error history of this error code is registered but no error response is sent.)	Sent a request message which matches the setting of the communication data code.     Change the communication data code to match the request message.	0	0
C0D8H	The number of specified blocks exceeds the range.	Correct the specified value of for the number of blocks.	0	0

# **APPENDIX**

# **Appendix 1** Device Memory Extension Specification

The following accesses are available by setting the subcommand of request data to 008□.

- · Access to module access device
- · Access with indirect specification of the device No. by using index register or long index register
- · Access with indirect specification of the device No. by using values stored in word device

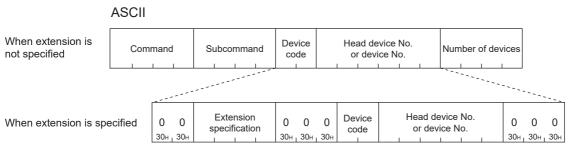


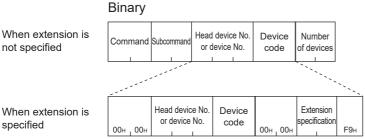
Device memory extension specification is available only for 3E frame.

# Access to module access device

Access to the buffer memory of SLMP compatible devices or intelligent function modules.

#### Request data





The following shows the module access device and request data.





Devices of FX5 CPU module can be accessed by specifying 0 in "extension specification" of commands which can specify multiple devices. (Fig. Page 66 Device range) However, when specifying 008 in "subcommand", specify the device in the message format shown above. Message formats when extension is not specified and message formats when extension is specified cannot coexist in the same message.

#### **■**Command

The following commands can be used for accessing.

Item	Command	
Туре	Operation	
Device	Read	0401
	Write	1401
	Read Random	0403
	Write Random	1402
	Read Block	0406
	Write Block	1406

#### **■**Subcommand

Subcommand						
ASCII code	Binary code					
0 0 8 0 30H   30H   38H   30H	80H , 00H					
0 0 8 2 30H, 30H, 38H, 32H	82H , 00H					

# **■**Extension specification

Specify the module number of intelligent function modules.

ASCII code	Binary code
Specify the module number in hexadecimal (ASCII code 3-digits). When described with 4-digits, specify the module number with the upper 3-digits.	Specify the module number in hexadecimal (2 bytes). When described with 4-digits, specify the module number with the upper 3-digits.
Example 001  U	Example 001



• Access to buffer memories of modules other than intelligent function modules

Specify 0 when accessing buffer memory of modules other than intelligent function modules, such as CC-Link

IE Field Network Ethernet adapter module.

#### **■**Device code

Specify the following device codes.

Туре	Device code			Device No. range		
	ASCII code <sup>*1</sup>		Binary code			
	2 digit code/ 6 digit 8 digit number number specification specification		2 digit code/ 6 digit 8 digit number number specification specification			
Word	G*	G***	ABH	AB00H	Specify within the device No. range of the module for access destination.	Decimal

<sup>\*1</sup> For ASCII codes, the device code is specified with 2 characters. If the device text is one character only, add "\*" (ASCII code: 2AH) or a space (ASCII code: 20H) after the device text.

#### ■Head device or device No.

Specify the head device or device No. in decimal, with the same format as the message when extension is not specified.



Indirect specification of the access target device No. can be performed by using the CPU module index register (Z) or long index register (LZ). ( Page 142 Access with indirect specification of the device No. by using index register or long index register)

# Response data

The same as when extension is not specified.

### Communication example

Access to the buffer memory (Address: 1) of the intelligent function module whose module number is 003H.

 When communicating data in ASCII code (Request data)

Subcommand				Extension specification									vice de	Head device No. or device No.										
0	0		8	0	0	0	U	0	0	3	0	0	0	G	*	0	0	0	0	0	1	0	0	0
30H	ı 30	Н	38н	. 30н	30н	. 30н	55н.	30н	. 30н	, 33н	30н	. 30н	. 30н	47н	. 2Ан	30н.	30н	. 30н	. 30н	. 30н .	31н	30н.	30н.	30н

 When communicating data in binary code (Request data)

S	ubcomman			devic evice		Device code	Extension specification						
	80H 00H	004 004	014	00H	OO <sub>H</sub>	AR⊔	004	004	03⊦	004	F8 <sub>H</sub>		

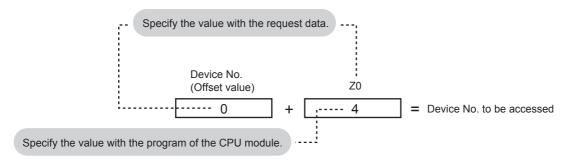
# Access with indirect specification of the device No. by using index register or long index register

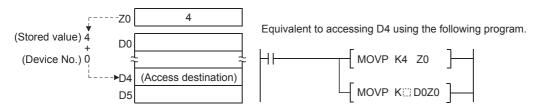
Indirect specification of the device No. can be performed by using the index register or long index register when accessing the device.

The access destination can be switched with one message, by changing the value of the index register or long index register in CPU module programs.



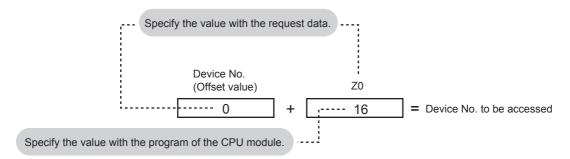
When accessing D4 with D0 and Z0 specifications



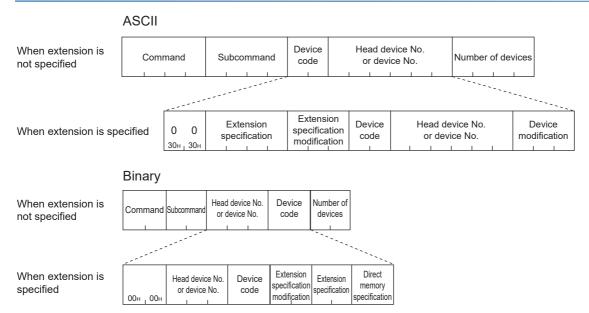


Ex.

When accessing M16 to M31 with M0 and Z0 specifications (Word units)

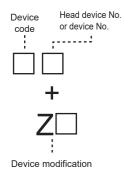


### Request data

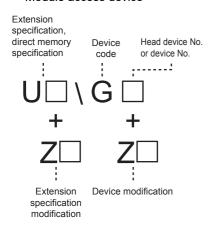


The following shows the approach for devices, index registers, long index registers and request data.

· Other than the module access device



Module access device



Point P

When specifying 008 in "subcommand", specify the device with the message format shown above. Message formats when extension is not specified and message formats when extension is specified cannot coexist in the same message.

### **■**Command

The following commands can be used for accessing.

Item	Command	
Туре	Operation	
Device	Read Random	0403
	Write Random	1402

### **■**Subcommand

Item	Subcommand								
	ASCII code	Binary code							
When accessing in bit units	0 0 8 1 30н, 30н, 38н, 31н	81H , 00H							
	0 0 8 3 30н, 30н, 38н, 33н	83H , 00H							
When accessing in word units	0 0 8 0 30H, 30H, 38H, 30H	80H , 00H							
	0 0 8 2 30H, 30H, 38H, 32H	82H , 00H							

### **■**Extension specification

Specify the module number.

The values specified in this item turn to the offset value when performing indirect specification of the module number in "extension specification modification".

Item	ASCII code	Binary code					
Module access device	Specify the module number in hexadecimal (2 bytes).	Specify the module number in hexadecimal (2 bytes).					
	Example 001  U	Example 001					
Devices other than the above	Specify 0.  0 0 0 0  30H, 30H, 30H, 30H	Specify 0.  00H , 00H					

### **■**Extension specification modification

Treat the value specified in "extension specification" as the offset value. Specify the index register or long index register number when performing indirect specification of the module number with index register or long index register.

• The following value is specified when the access point is a module of the MELSEC iQ-R/iQ-F Series.

Subcommand	ASCII code	Binary code
0083 0082	Specify the number of the index register in decimal (2-digit ASCII code).  • FX5S/FX5U/FX5UC CPU module: 0 to 23  • FX5UJ CPU module: 0 to 19  • Ethernet module: 0 to 24  Z  SAH, 20H	Specify the number of the index register (Z) in hexadecimal.  • FX5S/FX5U/FX5UC CPU module: 00H to 17H  • FX5UJ CPU module: 00H to 13H  • Ethernet module: 00H to 18H
0081 0080	Specify the number of the index register in decimal (2-digit ASCII code).  • FX5S/FX5U/FX5UC CPU module: 0 to 23  • FX5UJ CPU module: 0 to 19  • Ethernet module: 0 to 24	Specify the number of the index register (Z) in hexadecimal.  • FX5S/FX5U/FX5UC CPU module: 00H to 17H  • FX5UJ CPU module: 00H to 13H  • Ethernet module: 00H to 18H

• The following value is specified when the access point is a module of the MELSEC Q/L Series.

ASCII code	Binary code					
Specify the number of the index register in decimal (2-digit ASCII code). (Specification range: 0 to 15)	Specify the number of the index register in hexadecimal. (Specification range: 0 to F)					
Z	□□Н, 40Н					



The long index register (LZ) can not be used in the extension specification modification.

### **■**Device code

Specify the code of the device to be accessed. ( Page 66 Device range)

Specify the following device code when accessing the module access device.

Type	Device code		Device No. range					
	ASCII code*1		Binary code					
	2 digit code/6 digit number specification	4 digit code/8 digit number specification	2 digit code/6 digit number specification	4 digit code/8 digit number specification				
Word	G*	G***	ABH	AB00H	Specify within the device No. range of the module for access destination.	Decimal		

<sup>\*1</sup> For ASCII codes, the device code is specified with 2 characters. If the device text is one character only, add "\*" (ASCII code: 2AH) or a space (ASCII code: 20H) after the device text.

#### ■Head device or device No.

Specify the head device or device No. with the same format as the message when extension is not specified.

The values specified in this item turn to the offset value when performing indirect specification of the device No. in "device modification".

### **■**Device modification

Treat the value specified in "Head device or device No." as the offset value. Specify the index register or long index register number when performing indirect specification of the device No. with index register or long index register.

• The following value is specified when the access point is a module of the MELSEC iQ-R/iQ-F Series.

Subcommand	ASCII code	Binary code
0083 0082	Specify the number of the index register in decimal (2-digit ASCII code).*1  • FX5S/FX5U/FX5UC CPU module: 0 to 23  • FX5UJ CPU module: 0 to 19  • Ethernet module: 0 to 24  Specify the number of the long index register (LZ) in decimal (2-digit ASCII code).  • FX5S/FX5U/FX5UC CPU module: 0 to 11  • FX5UJ CPU module: 0, 1  • Ethernet module: 0 to 12  Z  Z  SAH 20H L  L  Z  4CH 5AH L  ACH 5AH L	Specify the number of the index register (Z) in hexadecimal.*1  • FX5S/FX5U/FX5UC CPU module: 00H to 17H  • FX5UJ CPU module: 00H to 13H  • Ethernet module: 00H to 18H  Specify the number of the long index register (LZ) in hexadecimal.  • FX5S/FX5U/FX5UC CPU module: 00H to 0BH  • FX5UJ CPU module: 00H, 01H  • Ethernet module: 00H to 0CH
0081 0080	Specify the number of the index register in decimal (2-digit ASCII code).  • FX5S/FX5U/FX5UC CPU module: 0 to 23  • FX5UJ CPU module: 0 to 19  • Ethernet module: 0 to 24	Specify the number of the index register (Z) in hexadecimal.  • FX5S/FX5U/FX5UC CPU module: 00H to 17H  • FX5UJ CPU module: 00H to 13H  • Ethernet module: 00H to 18H

<sup>\*1</sup> The device modification range of the index register (Z) is -32768 to 32767. When the device modification range is not within -32768 to 32767, use the long index register (LZ).

• The following value is specified when the access point is a module of the MELSEC Q/L Series.

ASCII code	Binary code
Specify the number of the index register in decimal (2-digit ASCII code).	Specify the number of the index register in hexadecimal. (Specification range:
(Specification range: 0 to 15)	0 to F)
Z	□□H <sub>1</sub> 40H

### **■**Direct memory specification (only when communicating in binary code)

Specify the device type when accessing the module access device.

Item	Binary code					
Module access device	Specify F8H.					
Other than the above	Specify 00H.					

### Response data

The same as when extension is not specified.

### Communication example

Accessing the device of D100 + Z4.

· When communicating data in ASCII code

(Request data)

	Sı	ıbcoı	mma	nd				Exter pecifi			spe	tens cifica difica	ation		evice ode				vice l			_	evice	-
	0	0	8	0	0	0	0	0	0	0	0	0	0	D	*	0	0	0	1	0	0	Z	0	4
;	30н <sub>г</sub>	30н	38н	, 30н	30н	30н	30н	30н г	30н	30н	30н	30н	30н	44н	2Ан	30н	30н	30н	31н г	30н г	30н	5Ан,	30н г	34н

When communicating data in binary code

(Request data)

Subcor	nmand	Dev modifi	ice cation		device levice l		Device code	Exter specifi modifi	cation			Direct memory specification
80н	00н	04н	40н	64н	00н	, 00н	А8н	00н	00н	00н	00н	00н

# Access with indirect specification of the device No. by using the values stored in word device

Access the device corresponding to the address stored in word device (for 2 points).

Ex.

When storing the address of D100 in D0, and trying to access D100 from external devices by accessing "@D0"

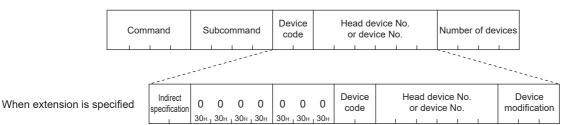
The ADRSET instruction is used on the Ethernet-equipped module side and the address of D100 is stored in D0.



D100 can be indirectly accessed by specifying "@D0" with the request data.

### Request data

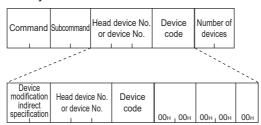




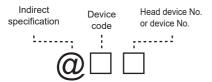
#### Binary

When extension is not specified

When extension is specified



The following shows the indirect specification devices and request data.





- When specifying 008 in "subcommand", specify the device with the message format shown above.
   Message formats when extension is not specified and message formats when extension is specified cannot coexist in the same message.
- The indirect specification and the device modification using index registers can not be set simultaneously.

### **■**Command

The following commands can be used for accessing.

Item	Command	
Туре	Operation	
Device	Read Random	0403
	Write Random	1402

### **■**Subcommand

ASCII code	Binary code				
0 0 8 0 30H, 30H, 38H, 30H	80H , 00H				

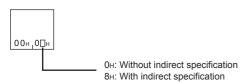
### ■Indirect specification, Device modification

Specify the "@" part of the indirect specification device. Indirect specification can be specified only for word devices.

When communicating data in ASCII code



When communicating data in binary code



### ■Device code (Only word device codes can be specified at indirect specification)

Specify the code of the device to be accessed. ( Page 66 Device range)

### ■Head device or device No.

Specify the head device or device No. with the same format as the message when extension is not specified.

### Response data

The same as when extension is not specified.

### Communication example

Access to @D0. (Consider @D0 indirect specification of D100.)

At command execution, store the D100 address in D0 with the following programs.



· When communicating data in ASCII code

(Request data)

S	ubcoı	nma	nd	Indi specifi		ı							Device Head device No. code or device No.				_	evice difica	-				
0	0	8	0	0	@	0	0	0	0	0	0	0	D	*	0	0	0	0	0	0	0	0	0
30н	30н	38н	30н	30н	40н	30н	30н	30н	30н	30н	1 30н	30н	44н	2Ан	30н	30н ј	30н I	30н	30н	30н	30н	30н	30н

· When communicating data in binary code

(Request data)

Subcommand	indirect specification	Head device No. or device No.	Device code					
80н ј 00н	00н <sub>г</sub> 08н	00н 00н 00н	А8н	00н ј	00н	00н	00н	00н

# Appendix 2 Command Comparison between MC Protocol and SLMP

The correspondence table of MC protocol and SLMP is shown below. When connecting an external device which uses MC protocol to a SLMP compatible device, check if replacement of command is required.

### Applicable 3E frame command list

The message format of 3E frame of the SLMP is the same as that of the QnA compatible 3E frame of MC protocol. The commands shown in the following table need not be replaced with SLMP commands.

MC protocol			SLMP		
Item	Command	Subcommand	Туре	Operation	
Batch read in bit units	0401	00□1	Device	Read	
Batch read in word units		00□0			
Batch write in bit units	1401	00□1		Write	
Batch write in word units		00□0			
Random read in word units	0403	00□0		Read Random	
Random write in bit units (Test)	1402	00□1		Write Random	
Random write in word units (Test)		00□0			
Multiple block batch read	0406	00□0		Read Block	
Multiple block batch write	1406	00□0		Write Block	
Remote RUN	1001	0000	Remote Control	Remote Run	
Remote STOP	1002	0000		Remote Stop	
Remote PAUSE	1003	0000		Remote Pause	
Remote latch clear	1005	0000		Remote Latch Clear	
Remote RESET	1006	0000		Remote Reset	
CPU model name read	0101	0000		Read Type Name	
Loopback test	0619	0000	Self-Test	•	
COM.ERR.LED off	1617	0000	Clear Error		
Remote password unlock	1630	0000	Password Unlock		
Remote password lock	1631	0000	Password Lock		

### Applicable 1E frame command list

The message format of 1E frame of the SLMP is the same as that of the A compatible 1E frame of MC protocol. The commands shown in the following table need not be replaced with SLMP commands.

MC protocol			SLMP	
Item	Command		Туре	Operation
Batch Reading	BR	4252H	Batch Reading	00H
	WR	5752H		01H
	QR	5152H		
Batch Writing	BW	4257H	Batch Writing	02H
	ww	5757H		03H
	QW	5157H		
Test (Random Write)	ВТ	4254H	Test (Random Write)	04H
	WT	5754H		05H
	QT	5154H		
Remote RUN	RR	5252H	Remote RUN	13H
Remote STOP	RS	5253H	Remote STOP	14H
Read CPU Model Name	PC	5043H	Read PC Type Name	15H
Global	GW	4757H	_	_
Loopback Test	TT	5454H	Loopback Test	16H

# **Appendix 3** CPU Module Processing Time of SLMP

When accessing the CPU module from an external device using SLMP communication, the following "intervention time to the scan time" and "number of scans for processing" of the CPU module side are required. On the request from the external device using SLMP communication, the CPU module processes a specified number of points during each END processing in case the CPU module is running.



The processing time of the following modules depends on the usage of other intelligent function modules.

- FX5-ENET
- FX5-ENET/IP
- FX5-CCLGN-MS
- FX5-CCLIEF
- FX5-40SSC-G, FX5-80SSC-G

### 3E frame

Item		Command	Subcommand	Access	Interve	ention tim	ne [ms] <sup>*2</sup> (	extensio	n of scar	n time)	Number of	
Туре	Operation			points 1) /	Acces	s point 1)	)	Access point 2)			scans	
				2)	FX5S	FX5UJ	FX5U/ FX5UC	FX5S	FX5UJ	FX5U/ FX5UC	for processing	
Device	Read	0401	0001	1/3584	0.04	0.04	0.03	2.30	2.23	1.33	1	
			0000	1/960	0.04	0.04	0.03	0.25	0.24	0.14	1	
	Write	1401	0001	1/3584	0.04	0.04	0.04	1.46	1.42	1.06	1	
			0000	1/960	0.04	0.04	0.03	0.28	0.26	0.20	1	
	Read Random	0403	0000	1/192	0.04	0.04	0.03	2.23	1.55	1.48	1	
	Write	1402	0001	1/188	0.04	0.04	0.03	2.11	1.49	1.41	1	
	Random		0000	1/160 <sup>*1</sup>	0.04	0.04	0.04	1.90	1.33	1.26	1	
	Read Block	0406	0000	1/960	0.04	0.04	0.03	0.26	0.24	0.14	1	
	Write Block	1406	0000	1/770	0.04	0.04	0.03	0.24	0.22	0.17	1	
Remote Control	Read Type Name	0101	0000	(one station)	0.04	0.04	0.02	_	_	_	1	

<sup>\*1</sup> This is the processing time when accessing with only word access points specified.

<sup>\*2</sup> This is the processing time (an average of actual measurements) when 1 is set to "CPU Parameter" - "Service Processing Setting" - "Device/Label Access Service Processing Setting" - "Set Processing Counts" of GX Works3.

### 1E frame

### **■When communicating data in ASCII code**

Operation	Command	Access points	Intervention time [ms]*2 (ext	tension of scan time)	Number of
		1) / 2)	Access point 1)	Access point 2)	scans required for processing
Batch Reading	00H	1/256	0.0187	0.0646	1
	01H	1/64	0.0196	0.0232	1
Batch Writing	02H	1/160	0.0206	0.0524	1
	03H	1/64	0.0212	0.0268	1
Test (Random Write)	04H	1/80	0.0221	0.5200	1
	05H	1/10 <sup>*1</sup>	0.0230	0.0788	1
Remote RUN	13H	_	0.0184	_	1
Remote STOP	14H	_	0.0187	_	1
Read PC Type Name	15H	_	0.0129	_	1
Loopback Test	16H	1/254	0.0201	0.0480	1

<sup>\*1</sup> This is the processing time when accessing with only word access points specified.

### **■**When communicating data in binary code

Operation	Command	Access points	Intervention time [ms]*2	(extension of scan time)	Number of	
		1) / 2)	Access point 1)	Access point 2)	scans required for processing	
Batch Reading	00H	1/256	0.0267	0.1250	1	
	01H	1/64	0.0287	0.1050	1	
Batch Writing	02H	1/160	0.0290	0.0950	1	
	03H	1/64	0.0304	0.0895	1	
Test (Random Write)	04H	1/80	0.0308	0.8010	1	
	05H	1/10 <sup>*1</sup>	0.0323	0.1210	1	
Remote RUN	13H	_	0.0210	_	1	
Remote STOP	14H	_	0.0222	_	1	
Read PC Type Name	15H	_	0.0240	_	1	
Loopback Test	16H	1/254	0.0265	0.2620	1	

<sup>\*1</sup> This is the processing time when accessing with only word access points specified.

<sup>\*2</sup> This is the processing time (an average of actual measurements) when 1 is set to "CPU Parameter" - "Service Processing Setting" - "Device/Label Access Service Processing Setting" - "Set Processing Counts" of GX Works3.



· Number of scans required for processing

The CPU module processes only one command during an END processing. If GX Works3 or other modules are also accessing the CPU module simultaneously, the number of scans required for processing may increase due to the waiting time.

• Method of reducing the intervention time to the scan time

Adjust the service process execution count of the CPU module in "CPU Parameter" - "Service Processing

Setting" - "Device/Label Access Service Processing Setting" to reduce the intervention time to the scan time.

( MELSEC iQ-F FX5 User's Manual (Application))

• When extension of scan time affects the control Access multiple times with less points.

<sup>\*2</sup> This is the processing time (an average of actual measurements) when 1 is set to "CPU Parameter" - "Service Processing Setting" - "Device/Label Access Service Processing Setting" - "Set Processing Counts" of GX Works3.

# **Appendix 4** Added and Enhanced Functions

The functions added or changed with the Ethernet-equipped module and engineering tool, and the supported Ethernet-equipped modules' firmware version and engineering tool software version are given below.

The CPU module firmware version can be confirmed with module diagnosis (CPU diagnosis). Refer to the following manuals for details on diagnosing the module (CPU diagnosis).

MELSEC iQ-F FX5S/FX5UJ/FX5U/FX5UC User's Manual (Hardware)

The firmware version of the Ethernet module can be found in the buffer memory (Un\G30).

Refer to the GX Works3 Operating Manual for details on the software version.

### **FX5S CPU module**

Add/Change Function	CPU module firmware version	Engineering tool software version	Reference
SLMP communication function	First released product or later	"1.080J" or later	_
MC protocol 1E frame	First released product or later	"1.080J" or later	_

### **FX5UJ CPU module**

Add/Change Function	CPU module firmware version	Engineering tool software version	Reference	
SLMP communication function	First released product or later	"1.060N" or later	_	
MC protocol 1E frame	"1.030" or later	"1.080J" or later	_	

### FX5U/FX5UC CPU module

Add/Change Function	CPU module firmware version	Engineering tool software version	Reference
Communication data code: ASCII code (X, Y HEX)	"1.040" or later	"1.030G" or later	Page 12
MC protocol 1E frame	"1.210" or later	_	_

### **Ethernet module**

### **■When FX5UJ CPU module is used**

Add/Change Function	Add/Change Function Applicable versions					
	CPU module firmware version	Ethernet module firmware version	Engineering tool software version			
SLMP communication function	"1.010" or later	"1.100" or later	"1.075D" or later	_		

### ■When FX5U/ FX5UC CPU module is used

Add/Change Function	Applicable versions			Reference
	CPU module firmware version	Ethernet module firmware version	Engineering tool software version	
SLMP communication function	"1.240" or later	"1.100" or later	"1.075D" or later	_

### CC-Link IE TSN master/local module

Add/Change Function	Applicable versions			Reference
	CPU module firmware version	FX5 intelligent function module firmware version	Engineering tool software version	
SLMP communication function	"1.210" or later	First released product or later	"1.065T" or later	_

### **Motion module**

Add/Change Function	Applicable versions			Reference
	CPU module firmware version	FX5 intelligent function module firmware version	Engineering tool software version	
SLMP communication function	"1.230" or later	First released product or later	"1.072A" or later	_

### **MEMO**

A

### **INDEX**

0 to 9
1E frame
A 47.10
Application data
В
Buffer memory 6
D
Data format
E
End code
Error information
External device
Н
Header
М
MC protocol7Module access device7Monitoring timer27,46
0
Other station.         6           Own station         6
Р
PC No
R
Relay station6Request data28,47Request data length26Request destination module I/O number24Request destination network number and requestdestination station number23Requested multi-drop station number25Response data28,48Response data length26
<u>S</u>
SLMP

## **REVISIONS**

Revision date	Revision	Description	
November 2014	A	First Edition	
January 2015	В	■Added function Data code of ASCII	
April 2015	С	A part of the cover design is changed.	
May 2016	D	■Added models  FX5U-32MR/DS, FX5U-32MT/DS, FX5U-32MT/DSS, FX5UC-64MT/D, FX5UC-64MT/DSS, FX5UC  96MT/D, FX5UC-96MT/DSS, FX5-CCLIEF  ■Added or modified parts  SAFETY PRECAUTIONS, RELEVANT MANUALS, TERMS, Section 1.2, 3.1, 4.1, 4.2, 4.3, 4.4, 4.5, 4.6, Appendix 1, WARRANTY	
October 2016	E	■Added models  FX5U-64MR/DS, FX5U-64MT/DS, FX5U-64MT/DSS, FX5U-80MR/DS, FX5U-80MT/DS,	
October 2019	F	■Added models  FX5UJ-24MR/ES, FX5UJ-24MT/ES, FX5UJ-24MT/ESS, FX5UJ-40MR/ES, FX5UJ-40MT/ES,  FX5UJ-40MT/ESS, FX5UJ-60MR/ES, FX5UJ-60MT/ESS, FX5UC-32MT/DS-TS,  FX5UC-32MT/DSS-TS, FX5UC-32MR/DS-TS  ■Added or modified parts  RELEVANT MANUALS, TERMS, Chapter 1, Section 3.1, 4.2, 4.3, Chapter 5, Appendix 1, 3, 4,  TRADEMARKS	
May 2020	G	■Added function  1E frame ■Added or modified parts  RELEVANT MANUALS, TERMS, Chapter 1, Section 2.1, 2.2, Chapter 3, 4, 5, 6, Appendix 1, 2, 3, 4  TRADEMARKS	
August 2020	Н	■Added or modified parts SAFETY PRECAUTIONS, WARRANTY	
April 2021	J	■Added models  FX5-ENET and FX5-ENET/IP  ■Added or modified parts  RELEVANT MANUALS, TERMS, Chapter 1, 2, 3, 4, 5, 6, Appendix 1, 3, 4	
April 2022	К	■Added models  FX5S CPU module, FX5-CCLGN-MS, FX5-40SSC-G, 80SSC-G  ■Added or modified parts  RELEVANT MANUALS, TERMS, GENERIC TERMS AND ABBREVIATIONS, Section 1.1, 3.1, 3.2  4.1, 4.2, 4.3, 4.6, Chapter 6, Appendix 1, 3, 4	

This manual confers no industrial property rights or any rights of any other kind, nor does it confer any patent licenses. Mitsubishi Electric Corporation cannot be held responsible for any problems involving industrial property rights which may occur as a result of using the contents noted in this manual.

### © 2014 MITSUBISHI ELECTRIC CORPORATION

### WARRANTY

Please confirm the following product warranty details before using this product.

# 1. Gratis Warranty Term and Gratis Warranty Range

If any faults or defects (hereinafter "Failure") found to be the responsibility of Mitsubishi occurs during use of the product within the gratis warranty term, the product shall be repaired at no cost via the sales representative or Mitsubishi Service Company. However, if repairs are required onsite at domestic or overseas location, expenses to send an engineer will be solely at the customer's discretion. Mitsubishi shall not be held responsible for any re-commissioning, maintenance, or testing on-site that involves replacement of the failed module.

#### [Gratis Warranty Term]

The gratis warranty term of the product shall be for one year after the date of purchase or delivery to a designated place. Note that after manufacture and shipment from Mitsubishi, the maximum distribution period shall be six (6) months, and the longest gratis warranty term after manufacturing shall be eighteen (18) months. The gratis warranty term of repair parts shall not exceed the gratis warranty term before repairs.

#### [Gratis Warranty Range]

- (1) The range shall be limited to normal use within the usage state, usage methods and usage environment, etc., which follow the conditions and precautions, etc., given in the instruction manual, user's manual and caution labels on the product.
- (2) Even within the gratis warranty term, repairs shall be charged for in the following cases.
  - Failure occurring from inappropriate storage or handling, carelessness or negligence by the user. Failure caused by the user's hardware or software design.
  - 2. Failure caused by unapproved modifications, etc., to the product by the user.
  - When the Mitsubishi product is assembled into a user's device, Failure that could have been avoided if functions or structures, judged as necessary in the legal safety measures the user's device is subject to or as necessary by industry standards, had been provided.
  - Failure that could have been avoided if consumable parts (battery, backlight, fuse, etc.) designated in the instruction manual had been correctly serviced or replaced.
  - Relay failure or output contact failure caused by usage beyond the specified life of contact (cycles).
  - Failure caused by external irresistible forces such as fires or abnormal voltages, and failure caused by force majeure such as earthquakes, lightning, wind and water damage.
  - Failure caused by reasons unpredictable by scientific technology standards at time of shipment from Mitsubishi.
  - Any other failure found not to be the responsibility of Mitsubishi or that admitted not to be so by the user.

### 2. Onerous repair term after discontinuation of production

- Mitsubishi shall accept onerous product repairs for seven (7) years after production of the product is discontinued.
  - Discontinuation of production shall be notified with Mitsubishi Technical Bulletins, etc.
- (2) Product supply (including repair parts) is not available after production is discontinued.

#### 3. Overseas service

Overseas, repairs shall be accepted by Mitsubishi's local overseas FA Center. Note that the repair conditions at each FA Center may differ.

## 4. Exclusion of loss in opportunity and secondary loss from warranty liability

Regardless of the gratis warranty term, Mitsubishi shall not be liable for compensation to:

- (1) Damages caused by any cause found not to be the responsibility of Mitsubishi.
- Loss in opportunity, lost profits incurred to the user by Failures of Mitsubishi products.
- (3) Special damages and secondary damages whether foreseeable or not, compensation for accidents, and compensation for damages to products other than Mitsubishi products.
- (4) Replacement by the user, maintenance of on-site equipment, start-up test run and other tasks.

### 5. Changes in product specifications

The specifications given in the catalogs, manuals or technical documents are subject to change without prior notice.

#### 6. Product application

- (1) In using the Mitsubishi MELSEC programmable controller, the usage conditions shall be that the application will not lead to a major accident even if any problem or fault should occur in the programmable controller device, and that backup and fail-safe functions are systematically provided outside of the device for any problem or fault.
- (2) The Mitsubishi programmable controller has been designed and manufactured for applications in general industries, etc. Thus, applications in which the public could be affected such as in nuclear power plants and other power plants operated by respective power companies, and applications in which a special quality assurance system is required, such as for railway companies or public service purposes shall be excluded from the programmable controller applications. In addition, applications in which human life or property that could be greatly affected, such as in aircraft, medical applications, incineration and fuel devices,
  - that could be greatly affected, such as in aircraft, medical applications, incineration and fuel devices, manned transportation, equipment for recreation and amusement, and safety devices, shall also be excluded from the programmable controller range of applications. However, in certain cases, some applications may be possible, providing the user consults their local Mitsubishi representative outlining the special requirements of the project, and providing that all parties concerned agree to the special circumstances, solely at the user's discretion.
- (3) Mitsubishi shall have no responsibility or liability for any problems involving programmable controller trouble and system trouble caused by DoS attacks, unauthorized access, computer viruses, and other cyberattacks.

### **TRADEMARKS**

Anywire and AnyWireASLINK are either registered trademarks or trademarks of Anywire Corporation.

The company names, system names and product names mentioned in this manual are either registered trademarks or trademarks of their respective companies.

In some cases, trademark symbols such as '™, or '®, are not specified in this manual.

**160** JY997D56001K

Manual number: JY997D56001K

Model: FX5-U-SL-E Model code: 09R541

### MITSUBISHI ELECTRIC CORPORATION

HEAD OFFICE : TOKYO BUILDING, 2-7-3 MARUNOUCHI, CHIYODA-KU, TOKYO 100-8310, JAPAN NAGOYA WORKS : 1-14 , YADA-MINAMI 5-CHOME , HIGASHI-KU, NAGOYA , JAPAN

When exported from Japan, this manual does not require application to the Ministry of Economy, Trade and Industry for service transaction permission.

Specifications subject to change without notice.