[Issue No.] T40-0007 [Title] Corrections in the QnPRHCPU User's Manual (Redundant System) [Relevant Models] Q12PRHCPU, Q25PRHCPU

[Page] 1/4 [Date of Issue] Dec., '06

Thank you for your continued support of Mitsubishi programmable logic controllers, MELSEC-Q series.

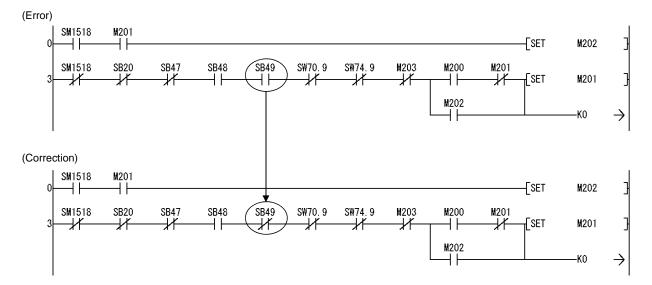
This bulletin provides information on corrections due to clerical errors in the program examples of the QnPRHCPU User's Manual (Redundant System) (SH-080486ENG) of "version F (printed in June, 2006)". The contents of this technical bulletin are included in the "version G (printed in December, 2006)".

1. Correction

- (1) Section 7.1 (1) (b) [Diagram 7.2 Example of REMFR instruction programming]
- (2) Section 7.3 (1) [Diagram 7.13 Program That Turns on the "USER" LED after System Switching]
- (3) Section 8.2 (2) (c) [Diagram 8.10 Sample Program for Clearing Standby System CPU Module Error]
- (4) Appendix 4.5 (1) (a) 2) [Diagram App.7 A sample program of CHANGE]
- (5) Appendix 5 (2) [Diagram App.20 A program example]

2. Correction details

 Section 7.1 (1) (b) [Diagram 7.2 Example of REMFR instruction programming] The setting condition for the host data link status has been corrected in the example of a program for reading intelligent function module data of the remote I/O station using the REMFR instruction as shown below.



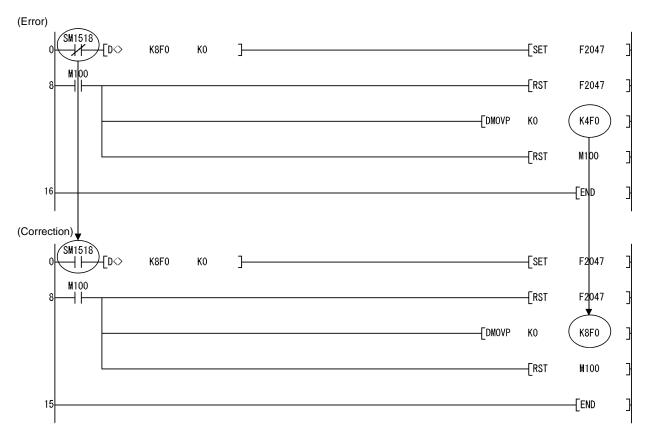
HEAD OFFICE : 1-8-12, OFFICE TOWER Z 14F HARUMI CHUO-KU 104-6212, JAPAN NAGOYA WORKS : 1-14, YADA-MINAMI 5-CHOME, HIGASHI-KU, NAGOYA, JAPAN

[Issue No.] T40-0007 [Title] Corrections in the QnPRHCPU User's Manual (Redundant System)

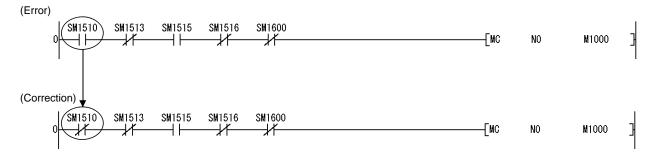
[Page] 2/4 [Date of Issue] Dec., '06

[Relevant Models] Q12PRHCPU, Q25PRHCPU

(2) Section 7.3 (1) [Diagram 7.13 Program That Turns on the "USER" LED after System Switching] The SM1518 contact and the storage destination device of the DMOV instruction have been corrected in the example of a program for turning ON "USER" LED on the CPU module in the new control system after switching as shown below.



(3) Section 8.2 (2) (c) [Diagram 8.10 Sample Program for Clearing Standby System CPU Module Error] The SM1510 contact has been corrected in the example of a program for clearing errors of the CPU module in standby system as shown below.



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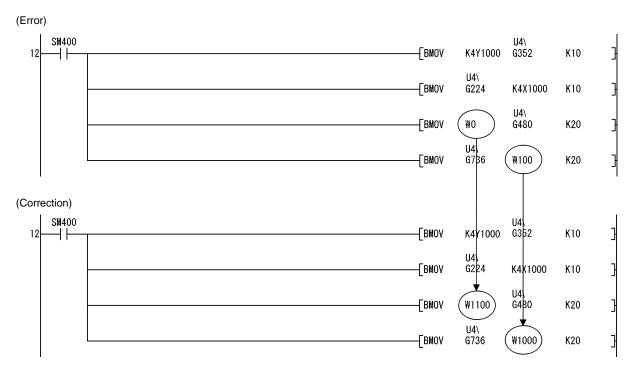
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[Issue No.] T40-0007 [Title] Corrections in the QnPRHCPU User's Manual (Redundant System)

[Page] 3/4 [Date of Issue] Dec., '06

[Relevant Models] Q12PRHCPU, Q25PRHCPU

(4) Appendix 4.5 (1) (a) 2) [Diagram App.7 A sample program of CHANGE] The head device number in the remote register has been corrected in the example of a program when using CC-Link as shown below.



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[Issue No.] T40-0007 [Title] Corrections in the QnPRHCPU User's Manual (Redundant System)

[Page] 4/4 [Date of Issue] Dec., '06

(5) Appendix 5 (2) [Diagram App.20 A program example]

[Relevant Models] Q12PRHCPU, Q25PRHCPU

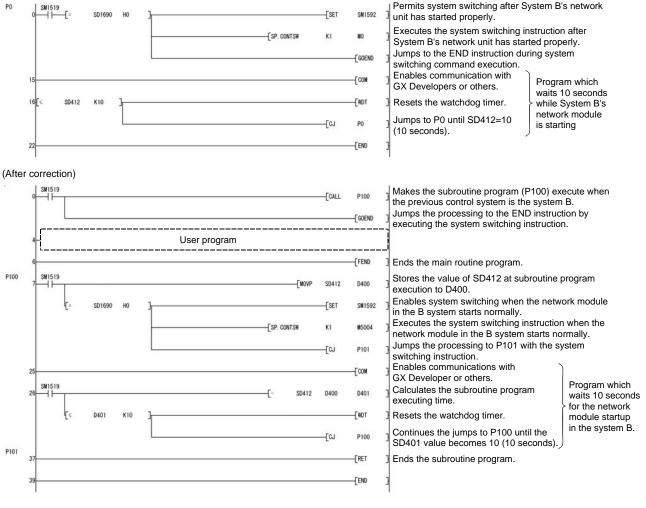
1) Operation of the program before correction

When 32768 seconds (around 9. 1 hours) elapses after the CPU module became RUN status, SD412 value will be -32768. In the following program (before correction), since the processing is repeated in the relevant program until the SD412 value will be 10 or more again (around 9. 1 hours), other sequence operations cannot be performed. Note when this occurs, the CPU module will not be STOP status even the RUN/STOP switch is set from RUN to STOP.

2) Corrections

The method for starting with the previous control system has been corrected in the example of a program when mounting a network module to the base unit as shown below.

(Before correction)



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