

Subject: Report of RT ToolBox3 Ver.1.20W release

Applicable to: FR series, F series, SQ series, SD series, S series
(CR800/CR750/CR700/CR500 series robot controller)

Thank you for your continued support of Mitsubishi industrial robot "MELFA".

This Technical news describes the new version 1.20W of the RT ToolBox3.
3F-14C-WINJ(E) / 3F-15C-WINJ(E) / 3F-16D-WINJ(E)

In order to use the functions described in this technical news, you need to download the latest version from MITSUBISHI ELECTRIC FA site, and upgrading the RT ToolBox3.

1. Additional model

- Corresponded to CR800-Q series.

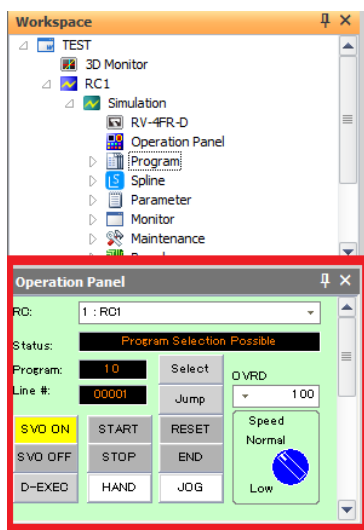
Corresponds to CR800-Q series robot.

Device monitor / Multi-CPU parameter / IO unit Parameter screen corresponds to CR800-Q series.

- Model added for RH-3CRH4018-D / RH-6CRH6020-D / RH-6CRH7020-D.

2. Operation Panel

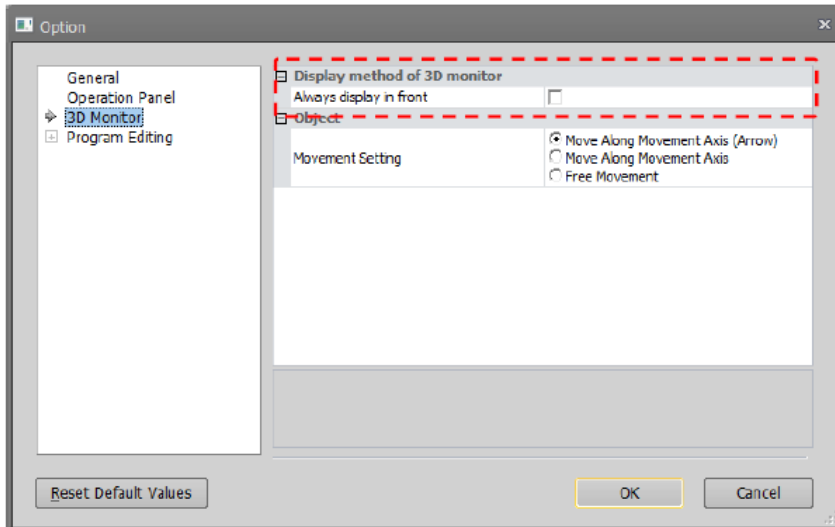
- Add function to switch base.
- Added function that display in docking window.



3. 3D monitor

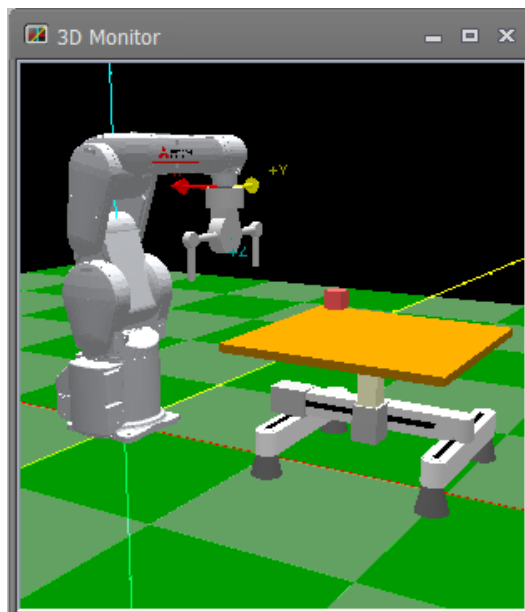
- Added setting to display 3D monitor always in front of option.

By checking [Always display in front] in [3D Monitor], it will always be displayed on the front from the time the next 3D monitor is started up and you can move outside the screen of RT ToolBox3.

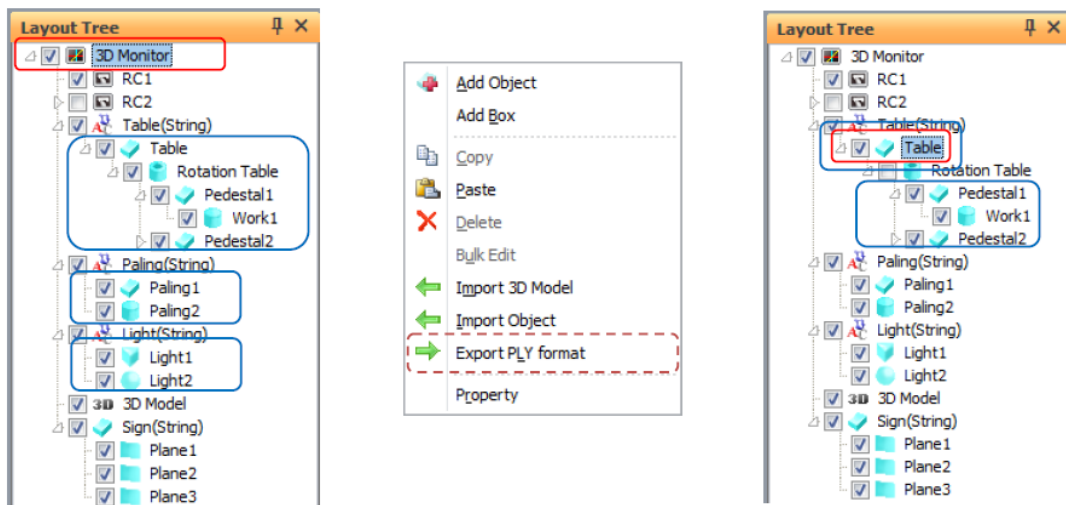


- Added function that display user mechanism.

Create a user mech. file from the [User Mech. File Manager] and add the user mech. item to the robot in the layout tree and select the user mech. file to be displayed.



- Added function that export layout object in PLY format.



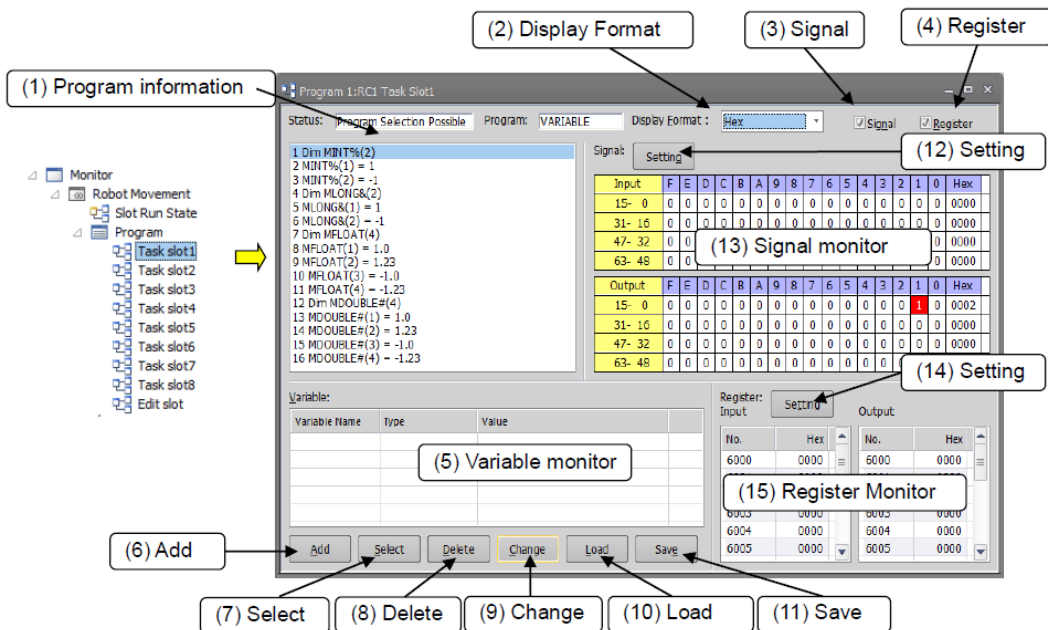
: Object to be the origin
 : Export object

4. Oscillograph

- Function safety items (Safety input , Safety input signal A , Safety input signal B) added to acquired data.

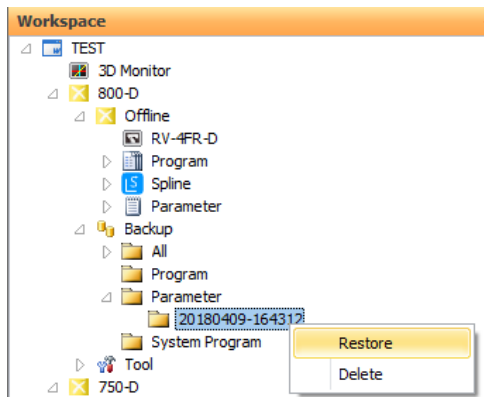
5. Program monitor

- Added general purpose signal monitor and register monitor on program monitor.



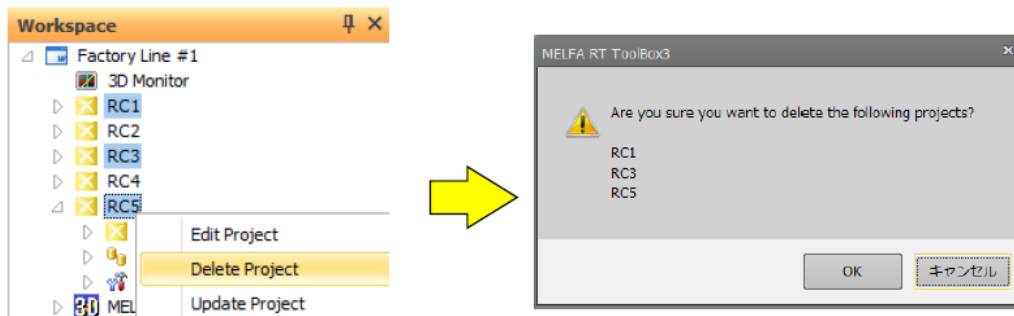
6. Restore

- The "parameter" backup can be restored to the offline project.



7. Project

- Added a function to delete multiple projects at once.



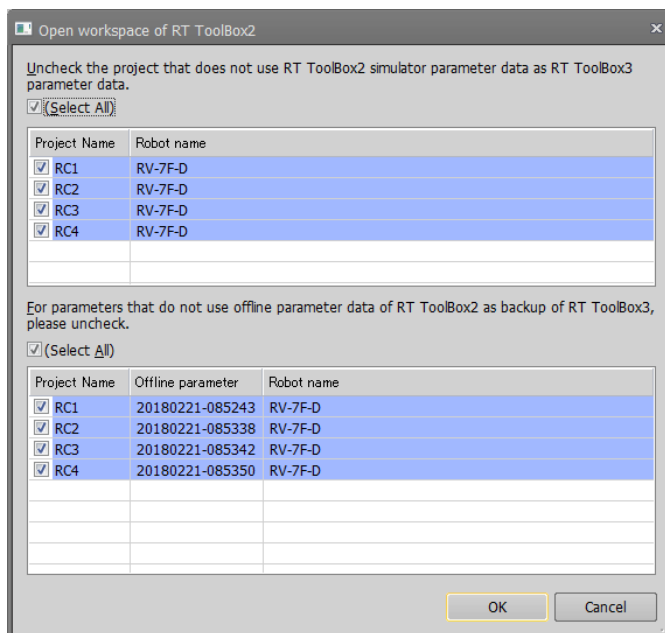
- Change the process of opening the project of RT Toolbox2.

When RT Toolbox2 workspace is opened with RT Toolbox3, a dialog is displayed to confirm whether to use RT Toolbox2 parameters for the first time only.

RT Toolbox3 displays the following RT Toolbox2 parameter information.

Simulator parameters -> Offline parameters

Offline parameters -> Backup parameter information



(End)