# Mitsubishi Electric Corporation Industrial Robot 



## Subject: Report about enabled faster command speed of the spline interpolation

## Applicable to: MELFA FR series (CR800-D/CR800-R/CR800-Q series)

Thank you for your continued support of Mitsubishi industrial robot "MELFA".
This Technical news describes that the spline interpolation function was improved and it became possible to specify the command speed faster than before.

## 1. Enabled faster command speed of the spline interpolation

In the spline interpolation, it is possible to specify a faster command speed than before.
To use this function, specify " 1 " for the parameter SPLHSPMD.
As shown in the table below, depending on the value of the parameter SPLHSPMD, the required distance between path points relative to the command speed changes. Setting the parameter SPLHSPMD to " 1 " makes it possible to specify a faster speed for the distance between the same path points.

| Command speed <br> $[\mathrm{mm} / \mathrm{s}]$ | Required distance between path points |  |
| :---: | :---: | :---: |
|  | SPLHSPMD=0 (Factory setting) | SPLHSPMD=1 |
| 10 | 0.6 mm or more | 0.08 mm or more |
| 20 | 1.2 mm or more | 0.16 mm or more |
| 50 | 3.0 mm or more | 0.4 mm or more |
| 100 | 6.0 mm or more | 0.8 mm or more |
| 200 | 12.0 mm or more | 1.6 mm or more |
| 500 | 30.0 mm or more | 4.0 mm or more |

For example, when the distance between path points is 0.6 mm , the speed that can be specified conventionally is up to $10 \mathrm{~mm} / \mathrm{s}$, but by using this function the speed that can be specified is up to $75 \mathrm{~mm} / \mathrm{s}$.

## 2. Corresponding software version

The software version corresponding to the above function is shown in the table below.

| Software | Corresponding version |
| :---: | :---: |
| Robot controller software | Ver.A3a or later ${ }^{\left({ }^{(1)}\right)}$ |
| Engineering software "RT ToolBox3" | Ver.1.31H or later ${ }^{(* 2)}$ |

(*1) Ver.A3a is applied sequentially from the robot controller manufactured in October 2018.
(*2) It is possible to make robot programs and spline files that operate at faster command speed even in versions prior to Ver.1.31H.

