## MITSUBISHI ELECTRIC

## Numerical Protection Relay

# MELPRO ${ }^{\text {Tw }}$-D Series <br> GENERATOR PROTECTION RELAY 

MODEL

## CGP2-A41D1/CGP2-A42D1

INSTRUCTION MANUAL

For the latest version of this instruction manual, please download from the URL below.
http://www.mitsubishielectric.co.jp/fa/download/search.do?mode=manual\&kisyu=/pror

## - Safety precautions -

Before installation, operation, maintenance, and inspection, please be sure to read this instruction manual and all other attached documents thoroughly in order to work safely with the equipment. Please ensure that you fully understand the equipment, safety information, and precautions that need to be taken before working with the equipment.
Safety precautions are classified as "Danger" and "Caution."


Danger
The case where a dangerous situation can arise and there is the possibility that death or seriously injury can occur if the equipment is handled incorrectly.


The case where a dangerous situation can arise and there is the possibility that moderate or minor injuries canl occur, or property damage can take place if the equipment is handled incorrectly.
Furthermore, even with items described as $\triangle$ Caution, there is the possibility of serious consequences depending on the situation. All of the described contents are important. Therefore, be sure to comply with them.

## [Transportation]



- Transport the equipment in the correct orientation.
-Do not apply excessive shock and/or vibration as this could affect the performance and life of the product.


## [Storage]



The storage environment shall comply with the following conditions (compliant with JEC25002010). Otherwise, there is a risk of reducing the performance and life of the product.

- Ambient temperature $\quad-20$ to $+60^{\circ} \mathrm{C}$ The state where dew condensation or freezing does not occur.
- Relative humidity $\quad 30$ to $80 \%$ on daily average
- Altitude $\quad 2000 \mathrm{~m}$ or lower
- The equipment must not be exposed to abnormal vibration, shock, inclination, or magnetic fields.
- The equipment must not be exposed to harmful smoke/gas, saline gas, water droplets or vapour, excessive dust or fine powder, explosive gas or fine powder, wind \& rain.


## [Installation, wiring work]

| The equipment must be correctly grounded using the designated grounding terminals where |
| :--- |
| they exist. Failure to do so may lead to the risk of electric shock, equipment failure, malfunction |
| or failure to operate. |
| Be sure to return all terminal covers, protection covers to their original positions once |
| any work is complete. If they remain uncovered there is a risk of electrical shock. |


| - Ensure that the equipment is mounted and connected correctly. Otherwise, there are risks of |  |  |
| :--- | :--- | :--- |
| failure, burning, or maloperation.. |  |  |
| - Securely tighten the terminal connection screws. Otherwise, there are risks of failure and burning. |  |  |
| - For tightening torque of screws, refer to the following Table. |  |  |
| Place of use Nominal dia. Standard value of torque <br> (steel screw)   | Allowable range |  |
| Terminal block | M3.5 | $1.10 \mathrm{~N} \cdot \mathrm{~m}(11.2 \mathrm{kgf} \cdot \mathrm{cm})$ |
| Panel mounting | M5.0 | $3.24 \mathrm{~N} \cdot \mathrm{~m}(33 \mathrm{kgf} \cdot \mathrm{cm})$ |

## [Operating and Setting the equipment]

| -The equipment must only be operated and handled by qualified personnel. Otherwise, there are |
| :--- |
| risks of electric shock, injury, failure, malfunction, and maloperation. |
| - Handling and maintenance of the equipment must only be carried out after gaining a thorough |
| understanding of the instruction manual. Otherwise, there is the risk of electric shock, injury, |
| failure, malfunction, or maloperation. |



The equipment must be used within the following range limits (compliant with JEC2500-2010). Otherwise, there is a risk of reducing the performance and life of the product.

- Variation range of control power supply voltage Within $-15 \%$ to $+10 \%$ of the rated voltage
- Frequency variation
- Ambient temperature
- Relative humidity
- Altitude

Within $\pm 5 \%$ of the rated frequency
0 to $+40^{\circ} \mathrm{C}$
(-10 to $50^{\circ} \mathrm{C}$ is allowable temporarily within few hours a day, but use under the state where dew condensation or freezing does not occur.)
30 to $80 \%$ on daily average
2000 m or lower

- The state where abnormal vibration, shock, inclination, magnetic field are not applied
- The state where it is not exposed to harmful smoke/gas, saline gas, water droplet or vapor, excessive dust or fine powder, explosive gas or fine powder, wind \& rain
-While energized, do not tamper with or remove any components other than those which have been designated. Otherwise, there is a risk of failure, malfunction, or maloperation.
-While energized, do not draw out the internal unit (subunit). Otherwise, there is a risk of electric shock, injury, failure, malfunction, or maloperation.
-When changing the setting value during the energized state, ensure that all trip circuits are locked in order not to operate. Otherwise, there is a risk of malfunction.

The equipment must only be operated and handled by qualified personnel. Otherwise, there are risks of electric shock, injury, failure, malfunction, and maloperation.
-Handling and maintenance of the equipment must only be carried out after gaining a thorough understanding of the instruction manual. Otherwise, there is the risk of electric shock, injury, failure, malfunction, or maloperation.
-Do not touch any live parts, such as terminals, etc. Otherwise, there is a risk of electric shock.


Caution
-When replacing the equipment, use a product of same model, rating, and specifications.
Otherwise, there is the risk of failure or fire.. If any other product is to be used, the manufacturer must be consulted.
-We recommend that any tests or inspections are carried out under the following conditions, as well as any additional conditions described in the instruction manual.

- Ambient temperature
$20 \pm 10^{\circ} \mathrm{C}$
- Relative humidity
- External magnetic field
$90 \%$ or less
- Atmospheric pressure
$80 \mathrm{~A} / \mathrm{m}$ or less
- Mounting angle
- Frequency

86 to $106 \times 10^{3} \mathrm{~Pa}$

- Frequency
(in the case of AC)
- AC component (in the case of DC)

Ripple factor 3\% or less
Ripple
factor $=$$\quad$ Max. value - Min. value $\quad$ Average value of DC $100(\%)$

- Control power supply voltage Rated voltage $\pm 2 \%$
-Do not exceed the overload capacity for voltage and current. Otherwise,equipment failure or fire could occur.
-Do not clean the equipment while energised. When the cover needs to be cleaned, make use of a damp cloth.


## [Repair and modification]

| Caution |
| :--- |
| -When carrying out repair and/or modification, please consult with the manufacturer in <br> advance.of carrying out the work. We will not take any responsibility for any repair and/or <br> modification (including software) which has been carried out without prior consent. |

## [Disposal]

| ! Cisposal must take place in accordance with the applicable legislation |
| :---: |

## Guarantee

1. Guarantee period

The guarantee period of this product should be one year after delivery, unless otherwise specified by both parties.
2. Scope of guarantee

When any fault or defect is detected during the period of guarantee and such fault or defect is proved to be caused apparently at the responsibility of MITSUBISHI ELECTRIC CORPORATION, the defective unit concerned will be repaired or replaced with substitute with free of charge.
However, the fee for our engineer dispatching to site has to be covered by the user.
Also, site retesting or trial operation caused along with replacing the defect units should be out of scope of our responsibilities.
It is to be acknowledged that the following faults and defects should be out of this guarantee.
(1) When the faults or defects are resulted from the use of the equipment at the range exceeding the condition/environment requirements stated in the catalogue and manual.
(2) When the faults or defects are resulted from the reason concerning without our products.
(3) When the faults or defects are resulted from the modification or repair carried out by any other entity than MITSUBISHI ELECTRIC CORPORATION.
(4) When the faults or defects are resulted from a phenomenon which cannot be predicted with the science and technology put into practical use at the time of purchase or contract
(5) In case of integrating our products into your equipment, when damages can be hedged by the proper function or structure in the possession of your equipment which should be completed according to the concept of the de fact standard of industry.
(6) In case of that the faults or defects are resulted from un-proper application being out of instruction of MITSUBISHI ELECTRIC CORPORATION.
(7) In case that the faults or defects are resulted from force majeure such a fire or abnormal voltage and as an act of God such as natural calamity or disaster.
3. Exclusion of loss in opportunity and secondary loss from warranty liability Regardless of the gratis warranty term, MITSUBISHI ELECTRIC CORPORATION shall not be liable for compensation of damages caused by any cause found not be the responsibility of MITSUBISHI ELECTRIC CORPORATION, loss in opportunity, lost profits incurred to the user by failures of MITSUBISHI ELECTRIC CORPORATION products, special damages and secondary damages whether foreseeable or not, compensation for accidents, and compensation for damages to products other than MITSUBISHI ELECTRIC CORPORATION products and other tasks.
4. Applications of products
(1) The user is requested to confirm the standards, the regulations and the restrictions which should be applied, in case of utilizing products described in this catalogue and another one in combination.
Also, the user is requested to confirm the suitability of our products to your applied system or equipment or apparatus by yourself.
MITSUBISHI ELECTRIC CORPORATION shall not be liable for any suitability of our products to your utilization.
(2) This MITSUBISHI ELECTRIC CORPORATION products described in the catalogue have been designed and manufactured for application in general industries, etc. Thus, application in which the life or an asset could be affected by special application such as medical system for life-sustaining, in nuclear power plants, power plants, aerospace, transportation devices(automobile, train, ship, etc.) shall be excluded from the application. In addition to above, application in which the life or an asset could be affected by potentially chemical contamination or electrical interference and also in which the circumstances and condition are not mentioned in this catalogue shall be excluded from the application.

Note even if the user wants to use for these applications with user's responsibility, the user to be requested to approve the specification of MITSUBISHI ELECTRIC CORPORATION products and to contact to the technical section of MITSUBISHI ELECTRIC CORPORATION prior to such applications.
If the user applies MITSUBISHI ELECTRIC CORPORATION products to such applications without any contact to our technical section, MITSUBISHI ELECTRIC CORPORATION shall not be liable for any items and not be insured, independently from mentioned in this clause.
(3) In using MITSUBISHI ELECTRIC CORPORATION product, the working conditions shall be that the application will not lead to a major accident even if any problem or fault occur, and that backup or duplicate system built in externally which should be decided depend on the importance of facility, is recommended.
(4) The application examples given in this catalogue are reference only and you are requested to confirm function and precaution for equipment and apparatus and then, use our products.
(5) The user is requested to understand and to respect completely all warning and caution items so that unexpected damages of the user or the third party arising out of un-correct application of our products would not be resulted.
5. Onerous repair term after discontinuation of product
(1) MITSUBISHI ELECTRIC CORPORATION shall accept onerous product repairs for 7(seven) years after production of the product is discontinued. (However, please consider the replacement of products after 15 years have been passed from ex-work of products.)
(2)Product supply (including repair parts) is not available after production is discontinued.
6. Changes in product specification

The specification given in the catalogue, manuals or technical documents are subject to change without prior to notice.
7. Scope of service

The technical service fee such as engineer dispatching fee is excluded in the price of our products.
Please contact to our agents if you have such a requirement.

Improvement on the reliability of protection function

Any parts and materials applied to the protection relay have limited life time which will bring the degradation to the relay.
The degree of degradation will be variable and depend on the purpose, period in use, applied circumstance and unevenness on the performance of each part.
MITSUBISHI ELECTRIC CORPORATION design the relay so as to realize that the recommended replaced duration is more than 15 years.
However, there may be some possibilities to occur some defects before reaching 15 years due to above mentioned the degree of degradation of parts and materials being depended on the condition in use.
To prevent unwanted operation or no operation of relay due to above reasons, it is recommended to apply the relay with self-diagnosis function and/or multiplexing relay system such as dual or duplex scheme.

## Introduction

Thank for your purchasing MITSUBISHI ELECTRIC MELPRO ${ }^{\text {TM }}$ - D Series Digital Protection Relay.
Please read this instruction manual carefully to be familiar with the functions and performances enough to use the product properly.
It is necessary to forward this instruction manual to end users and a person in charge of maintenance.
In regard to the instruction manual for PC software, read the following document.

| Title of document | Document No. |
| :---: | :---: |
| MELPRO-D Series Protection Relay <br> PC-HMI Instruction Manual | JEP0-IL9504 |

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## 1. General description

Mitsubishi Electric MELPRO ${ }^{\text {TM }}$ - D Series is a digital protection relay product with a microprocessor for protection of high/extra-high voltage electric power systems.
With its improved functions, such as PLC (Programmable Logic Controller), data saving at the time when relay elements are operated, and measurement of input value, this series of protection relay allows stable and effective control and monitoring of electric power systems as well as high-reliable protection.

## High accurate digital computation

The digital computation with high-speed sampling minimizes the effect of higher harmonics, etc., which enables high accurate protections. As this computation is implemented in software, stable operation without aging is obtained.

Advanced self-diagnosis function improves reliability
The relay continuously monitors electronic circuits from input to output so that it can detect internal component failure, which enables to improve reliability.

## Measurement functions

The input values of the relay (e.g. current, voltage, phase and frequency) can be measured at a steady state, which is useful for energy-saving management. Measurement items differ depending on the types of the relay units.

Data saving functions
Various record functions as shown below are useful for fault investigations.
(1) The data savings of input value at the time when relay element are operated.
(2) The operation logs of the relay.

## Programmable output contacts with PLC provide flexibility

The operation of output contacts can be set by combining the detection or definitive signals of the protection elements with PLC which incorporates logic circuit (e.g. OR, AND, NOT, and flip-flop) and timer (e.g. on-delay, offdelay, and one-shot). This is useful for easy designing of sequential circuits and reducing labor-hours of wiring.

## Forced contact test enables checking of relay sequence

The output contacts can be forced to operate in the test menu, which enables checking of relay sequence easily.

## Easy replacement

The cut-out dimensions of panel are the same as MULTICAP-C series or the old model of MELPRO-DASH series. Replacing an existing relay with this new type is easy. (There are some exceptions.)

## Easy maintenance

The relay adopts draw-out unit mechanisms with automatic CT shorting at drawing, thereby making it easy to maintain the relay.

## Diverse operation and reset characteristics

The relay incorporates various operation and reset characteristics including the standards of IEC 60255-3, which can be adopted to the protection of various types of electric systems.

Communication network (will be supported in the future)
The relay can build a network system which allows monitoring and control of measurement values, operation status, and setting changes, etc., from a remote location. This leads to labor-saving of maintenance.
2. Structure

### 2.1. Front view of relay

For the details about front panel, refer to Section 5.1.


Fig. 2-1 Front view of relay

### 2.2. Terminal layout on the back of relay



Fig. 2-2 Terminal layout on the back of relay


Fig. 2-3 Terminal number on the back of relay
2.3. Dimensions of relay and Cut-Out dimensions of panel


Fig. 2-4 Dimensions of relay


Fig. 2-5 Cut-Out dimensions of panel

### 2.4. External view of relay



Fig. 2-6 External view of relay

## 3. Handling, Mounting

### 3.1. Unpacking

Usually this relay is packed in a case for transportation. However, it may occur that only the sub-unit is transported independently for the convenience at repair. In such a case, fully brush off the dust, dirt, etc. adhered to the sub unit after completion of unpacking, and further visually check that the parts mounted on the front panel or built in the sub unit are not damaged.

### 3.2. Transportation and storage

To carry the equipment within the place of use, handle it carefully so that the parts installed on the front panel of the sub-unit or built-in parts cannot be deformed or broken.

### 3.3. How to draw sub-unit out

The relay has draw-out construction to facilitate inspection and testing. Therefore, it is possible to draw out the sub-unit without disconnecting the external wiring

When drawing out the subunit, be sure to take the following steps to avoid the unwanted operation of primary equipment:

- Open control power supply of the relay (Note: Take care that the appropriate circuit is opened.)
- Shunt / Isolate the CT circuit
- Lock out the tripping circuit including breakers etc.
- Disconnect the main control circuits

As an additional precaution, the CT circuit is provided with an automatic short-circuiting mechanism. This will ensure that the CT secondary circuit is not opened when the sub-unit is removed even if the CT circuits have not been shunted.
3.3.1. Procedures for drawing out subunit
(1) Removing screws


When drawing out the subunit from the outer case, open upper \& lower screw covers at the front side of the subunit and detach both screws.
(2) Drawing out the subunit


Draw out subunit horizontally by using fingers on the upper \& lower grooves of it.
3.3.2. Procedures for housing subunit
(1) Inserting the subunit


Insert subunit into the outer case horizontally by using fingers on the upper \& lower grooves of it. Ensure that there is no gap between front side of the subunit and outer case.
(2) Fixing the screws


Tighten upper \& lower screws and fix the subunit to the outer case. After that, close screw covers.

### 3.4. Mounting



When inserting this relay into control panel, take care in order not to damage it.
After inserting, fix this relay with washers and nuts which are supplied with the product.

Section 2.3 explains Cut-Out dimensions of panel.

### 3.5. Distance between two devices

If you install more than one relay devices in a control panel, please leave 50 mm between one device and another.


## 4. Connection

### 4.1. Precautions for wiring work

(1) Multiplexing

Important facilities should be provided with fail-safe measures such as dual or duplex system in order to improve reliability of the facilities.

## (2) Effects of external surge

Some types of surge with a certain condition may negatively affect the relay. If so, take it into account to install surge absorbers. (MF type surge absorbers made by Mitsubishi Electric, for example.)
(3) Guarantee of control power supply against power interruption

The control power supply of the relay is not guaranteed against power interruption. When you do not have an uninterruptible power supply (UPS), please purchase it that is made by Mitsubishi Electric or commercially available. When you select UPS, please confirm rated values, ambient temperature, and other service conditions.
(4) Inrush current of control power supply

Since inrush current may flow in the relay when the control power supply is turned on as shown in the figure below, make consideration of this point when selecting the breaker for the control power supply circuit.


Fig. 4-1 Inrush current of control power supply

## (5) Self-diagnosis output circuit

In order to be able to continue monitoring even if the built-in power fuse is blown, the self-diagnosis output circuit adopts normally-closed contact which is excited (opened) at the time of normal condition of monitoring. Therefore, connect the timer to the external wiring. For details, refer to Fig. 4-2.
(6) Trip circuit

There are two kinds of output contacts for the trip circuits and the control circuits. Please keep in mind that the output contacts for control circuits cannot be used for the trip circuit. (If used, the contact may burn.)
Connect the pallet contact (52a) of the circuit breaker to the trip circuit.

## (7) Ground circuit

Be sure to earth the ground terminal located on the back of the relay with D class grounding method whose ground resistance is $100 \Omega$ or less.
(8) ZCT circuit

It is necessary to reduce surge or noise which is entered into the relay as much as possible, thus the connection from ZCT to the relay should be done with 2 core shielded cable whose cross-sectional area is $0.75 \sim 1 \mathrm{~mm}^{2}$. The shield of the cable should be connected to the ground terminal of the relay or that of the cubicle.
The burden should be less than $5 \Omega$ as a round-trip (e.g. about 100 meters one way for $0.75 \mathrm{~mm}^{2}$ cable).

### 4.2. Terminal layout

Regarding to the terminal layout, refer to Section 2.2. The screw size of each terminal is M3.5. Recommended wire size is $2 \mathrm{~mm}^{2}$ or less.

### 4.3. External connection

4.3.1. Connection example of control circuit

$\left(^{*}\right)$ Refer to Section 4.1-(3) "Guarantee of control power supply against power interruption".
Fig. 4-2 Connection example of control power supply and self-diagnosis output circuit.
4.3.2. Connection example of input circuit

This figure shows concept of the connection to the relay. Therefore, the position or condition of CT, VT, and other devices sometimes differs from the actual state.


Fig. 4-3 CGP2-A41D1 Example of AC input circuit
In the case of normal condition of generator (which flows through-current), the current flows into the lower number terminal of the relay on the output side of generator and flows from the lower number terminal of the relay on the neutral point side of generator.


Fig. 4-4 CGP2-A41D1 Example of AC input circuit
(In the case of using only LOF element on A and B phase)


Fig. 4-5 CGP2-A41D1 Example of AC input circuit
(In the case of using only LOF element on A and C phase)
Note: This relay calculates LOF element from current inputs of [A-01~A-02], [A-03 ~ A-04] and voltage inputs of $[\mathrm{A}-15 \sim \mathrm{~A}-16]$ and phase relation of them.


Fig. 4-6 CGP2-A42D1 Example of AC input circuit
In the case of normal condition of generator (which flows through-current), the current flows into the lower number terminal of the relay on the output side of generator and flows from the lower number terminal of the relay on the neutral point side of generator.

## 5. Human machine interface

There are three ways to set and operate the relay:
(1) Operation from the front panel
(2) Operation from a locally connected PC

This chapter describes about "(1) Operation from the front panel" by pushbuttons and the indication display. The operation method (2) is described in a separate volume. Please refer to the following document.

| Title of document | Document No. |
| :---: | :---: |
| MELPRO-D Series Protection Relay | JEP0-IL9504 |
| PC-HMI Instruction Manual |  |

### 5.1. Pushbutton switches and indication display

This section describes the pushbuttons and indication display on the front panel.


Fig. 5-1 Front view of relay


Fig. 5-2 Operation display LEDs of CGP2-A41D1


Fig. 5-3 Operation display LEDs of CGP2-A42D1

Table 5-1 Description of front panel

(*) The LED continues lighting after resetting the protection element. You can turn the LED off by pushing ESC/C button if the trouble has been resolved.

### 5.2. List of menus

The operation mode includes the DISPLAY and SETTING modes, which respectively have different menus. Table 5-2 lists the menus available in the respective modes.

Table 5-2 List of menu
O: DISPLAY only ©: DISPLAY and SETTING -: Not shown

| Menu |  | Operation mode |  |
| :---: | :---: | :---: | :---: |
|  |  | DISPLAY | SETTING |
| Status (STATUS) | Clock (CLOCK) | O | - |
|  | Measured analog value (METERING) | 0 | - |
|  | DI/DO status (DIGITAL I/O) | $\bigcirc$ | - |
|  | Trip counter (TRIP COUNTER) | $\bigcirc$ | - |
|  | Device name (DEVICE NAME) | 0 | - |
| Record (RECORD) | Fault record (FAULT RECORD) | $\bigcirc$ | - |
|  | Event record (EVENT RECORD) | 0 | - |
|  | Access record (ACCESS RECORD) | $\bigcirc$ | - |
|  | Alarm record (ALARM RECORD) | $\bigcirc$ | - |
| Setting (SETTING) | Active group (ACTIVE WG) | 0 | $\bigcirc$ |
|  | Group 1 setting (G1) | 0 | $\bigcirc$ |
|  | Group 2 setting (G2) | $\bigcirc$ | $\bigcirc$ |
| Control (CONTROL) | Control mode (CTRL MODE) | $\bigcirc$ | $\bigcirc$ |
|  | CB control (CB CONTROL) | - | $\bigcirc$ |
| Configuration (CONFIG) | Communication setting (COMMUNICATION) | $\bigcirc$ | $\bigcirc$ |
|  | Clock adjustment (CLOCK ADJUST) | - | $\bigcirc$ |
|  | Analog value display switching (METERING) | 0 | $\bigcirc$ |
|  | Trip counter (TRIP COUNTER) | 0 | $\bigcirc$ |
|  | Disturbance record (DISTURBANCE) | $\bigcirc$ | $\bigcirc$ |
|  | DI voltage (DI VOLTAGE) | 0 | $\bigcirc$ |
|  | Password use/unuse (PASSWORD USE) | - | $\bigcirc$ |
|  | Password registration (PASSWORD REGIST) | - | $\bigcirc$ |
| Test <br> (TEST) | DO contact test (CONTACT TEST) | - | $\bigcirc$ |
|  | Test mode (MODE) | - | $\bigcirc$ |
|  | LED/VFD lighting test (LED/VFD TEST) | - | $\bigcirc$ |
| Clear record (RECORDCLR) | Clear fault record (FAULT REC CLEAR) | - | $\bigcirc$ |
|  | Clear alarm record (ALARM REC CLEAR) | - | $\bigcirc$ |
|  | Clear event record (EVENT REC CLEAR) | - | $\bigcirc$ |

### 5.3. Operation method

This section describes the operations for mode selection and various menus.

### 5.3.1. DISPLAY/SETTING mode selection

Press a key except for ESC/C when VFD is OFF to show the DISPLAY/SETTING mode selection screen. The DISPLAY and SETTING modes offer different sets of menus available.
For the details about the menus in the respective modes, see Table 5-2.


### 5.3.2. DISPLAY mode menu operations

This subsection describes the menu operations in the DISPLAY mode.
The menu screen has five selectable items. Use the Up and Down keys to select the item and press SELECT. For the details about the menus available in the DISPLAY mode, see Table 5-2.


Use $\boldsymbol{\Delta}$ and $\boldsymbol{\nabla}$ to switch between items and press SELECT to select an item.

This subsection describes the Status (STATUS) menu.
The Status menu shows the current time, measured value, DI/DO status, trip counter, device name and Software version.

5.3.2.1.1. Clock (CLOCK) menu
[Operation path] DISPLAY MODE > STATUS > CLOCK
The clock (CLOCK) menu allows viewing of the current time and synchronization type.

$$
\begin{array}{lr}
\hline \text { CLOCK } & (\text { LOCAL }) \\
2017-01-01 & 00: 00: 00
\end{array}
$$

The text in the upper right part of the screen indicates the synchronization type for the time shown. (Part showing "LOCAL" in figure above)
[Operation path] DISPLAY MODE > STATUS > METERING
The Measured analog value (METERING) menu allows viewing of the current measured value.
The Configuration menu can specify the measured value of the primary or secondary value of CT/VT. For the setting procedure, see 5.3.4.3.3.


Note: This is an example.

By pressing SELECT, you can expand the character size of the measured value. Pressing SELECT again goes back to the original state.


Table 5-3 Measured value display items

- CGP2-A41D1

| No. | Signal name | Unit (primary/secondary) | No. | Signal name | Unit (primary/secondary) |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 11a | A / A | 10 | Vab | kV / V |
| 2 | 11b | A/A | 11 | 11a-ph | ${ }^{\circ} \mathrm{LAG} /{ }^{\circ} \mathrm{LAG}$ |
| 3 | 11 c | A / A | 12 | 11b-ph | ${ }^{\circ} \mathrm{LAG} /{ }^{\circ} \mathrm{LAG}$ |
| 4 | 12a | A / A | 13 | I1c-ph | ${ }^{\circ} \mathrm{LAG} /{ }^{\circ} \mathrm{LAG}$ |
| 5 | 12b | A/A | 14 | 12a-ph | ${ }^{\circ} \mathrm{LAG} /{ }^{\circ} \mathrm{LAG}$ |
| 6 | I2c | A/A | 15 | I2b-ph | ${ }^{\circ} \mathrm{LAG} /{ }^{\circ} \mathrm{LAG}$ |
| 7 | Ida | A / A | 16 | I2c-ph | ${ }^{\circ} \mathrm{LAG} /{ }^{\circ} \mathrm{LAG}$ |
| 8 | Idb | A/A | 17 | Vab-ph | ${ }^{\circ} \mathrm{LAG} /{ }^{\circ} \mathrm{LAG}$ |
| 9 | Idc | A / A |  |  |  |

- CGP2-A42D1

| No. | Signal name | Unit (primary/secondary) | No. | Signal name | Unit (primary/secondary) |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 11a | A / A | 10 | 11a-ph | ${ }^{\circ} \mathrm{LAG} /{ }^{\circ} \mathrm{LAG}$ |
| 2 | 11b | A / A | 11 | 11b-ph | LAG / ${ }^{\circ} \mathrm{LAG}$ |
| 3 | 11c | A/A | 12 | 11c-ph | ${ }^{\circ} \mathrm{LAG} /{ }^{\circ} \mathrm{LAG}$ |
| 4 | 12a | A / A | 13 | 12a-ph | ${ }^{\circ} \mathrm{LAG} /{ }^{\circ} \mathrm{LAG}$ |
| 5 | 12b | A/A | 14 | 12b-ph | ${ }^{\circ} \mathrm{LAG} /{ }^{\circ} \mathrm{LAG}$ |
| 6 | 12c | A/A | 15 | I2c-ph | ${ }^{\circ} \mathrm{LAG} /{ }^{\circ} \mathrm{LAG}$ |
| 7 | Ida | A/A |  |  |  |
| 8 | Idb | A / A |  |  |  |
| 9 | Idc | A / A |  |  |  |

5.3.2.1.3. DI/DO status (DIGITAL I/O) menu
[Operation path] DISPLAY MODE > STATUS > DIGITAL I/O The DI/DO status (DIGITAL I/O) menu allows viewing of the current DI/DO.


Table 5-4 DI/DO status display items

| No. | Signal name | No. | Signal name |
| :---: | :---: | :---: | :---: |
| 1 | DI1 | 9 | DO1 |
| 2 | DI2 | 10 | DO2 |
| 3 | DI3 | 11 | DO3 |
| 4 | DI4 | 12 | DO4 |
| 5 | DI5 | 13 | DO5 |
| 6 | DI6 | 14 | DO6 |
| 7 | DI7 | 15 | DO7 |
| 8 | DI8 | 16 | DO8 |

5.3.2.1.4. Trip counter (TRIP COUNTER) menu
[Operation path] DISPLAY MODE > STATUS > TRIP COUNTER
The Trip counter (TRIP COUNTER) menu allows viewing of the number of trips.

```
TRIP COUNTER
Trip CNT : O
```

5.3.2.1.5. Device name (DEVICE NAME) menu
[Operation path] DISPLAY MODE > STATUS > DEVICE NAME
The Device name (DEVICE NAME) menu allows viewing of the device name.

> DEVICE NAME DEVICE 1

### 5.3.2.2. Record (RECORD) menu

This subsection describes the operation logs in the Record (RECORD) menu.
The Record menu allows viewing four types of log data.
(Fault record, Event record, Access record and Alarm record)

[Operation path] DISPLAY MODE > RECORD > FAULT RECORD
The Fault record (FAULT RECORD) menu allows viewing of the time, operating values and operating elements when the fault is detected. Fault records of up to five phenomena are stored and the respective fault record can be viewed. For selecting record for display, use the Up and Down keys to select the date of the fault record and press SELECT.


Use $\boldsymbol{\Delta}$ and $\boldsymbol{\nabla}$ to switch between items and press SELECT to select an item.

Note: This is an example.

After a fault record is selected, use the Up and Down keys to view the trip factors and measured values.


Note: This is an example.

## Table 5-5 Elements of fault records (CGP2-A41D1)

| Element name displayed |
| :---: |
| DIFF-A Trip |
| DIFF-B Trip |
| DIFF-C Trip |
| LOF Trip |

Table 5-6 Elements of fault records (CGP2-A42D1)

| Element name displayed |
| :---: |
| DIFF-A Trip |
| DIFF-B Trip |
| DIFF-C Trip |

Table 5-7 Measured values of fault records (CGP2-A41D1)

| No. | Signal name | Unit |
| :---: | :---: | :---: |
| 1 | I a | A |
| 2 | I b | A |
| 3 | I c | A |
| 4 | I a | A |
| 5 | I b | A |
| 6 | I c | A |
| 7 | Vab | kV |
| 8 | Ida | A |
| 9 | Idb | A |
| 10 | Idc | A |
| 11 | I1a-ph | ${ }^{\circ}$ LAG |
| 12 | I1b-ph | ${ }^{\circ}$ LAG |
| 13 | I1c-ph | ${ }^{\circ}$ LAG |
| 14 | I2a-ph | ${ }^{\circ}$ LAG |
| 15 | I2b-ph | ${ }^{\circ}$ LAG |
| 16 | I2c-ph | ${ }^{\circ}$ LAG |
| 17 | Vab-ph | ${ }^{\circ}$ LAG |

Table 5-8 Measured values of fault records (CGP2-A42D1)

| No. | Signal name | Unit |
| :---: | :---: | :---: |
| 1 | 11 a | A |
| 2 | 11 b | A |
| 3 | $\mathrm{I1c}$ | A |
| 4 | I a | A |
| 5 | I b | A |
| 6 | I c | A |
| 7 | Ida | A |
| 8 | Idb | A |
| 9 | Idc | A |
| 10 | I1a-ph | ${ }^{\circ}$ LAG |
| 11 | $11 \mathrm{~b}-\mathrm{ph}$ | ${ }^{\circ}$ LAG |
| 12 | I1c-ph | ${ }^{\circ}$ LAG |
| 13 | I2a-ph | ${ }^{\circ}$ LAG |
| 14 | I2b-ph | ${ }^{\circ}$ LAG |
| 15 | I2c-ph | ${ }^{\circ}$ LAG |

[Operation path] DISPLAY MODE > RECORD > EVENT RECORD

The Event record (EVENT RECORD) menu allows viewing of event records saved.
Event records of up to 512 events are stored and the respective event record can be viewed.
Press the Up and Down keys to switch the indication on the screen as below.
Date of occurrence > Record description > Date of occurrence...

Press the Right key to display from the current event record to the past $10^{\text {th }}$ record.


Use $\boldsymbol{\Delta}$ and $\boldsymbol{\nabla}$ to change the display item.
Use to move from the record currently shown to the date of the tenth record into past.

Note: This is an example.

Table 5-9 List of event record (CGP2-A41D1)

|  |  |
| :--- | :--- |
| DI1 | Status of DI1 |
| DI2 | Status of DI2 |
| DI3 | Status of DI3 |
| DI4 | Status of DI4 |
| DI5 | Status of DI5 |
| DI6 | Status of DI6 |
| DI7 | Status of DI7 |
| DI8 | Status of DI8 |
| DO1 | Status of DO1 |
| DO2 | Status of DO2 |
| DO3 | Status of DO3 |
| DO4 | Status of DO4 |
| DO5 | Status of DO5 |
| DO6 | Status of DO6 |
| DO7 | Status of DO7 |
| DO8 | Status of DO8 |
| TCNT_ALM | Alarm of trip counter |
| CBa1 | Status of CB |
| INT_LK_OP | Interlock signal (OPEN) |
| INT_LK_CL | Interlock signal (CLOSE) |
| CTL_OP_OK | Possible to CB open control |
| CTL_CL_OK | Possible to CB close control |
| CB_CTL_OK | Success of CB control |
| CB_CTL_NG | Failure of CB control |
| OP_TS | CB open control (local) |
| CL_TS | CB close control (local) |
| MANU_CLS | Command of CB close |
| MANU_OPN | Command of CB open |
| CB_LR | Aocal or Remote |
| CTL_BLOP1 | Prohibition of open |
| CTL_BLCL1 | Prohibition of close |
| 43INT_FLG | Use / Non-use setting of interlock |
| VL4000000 | Choice failure |
| RES_STS00 | Success of control |
| RES_STS02 | Lack of control / Prohibition of operation |
| RES_STS05 | Control of the same direction |
| RES_STS0A | Failure of interlock condition |
| RES_STS10 | Time out |
| CL_DI | DI command of close |
| OP_DI | DI command of open |
| P_INT_LK1 | Interlock of close-side |
| P_INT_LK2 | Active status of DI for CB control |
| CB_DI_CTL | ALAR of constant supervision (serious failure) |
| ALARM | ALARM-L |


| RY-LOCK | Locking of relay |
| :--- | :--- |
| SV-LK | Locking of supervision |
| TCNT-LK | Locking of trip counter |
| ALLEL-O | OR of all "definitive signal AND operation lock signal" |
| DS_TRIG | Pulse signal from start-up until the end of data saving <br> (Except for pre-fault time) |
| DIFF-A | Definitive signal of DIFF A-phase or forced operation from PC-HMI |
| DIFF-B | Definitive signal of DIFF B-phase or forced operation from PC-HMI |
| DIFF-C | Definitive signal of DIFF C-phase or forced operation from PC-HMI |
| LOF | Definitive signal of LOF or forced operation from PC-HMI |

Table 5-10 List of event record (CGP2-A42D1)

|  |  |
| :--- | :--- |
| DI1 | Status of DI1 |
| DI2 | Status of DI2 |
| DI3 | Status of DI3 |
| DI4 | Status of DI4 |
| DI5 | Status of DI5 |
| DI6 | Status of DI6 |
| DI7 | Status of DI7 |
| DI8 | Status of DI8 |
| DO1 | Status of DO1 |
| DO2 | Status of DO2 |
| DO3 | Status of DO3 |
| DO4 | Status of DO4 |
| DO5 | Status of DO5 |
| DO6 | Status of DO6 |
| DO7 | Status of DO7 |
| DO8 | Status of DO8 |
| TCNT_ALM | Alarm of trip counter |
| CBa1 | Status of CB |
| INT_LK_OP | Interlock signal (OPEN) |
| INT_LK_CL | Interlock signal (CLOSE) |
| CTL_OP_OK | Possible to CB open control |
| CTL_CL_OK | Possible to CB close control |
| CB_CTL_OK | Success of CB control |
| CB_CTL_NG | Failure of CB control |
| OP_TS | CB open control (local) |
| CL_TS | CB close control (local) |
| MANU_CLS | Command of CB close |
| MANU_OPN | Command of CB open |
| CB_LR | Aocal or Remote |
| CTL_BLOP1 | Prohibition of open |
| CTL_BLCL1 | Prohibition of close |
| 43INT_FLG | Use / Non-use setting of interlock |
| VL4000000 | Choice failure |
| RES_STS00 | Success of control |
| RES_STS02 | Lack of control / Prohibition of operation |
| RES_STS05 | Control of the same direction |
| RES_STS0A | Failure of interlock condition |
| RES_STS10 | Time out |
| CL_DI | DI command of close |
| OP_DI | DI command of open |
| P_INT_LK1 | Interlock of close-side |
| P_INT_LK2 | Active status of DI for CB control |
| CB_DI_CTL | ALARM |
| ALARM-L | Abonstant supervision (serious failure) |
|  |  |


| RY-LOCK | Locking of relay |
| :--- | :--- |
| SV-LK | Locking of supervision |
| TCNT-LK | Locking of trip counter |
| ALLEL-O | OR of all "definitive signal AND operation lock signal" |
| DS_TRIG | Pulse signal from start-up until the end of data saving <br> (Except for pre-fault time) |
| DIFF-A | Definitive signal of DIFF A-phase or forced operation from PC-HMI |
| DIFF-B | Definitive signal of DIFF B-phase or forced operation from PC-HMI |
| DIFF-C | Definitive signal of DIFF C-phase or forced operation from PC-HMI |

5.3.2.2.3. Access record (ACCESS RECORD) menu
[Operation path] DISPLAY MODE > RECORD > ACCESS RECORD
The Access record (ACCESS RECORD) menu allows viewing of the saved access records.
Access records of up to 512 accesses are stored and the records for the respective accesses can be viewed. Press the Up and Down keys to switch the indication on the screen as below.

Date of occurrence > Record description > Date of occurrence...

Press the Right key to display from the current access record to the past 10th record.



Use $\triangle$ and $\nabla$ to change the display item.
Use to move from the record currently shown to the date of the tenth record into past.

Note: This is an example.

Access record description registered (operator)

| Display item | Operation description |
| :--- | :--- |
| RY | Front panel |
| PC | PC-HMI |
| AUT | Automatic cancelation on device |

Access record description registered (operation description)

| Display item | Operation description |
| :--- | :--- |
| CHG_ACT_SET_G | Change of active setting group |
| CHG_DI_VOLTAGE | Change of configuration of DI voltage |
| CHG_DIST_REC_T | Change of configuration of disturbance record |
| CHG_USE_PASSWD | Change of password use setting |
| CHG_PASSWD | Change of password |
| CHG_USB_CONN | Change of USB connection channel |
| CHG_TRIP_CNTR | Change of trip counter |
| CHG_DEV_NAME | Change of device name |
| CHG_CFG_METER | Change of configuration of analog measurement status display |
| CHG_CFG_ENERGY | Change of configuration of electric energy |
| CHG_TIMEMANAGE | Change of configuration of time management |
| CHG_CTRL_MODE | Change of CB control mode |
| CHG_CONTACT_T | Change of configuration of DO contact test |
| CHG_PLC_DATA | Change of PLC data |
| CHG_SET_DATA | Change of relay setting |
| CLR_FAULT_REC | Clearing of fault/disturbance record |
| CLR_ALARM_REC | Clearing of alarm record |
| CLR_EVENT_REC | Clearing of event record |
| ADJ_CLOCK | Adjustment of system clock |
| ACT_TST_MODE | Activation of test mode |
| DEACT_TST_MODE | Deactivation of test mode |
| RESET_LED | LED reset |
| STA_CONTACTTST | Start of DO contact test |
| STP_CONTACTTST | Stop of DO contact test |
| LOCK_SV | Lock of self-diagnosis |
| UNLOCK_SV | Unlock of self-diagnosis |
| STA_I/F_TST | Start of forced operation |
| STP_I/F_TST | Stop of forced operation |
| OPERATE_CB | Operation of CB control (open / close) |

[Operation path] DISPLAY MODE > RECORD > ALARM RECORD
The Alarm record (ALARM RECORD) menu allows viewing of the saved alarm records.
Alarm records of up to 200 alarms are stored and the records for the respective alarms can be viewed. Press the Up and Down keys to switch the indication on the screen as below.

Date of occurrence > Record description > Date of occurrence...
Press the Right key to display from the current alarm record to the past 10th record.


Use $\boldsymbol{\triangle}$ and $\boldsymbol{\nabla}$ to change the display item.
Use to move from the record currently shown to the date of the tenth record into past.

Note: This is an example.

The Setting menu can be selected in either DISPLAY or SETTING mode but the DISPLAY mode only allows viewing of the setting values.
The setting values can be changed only in the SETTING mode.
For operations for the Setting menu, see 5.3.4.1.

### 5.3.2.4. Control (CONTROL) menu

The Control menu can be selected in either DISPLAY or SETTING mode but the DISPLAY mode only allows viewing of the setting of Control mode.
In the SETTING mode, both Control mode and CB control can be shown and set.

For operations for the Control menu, see 5.3.4.2.
5.3.2.5. Configuration (CONFIG) menu

The Configuration menu can be selected in either DISPLAY or SETTING mode. Clock adjustment (CLOCK ADJUST), Password use/unuse (PASSWORD USE) and Password registration (PASSWORD REGIST) can be selected only in the SETTING mode.
For other settings, the DISPLAY mode allows only viewing of the setting values.
The setting values can be changed only in the SETTING mode.

For operations for the Configuration menu, see 5.3.4.3.

If the password use/unuse setting is "USE," a four-digit password is requested when the SETTING mode is selected.

* For the password use/unuse setting, see 5.3.4.3.7.

For how to set the password input, see 5.3.4.3.8.


Use $\boldsymbol{\Delta}$ and $\boldsymbol{\nabla}$ to change the value of the each digit selected. Pressing SELECT confirms the value for the digit entered and moves the cursor to the next digit on the right.

If the password input is wrong, a screen as shown below appears.
PASSWORD INCORRECT
TRY AGAIN

The main menu appears when the correct password has been input.
MAIN MENU $\boldsymbol{\Delta ~ V}$
SETTINGS

This subsection describes the SETTING mode menu.
The menu screen has five selectable items. Use the Up and Down keys to select the item and press SELECT. For the details about the menus available in the SETTING mode, see Table 5-2.


Use $\boldsymbol{\Delta}$ and $\boldsymbol{\nabla}$ to switch between items and press SELECT to select an item.

The Setting (SETTING) menu allows viewing/changing of the active setting group and viewing/changing of the group setting values.
The Setting menu can be selected in either DISPLAY or SETTING mode but the setting values can be changed only in the SETTING mode.
(The DISPLAY mode allows only viewing of the setting values.)


### 5.3.4.1.1. Active group (ACTIVE WG) menu

## [Operation path] SETTING MODE > SETTING > ACTIVE WG

The Active group (ACTIVE WG) menu allows changing of the active group numbers setting.
(Active group numbers can be changed only in the SETTING mode.
The DISPLAY mode allows only viewing of the current group numbers.)

## ACTIVE WG

```
:G1
```

To change the active group number, in the Active group menu, press SELECT.
A cursor appears, which allows the selection of a group number with the Up and Down keys. Select the group number to change and press SELECT to confirm the change.

| ACTIVE WG | Use $\boldsymbol{\Delta}$ and $\boldsymbol{\nabla}$ to switch between group <br> $: \square 1$ |
| :---: | :--- |
| Nos. and press SELECT to confirm the change |  |

Press ENTER to show the confirmation screen below. Press SELECT to initiate the change to the group number selected.
When the new active group setting is not required, press the Left key to return the display back.

```
CHANGE ACTIVE WG?
YES=SELECT NO=<
```



Press ENTER to show the screen on the left.
The next message shows the Successful or Unsuccessful change of active group number.
Pressing SELECT brings the display back to the Setting menu.
SETTING
HAVE CHANGED

Message for a successful change of the active group

## SETTING

## FAILED TO CHANGE

Message for an unsuccessful change of the active group

The cancel message will appear by pressing the Left key in the Active group menu.
Pressing SELECT exits the Active group menu without changing the active group and brings the display back to the Setting menu.
Pressing the Left key brings the display back to the Active group menu.
CANCEL ACTIVE WG?
YES=SELECT NO=4
5.3.4.1.2. Group 1 setting (G1) and Group 2 setting (G2) menus
[Operation path] SETTING MODE $>$ SETTING $>$ G1(G2)
The Group 1 setting (G1) and Group 2 setting (G2) menus allow viewing and changing of the setting values for the respective group settings.
(Setting values can be changed only in the SETTING mode. The DISPLAY mode allows only viewing of the setting values)
The operation procedure for changing group settings is explained by changing G1 (for example).

1. First, select the setting value group in the Setting menu to change and press SELECT.

## SET-SETTING

```
:G1
```

2. The Group setting menu appears.

Select the protective element to change with pressing the Up and Down key, and press SELECT.


Note: This is an example.
3. The cursor moves to the setting parameter indication.

Use the Up and Down keys to select the setting parameter to be changed and press SELECT. The cursor moves to the setting value indication.

4. Use the Left and Right keys to select the digit to change and use the Up and Down keys to set the value.

```
G1 Ope. Curt.
DIFF
5A
```

For setting a value as shown on the left, use $\boldsymbol{4}$ and to select the digit to change, and $\boldsymbol{\Delta}$ and $\boldsymbol{\nabla}$ to set the value.
Press SELECT to confirm the change.
5. When the value has been changed, press SELECT to move the cursor to the setting parameter indication.

6. Complete setting of all parameters in the element to change by repeating steps 2 to 5 above.
7. Press the Left key to return the cursor back to the protective element indication.

Complete setting of any other protective elements to change by repeating steps 1 to 6 above.
8. When the all necessary change of the setting values has been completed, press ENTER.

A confirmation message of the setting value changes appears as shown in the figure below. After confirmation of correct settings, press SELECT. If discarding the setting value changes, press the Left key.

```
CHANGE SETTING?
YES=SELECT NO=<
Press SELECT to change the setting. Press \(\boldsymbol{4}\) to discard the change.
```

The following messages are shown respectively to check the successful or unsuccessful setting change, The display returns back to the Setting menu by pressing SELECT while either of the messages below.

## SETTING <br> HAVE CHANGED

Message for successful
changes of setting value

## SETTING <br> FAILED TO CHANGE

Message for unsuccessful changes of setting value
5.3.4.2. Control (CONTROL) menu

The Control (CONTROL) menu allows viewing/changing of Control mode and CB control.
The Control menu can be selected in either DISPLAY or SETTING mode but the DISPLAY mode only allows viewing of the setting of Control mode.
In the SETTING mode, both Control mode and CB control can be shown and set.


Use $\boldsymbol{\Delta}$ and $\boldsymbol{\nabla}$ to switch between items 'and press SELECT to select an item.

### 5.3.4.2.1. Control mode (CTRL MODE) menu

[Operation path] SETTING MODE > CONTROL > CTRL MODE
The Control mode (CTRL MODE) menu allows setting of the Local/remote control, Interlock selection and Circuit breaker operation blocking.
(Note that they can be set only in the SETTING mode. The DISPLAY mode only allows viewing of the settings.)

1. Use the Up and Down keys to show the control mode item to change and press the SELECT key for selection.

2. The cursor moves to the setting value. Use the Up and Down keys to change the setting value.
(The setting value below shows a selection setting. For a numeric value setting, use the Left and Right keys to change the digit for setting.)
CTRL MODE
LOCAL/REMOTE:R
3. Press the SELECT key to change the setting value.
```
CTRL MODE \ V
LOCAL/REMOTE:L
```

4. Repeat steps 1 to 3 until there are no more items you want to change.
5. Press the ENTER key, and a message appears to confirm application of the control mode settings that were just changed as shown in the figure below.
Press the SELECT key to apply the control mode settings that were just changed by steps 1 to 4 and complete the control mode setting.
```
CHANGE CTRL MODE?
YES=SELECT NO=\
```

Press the Left key to go back to the Control mode menu without applying the settings that were just changed.

CANCEL CTRL MODE?
YES=SELECT NO=

Table 5-11 Setting items of Control mode

| NO. | Item | Description | Setting range | Unit |
| :---: | :--- | :--- | :--- | :--- |
| 1 | REMOTE/LOCAL | Remote / Local setting | R / L | - |
| 2 | INTERLOCK | Interlock unuse/use selection setting | UNUSE / USE | - |
| 3 | CB OPEN | CB open control operation block setting | UNBLK / BLK | - |
| 4 | CB CLOSE | CB close control operation block setting | UNBLK / BLK | - |
| 5 | ON TIMER | Control waiting time | $0-60$ | s |

5.3.4.2.2. CB Control (CB CONTROL) menu
[Operation path] SETTING MODE > CONTROL $>$ CB CONTROL
The CB control (CB CONTROL) menu allows CB open control/CB close control.
This item can be selected for implementing CB control only in the SETTING mode.
For CB control, the control mode settings must be as shown in the table below.
For details about control mode operation, refer to 5.3.4.2.1.
For details about the CB control functions including other conditions required for CB control, refer to Chapter 9.

Table 5-12 Control mode settings when CB Control is executed

- CB open control

| Item | Setting value | Description of the setting value |
| :--- | :--- | :--- |
| REMOTE/LOCAL | L | Set to the local state. |
| INTERLOCK | UNUSE | Set to the interlock unuse state. |
| CB OPEN | UNBLK | Set to the CB open control operation block resetting state. <br> Set to UNBLK to enable CB open control. |

- CB close control

| Item | Setting value | Description of the setting value |
| :--- | :--- | :--- |
| REMOTE/LOCAL | L | Set to the local state. |
| INTERLOCK | UNUSE | Set to the interlock unuse state. |
| CB CLOSE | UNBLK | Set to the CB close control operation block resetting state. <br> Set to UNBLK to enable CB close control. |

1. Use the Up and Down keys to show the CB control setting item to change and press the SELECT key.

* Select CB OPEN for CB open control and CB CLOSE for CB close control.
(The figure below shows an example of a screen that appears when CB OPEN is selected.)


[^0] and press the SELECT key to select an item.
2. The display switches to the CB status indication screen.

Press the Up and Down keys to cycle through items of CB status indication.

3. After confirming the CB status, press the ENTER key while the CB status indication screen is shown. The following screen appears to confirm whether to execute CB control. Press the SELECT key to execute the control and press the Left key not to execute the control.

```
CB OPEN EXECUTE OK?
YES=SELECT NO=
```

If CB control has been successful, a control success message is displayed.

## CB OPEN SUCCEED

If $C B$ control has been unsuccessful, a control failure message is displayed.
CB OPEN FAILED

If the control mode is not set as specified in Table 5-12 or if control condition is not satisfied, an error message as shown below is displayed.

```
CB OPEN
CONDITION FAILURE
```

Pressing the SELECT key while the above control success message, control failure message, or error message is shown brings the display back to the CB control menu.

### 5.3.4.3. Configuration (CONFIG) menu

This subsection describes the operations for the Configuration (CONFIG) menu.
The Configuration menu can be selected in either DISPLAY or SETTING mode. Clock adjustment (CLOCK ADJUST), Password use/unuse (PASSWORD USE) and Password registration (PASSWORD REGIST) can be selected only in the SETTING mode.
The other settings can be changed in the SETTING mode only.
(The DISPLAY mode only allows viewing of the setting values)

5.3.4.3.1. Communication setting (COMMUNICATION) menu
[Operation path] SETTING MODE > CONFIG > COMMUNICATION
In regard to the standard products, there is no communication function.
In this menu, the message "NONE" appears on the display.

COMMUNICATION
:NONE
5.3.4.3.2. Clock adjustment (CLOCK ADJUST) menu
[Operation path] SETTING MODE > CONFIG > CLOCK ADJUST
The Clock adjustment (CLOCK ADJUST) menu allows time setting.
This item can be selected only in the SETTING mode.

1. When the Clock adjustment menu is selected, the current time is indicated as shown below.

Pressing SELECT while this screen is shown allows changing of the year, month, day, hour, minute and second settings.

2. Pressing the Up and Down keys cycles through the year, month, day, hour, minute and second selection items. Select the item to change and press SELECT.

3. The cursor moves to the setting value. Use the Up and Down keys to select the value and the Left and Right keys to select the digit to make the change.

4. Press SELECT to change the setting value.

| CFG-CLOCK |  | $\boldsymbol{\Delta} \boldsymbol{\nabla}$ |  |
| :--- | :--- | :--- | :--- |
| MONTH | $:$ | 11 |  |

5. Complete setting of all other items to change by repeating steps 1 . to 3 ..
6. Press ENTER and the confirmation message of the time setting appears.

Press SELECT to apply the time setting changed by steps 1. to 4 . and complete the Clock adjustment setting.
Press the Left key to go back to the Clock adjustment menu without applying the setting changes.

> CHANGE SETTING? YES=SELECT NO=
5.3.4.3.3. Analog value display switching (METERING) menu
[Operation path] SETTING MODE > CONFIG > METERING
The Analog value display switching (METERING) menu allows configuration of the following settings.
(1) Set the indication type from the primary or secondary side of CT/VT
(2) Set the rating of CT/VT.
(The DISPLAY mode only allows viewing of the setting values)

The following describes the operation procedure for viewing and changing the settings for the Measurement value display switching menu.


Note: This is an example.

1. Use the Up and Down keys to select the item to change and press SELECT for selection.

| CFG-METERING $\boldsymbol{\Delta}$ |
| :--- | :--- |
| AI Disp. $:$ PRIMARY |

2. The cursor moves to the setting value. Use the Up and Down keys to select the value and the Left and Right keys to select the digit to make the change.
3. Press SELECT to change the setting value.
4. Complete setting of all other items to change by repeating steps 1 . to 3 ..
5. Press ENTER and the confirmation message of the new measurement settings appears as shown in the figure below.
Press SELECT to apply the measurement value settings changed by steps 1 . to 4 . and complete the setting.
Press the Left key to go back to the Analog value display switching menu without applying the setting changes.

CHANGE SETTING?
YES=SELECT NO=

Table 5-13 Setting items of analog value display

- CGP2-A41D1

| No. | Item | Setting description | Setting range | Unit |
| :---: | :--- | :--- | :--- | :--- |
| 1 | AI Disp | Al display primary value / <br> secondary value selection | PRIMARY / <br> SECONDARY | - |
| 2 | PTP | VT primary side rating | $0.1 \sim 500.0$ | kV |
| 3 | PTS | VT secondary side rating | $100 \sim 125$ | V |
| 4 | CTP | CT primary side rating | $5 \sim 30000$ | A |
| 5 | CTS | CT secondary side rating | 5 (fixed value) | A |

- CGP2-A42D1

| No. | Item | Setting description | Setting range | Unit |
| :---: | :--- | :--- | :--- | :--- |
| 1 | AI Disp | Al display primary value / <br> secondary value selection | PRIMARY / <br> SECONDARY | - |
| 2 | CTP | CT primary side rating | $5 \sim 30000$ | A |
| 3 | CTS | CT secondary side rating | 5 (fixed value) | A |

5.3.4.3.4. Trip counter (TRIP COUNTER) menu
[Operation path] SETTING MODE > CONFIG > TRIP COUNTER
The Trip counter (TRIP COUNTER) menu allows setting of the initial counter and alarm counter values. The trip counter will count the number of trip times.
(The DISPLAY mode only allows viewing of the setting values)


1. The trip counter setting menu appears. Use the Up and Down keys to select the item to change and press SELECT.

2. The cursor moves to the setting value. Use the Up and Down keys to select the value and the Left and Right keys to select the digit to make the change.

| CFG-TRIP COUNTER 4 V |
| :--- |
| Initial: $2 \boldsymbol{\square}$ |

3. Press SELECT to change the setting value.
CFG-TRIP COUNTER』 V
Initial: 28
4. Complete setting of all other items to change by repeating steps 1 . to 3 ..
5. Press ENTER and the confirmation message of the trip counter settings appears.

Press SELECT to apply the trip counter settings changed by steps 1 . to 4 . and complete the setting. Press the Left key to go back to the setting menu in step 1. above without applying the setting changes.

$$
\begin{aligned}
& \text { CHANGE SETTING? } \\
& \text { YES=SELECT NO= }
\end{aligned}
$$

Table 5-14 Setting items of trip counter

| No. | Item | Setting description | Setting range | Unit |
| :---: | :--- | :--- | :--- | :--- |
| 1 | Initial | Initial value of trip counter | $0 \sim 10000$ | Times |
| 2 | Alarm | Alarm value of trip counter | $1 \sim 10000$ | Times |

## [Operation path] SETTING MODE > CONFIG > DISTURBANCE

The Disturbance record (DISTURBANCE) menu allows setting of maximum recording time and pre-fault recording time of each disturbance (fault) record.
(The DISPLAY mode only allows viewing of the setting values)


1. Use the Up and Down keys to select the item to change and press SELECT.

2. The cursor moves to the setting value. Use the Up and Down keys to select the value and the Left and Right keys to select the digit to make the change.

3. Press SELECT to change the setting value.

| CFG-DISTURBANCE $\boldsymbol{\Delta v}$ |
| :--- |
| Pre-Rec. : 300 ms |

4. Complete setting of all other items to change by repeating steps 1 . to 3 ..
5. Press ENTER and the message to confirm application of the disturbance record time settings appears.

Press SELECT to apply the disturbance record time settings changed by steps 1. to 4. and complete the setting.
Press the Left key to go back to the setting menu in step 1. above without applying the setting changes.

> CHANGE SETTING?
> YES=SELECT NO=

Table 5-15 Setting items of disturbance record time

| No. | Item | Setting description | Setting range | Unit |
| :---: | :--- | :--- | :--- | :--- |
| 1 | Pre-Rec. | Save time of pre-fault waveform data | $100 \sim 4500$ | ms |
| 2 | Rec. | Save time of waveform data | $200 \sim 5000$ | ms |

Note: The save time of "Pre-Rec." is included in that of "Rec.".
In other words, the setting value of "Rec." must be larger than that of "Pre-Rec.".
5.3.4.3.6. DI voltage (DI VOLTAGE) menu
[Operation path] SETTING MODE > CONFIG > DI VOLTAGE
The DI voltage (DI VOLTAGE) menu allows setting of the DI rated voltage.
(The DISPLAY mode only allows viewing of the setting values)


1. In the DI voltage setting menu, display the item "DI" and press the SELECT key.

* The DI voltage setting menu has one item: "DI"


Press the SELECT key to select an item.
2. The cursor moves to the setting value. Use the Up and Down keys to select the setting to make the change.

CFG-DI VOLTAGE
DI: DC110V
3. Press the SELECT key to change the setting value.

CFG-DI VOLTAGE DI: DC220V
4. Press the ENTER key, and a message appears to confirm application of the DI voltage setting value that was just changed.
Press the SELECT key to apply the DI voltage setting value and complete the setting.

> CHANGE SETTING?
> YES=SELECT NO=

Press the Left key to go back to the DI voltage setting menu without applying the setting that was just changed.

CANCEL SETTING?
YES=SELECT NO=

Table 5-16 Setting item of DI voltage

| No. | Item | Setting description | Setting |
| :---: | :--- | :--- | :--- |
| 1 | DI | DI voltage setting | DC $110 / 220 \mathrm{~V}$ |

5.3.4.3.7. Password use/unuse (PASSWORD USE) menu
[Operation path] SETTING MODE > CONFIG > PASSWORD USE
The Password use/unuse (PASSWORD USE) menu specifies whether to use or not use a password input when the SETTING mode is selected.
(This item is not shown in the DISPLAY mode)

| SET-CONFIG <br> :PASSWORD USE | $\longrightarrow \boldsymbol{V}$ |
| :--- | :--- |$\quad$| CFG-PW USE |
| :--- |
| PASSWORD:UNUSE |

1. In the Password use/unuse menu, press SELECT.
CFG-PW USE

PASSWORD:USE


Press SELECT to select an item
2. The cursor moves to the setting value. Use the Up and Down keys to select the setting to be changed.

$$
\begin{aligned}
& \text { CFG-PW USE } \\
& \text { PASSWORD: } \quad \text { SE }
\end{aligned}
$$

3. Press SELECT to change the setting value.

$$
\begin{aligned}
& \text { CFG-PW USE } \\
& \text { PASSWORD:UNUSE }
\end{aligned}
$$

4. Press ENTER and the confirmation message of the password use/unuse setting changed appears as shown in the figure below.
Press SELECT to apply the password use/unuse setting and complete the setting.
Press the Left key to go back to the setting menu in step 1. above without applying the setting changes.

$$
\begin{aligned}
& \text { CHANGE SETTING? } \\
& \text { YES=SELECT NO= }
\end{aligned}
$$

Table 5-17 Setting item of Password use/unuse

| No. | Item | Setting description | Setting |
| :---: | :---: | :---: | :---: |
| 1 | PASSWORD | Password use/unuse setting | USE / UNUSE |

### 5.3.4.3.8. Password registration (PASSWORD REGIST) menu

[Operation path] SETTING MODE > CONFIG > PASSWORD REGIST
The Password registration (PASSWORD REGIST) menu allows the setting of the password input when the SETTING mode is selected.
(This item is not shown in the DISPLAY mode)


1. In the Password registration menu, press SELECT.

| CFG-PW | REGIST |
| ---: | :--- |
|  | $: \bigcirc 00$ |



Press SELECT to select an item
2. The Password registration screen appears.

For registering a password, press SELECT after each digit is entered.
Pressing SELECT confirms the value for the digit entered and moves the cursor to the digit on the right. It is not possible to return to the previous digit by using the Left key.
Use the Up and Down keys to select a value out of 0 to 9 for each digit.

3. When the four digits have been entered, password input is requested again.

Enter the same password as that registered in step 2 above.

$$
\begin{aligned}
\text { PASSWORD } & \bullet \bullet \bullet \bullet \\
& : 0 \bullet 0 \bullet
\end{aligned}
$$

4. If the above two password-inputs in steps 2 and 3 are same, the screen shown in step 1 appears.

Press ENTER and the confirmation message of the password registration appears.
Press SELECT to apply the password registration and complete the setting.
Press the Left key to go back to the setting menu in step 1. above without applying the setting changes.

```
CHANGE SETTING?
YES=SELECT NO=4
```

If the two password-inputs in steps 2 and 3 are not same, an error message as shown below appears.

```
PASSWORD
MATCHING ERR
```


### 5.3.4.4. TEST menu

This subsection describes the operations for the Test menu.
The Test menu can be selected only in the SETTING mode.

5.3.4.4.1. DO contact test (CONTACT TEST) menu
[Operation path] SETTING MODE > TEST > CONTACT TEST
The DO contact test (CONTACT TEST) menu allows contact testing of DO signals (DO1 to DO8).

1. When the DO contact test menu has been selected, the caution message appears.
```
TRP-CIRCUIT BLOCK?
YES=SELECT NO=<
```

When pressing SELECT, the next message appears. Then, press "SELECT" again.
AFTER SPECIFYING.
PRESS ‘ENTER‘
2. The setting screen for the DO contact test appears.

Use the Up and Down keys to select the item to set and press SELECT.

| CONTACT | TEST | - V |
| :--- | :--- | :--- |
| DO1-T | OFF |  |

3. The cursor moves to the setting of the selected item.

Use the Up and Down keys to switch the setting.
Select ON to conduct a contact test on the selected DO. If not, select OFF.
CONTACT TEST
DO1-T : $\quad$ FF
4. Press SELECT to change the setting and bring the cursor back to the item name.

5. Complete settings of all the items to change by repeating steps 2 . to 4 . above.
6. After the settings are completed, press ENTER while the setting item selection screen in step 4 is shown in order to operate DO contact test.
*The selected DO contact(s) is(are) operated while ENTER is held down. The operation of the respective DO contact corresponds to the settings in steps (2) to (5) above.

To exit the DO contact test setting screen, press the Left key.

## Table 5-18 Setting items of DO contact test

| No. | Item |
| :---: | :--- |
| 1 | DO1-T |
| 2 | DO2-T |
| 3 | DO3-T |
| 4 | DO4-T |
| 5 | DO5-T |
| 6 | DO6-T |
| 7 | DO7-T |
| 8 | DO8-T |

5.3.4.4.2. Test mode (MODE) menu
[Operation path] SETTING MODE > TEST > MODE
The Test mode (MODE) menu allows setting of the test mode.

1. Use the Up and Down keys to select the item to set and press SELECT.

2. The cursor moves to the setting of the selected item. Use the Up and Down keys to switch the setting.

3. Press SELECT to change the setting.

4. Complete setting of all other items to change by repeating steps 1 . to 3 . above.
5. Press ENTER to be enable the test mode as set in steps 1. to 4. above. The RUN LED flashes during the test mode.

Caution
During the test mode, use of the Left or ESC key to exit the SETTING mode is disabled. (Operations implemented in the SETTING mode are enabled)
When turning off the VFD screen or moving to the DISPLAY mode, it exits the test mode.
5.3.4.4.3. LED/VFD lighting test (LED/VFD TEST) menu
[Operation path] SETTING MODE > TEST > LED/VFD TEST
The LED/VFD lighting test (LED/VFD TEST) menu allows lighting of all LEDs/VFDs.
When LED/VFD TEST is selected in the Test menu, a screen as shown below appears. Pressing ENTER and all LEDs and VFDs are lighting while the key is held down. It can be checked the LED/VFD indication visually.

LED/VFD TEST
PREESS 'ENTER'

### 5.3.4.5. Clear record (RECORD-CLR) menu

The Clear record (RECORD-CLR) menu allows clearing three types of log data: fault, event and alarm records.
*Access record log data cannot be cleared.


### 5.3.4.5.1. Clear fault record (FAULT REC CLEAR) menu

[Operation path] SETTING MODE > RECORD-CLR > FAULT RECORD
The Clear fault record (FAULT REC CLEAR) menu allows clearing of fault records.
In the Clear record menu, select FAULT RECORD and press ENTER. Then, the next screen appears. Press SELECT to clear the fault records.
When pressing the Left key, the display returns to the selection screen of Clear record menu without clearing the fault records.

> FAULT REC CLEAR? YES=SELECT NO=

When clearing of the fault records are completed, the display returns to the Clear record menu. If the clearing is unsuccessful, a message screen as shown below appears.
Pressing SELECT while the message below is shown brings the display back to the Clear record menu selection screen.

## FAULT RECORD <br> CLEAR NG

[Operation path] SETTING MODE > RECORD-CLR > ALARM RECORD
The Clear alarm record (ALARM REC CLEAR) menu allows clearing of alarm records. In the Clear record menu, select ALARM RECORD and press ENTER. Then, the next screen appears. Press SELECT to clear the alarm records.
When pressing the Left key, the display returns to the selection screen of Clear record menu without clearing the alarm records.

```
ALARM REC CLEAR?
YES=SELECT NO=<
```

When clearing of the alarm records are completed, the display returns to the Clear record menu. If the clearing is unsuccessful, a message screen as shown below appears.
Pressing SELECT while the message below is shown brings the display back to the Clear record menu selection screen.

```
ALARM RECORD
CLEAR NG
```


### 5.3.4.5.3. Clear event record (EVENT REC CLEAR) menu

[Operation path] SETTING MODE > RECORD-CLR > EVENT RECORD
The Clear event record (EVENT REC CLEAR) menu allows clearing of event records. In the Clear record menu, select EVENT RECORD and press ENTER. Then, the next screen appears. Press SELECT to clear the event records.
When pressing the Left key, the display returns to the selection screen of Clear record menu without clearing the event records.

```
EVENT REC CLEAR?
YES=SELECT NO=
```

When clearing of the event records are completed, the display returns to the Clear record menu.
If the clearing is unsuccessful, a message screen as shown below appears.
Pressing SELECT while the message below is shown brings the display back to the Clear record menu selection screen.

> EVENT RECORD CLEAR NG

## 6. PC-HMI

PC-HMI is a software for setting, configuration, and supervision of this relay.
The software can be downloaded on the web site of Mitsubishi Electric FA (Factory Automation). The operation method is described in a separate volume. Please refer to the following document.

| Title of document | Document No. |
| :---: | :---: |
| MELPRO-D Series Protection Relay <br> PC-HMI Instruction Manual | JEP0-IL9504 |

In regard to PLC signals, refer to Table 6-1 and Table 6-2.

Table 6-1 PLC signals of CGP2-A41D1

| Signal name | Description |
| :---: | :---: |
| DI1 | Status of DI1 |
| DI2 | Status of DI2 |
| DI3 | Status of DI3 |
| DI4 | Status of DI4 |
| DI5 | Status of DI5 |
| DI6 | Status of DI6 |
| DI7 | Status of DI7 |
| DI8 | Status of DI8 |
| TCNT_ALM | Alarm of trip counter |
| DIFSV-A | Definitive signal of supervision of differential current on A phase |
| DIFSV-B | Definitive signal of supervision of differential current on B phase |
| DIFSV-C | Definitive signal of supervision of differential current on C phase |
| MANU_CLS | Command of CB close |
| MANU_OPN | Command of CB open |
| DIFF-AD | Detection signal of current ratio differential (87G) element on A phase |
| DIFF-BD | Detection signal of current ratio differential (87G) element on B phase |
| DIFF-CD | Detection signal of current ratio differential (87G) element on C phase |
| LOF-D | Detection signal of loss of field (40) element |
| LOF_OC-D | Detection signal of overcurrent for loss of field (40) element |
| DIFSV-AD | Detection signal of supervision of differential current on A phase |
| DIFSV-BD | Detection signal of supervision of differential current on B phase |
| DIFSV-CD | Detection signal of supervision of differential current on C phase |
| ALARM | Abnormal condition of constant supervision (serious failure) |
| ALARM-L | Abnormal condition of constant supervision (minor failure) |
| RY-LOCK | Locking of relay |
| RESET | Reset signal (activated by pushing ESC/C button for more than 3 seconds) |
| INTER1 | 1st intermediate output signal of PLC |
| INTER2 | 2nd intermediate output signal of PLC |
| INTER3 | 3rd intermediate output signal of PLC |
| INTER4 | 4th intermediate output signal of PLC |
| INTER5 | 5 th intermediate output signal of PLC |
| INTER6 | 6th intermediate output signal of PLC |
| INTER7 | 7th intermediate output signal of PLC |
| INTER8 | 8th intermediate output signal of PLC |
| DIFF-3D_O | Detection signal of any DIFF of A, B, and C phase |
| DFSV-3D_O | Detection signal of any DIFFSV of A, B, and C phase |
| ALLEL-D_O | Detection signal of any of all elements (OR of all detection signals) |
| DIFF-3T_O | "DIFF_A-T" OR "DIFF_B-T" OR "DIFF_C-T" |
| DFSV-3_O | Definitive signal of any DIFFSV of A, B, and C phase |
| ALLEL-O | OR of all "Definitive signal AND Operation lock signal" |
| DIFF-A | "DIFF_A-T" or forced operation from PC-HMI |
| DIFF-B | "DIFF_B-T" or forced operation from PC-HMI |
| DIFF-C | "DIFF_C-T" or forced operation from PC-HMI |
| LOF | "LOF-T" or forced operation from PC-HMI |
| OPLK-DIFA | Operation lock on DIFF element of A phase |
| OPLK-DIFB | Operation lock on DIFF element of B phase |


| OPLK-DIFC | Operation lock on DIFF element of C phase |
| :--- | :--- |
| OPLK-LOF | Operation lock on LOF element |
| DIFF_A-T | "Definitive signal of DIFF on A phase" AND "Operation lock signal" |
| DIFF_B-T | "Definitive signal of DIFF on B phase" AND "Operation lock signal" |
| DIFF_C-T | "Definitive signal of DIFF on C phase" AND "Operation lock signal" |
| LOF-T | "Definitive signal of LOF" AND "Operation lock signal" |
| DIFF_A-TL | Latch signal of DIFF_A-T ( ${ }^{*}$ ") |
| DIFF_B-TL | Latch signal of DIFF_B-T ( $\left.{ }^{*}\right)$ |
| DIFF_C-TL | Latch signal of DIFF_C-T (*) |
| LOF-TL | Latch signal of LOF-T (*) |

${ }^{(*)}$ Note: The latch signal can be reset by pushing ESC/C button for more than 3 seconds.

Table 6-2 PLC signals of CGP2-A42D1

| Signal name |  |
| :--- | :--- |
| DI1 | Status of DI1 |
| DI2 | Status of DI2 |
| DI3 | Status of DI3 |
| DI4 | Status of DI4 |
| DI5 | Status of DI5 |
| DI6 | Status of DI6 |
| DI7 | Status of DI7 |
| DI8 | Status of DI8 |
| TCNT_ALM | Alarm of trip counter |
| DIFSV-A | Definitive signal of supervision of differential current on A phase |
| DIFSV-B | Definitive signal of supervision of differential current on B phase |
| DIFSV-C | Definitive signal of supervision of differential current on C phase |
| MANU_CLS | Command of CB close |
| MANU_OPN | Command of CB open |
| DIFF-AD | Detection signal of current ratio differential (87G) element on A phase |
| DIFF-BD | Detection signal of current ratio differential (87G) element on B phase |
| DIFF-CD | Detection signal of current ratio differential (87G) element on C phase |
| DIFSV-AD | Detection signal of supervision of differential current on A phase |
| DIFSV-BD | Detection signal of supervision of differential current on B phase |
| DIFSV-CD | Detection signal of supervision of differential current on C phase |
| ALARM | Abnormal condition of constant supervision (serious failure) |
| ALARM-L | Abnormal condition of constant supervision (minor failure) |
| RY-LOCK | Locking of relay |
| RESET | Reset signal (activated by pushing ESC/C button for more than 3 seconds) |
| INTER1 | 1st intermediate output signal of PLC |
| INTER2 | 2nd intermediate output signal of PLC |
| INTER3 | 3rd intermediate output signal of PLC |
| INTER4 | 4th intermediate output signal of PLC |
| INTER5 | 5th intermediate output signal of PLC |
| INTER6 | 6th intermediate output signal of PLC |
| INTER7 | 7th intermediate output signal of PLC |
| INTER8 | 8th intermediate output signal of PLC |
| DIFF-3D_O | Detection signal of any DIFF of A, B, and C phase |
| DFSV-3D_O | Detection signal of any DIFFSV of A, B, and C phase |
| ALLEL-D_O | Detection signal of any of all elements <br> (OR of all detection signals) <br> DIFF-3T_O |
| "DIFF_A-T" OR "DIFF_B-T" OR "DIFF_C-T" |  |
| DFSV-3_O | Definitive signal of any DIFFSV of A, B, and C phase |
| ALLEL-O | OR of all "Definitive signal AND Operation lock signal" |
| DIFF-A | "DIFF_A-T" or forced operation from PC-HMI |
| DIFF-B | "DIFF_B-T" or forced operation from PC-HMI |
| DIFF-C | "DIFF_C-T" or forced operation from PC-HMI |
| OPLK-DIFA | Operation lock on DIFF element of A phase |
| OPLK-DIFB | Operation lock on DIFF element of B phase |
| OPLK-DIFC | Operation lock on DIFF element of C phase |
| DIFF_A-T | "Definitive signal of DIFF on A phase" AND "Operation lock signal" |
| "Definitive signal of DIFF on B phase" AND "Operation lock signal" |  |


| DIFF_C-T | "Definitive signal of DIFF on C phase" AND "Operation lock signal" |
| :--- | :--- |
| DIFF_A-TL | Latch signal of DIFF_A-T $\left(^{*}\right)$ |
| DIFF_B-TL | Latch signal of DIFF_B-T $\left(^{*}\right)$ |
| DIFF_C-TL | Latch signal of DIFF_C-T (*) |



## 7. Rating, Specification

### 7.1. Features

(1) Multi-function

- The relay incorporates a variety of protection functions which are required for generator protection.
- The relay has two Group settings sets. Therefore, it can be used for different purposes, such as operation/test, or quickly adapted to meet load conditions.
- Control of a circuit breaker is possible via the font panel, PC-HMI, or DI terminal.
(2) High-precision measuring functions
- Measurement functions are enhanced.

Measurement values (e.g. current and voltage) can be viewed via the front panel display on the relay or using interface software on a PC.
In addition, you can expand the character size of the measured values on the front panel display, which enables to check values easily.

- Fault / Disturbance Recording

The relay stores up to 5 fault / disturbance records which can be used for fault investigations. Fault record function is the record of analog input values (as RMS) at the time when relay elements are operated. Disturbance record function is the record of waveform data for the prescribed period before and after occurrence of fault at sampling rate of 24 samples/cycle.
(3) Programmable Output Contacts provide flexibility

The configuration of output contact is possible by PLC (Programmable Logic Controller), which enables to apply the relay to various systems.
(4) Advanced constant monitoring function improves reliability

The relay continuously monitors the electronic circuits and can detect internal component failure, which enables to improve reliability.
The relay's behavior is as follows:

- In normal conditions: RUN LED lights.
- In abnormal conditions: ALARM LED lights.

During serious abnormal conditions, the protection elements are locked to prevent an unnecessary output, and the relay fail alarm is issued.
(5) The draw-out Subunit improves maintainability

The provision of an automatic CT shorting mechanism at the time of drawing out the unit makes it very easy to maintain the relay.
Remarks: This mechanism is installed only in relay devices with current protection element.

### 7.2. Standard Ratings

| Item |  |  | Contents |
| :---: | :---: | :---: | :---: |
| Rating | Current |  | 5 A |
|  | Line voltage |  | 57 ~ 120 V |
|  | Frequency |  | $50 \mathrm{~Hz} / 60 \mathrm{~Hz}$ |
|  | Dl input voltage |  | DC 110 V (Variation range: 88 ~ 150 V ) <br> DC 220 V (Variation range: 176 ~ 300 V ) |
|  | Power <br> Supply | Voltage | $\begin{aligned} & \text { DC: } 100 \sim 220 \mathrm{~V} \\ & \text { AC: } 100 \sim 220 \mathrm{~V} \end{aligned}$ |
|  |  | Variation range | DC: $85 \sim 242 \mathrm{~V}$ (Range of $80 \sim 286 \mathrm{~V}$ is allowable temporarily.) <br> AC: $85 \sim 242 \mathrm{~V}$ (Range of $85 \sim 253 \mathrm{~V}$ is allowable temporarily.) |
| Communication function | CC-LINK |  | Option |

### 7.3. Protection elements

| Protection element |  | Operating value | Operating time | Other setting |
| :---: | :---: | :---: | :---: | :---: |
| 87G | Current ratio differential (DIFF) | Minimum operating current: 0.4 ~ 1.0 A (0.1 A step) <br> Ratio: 5 ~ 50 \% ( 1 \% step) | $0.00 \sim 10.00 \mathrm{~s}$ (0.01 s step) <br> In setting 0.00 s , instantaneous operating time is less than 50 ms . |  |
| $\begin{aligned} & 40 \\ & \left({ }^{*}\right) \end{aligned}$ | Loss of field (LOF) | $\begin{aligned} & \text { Impedance ZF: } 5.0 \sim 50.0 \Omega \\ & (0.1 \Omega \text { step) } \\ & \text { Impedance ZB: } 0.40 \sim 4.00 \Omega \\ & \quad(0.01 \Omega \text { step }) \\ & \hline \end{aligned}$ | $\begin{aligned} & 0.20 \sim 10.00 \mathrm{~s} \\ & (0.01 \mathrm{~s} \text { step }) \end{aligned}$ |  |
| $\begin{aligned} & \text { OP } \\ & \text { LOCK } \end{aligned}$ | Operation lock function (OPLOCK) | - | 0.0 ~ 10.0 s (0.1 s step) <br> In setting 0.0 s, instantaneous operating time is less than 50 ms . |  |

* In CGP2-A42D1, there are no 40 (Loss of field) element.
* Factory settings are set to a default of "OFF (Non-use)" for the items with setting of Use/Non-use. In regard to other default settings, refer to Chapter 13.
* For details about protective function, refer to Chapter 8.


### 7.4. Measuring element

- CGP2-A41D1

| Contents displayed |  | Range | Meas | d value | Accident record | Waveform record |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Name of signal | Item | (Secondary value / Primary value) | Primary | Secondary | Primary only | Common |
| 11a | A-phase current on output side | $\begin{aligned} & 0.00 \sim 10.00 \text { A ( } 0.01 \text { A step) } / \\ & 0 \sim 60000 \text { A (1 A step) } \end{aligned}$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 11b | B-phase current on output side |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| I1c | C-phase current on output side |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 12a | A-phase current on neutral side |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| I2b | B-phase current on neutral side |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| I2c | C-phase current on neutral side |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| Vab | AB-phase voltage | $\begin{aligned} & \hline 0.0 \sim 260.0 \mathrm{~V}(0.1 \mathrm{~V} \text { step }) / \\ & 0.0 \sim 750.0 \mathrm{kV}(0.1 \mathrm{kV} \text { step }) \end{aligned}$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| Ida | A-phase differential current | $\begin{aligned} & 0.00 \sim 10.00 \text { A ( } 0.01 \text { A step) / } \\ & 0 \sim 60000 \text { A ( } 1 \text { A step) } \end{aligned}$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\times$ |
| Idb | B-phase differential current |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\times$ |
| Idc | C-phase differential current |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\times$ |
| I1a-phase | Phase angle of la on output side | $0.0 \sim 359.9^{\circ}\left(0.1^{\circ}\right.$ step $)$ On the basis of Vab (Lag angle) | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\times$ |
| I1b-phase | Phase angle of lb on output side |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\times$ |
| I1c-phase | Phase angle of Ic on output side |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\times$ |
| I2a-phase | Phase angle of la on neutral side |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\times$ |
| I2b-phase | Phase angle of lb on neutral side |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\times$ |
| I2c-phase | Phase angle of Ic on neutral side |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\times$ |
| Vab-phase | Phase angle of Vab |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\times$ |

- CGP2-A42D1

| Contents displayed |  | Range | Measu | d value | Accident record | Waveform record |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Name of signal | Item | (Secondary value / Primary value) | Primary | Secondary | Primary only | Common |
| 11a | A-phase current on output side | $\begin{aligned} & 0.00 \sim 10.00 \mathrm{~A}(0.01 \text { A step) } / \\ & 0 \sim 60000 \mathrm{~A}(1 \mathrm{~A} \mathrm{step}) \end{aligned}$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 11b | B-phase current on output side |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| I1c | C-phase current on output side |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 12a | A-phase current on neutral side |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 12 b | B-phase current on neutral side |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| I2c | C-phase current on neutral side |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| Ida | A-phase differential current | $\begin{aligned} & 0.00 \sim 10.00 \text { A ( } 0.01 \text { A step) / } \\ & 0 \sim 60000 \text { A (1 A step) } \end{aligned}$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\times$ |
| ldb | B-phase differential current |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\times$ |
| Idc | C-phase differential current |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\times$ |
| I1a-phase | Phase angle of la on output side | $0.0 \sim 359.9^{\circ}\left(0.1^{\circ}\right.$ step $)$ On the basis of Vab (Lag angle) | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\times$ |
| I1b-phase | Phase angle of lb on output side |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\times$ |
| I1c-phase | Phase angle of Ic on output side |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\times$ |
| 12a-phase | Phase angle of la on neutral side |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\times$ |
| 12b-phase | Phase angle of lb on neutral side |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\times$ |
| I2c-phase | Phase angle of Ic on neutral side |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\times$ |

### 7.5. List of functions

| Menu | Item | Operation system |  |
| :---: | :---: | :---: | :---: |
|  |  | PC-HMI | Front panel |
| Status (STATUS) | Clock (CLOCK) | $\bigcirc$ | $\bigcirc$ |
|  | Measured analog value (METERING) | $\bigcirc$ | $\bigcirc$ |
|  | DI/DO status (DIGITAL I/O) | $\bigcirc$ | $\bigcirc$ |
|  | Trip counter (TRIP COUNTER) | $\bigcirc$ | $\bigcirc$ |
|  | Device name (DEVICE NAME) | $\bigcirc$ | $\bigcirc$ |
|  | Monitoring | $\bigcirc$ | $\times$ |
|  | LED reset | $\bigcirc$ | $\times$ |
| Record <br> (RECORD) | Waveform analysis | $\bigcirc$ | $\times$ |
|  | Disturbance record | $\bigcirc$ | $\times$ |
|  | Fault record (FAULT RECORD) | $\bigcirc{ }^{*}$ ) | $\bigcirc$ |
|  | Event record (EVENT RECORD) | $\bigcirc$ | $\bigcirc$ |
|  | Access record (ACCESS RECORD) | $\bigcirc$ | $\bigcirc$ |
|  | Alarm record (ALARM RECORD) | $\bigcirc$ | $\bigcirc$ |
| Setting <br> (SETTING) | Active group (ACTIVE WG) | $\bigcirc$ | $\bigcirc$ |
|  | Group 1 setting (G1) | $\bigcirc$ | $\bigcirc$ |
|  | Group 2 setting (G2) | $\bigcirc$ | $\bigcirc$ |
|  | PLC | $\bigcirc$ | $\times$ |
| Control (CONTROL) | Control mode (CTRL MODE) | $\bigcirc$ | $\bigcirc$ |
|  | CB control (CB CONTROL) | $\bigcirc$ | $\bigcirc$ |
| Configuration (CONFIG) | Communication setting (COMMUNICATION) | $\times$ | $\bigcirc$ |
|  | Clock adjustment (CLOCK ADJUST) | $\bigcirc$ | $\bigcirc$ |
|  | Analog value display switching (METERING) | $\bigcirc$ | $\bigcirc$ |
|  | Trip counter (TRIP COUNTER) | $\bigcirc$ | $\bigcirc$ |
|  | Disturbance record (DISTURBANCE) | $\bigcirc$ | $\bigcirc$ |
|  | DI voltage (DI VOLTAGE) | $\bigcirc$ | $\bigcirc$ |
|  | Password use/unuse <br> (PASSWORD USE) | $\times$ | $\bigcirc$ |
|  | Password registration (PASSWORD REGIST) | $\times$ | $\bigcirc$ |
|  | Device name setting | $\bigcirc$ | $\times$ |
|  | Time management setting | $\bigcirc$ | $\times$ |
|  | DO contact test setting | $\bigcirc$ | $\times$ |
| Test (TEST) | DO contact test (CONTACT TEST) | $\bigcirc$ | $\bigcirc$ |
|  | Test mode (MODE) | $\bigcirc$ | $\bigcirc$ |
|  | LED/VFD lighting test (LED/VFD TEST) | $\times$ | $\bigcirc$ |
|  | Forced operation of relay | $\bigcirc$ | $\times$ |
| Clear record (RECORD-CLR) | Clear fault record (FAULT REC CLEAR) | $\bigcirc$ | $\bigcirc$ |
|  | Clear alarm record (ALARM REC CLEAR) | $\bigcirc$ | $\bigcirc$ |
|  | Clear event record (EVENT REC CLEAR) | $\bigcirc$ | $\bigcirc$ |

$\left(^{*}\right)$ In PC-HMI, the item of Fault record is included in Disturbance record.

## 8. Protective function

In the relay, following protection elements are provided for the purposes of generator protection. In this chapter, the protection elements incorporated in the relay are described.


| Model | Protection elements | Input | Purpose |
| :--- | :--- | :--- | :--- |
| CGP2-A41D1 | $87 \mathrm{G}, 40$ | IIa, I1b, I1c, <br> I2a, I2b, I2c (6 phase) <br> Vab (1 phase) |  |
| CGP2-A42D1 |  | 87 G | I1a, I1b, I1c, <br> I2a, I2b, I2c (6 phase) |

### 8.1. Current ratio differential element

A current ratio differential element is incorporated in CGP2-A41D1 and CGP2-A42D1, and this enables rapid detection of faults in a generator.

| Apparatus <br> No. | Display name | Protective function |
| :--- | :--- | :--- |
| 87 G | DIFF | Current ratio differential element |

### 8.1.1. DIFF element

Fig. 8-1 shows the internal function blocks of DIFF element.
The DIFF element takes in the inflow current (generator's neutral side) and the outflow current (generator's output side) and calculates the differential current and the restraint current (*) inside the relay.
The DIFF element outputs a definitive signal after the preset time of the operation timer (Ope. Time) has passed, when the ratio of the differential current to the restraint current is within the operating range as shown in Fig. 8-2.
An off-delay timer of 200 ms is added in order to prevent chattering of the output contacts.
( $^{*}$ ) The restraint current is calculated according to the setting of the calculation method of restraint current (Ires Meth.).

Furthermore, this element is enabled only when the setting of Use/Non-use of DIFF element (DIFF EN) is set to ON. Therefore, when this element is not used, unnecessary operation can be prevented by setting to OFF. It is not necessary to set other setting items with regard to DIFF element.
This element is provided with two DI circuits for interlocking the operation (OPLOCK element).
For the operations of the OPLOCK element, refer to 8.3.1.


Fig. 8-1 Internal function block diagram of DIFF element

* [ ] shows setting values.


Fig. 8-2 Operating characteristics of DIFF element

Table 8-1 Setting items of DIFF element

| Display name | Setting parameter | Setting |  | Description |
| :---: | :---: | :---: | :---: | :---: |
|  |  | Range of setting | step |  |
| DIFF | DIFF EN | OFF, ON | - | OFF: Non-use, ON: Use When this element is used, set to ON. |
|  | Ires Meth. | Max, MIN, SUM | - | Calculation method of restraint current: MAX: 11 or 12 , whichever is greater MIN: I1 or I2, whichever is smaller SUM: vectorial sum (\| $\|\dot{1}+\|\dot{2}\|$ ) |
|  | Ope. Curt. | $0.4 \sim 1.0 \mathrm{~A}$ | 0.1 A | Minimum operating current |
|  | ratio K1 | $5 \sim 50 \%$ | $1 \%$ | Ratio K1 for small current region |
|  | ratio K2 | 5 ~ 50 \% | 1 \% | Ratio K2 for large current region K1 1 K2 |
|  | Is Curt. | $0.4 \sim 10.0 \mathrm{~A}$ | 0.1 A | Ratio switching point |
|  | Ope. Time | $0.00 \sim 10.00 \mathrm{~s}$ | 0.01 s | Operating time INST: $\leq 50 \mathrm{~ms}$ |

*1 Setting the ratio K 1 and ratio K2
Normally, as shown in Fig. 8-3, increase the ratio setting in the large current area (ratio K1 < ratio K2) to expand the non-operating area. Or, as shown in Fig. 8-4, set the non-operating area to the same setting (ratio K1 = ratio K2) even when the current is large.


Fig. 8-3 DIFF element characteristic (ratio K1 < ratio K2)


Fig. 8-4 DIFF element characteristic (ratio K1 = ratio K2)

If the setting is incorrect (ratio K1 > ratio K2), the DIFF Element operates in the area indicated by the expression [3] as shown in Fig. 8-5.


Fig. 8-5 DIFF element characteristic (ratio K1 > ratio K2)

### 8.1.1.1.Operating principles

Assuming that the current on the neutral side of the generator (inflow current) is $I 1$ and the current on the output side of the generator (outflow current) is I 2 as shown in Fig. 8-6, the differential current is calculated inside the Relay according to the following equation.

Differential current: ID =|İ-| $\mid$


Fig. 8-6 Input current of the DIFF element

The ratio is expressed as the ratio of the differential current to I1 and I2. The DIFF element operates when the ratio is equal to or greater than the setting value (ratio K1 or ratio K2) and the ID is equal to or greater than the minimum operating current setting value (Ope. Curt.).

Operation determination formula
[1] Ratio: $\frac{\text { Differential current }}{\text { Restraint current }} \times 100(\%)$
(1) When the restraint method selection setting (Ires Meth.) is set to "MAX"

- Ratio K1 determination

$$
\frac{I D}{\operatorname{MAX}(11, \mid 2)}=\frac{|11-|\dot{12}|}{\text { Larger of }|11| \text { and }|12|} \times 100(\%) \geq \text { ratio K1 }
$$

- Ratio K2 determination

$$
|1 \dot{1}-|\dot{2}|
$$

Larger of |11| and ||2| - Ratio switching point (Is Curt.)
$+($ ratio K1) $\times($ Is Curt. $) \times 100(\%) \geq$ ratio K2
(2) When the restraint method selection setting (Ires Meth.) is "MIN"

- Ratio K1 determination

- Ratio K2 determination
$\frac{||1-|\dot{2}|}{\text { Smaller of }|I 1| \text { and }||2|-\text { Ratio switching point (Is Curt.) }}$
$+($ ratio K1 $) \times($ Is Curt. $) \times 100(\%) \geq$ ratio K2
(3) When the restraint method selection setting (Ires Meth.) is "SUM"
- Ratio K1 determination

- Ratio K2 determination
$\frac{||\dot{1}-|\dot{2}|}{||\dot{1}+|\dot{2}|-\text { Ratio switching point (Is Curt.) }}$
$+($ ratio K1 $) \times($ Is Curt. $) \times 100(\%) \geq$ ratio K2
[2] Minimum operating value: $I D=||\dot{1}-12| \geq$ Minimum operating current setting value (Ope. Curt.)

If a large current passes through due to an external accident, an unbalanced differential current will flow due to the difference in the characteristic of the CT itself, the length of the secondary wiring, or the unbalance of loads. Therefore, when the current is large, increase the ratio to prevent the protection element from malfunctioning due to unbalanced differential current.
Fig. 8-7 shows the inflow current versus outflow current characteristic and Fig. 8-8 shows the outflow current versus differential current characteristic.
Note: The setting values shown in the figure are examples.


Fig. 8-7 Inflow current versus Outflow current characteristic of DIFF element

Ope. Curt. 0.4 A setting (Minimum operating value)


Fig. 8-8 Outflow current versus Differential current characteristic of DIFF element

### 8.2. Loss of field element

A loss of field element is incorporated in CGP2-A41D1 to detect decline or loss of field due to the open or short of the field circuit of the generator.

| Apparatus <br> No. | Display name | Protective function |
| :--- | :--- | :--- |
| 40 | LOF | Loss of field element |

### 8.2.1. LOF element

Fig. 8-9 shows the internal function blocks of LOF element.

LOF element calculates the impedance from the line voltage (Vab) and the phase current (I1a, I1b) and compares it with the setting value (LOF ZF, LOF ZB).
LOF element outputs a definitive signal after the preset time of the operation timer (Ope. Time) has passed, when the calculated impedance is within the operating range.
An off-delay timer of 200 ms is added in order to prevent chattering of the output contacts.

Furthermore, this element is enabled only when the setting of Use/Non-use of LOF element (LOF EN) is set to ON. Therefore, when this element is not used, unnecessary operation can be prevented by setting to OFF. It is not necessary to set other setting items with regard to LOF element.
This element is provided with two DI circuits for interlocking the operation (OPLOCK element).
For the operations of the OPLOCK element, refer to 8.3.1.


Fig. 8-9 Internal function block diagram of LOF element

Table 8-2 Setting items of LOF element

| Display name | Setting parameter | Setting |  | Description |
| :---: | :---: | :---: | :---: | :---: |
|  |  | Range of setting | step |  |
| LOF | LOF EN | OFF, ON | - | OFF: Non-use, ON: Use When this element is used, set to ON. |
|  | LOF ZF | $5.0 \sim 50.0 \Omega$ | $0.1 \Omega$ | Impedance of ZF |
|  | LOF ZB | $0.40 \sim 4.00 \Omega$ | $0.01 \Omega$ | Impedance of ZB |
|  | Ope. Time | $0.20 \sim 10.00 \mathrm{~s}$ | 0.01 s | Operating time |

### 8.2.1.1.Impedance during operation

This section describes the impedance detected by the loss of field element at the time when the loss of field or the step-out occurs.


Fig. 8-10 Impedance of the Loss of field element

In a system as seen in Fig. 8-10, the system voltage and the current are respectively expressed as follows.

$$
\begin{align*}
& \dot{I_{R}}=\frac{\dot{E_{A}}-\dot{E_{B}}}{\dot{Z_{A}}+\dot{Z_{B}}}  \tag{1}\\
& \dot{E_{R}}=\dot{E_{A}}-\dot{I_{R}} \cdot \dot{Z_{A}} \tag{2}
\end{align*}
$$

Substitute Equation (1) into Equation (2) to get the following equation.

$$
\begin{equation*}
\dot{E_{R}}=\frac{\dot{E_{A}} \dot{Z}_{B}+\dot{E_{B}} \dot{Z}_{A}}{\dot{Z_{A}}+\dot{Z_{B}}} \tag{3}
\end{equation*}
$$

The impedance seen by the relay $Z_{R}$ is as follows,

$$
\begin{equation*}
\dot{Z}_{R}=\frac{\dot{E_{R}}}{\dot{I_{R}}}=\frac{\dot{E_{A}} \dot{Z}_{B}+\dot{E_{B}} \dot{Z}_{A}}{\dot{E_{A}}-\dot{E_{B}}} \tag{4}
\end{equation*}
$$

This Equation (4) is the basic equation for the impedance seen by the relay.
(a)When the loss-of-field occurs

When the field is completely lost, the internal induced voltage ( $\mathrm{E}_{\mathrm{A}}$ ) of the generator finally becomes 0 , and the impedance seen by the relay becomes

$$
\begin{equation*}
\dot{Z}_{R}=-\dot{Z}_{A} \tag{5}
\end{equation*}
$$

from Equation (4).
If $\dot{Z}_{A}$ is the direct-axis transient reactance of the generator jxd', the equation becomes,

$$
\begin{equation*}
\dot{Z}_{R}=-j x d^{\prime} \tag{6}
\end{equation*}
$$

and the impedance locus heads toward -jxd'.
Furthermore, the (synchronous) relationship with the unprotected generators connected in the system shows that the end of the impedance locus eventually heads toward the direct-axis synchronous reactance -jxd.

On the R-X diagram, it looks like the figure shown in Fig. 8-11.


Fig. 8-11
(b)When the step-out occurs

When the magnitude of the generator's internal induced voltage and the infinite bus bar voltage are equal and the phase is different by $180^{\circ}$, the equation can be expressed as,

$$
\begin{equation*}
\dot{E_{A}}=-\dot{E_{B}} \tag{7}
\end{equation*}
$$

which is further expressed as.

$$
\begin{equation*}
\dot{Z}_{R}=-\frac{1}{2}\left(\dot{Z}_{A}-\dot{Z}_{B}\right) \tag{8}
\end{equation*}
$$

Assuming that $Z_{A}$ is the generator's transient reactance $j x d$ ' and $Z_{B}$ is the transformer reactance $j x t$, the equation (8) is expressed as follows.

$$
\begin{equation*}
Z_{R}=-j \frac{1}{2} x d^{\prime}+j \frac{1}{2} x t \tag{9}
\end{equation*}
$$

Therefore, it can be seen that the impedance locus at the time of step-out passes through a value less than -xd'/2 on the -X axis or on the +X axis as shown in Fig. 8-12.


Fig. 8-12

It should be noted that the internal induced voltage $\dot{E}_{A}$ of the generator does not immediately become $\dot{E_{A}}=-\dot{E_{B}}$ or zero when the loss-of-field or the step-out actually occurs. The process depends on the time constant of the field circuit, system conditions, and the AVR response.
Taking into account the impedance locus for the step-out, it is possible to detect the loss-of-field by installing this relay that has an operating area within the circle which has its center on the X -axis and whose diameter extends from the point of -xd'/2 (transient impedance: -xd') to the point of synchronous impedance -xd as shown in Fig. 8-13.


Fig. 8-13 Loss-of-field impedance locus

### 8.2.1.2.Operating principles

The impedance must be calculated with the current and voltage in the same phase relationship. Since the line voltage Vab is used as the voltage for this element, the currents IIa and I1b are taken in to match the phase and they are calculated (11a-11b) internally to be used for impedance calculation.
The operation principle of this element is to obtain a certain voltage component proportional to the system voltage and current from the voltage transformer and the current transformer, to derive the vector $\mathrm{V}_{1}$ and the vector $\mathrm{V}_{2}$, and to determine the operation based on the relationship between the vectors.

$$
\begin{aligned}
& V_{1}=E_{(n)}-Z_{F}(11 a-11 b) \\
& V_{2}=-E_{(n)}+Z_{B}(11 a-11 b)
\end{aligned}
$$



Fig. 8-14 Operating principle (Phase discrimination principle)

If the phase difference $\alpha$ between the vectors $\mathrm{V}_{1}$ and $\mathrm{V}_{2}$ is larger than $90^{\circ}$ as shown in Fig. 8-14 (i), the operation is disabled. If $\alpha$ is smaller than $90^{\circ}$ as shown in (iii), the operation is performed.
As shown in (ii), the operating limit occurs when $\alpha$ is $90^{\circ}$, which results in a circular characteristic where the operating area is limited within the circle.
This indicates that operation is performed when $\mathrm{V}_{2}$ is within a phase difference of $90^{\circ}$ with respect to $\mathrm{V}_{1}$, as shown in Fig. 8-15.
This element is provided with a 51 stopper element, which does not operate at ( $11 \mathrm{a}-\mathrm{I} 1 \mathrm{~b}$ )/2 $/ 2.8 \mathrm{~A}$ or less, in order to prevent malfunction of the phase discrimination in the small current area.


Fig. 8-15 Phase discrimination characteristic

### 8.2.1.3.Examples of setting calculation

This element is set as follows.

Setting data:

$$
\begin{array}{ll}
\text { Generator's rated capacity ........................... } & \text { kVA } \\
\text { Rated voltage............................................... } & \text { kV } \\
\text { Synchronous impedance (p.u. value).......... } & \text { xd p.u. } \\
\text { Transient impedance (p.u. value).............. } & \text { xd'p.u. } \\
\text { CT ratio and VT ratio }
\end{array}
$$

From the above, the following are obtained:
The generator's reference impedance: $\mathrm{GZ}=\frac{(\text { Rated voltage })^{2}}{\text { Generator's rated capacity }} \times 1000$
Relay conversion value of $\mathrm{GZ}: \mathrm{RZ}=\mathrm{GZ} \times \frac{\mathrm{CT} \text { ratio }}{\text { PT ratio }}$

Relay conversion value of the synchronous impedance $x d$ : $R x d=R Z \times x d p . u$. ( $\Omega$ )
Relay conversion value of the transient impedance $x d^{\prime}: \mathrm{Rxd}^{\prime}=R Z \times x d^{\prime}$ p.u. ( $\Omega$ )
Therefore, the setting impedance on the relay side is as shown in Fig. 8-16.


Fig. 8-16

Setting example

| Generator's rated capacity .........................kVA | 112500 kVA |
| :---: | :---: |
| Rated voltage .......................................... kV | 11 kV |
| Synchronous impedance (p.u. value) ...........xd p.u. | 2.66 p.u. |
| Transient impedance (p.u. value) ................xd'p.u. | 0.24 p.u. |
| CT ratio | 8000/5 A |
| VT ratio | 11000/110 V |

Generator's reference impedance

$$
\begin{aligned}
\text { GZ } & =\frac{(\text { Rated voltage })^{2}}{\text { Generator's rated capacity }} \times 1000 \\
& =\frac{11^{2}}{112500} \times 1000 \\
& =1.08(\Omega)
\end{aligned}
$$

Relay conversion value of GZ

$$
\begin{aligned}
R Z & =G Z \times \frac{C T}{\text { PT ratio ratio }} \\
& =1.08 \times \frac{8000 / 5}{11000 / 110} \\
& =17.28(\Omega)
\end{aligned}
$$

Relay side conversion value of the synchronous impedance $x d$

$$
\begin{aligned}
R x d & =R Z \times x d p . u . \\
& =17.28 \times 2.66 \\
& =45.96(\Omega)
\end{aligned}
$$

Relay side conversion value of the transient impedance $x d^{\prime}$

$$
\begin{aligned}
R x d^{\prime} & =R Z \times x d^{\prime} p . u . \\
& =17.28 \times 0.24 \\
& =4.15(\Omega)
\end{aligned}
$$

Therefore, the setting value can be obtained as follows.

$$
\begin{aligned}
Z_{B} & =\frac{1}{2} R x d^{\prime} \quad=\frac{1}{2} \times 4.15 \\
& =2.075 \fallingdotseq 2.1(\Omega)
\end{aligned}
$$

$$
\begin{aligned}
\mathrm{Z}_{\mathrm{F}} & =\mathrm{Rxd} \\
& =45.96(\Omega) \quad \fallingdotseq 46.0(\Omega)
\end{aligned}
$$

### 8.3. Operation lock function

An operation lock function is incorporated in CGP2-A41D1 and CGP2-A42D1.

| Apparatus <br> No. | Display name | Protective function |
| :--- | :--- | :--- |
| OPLOCK | OPLOCK | Operation lock function |

### 8.3.1. OPLOCK element

OPLOCK element is provided with two DI circuits for interlocking the operation of protection elements. This element remains in the operation lock state while voltage is applied to DI6 or DI7, and the lock is reset without the voltage after a preset time of the resetting timer (Rst. Time) has passed. The protection elements subject to operation lock can be switched to one of the four patterns (OFF: Not used, DI6: Locked by DI6 input, DI7: Locked by DI7 input, DI67: Locked by either DI6 or DI7 input) depending on the lock element setting (o० Lock EN*) for each element. *oo represents each element name.

Furthermore, this element is enabled only when the setting of Use/Non-use of OPLOCK element (OPLOCK EN) is set to ON. Therefore, when this element is not used, unnecessary operation can be prevented by setting to OFF. It is not necessary to set other setting items with regard to OPLOCK element.

Table 8-3 Setting items of OPLOCK element

| Display <br> name | Setting <br> parameter | Setting |  | Description |
| :---: | :---: | :---: | :---: | :--- |
|  | OPLOCK EN | Range of setting | step |  |
|  |  | - | OFF: Non-use, ON: Use <br> When this element is used, set to ON. |  |
|  | Rst. Time | $0.0 \sim 10.0 \mathrm{~s}$ | 0.1 s | Resetting time for unlocking <br> INST: $\leq 50 \mathrm{~ms}$ |
|  | DIFFA Lock | OFF, DI6, DI7, DI67 | - | DIFF-A Lock |
|  | DIFFB Lock | OFF, DI6, DI7, DI67 | - | DIFF-B Lock |
|  | DIFFC Lock | OFF, DI6, DI7, DI67 | - | DIFF-C Lock |
|  | LOF Lock | OFF, DI6, DI7, DI67 | - | LOF Lock (CGP2-A41D1 only) |

OFF: Non-use
DI6: DI6 is activated.
DI7: DI7 is activated.
DI67: Both DI6 and DI7 are activated.

## 9. CB control function

In the relay, following CB control function is provided.
In this chapter, the CB control function incorporated in the relay are described.
CB control can be performed in the following three ways.
(1) Operation from the front panel (Refer to 5.3.4.2.)
(2) Operation from a locally attached PC (PC-HMI)
(3) Operation from the DI control instructions

### 9.1. CB open control

Fig. 9-1 shows the internal function blocks of CB open control.
Table 9-1 shows the control conditions.

The CB open control provides control output by receiving control instructions.
To output the control signal, check the presence or absence of interlock condition and the presence or absence of operation block setting (CB OPEN), and then output the control instruction.

When the Remote/Local setting (REMOTE/LOCAL) is set to REMOTE, the control output is performed after a preset time set on the operation timer (ON TIMER). When the Remote/Local setting (REMOTE/LOCAL) is set to LOCAL, the control output is performed instantaneously after the operation. At this time, the control state is held by the flip-flop, but it is reset when the control result becomes clear. When the Remote/Local setting (REMOTE/LOCAL) is set to REMOTE, the DI control signal must be continuously input so as to exceed the set time of the operation timer (ON TIMER). If you want to stop the control for some reason, it is possible to stop the control by stopping the DI input during the timer count.

An one-shot timer of 200 ms is added to the control output for performing open control to maintain the output until the CB is fully opened. This is because, if the breaking current that flows when the CB is opened is released by relay's own contact, the contact will be welded.


Fig. 9-1 Internal function block diagram of CB open control

As shown in Table 9-1, when "CB control: DI input" and "CB control: Setting" are both established, it is possible to execute the CB open instruction.
Note that the open instruction method that can be used in Local mode is different from that used in Remote mode.

Local: Open instruction is executed by panel operation or PC-HMI operation.
Remote: Open instruction is executed by the input to DI (ch5).

Table 9-1 Control conditions of CB open

|  | CB control: DI input |  | CB control: Setting(Refer to 5.3.4.2) |  |  | CB open instruction |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | CB State (Closed) (Dl:ch1) | Interlock condition (Dl:ch3) | Interlock | CB OPEN | LOCAL/ REMOTE | $\begin{gathered} \hline \text { Open } \\ \text { instruction } \\ \text { (Panel or } \\ \text { PC-HMI) } \end{gathered}$ | Open instruction (Dl:ch5) |
| Local | $\bigcirc$ |  | UNUSE | UNBLK | L | Possible |  |
|  | $\bigcirc$ | $\bigcirc$ | UNUSE | UNBLK | L | Possible |  |
|  | $\bigcirc$ |  | USE | UNBLK | L | Possible |  |
| Remote | $\bigcirc$ |  | UNUSE | UNBLK | R |  | Possible |
|  | $\bigcirc$ | $\bigcirc$ | UNUSE | UNBLK | R |  | Possible |
|  | $\bigcirc$ |  | USE | UNBLK | R |  | Possible |

* The cell with a circle "O" under the "DI:ch*" column means that "the DI input is on".


### 9.2. CB close control

Fig. 9-2 shows the internal function blocks of CB close control.
Table 9-2 shows the control conditions.

The CB close control provides control output by receiving control instructions.
To output the control signal, check the presence or absence of interlock condition and the presence or absence of operation block setting (CB CLOSE), and then output the control instruction.

When the Remote/Local setting (REMOTE/LOCAL) is set to REMOTE, the control output is performed after a preset time set on the operation timer (ON TIMER). When the Remote/Local setting (REMOTE/LOCAL) is set to LOCAL, the control output is performed instantaneously after the operation. At this time, the control state is held by the flip-flop, but it is reset when the control result becomes clear. When the Remote/Local setting (REMOTE/LOCAL) is set to REMOTE, the DI control signal must be continuously input so as to exceed the set time of the operation timer (ON TIMER). If you want to stop the control for some reason, it is possible to stop the control by stopping the DI input during the timer count.

An one-shot timer of 200 ms is added to the control output for performing close control to maintain the output until the CB is fully closed. This is because, if the making current that flows when the CB is closed is released by relay's own contact, the contact will be welded.


Fig. 9-2 Internal function block diagram of CB close control

As shown in Table 9-2, when "CB control: DI input" and "CB control: Setting" are both established, it is possible to execute the CB close instruction.
Note that the close instruction method that can be used in Local mode is different from that used in Remote mode.

Local: Close instruction is executed by panel operation or PC-HMI operation.
Remote: Close instruction is executed by the input to DI (ch5).

Table 9-2 Control conditions of CB close

|  | CB control: DI input |  | CB control: Setting (Refer to 5.3.4.2) |  |  | CB close instruction |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | CB State (Closed) (DI:ch1) | Interlock condition (DI:ch2) | Interlock | $\begin{aligned} & \text { CB } \\ & \text { CLOSE } \end{aligned}$ | LOCAL/ REMOTE | Close instruction (Panel or PC-HMI) | Close instruction <br> (DI:ch4) |
| Local |  |  | UNUSE | UNBLK | L | Possible |  |
|  |  | $\bigcirc$ | UNUSE | UNBLK | L | Possible |  |
|  |  |  | USE | UNBLK | L | Possible |  |
| Remote |  |  | UNUSE | UNBLK | R |  | Possible |
|  |  | $\bigcirc$ | UNUSE | UNBLK | R |  | Possible |
|  |  |  | USE | UNBLK | R |  | Possible |

[^1]
## 10. Standard (Technical data)

Compliance standards: Standard of the Japanese Electrotechnical Committee (JEC)
JEC2500 (2010) Protection relays for electric power systems
JEC2501 (2010) Electromagnetic compatibility tests for protection relays
JEC2515 (2005) Percentage differential relays for electric power apparatus protection
Guaranteed performance

| Common conditions | Frequency: Rated frequency <br> Control power supply voltage: Rated voltage <br> Ambient temperature: $20^{\circ} \mathrm{C}$ <br> Relative humidity: 30 to $80 \%$ on daily average | Unless otherwise indicated, the <br> common conditions shall be as <br> described in the left column. |
| :--- | :--- | :--- |

10.1. Relay characteristic data

| Item |  |  | Test condition | Standard |
| :---: | :---: | :---: | :---: | :---: |
| Operating value | Current ratio differential element (87G) | Minimum operating current | ```Setting: Minimum operating current \(=0.4 \mathrm{~A}\) Operating time \(=\) Minimum Restraint current method: All methods Input: Input to one terminal on the neutral side or output side``` | Setting $\pm 5 \%$ |
|  | Loss of field element (40) | ZF operating value $\overline{\mathrm{ZB}}$ <br> operating value | Setting: $\begin{aligned} & \mathrm{ZF}=5.0,27.5,50.0 \Omega \\ & \mathrm{ZB}=0.40,2.2,4.00 \Omega \end{aligned}$ <br> Operating time $=$ Minimum <br> Input: <br> Current $=$ Rated current $\times 2$ (10 A) <br> (As follows: $11 \mathrm{a}=5 \mathrm{~A}, \mathrm{I} 1 \mathrm{~b}=5 \mathrm{~A}, \mathrm{I} 1 \mathrm{a}-11 \mathrm{~b}=10 \mathrm{~A}$ ) Current lags by $270^{\circ}$ to voltage <br> * When the voltage becomes 110 V or more for the constant current of the rated current $\times 2$, keep the voltage constant at 110 V and decrease the current for measurement. | Setting $\pm 5 \%$ |
| Resetting value | Current ratio differential element (87G) | Minimum operating current | Setting: <br> Minimum operating current $=0.4 \mathrm{~A}$ <br> Operating time $=$ Minimum <br> Restraint current method: All methods <br> Input: <br> Input to one terminal on the neutral side or output side | Operating value $\times 90 \%$ or more |
|  | Loss of field element (40) | ZF operating value | Setting: $\begin{aligned} & \mathrm{ZF}=5.0,27.5,50.0 \Omega \\ & \mathrm{ZB}=0.40,2.2,4.00 \Omega \end{aligned}$ <br> Operating time $=$ Minimum <br> Input: <br> Current $=$ Rated current $\times 2$ (10 A) <br> (As follows: $11 \mathrm{a}=5 \mathrm{~A},\|1 \mathrm{~b}=5 \mathrm{~A}\| 1 \mathrm{a}-,11 \mathrm{~b}=10 \mathrm{~A}$ ) Lags by $270^{\circ}$ to voltage <br> * When the voltage becomes 110 V or more for the constant current of the rated current $\times 2$, keep the voltage constant at 110 V and decrease the current for measurement. | Operating value $\times 105 \%$ or less |
|  |  | ZB operating value |  | Operating value $\times 95 \%$ or more |


| Operating time | Current ratio differential element (87G) | Setting: <br> Minimum operating current $=0.4 \mathrm{~A}$ <br> Ratio switching point $=$ Minimum Restraint current method: All methods Input: Input to one terminal <br> Current $=0 \rightarrow$ Setting value $\times 300 \%$ <br> (a) Ope.Time : 0.00 s <br> (b) Ope.Time : $0.01 \mathrm{~s} \leq$ Ope.Time $<1.00$ s <br> (c) Ope.Time : $1.00 \mathrm{~s} \leq$ Ope.Time $\leq 10.00 \mathrm{~s}$ | (a) Within 50 ms <br> (b) Ope.time setting $\pm 50 \mathrm{~ms}$ <br> (c) Ope.time setting $\pm 5 \%$ |
| :---: | :---: | :---: | :---: |
|  | Loss of field element (40) | Setting: <br> ZF, ZB = Minimum <br> Input: <br> Current $=0 \rightarrow$ Rated current $\times 2$ (10 A) <br> Voltage $=110 \mathrm{~V} \rightarrow$ Voltage corresponding to $80 \%$ of the impedance setting value <br> Current lags behind voltage by $270^{\circ}$ <br> (a) Ope.Time : $0.20 \mathrm{~s} \leq$ Ope.Time $<1.00$ s <br> (b) Ope.Time : $1.00 \mathrm{~s} \leq$ Ope.Time $\leq 10.00 \mathrm{~s}$ | (a) Ope.time setting $\pm 50 \mathrm{~ms}$ <br> (b) Ope.time setting $\pm 5 \%$ |
| Resetting time for unlocking | Operation lock function (OPLOCK) | DI input voltage: Rated voltage $\rightarrow 0$ <br> (a) Ope.Time : 0.0 s <br> (b) Ope.Time: $0.1 \mathrm{~s} \leq$ Ope.Time $<1.0 \mathrm{~s}$ <br> (c) Ope.Time : $1.0 \mathrm{~s} \leq$ Ope.Time $\leq 10.0 \mathrm{~s}$ | Operation time of relay element <br> (a) Within 50 ms <br> (b) Ope.time setting $\pm 50 \mathrm{~ms}$ <br> (c) Ope.time setting $\pm 5 \%$ |
| Resetting time | Current ratio differential element (87G) <br> Loss of field element (40) | Setting: <br> Minimum operating current $=0.4 \mathrm{~A}$ <br> Ratio switching point $=$ Minimum <br> Restraint current method: All methods <br> Input: Input to one terminal <br> Current $=$ Setting value $\times 300 \% \rightarrow 0$ <br> Setting: <br> ZF, ZB = Minimum <br> Input: <br> Current $=$ Rated current $\times 2(10 \mathrm{~A}) \rightarrow 0$ <br> Voltage $=$ Voltage corresponding to $80 \%$ of the impedance setting value $\rightarrow 110 \mathrm{~V}$ <br> Current lags behind voltage by $270^{\circ}$ | $200 \mathrm{~ms} \pm 50 \mathrm{~ms}$ |
| Ratio characteris tic | Current ratio differential element (87G) | Setting: <br> Minimum operating current $=$ Minimum <br> Operating time $=$ Minimum <br> Restraint current method: MIN <br> ratio $\mathrm{K} 1=5,28,50 \%$ <br> ratio $\mathrm{K} 2=5,28,50 \%$ <br> Ratio switching point $=0.4,5.2,10.0 \mathrm{~A}$ <br> Input: <br> Fix the inflow current I1 and vary the outflow current 12. <br> Input the inflow current I1 to so that the outflow current I2 becomes $100 \%$, $200 \%$, or $500 \%$ of I1. | Setting $\pm 5 \%$ |
| Phase characteris tics | Current ratio differential element (87G) | Setting: <br> Minimum operating current $=$ Minimum <br> Operating time $=$ Minimum <br> Restraint current method: All methods ratio (K1, K2) $=5,50 \%$ <br> Ratio switching point $=0.4 \mathrm{~A}$ <br> Input: <br> Fix both the inflow current I1 and the outflow current I2 at $\mathrm{N}\left(^{*}\right)$, change the phase of the outflow current I 2 relative to the inflow current I1, and measure the operating phase angle. <br> (*) N...100\%(=5A), 200\% (=10A) | Within $\pm 5^{\circ}$ of the nominal value |



| Maximum <br> current in <br> guaranteed <br> operating <br> range <br> (Internal <br> fault) | Current ratio differential <br> element (87G) | Input current 100 A, for 300 ms, twice, at <br> intervals of 1 min | The relay shall operate. |
| :--- | :--- | :--- | :--- |
| Maximum <br> current in <br> guaranteed <br> operating <br> range <br> (External <br> fault) | Current ratio differential <br> element (87G) | Input: Through current $=25 \mathrm{~A}$ <br> (300ms, 10th) | The relay shall not operate. |
| Minimum <br> current in <br> guaranteed <br> operating <br> range | Loss of field element (40) | Setting: <br> ZF $=$ Maximum <br> ZB, Operating time = Minimum |  |

### 10.2. General specification data

| Item | Test condition |  |  |  | Standard |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Contact capacity | Contact for tripping |  |  | Closed circuit capacity | $\begin{aligned} & \hline \text { DC } 110 \mathrm{~V}: 15 \mathrm{~A} \\ & \text { DC } 220 \mathrm{~V}: 10 \mathrm{~A} \\ & 0.5 \mathrm{~s} \mathrm{~L} / \mathrm{R}=0 \\ & \hline \end{aligned}$ |
|  |  |  |  | Open-circuit capacity | DC $110 \mathrm{~V}: 0.3 \mathrm{~A}$ DC $220 \mathrm{~V}: 0.15 \mathrm{~A}$ $\mathrm{L} / \mathrm{R}=40 \mathrm{~ms}$ |
|  | Contact for annunciator |  |  |  | Open- / Closed circuit capacity : $\begin{aligned} & 500 \mathrm{VA}(\cos \varphi=0.4) \\ & 60 \mathrm{~W}(\mathrm{~L} / \mathrm{R}=7 \mathrm{~ms}) \end{aligned}$ <br> Max. current : 5 A <br> Max. voltage : AC 380 V <br> DC 125 V |
| Overload capacity | Current circuit | Rated current $\times 40$ times, for 2 s , twice, at intervals of 1 min |  |  | No malfunction, no unnecessary operation, no abnormal indication, and etc. |
|  |  |  | Rated voltage $\times 1.15$ times, 3 hr |  |  |
|  |  |  | Positive-phase-sequence voltage : <br> Rated voltage $\times 2.17$ times, for 10 s , once |  |  |
| Insulation resistance | DC500 V meg-ohm-meter is used. <br> (1) Between collective electric circuit and ground (However, the serial communication circuit is excluded.) <br> (2) Between mutual circuits, between contact poles (However, the serial communication circuit is excluded.) |  |  |  | (1) $10 \mathrm{M} \Omega$ or more <br> (2) $5 \mathrm{M} \Omega$ or more |
| Withstand voltage at commercial frequency | (1) Between collective electric circuit and ground : $\text { AC2000 V, } 1 \text { min }$ <br> (2) Between mutual circuits, between contact poles: <br> AC2000 V, 1 min <br> (However, the serial communication circuit is excluded.) <br> (3) Between contact terminals (between poles) : <br> AC1000 V, 1 min |  |  |  | No malfunction, no unnecessary operation, no abnormal indication, and etc. |
| Withstand voltage against lightning impulse | Standard shock voltage waveform $(1.2 / 50 \mu \mathrm{~s})$ <br> Application to each of positive and negative pole for 3 times | 4.5 kV | - Between <br> - Between measuri <br> - Between instrume (However, excluded.) | collective electric circuit and ground mutual transformer circuits for ing instruments the transformer circuit for measuring nt and the control circuit the serial communication circuit is | No malfunction, no unnecessary operation, no abnormal indication, and etc. |
|  |  | 3 kV | - Between <br> - Between measuri <br> - Between poles) <br> - Between circuit <br> (However, excluded.) | mutual control circuits terminals of transformer circuit for ing instrument contact circuit terminals (between terminals of control power supply the serial communication circuit is |  |


| Item | Test condition | Standard |
| :---: | :---: | :---: |
| Trouble of control power supply | - Turning on/off control power supply <br> - Instantaneous interruption of control power supply <br> - Slow variation of control power supply | No malfunction, no unnecessary operation, no abnormal indication, and etc. |
| Immunity against electrostatic discharge | 8 kV : Contact discharge 15 kV : Aerial discharge <br> 10 times of each of positive and negative pole at intervals of more than 1 s | No malfunction, no unnecessary operation, no abnormal indication, and etc. |
| Immunity against commercial frequency | Applied point: Between line and ground <br> Test voltage: 300 V , Test time: 10 s <br> Applied point: Between lines <br> Test voltage: 150 V , Test time: 10 s | No malfunction, no unnecessary operation, no abnormal indication, and etc. |
| Immunity against damped oscillatory wave | - Peak value of 1 st wave: 2.5 kV <br> - Vibration frequency: $1 \mathrm{MHz} \pm 10 \%$ <br> - Damping time to $1 / 2: 3 \sim 6$ cycles <br> - Frequency of repetition: $6 \sim 10$ times/ 1 cycle of commercial frequency (asynchronous) <br> - Output impedance of test circuit: $200 \Omega \pm 10 \%$ <br> Applied point: <br> - Between collective transformer circuit and ground <br> - Between collective control power supply circuit and ground <br> - Between terminals of control power supply circuit | No malfunction, no unnecessary operation, no abnormal indication, and etc. |
| Electric fast transient/Burst immunity | Applied voltage: $\pm 2.0 \mathrm{kV}$ <br> Repetition frequency: 5.0 kHz <br> Port for applied: Between collective control power supply circuit and ground <br> Applied voltage: $\pm 1.0 \mathrm{kV}$ <br> Repetition frequency: 5.0 kHz <br> Port for applied: <br> - Between collective transformer circuit for measuring instruments and ground <br> - Between collective binary input/output (DI/DO) circuit and ground | No malfunction, no unnecessary operation, no abnormal indication, and etc. |
| Immunity to square wave impulse | Applied voltage: $1.0 \mathrm{kV} \pm 10 \%$ <br> Test time: 2s <br> Each of positive and negative pole <br> Output impedance : $50 \Omega$ <br> Pulse duration: $100 \mathrm{~ns} \pm 30 \%$ <br> Pulse rise time : 1 ns or less <br> Port for applied: <br> - Between collective transformer circuit and ground <br> - Between collective control power supply circuit and ground <br> - Between collective binary input/output (DI/DO) circuit and ground <br> - Between terminals of control power supply circuit | No malfunction, no unnecessary operation, no abnormal indication, and etc. |


| Item | Test condition | Standard |
| :---: | :---: | :---: |
| Surge immunity | Applied time : $1.2 / 50 \mu \mathrm{~s}$ at open circuit condition <br> $8 / 20 \mu \mathrm{~s}$ at short circuit condition <br> Effective output impedance : $2 \Omega$ <br> 5 times of each of positive and negative pole at intervals 1 min <br> Port for applied and applied voltage: <br> - Between control power supply terminals: <br> Applied voltage : $0.5,1 \mathrm{kV}(0 \Omega, 18 \mu \mathrm{~F}, 1.5 \mathrm{mH})$ <br> - Between collective control power supply and ground: <br> Applied voltage : $0.5,1,2 \mathrm{kV}(10 \Omega, 9 \mu \mathrm{~F}, 1.5 \mathrm{mH})$ <br> - Between binary input/output circuit terminals: <br> Applied voltage : $0.5,1 \mathrm{kV}(40 \Omega, 0.5 \mu \mathrm{~F}, 20 \mathrm{mH})$ <br> - Between collective binary input/output circuit and ground: <br> Applied voltage : $0.5,1,2 \mathrm{kV}(40 \Omega, 0.5 \mu \mathrm{~F}, 20 \mathrm{mH})$ <br> - Between transformer circuits for measuring instruments: <br> Applied voltage : $0.5,1 \mathrm{kV}(40 \Omega, 0.5 \mu \mathrm{~F}, 20 \mathrm{mH})$ <br> - Between collective transformer circuit for measuring instruments and ground: <br> Applied voltage : $0.5,1,2 \mathrm{kV}(40 \Omega, 0.5 \mu \mathrm{~F}, 20 \mathrm{mH})$ | No malfunction, no unnecessary operation, no abnormal indication, and etc. |
| Commercial frequency magnetic field immunity | Magnetic field intensity : $30 \mathrm{~A} / \mathrm{m}$, for 60 s (continuous), at once $300 \mathrm{~A} / \mathrm{m}$, for 2 s , three times at intervals of 1 min <br> * Setting value of the 10 circuit for ZCT input shall be 5 mA or more. | No malfunction, no unnecessary operation, no abnormal indication, and etc. |
| Immunity to conducted disturbances, induced by radio- frequency fields | Voltage level : 10 V <br> Amplitude modulation: $1 \mathrm{kHz}, \pm 80 \%$ <br> Frequency range : <br> (a) Sweep test: $150 \mathrm{kHz} \sim 80 \mathrm{MHz}$ <br> (b) Spot test : 27, 68 MHz <br> Test time : <br> (a) Sweep test : 0.5 s or more at each step of frequency <br> (b) Spot test: 10 s or more at each frequency <br> Port for applied : <br> - Between collective control power supply and ground <br> - Between collective binary input/output circuit and ground <br> - Between collective transformer circuit for measuring instruments and ground | No malfunction, no unnecessary operation, no abnormal indication, and etc. |
| Radiated, radiofrequency, electromagnetic field immunity | Voltage level: $10 \mathrm{~V} / \mathrm{m}$ <br> Amplitude modulation: $1 \mathrm{kHz}, \pm 80 \%$ <br> Frequency range : <br> (a) Sweep test : $80 \mathrm{MHz} \sim 1.0 \mathrm{GHz}, 1.4 \mathrm{GHz} \sim 2.7 \mathrm{GHz}$ <br> (b) Spot test : 80, 160, 380, 450, 900, 1850, 2150 MHz <br> Test time : <br> (a) Sweep test : 0.5 s or more at each step of frequency <br> (b) Spot test : 10 s or more at each frequency <br> Number of test time : <br> Twice at each frequency for each direction of back and forth, right and left (4 directions) ; In total, 8 times at each frequency | No malfunction, no unnecessary operation, no abnormal indication, and etc. |


| Item | Test condition |  |  |  |  |  |  | Standard |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Vibration | Frequency$(\mathrm{Hz})$ | Amplitude (mm) |  | Time <br> (s) |  | $\begin{aligned} & \text { celerati } \\ & \left(\mathrm{m} / \mathrm{s}^{2}\right) \end{aligned}$ |  | No malfunction, no unnecessary operation, no abnormal indication, and etc. |
|  |  | Back Right <br> and and <br> forth left | Up <br> and down | Each direction | Back <br> and <br> forth | Right <br> and <br> left | Up <br> and down |  |
|  | 10 | 5 | 2.5 | 30 | 10 |  | 5 |  |
|  | 16.7 | 0.4 |  | 600 | 2 |  |  |  |
| Shock | - Shock acceleration : $300 \mathrm{~m} / \mathrm{s}^{2}$ <br> - Duration of pulse : 11 ms <br> - Direction of pulses : Respective 3 directions in back and forth, right and left, up and down ( 6 directions) <br> - Number of pulses : 3 times for 6 directions (In total : 18 times) |  |  |  |  |  |  | No malfunction, no unnecessary operation, no abnormal indication, and etc. |
| Load | (1) Current circuit <br> (2) Voltage circuit <br> (3) Control power supply |  |  |  |  |  |  | (1) At the rating of $5 \mathrm{~A}: 0.6$ <br> VA or less <br> At the rating of $1 \mathrm{~A}: 0.1$ VA or less <br> (2) 0.1 VA or less <br> (3) 10 W or less |
| Mass | (1) Subunit <br> (2) Subunit and outer case |  |  |  |  |  |  | (1) About 2.3 kg (2) About 3.7 kg |

## 11. Test

Although all necessary functional tests are implemented for this relay before shipment from the factory, it is recommendable to perform the tests with reference to the following items, before use.

### 11.1. Visual inspection

Perform the visual inspection check with reference to the following items.

| Inspection item | Contents of inspection |
| :---: | :--- |
| Unit | (1) No deformation <br> (2) Operational check of the operation key switches <br> (working part) |
| (3) Neither discoloration nor deformation of the front <br> name plate <br> (4) No damage at the terminal connectors |  |
| Case | No damage including the terminal connectors |
| Others | No foreign substances, such as dust, iron pieces, etc. |

### 11.2. Characteristic test

11.2.1. Notes related to the tests
(1) Recommended test condition

Regarding the ambient conditions, following conditions shall be complied with, as far as possible.
If the test is performed at the condition which is significantly different from the next condition, the correct test results may not be obtained.

- Ambient temperature: $20^{\circ} \mathrm{C} \pm 10^{\circ} \mathrm{C}$
- Rated frequency: $\pm 1 \%$
- Waveform (AC): Distortion factor 2\% or less
- Control voltage: Rated voltage $\pm 2 \%$
(2) Functional control points

Refer to Chapter 10.
The functional control point (standard point) of each relay's element shall be checked by the relay alone. Therefore, when the combined test with external devices such as CT, ZCT, etc. is performed, it shall be considered the error factor of external devices.
Furthermore, if user-defined control point is specified (e.g. accracy of relay characteristic is controlled at service conditions), execute the test at the manufacturer-defined control point (mentioned in Section 10.1) before in-service operation and then check accuracy of the relay. After that, execute the test at the user-defined control point, and set this data to the subsequent standards.
(3) Setting change

Refer to 5.3.4.1 for the setting change.
(4) Judgment of operation

Basically, the measurement of the operating value, operating time, etc. shall be done by open/close of the output relay contact of each element.

### 11.2.2. Characteristic test

(1) Test circuit

The external connection of $A C$ input circuit is as shown below as a reference.
Refer to Fig. 2-3 for the terminal arrangement.
[1] Current ratio differential element

- Minimum operating current test
- Operating/Resetting time test

- Ratio characteristic test

- Phase characteristic test

[2] Loss of field element


Current value measured by this test circuit is represented by I.

$$
\mathrm{Z}=\frac{\mathrm{Vab}}{2 \times 1}
$$

Calculate $Z(\Omega)$ using the above equation.
Note: $2 \times 1=(11 a-11 b)$
I = Input current
[3] Operation lock function


When the above switch (SW) is changed from closed to open on the conditions of operation of protection elements, the relay is locked up until the setting value of the unlocking time, and then the relay operates.
(When the SW is closed, "OP-LOCK" on the front panel lights up and the relay is locked.)
(2) Test items
[1] Test setting
Before staring test, it is recommended to to use 'Test setting' function in order to lock the operation of un-tested phases and elements.

As for the method of test setting, refer to 5.3.4.4.2 in Chapter 5.
As for the list of test setting items, refer to the table shown below.

## List of test setting items

| No. | Name of <br> items | Contents of setting | Setting |
| :---: | :--- | :--- | :--- |
| 1 | SV-LK | Locking of alarm function | UNLOCKED / LOCKED |
| 2 | TCNT-LK | Locking of trip counter | UNLOCKED / LOCKED |

[2] Forced operation test (DO contact test)
Refer to 5.3.4.4.1 in Chapter 5.
[3] Operating value test
Refer to the "Operating value" and "Resetting value" in Chapter 10.
[4] Operating time test
Refer to the "Operating time" in Chapter 10.
[5] Reset time test
Refer to the "Reset time" in Chapter 10.
[6] Phase characteristics test
Refer to the "Phase characteristics" in Chapter 10.
[7] LED/VFD full lighting test
Refer to 5.3.4.4.3 in Chapter 5.
(Supplement) How to find the characteristic control point for the Loss of field element
$Z_{\mathrm{F}}$ : Operating measured value at $\theta=90^{\circ}(\mathrm{ohm})$
$\mathrm{Z}_{\mathrm{B}}$ : Operating measured value at $\theta=90^{\circ}(\mathrm{ohm})$
L: Theoretical value of operation at $\theta=60^{\circ}$ and $120^{\circ}$ for the above $Z_{F}$ and $Z_{B}$ values
(Ohm value: x dot in the figure on the right)
(Note) Maximum sensitivity angle: $\theta=90^{\circ}$
The characteristic circle in the right figure is expressed as follows.

$$
\begin{equation*}
x^{2}+\left(y-\frac{z_{F}+Z_{B}}{2}\right)^{2}=\left(\frac{z_{F}-Z_{B}}{2}\right)^{2} \tag{1}
\end{equation*}
$$



Substituting the relationship $X=L \sin 30^{\circ}$ and $y=L \cos 30^{\circ}$ into (1) yields the following quadratic equation.

$$
\begin{equation*}
L^{2}-\quad L 0.866\left(Z_{F}+Z_{B}\right)+Z_{F} Z_{B}=0 \tag{2}
\end{equation*}
$$

By determining the root of the Equation (2), the theoretical values of $\theta=60^{\circ}$ and $120^{\circ}$ are given as follows.

$$
\begin{align*}
& L=0.433\left(Z_{F}+Z_{B}\right)+\sqrt{ }\left(0.187\left(Z_{F}+Z_{B}\right)^{2}-Z_{F} Z_{B}\right)=0  \tag{3}\\
& L_{F}=0.433\left(Z_{F}+Z_{B}\right)+\sqrt{ }\left(0.187\left(Z_{F}+Z_{B}\right)^{2}-Z_{F} Z_{B}\right) \quad .  \tag{3}\\
& L_{B}=0.433\left(Z_{F}+Z_{B}\right)-\sqrt{ }\left(0.187\left(Z_{F}+Z_{B}\right)^{2}-Z_{F} Z_{B}\right) \quad . \tag{4}
\end{align*}
$$

The setting values of the phase characteristic control point are $Z_{F}=5 \Omega$ and $Z_{B}=0.4 \Omega$. When these are substituted into Equations (3) and (4) to obtain $L_{F}$ and $L_{B}$, the following results are obtained: $L_{F}=4.2 \Omega$ and $L_{B}=0.476 \Omega$.

As the theoretical value $\pm 5 \%$ at the characteristic control point falls within the range of the impedance value at the characteristic control point $\pm 5^{\circ}$, the warranty conditions are for the theoretical value $\pm 5 \%$ at the characteristic control point.
Therefore, the warranty conditions are as follows.

| Name | $\mathrm{Z}_{\mathrm{F}}\left(\mathrm{L}_{\mathrm{F}}\right)$ |  | $\mathrm{Z}_{\mathrm{B}}\left(\mathrm{L}_{\mathrm{B}}\right)$ |  |
| :--- | :---: | :---: | :---: | :---: |
| Phase $\theta\left({ }^{\circ}\right)$ | 60 | 120 | 60 | 120 |
| Operating theoretical <br> value $(\Omega)$ | 4.20 | 4.20 | 0.476 | 0.476 |
| Allowable error: <br> Operating theoretical <br> value $\pm 5 \%$ | $4.20 \Omega \pm 5 \%$ <br> $: 3.99$ |  | 0 |  |

## 12. Maintenance and self diagnosis

### 12.1. Maintenance

12.1.1. Daily inspection

It is recommended to check the following items daily;

- No dust (such as iron powder, etc) is in/on the relay case
- No abnormal noise is generated
- 'RUN' LED is lighting
12.1.2. Periodic inspection

It is recommended to test the following items periodically.

- Visual inspection, referring to Section 11.1.
- Characteristic test, referring to Section 11.2.


### 12.2. Self diagnosis

Monitoring of the electronic circuit as well as the incorporated power supply is performed. If any trouble is generated, fault display by LED and output by alarm DO (b contact) are executed.

## 1. Alarm indication

The relay alarm, which would be appeared at relay failure, is divided two types, minor failure and serious failure.

Minor failure ------ This alarm may appear by detecting the abnormal current or voltage input, or abnormality of the circuits which would not affect the relay's trip operation directly.
Serious failure --- This alarm may appear by detecting abnormality of the important circuits which would affect the relay's trip operation directly.
The operation of LED display and alarm DO output are shown in next table.
Table 12-1 LED display, Alarm DO

| Status of the <br> relay | Alarm DO | RUN LED | ALARM LED |
| :--- | :---: | :---: | :---: |
| Minor failure | OFF | ON | ON |
| Serious failure | ON | OFF | ON |

Since the indication of 'ALARM LED' at fault detection is latched, it is necessary to press 'ESC/C' key for 3 sec or more after removing the cause of trouble.
2. Handling of Alarm indication

When any trouble is generated, please collect the necessary information as shown below which would be useful for finding the cause of trouble.
[1] Confirm the state of LED display and the contact of alarm DO.
Refer to Fig. 12-1, Fig. 12-2 for LED display and alarm DO.
[2] Confirm the error code in monitoring
Refer to 5.3.2.2.4 in Chapter 5 for the confirmation method of the error code,
[3] Please contact your service provider.


Fig. 12-1 Position of RUN LED, ALARM LED


Fig. 12-2 Position of alarm DO

## 13. Default setting or configuration value

### 13.1. Setting

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| Category | Element | Setting |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Item name or Setting parameter |  | Range |  | Step | Default value |  | Please make a note about setting. |  |
|  |  | VFD | PC-HMI | VFD | PC-HMI |  | VFD | PC-HMI | Group 1 (G1) | Group 2 (G2) |
| DIFF | DIFF | DIFF EN | DIFF EN | OFF ON | Off On | - | OFF | Off |  |  |
|  |  | Ires Meth. | DIFF Ires Meth. | MAX MIN SUM |  | - | MAX | MAX |  |  |
|  |  | Ope. Curt. | DIFF Ope. Curt. | $0.4 \sim 1.0 \mathrm{~A}$ |  | 0.1A | 0.4A | 0.4A |  |  |
|  |  | ratio K1 | DIFF ratio K1 | $5 \sim 50 \%$ |  | 1\% | 5\% | 5\% |  |  |
|  |  | ratio K2 | DIFF ratio K2 | $5 \sim 50 \%$ |  | 1\% | 5\% | 5\% |  |  |
|  |  | Is Curt. | DIFF Is Curt. | $0.4 \sim 10.0 \mathrm{~A}$ |  | 0.1 A | 0.4A | 0.4A |  |  |
|  |  | Ope. Time | DIFF Ope. Time | $0.00 \sim 10.00 \mathrm{~s}$ |  | 0.01s | 0.00s | 0.00s |  |  |
| LOF | LOF | LOF EN | LOF EN | OFF ON | Off On | - | OFF | Off |  |  |
|  |  | LOF ZF | LOF ZF | $5.0 \sim 50.0 \Omega$ |  | $0.1 \Omega$ | $5.0 \Omega$ | $5.0 \Omega$ |  |  |
|  |  | LOF ZB | LOF ZB | $0.40 \sim 4.00 \Omega$ |  | $0.01 \Omega$ | $0.40 \Omega$ | $0.40 \Omega$ |  |  |
|  |  | Ope. Time | LOF Ope. Time | $0.20 \sim 10.00 \mathrm{~s}$ |  | 0.01s | 0.20 s | 0.20s |  |  |
| OPLOCK | $\begin{aligned} & \mathrm{OPLOC} \\ & \mathrm{~K} \end{aligned}$ | OPLOCK EN | OPLOCK EN | OFF ON | Off On | - | OFF | Off |  |  |
|  |  | Rst. Time | OPLOCK Rst. Time | $0.0 \sim 10.0 \mathrm{~s}$ |  | 0.1 s | 0.0s | 0.0s |  |  |
|  |  | DIFFA Lock | OPLOCK DIFFALock | OFF D16 DI7 D167 | Off D16 DI7 D167 | - | OFF | Off |  |  |
|  |  | DIFFB Lock | OPLOCK DIFFB Lock | OFF D16 DI7 D167 | Off D16 D17 D167 | - | OFF | Off |  |  |
|  |  | DIFFC Lock | OPLOCK DIFFC Lock | OFF DI6 DI7 D167 | Off D16 D17 D167 | - | OFF | Off |  |  |
|  |  | LOF Lock | OPLOCK LOF Lock | OFF DI6 DI7 DI67 | Off D16 DI7 DI67 | - | OFF | Off |  |  |
| System setting | - | DI VOLTAGE | DI Voltage Level | DC110V DC220V |  | - | DC110V | DC110V |  |  |
|  | - | Pre-Rec. | Pre-Rec. Time | $100 \sim 4500 \mathrm{~ms}$ |  | 10 ms | 100 ms | 100 ms |  |  |
|  | - | Rec. | Max. Rec. Time | $200 \sim 5000 \mathrm{~ms}$ |  | 10 ms | 200 ms | 200 ms |  |  |
|  | - | PASSWORD | - | UNUSE USE | - | - | UNUSE | - |  |  |
|  | - | PASS | - | $0000 \sim 9999$ |  | 1 | 0000 | - |  |  |
| Trip counter | - | Initial | Initial Value | $0 \sim 10000$ |  | 1 | 0 | 0 |  |  |
|  | - | Alarm | Alarm Value | $1 \sim 10000$ |  | 1 | 1 | 1 |  |  |
| Analog value display | - | Al Disp. | Al Display Style | PRIMARY SECONDARY | Primary Secondary | - | PRIMARY | Primary |  |  |
|  | - | PTP | PTP | $0.1 \sim 500.0 \mathrm{kV}$ |  | 0.1 kV | 5.0 kV | 5.0 kV |  |  |
|  | - | PTS | PTS | $100 \sim 125 \mathrm{~V}$ |  | 1 V | 100 V | 100 V |  |  |
|  | - | CTP | CTP | $5 \sim 30000 \mathrm{~A}$ |  | 1A | 5A | 5A |  |  |
|  | - | CTS | CTS | 5A |  | - | 5A | 5A |  |  |
| CB control | - | REMOTE/LOCAL | Remote/Local | R L | Remote Local | - | R | Remote |  |  |
|  | - | INTERLOCK | Interlock Use | UNUSE USE | Non-Use Use | - | USE | Use |  |  |
|  | - | CB OPEN | CB Open Block | UNBLK BLK | Unblocked Blocked | - | UNBLK | Unblocked |  |  |
|  | - | CB CLOSE | CB Close Block | UNBLK BLK | Unblocked Blocked | - | UNBLK | Unblocked |  |  |
|  | - | ON TIMER | CB On-Delay Timer | $0 \sim 60 \mathrm{~s}$ |  | 1s | 0s | Os |  |  |
| $\begin{array}{\|l\|} \hline \text { DO contact } \\ \text { test setting } \\ \hline \end{array}$ | - | - | One-Shot Time | - | $1 \sim 20 s$ | 1 s | - | 1s |  |  |

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| Category | Element | Setting |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Item name or Setting parameter |  | Range |  | Step | Default value |  | Please make a note about setting. |  |
|  |  | VFD | PC-HMI | VFD | PC-HMI |  | VFD | PC-HMI | Group 1 (G1) | Group 2 (G2) |
| DIFF | DIFF | DIFF EN | DIFF EN | OFF ON | Off On | - | OFF | Off |  |  |
|  |  | Ires Meth. | DIFF Ires Meth. | MAX MIN SUM |  | - | MAX | MAX |  |  |
|  |  | Ope. Curt. | DIFF Ope. Curt. | $0.4 \sim 1.0 \mathrm{~A}$ |  | 0.1A | 0.4A | 0.4A |  |  |
|  |  | ratio K1 | DIFF ratio K1 | $5 \sim 50 \%$ |  | 1\% | 5\% | 5\% |  |  |
|  |  | ratio K2 | DIFF ratio K2 | $5 \sim 50 \%$ |  | 1\% | 5\% | 5\% |  |  |
|  |  | Is Curt. | DIFF Is Curt. | $0.4 \sim 10.0 \mathrm{~A}$ |  | 0.1A | 0.4A | 0.4A |  |  |
|  |  | Ope. Time | DIFF Ope. Time | $0.00 \sim 10.00 \mathrm{~s}$ |  | 0.01 s | 0.00s | 0.00s |  |  |
| OPLOCK | $\begin{aligned} & \mathrm{OPLOC} \\ & \mathrm{~K} \end{aligned}$ | OPLOCK EN | OPLOCK EN | OFF ON | Off On | - | OFF | Off |  |  |
|  |  | Rst. Time | OPLOCK Rst. Time | $0.0 \sim 10.0 \mathrm{~s}$ |  | 0.1s | 0.0s | 0.0s |  |  |
|  |  | DIFFALock | OPLOCK DIFFA Lock | OFF DI6 DI7 DI67 | Off D16 DI7 DI67 | - | OFF | Off |  |  |
|  |  | DIFFB Lock | OPLOCK DIFFB Lock | OFF DI6 DI7 D167 | Off D16 DI7 D167 | - | OFF | Off |  |  |
|  |  | DIFFC Lock | OPLOCK DIFFC Lock | OFF DI6 DI7 DI67 | Off D16 DI7 DI67 | - | OFF | Off |  |  |
| $\begin{aligned} & \text { System } \\ & \text { setting } \end{aligned}$ | - | DI VOLTAGE | DI Voltage Level | DC110V DC220V |  | - | DC110V | DC110V |  |  |
|  | - | Pre-Rec. | Pre-Rec. Time | $100 \sim 4500 \mathrm{~ms}$ |  | 10 ms | 100 ms | 100 ms |  |  |
|  | - | Rec. | Max. Rec. Time | $200 \sim 5000 \mathrm{~ms}$ |  | 10 ms | 200 ms | 200 ms |  |  |
|  | - | PASSWORD | - | UNUSE USE | - | - | UNUSE | - |  |  |
|  | - | PASS | - | $0000 \sim 9999$ |  | 1 | 0000 | - |  |  |
| Trip counter | - | Initial | Initial Value | $0 \sim 10000$ |  | 1 | 0 | 0 |  |  |
|  | - | Alarm | Alarm Value | $1 \sim 10000$ |  | 1 | 1 | 1 |  |  |
| Analog value display | - | Al Disp. | Al Display Style | PRIMARY SECondary | Primary Secondary | - | PRIMARY | Primary |  |  |
|  | - | CTP | CTP | $5 \sim 30000 \mathrm{~A}$ |  | 1A | 5A | 5A |  |  |
|  | - | CTS | CTS | 5A |  | - | 5A | 5A |  |  |
| CB control | - | REMOTE/LOCAL | Remote/Local | R L | Remote Local | v | R | Remote |  |  |
|  | - | INTERLOCK | Interlock Use | UNUSE USE | Non-Use Use | - | USE | Use |  |  |
|  | - | CB OPEN | CB Open Block | UNBLK BLK | Unblocked Blocked | - | UNBLK | Unblocked |  |  |
|  | - | CB CLOSE | CB Close Block | UNBLK BLK | Unblocked Blocked | - | UNBLK | Unblocked |  |  |
|  | - | ON TIMER | CB On-Delay Timer | $0 \sim 60 \mathrm{~s}$ |  | 1 s | 0s | 0s |  |  |
| $\begin{aligned} & \hline \text { DO contact } \\ & \text { test setting } \\ & \hline \end{aligned}$ | - | - | One-Shot Time | - | 1~20s | 1 s | - | 1s |  |  |

### 13.2. Output contacts

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|  | Item name (PC-HMI) | Default value (PLC signal) | Please make a note about setting. |
| :---: | :---: | :---: | :---: |
| CB control Condition (DI) | CB status | DI1 |  |
|  | Interlock of CB close | DI2 |  |
|  | Interlock of CB open | DI3 |  |
|  | CB close | DI4 |  |
|  | CB open | DI5 |  |
| Operation lock <br> (DI) | - | DI6 |  |
|  | - | DI7 |  |
| Contacts for tripping (DO) | DO1 | ALLEL-O |  |
|  | DO2 | ALLEL-O |  |
|  | DO3 | ALLEL-O |  |
|  | DO4 | ALLEL-O |  |
| Contacts for annunciator (DO) | DO5 | DIFF_A-T |  |
|  | DO6 | DIFF_B-T |  |
|  | DO7 | DIFF_C-T |  |
|  | DO8 | LOF-T |  |

- CGP2-A42D1

|  | Item name (PC-HMI) | Default value <br> (PLC signal) | Please make a note <br> about setting. |
| :--- | :--- | :--- | :--- |
| CB control <br> Condition <br> (DI) | CB status | DI1 |  |
|  | Interlock of CB close | DI2 |  |
|  | Interlock of CB open | DI3 |  |
|  | CB close | DI4 |  |
|  | CB open | DI5 |  |
| Operation <br> lock <br> (DI) | - | DI6 |  |
|  | - | DO1 | DI7 |
|  | DO2 | ALLEL-O |  |
|  | DO3 | ALLEL-O |  |
|  | DO4 | ALLELEL-O |  |
| Contacts <br> for <br> annunciator | DO5 | DO6 | DIFF_A-T |
|  | DO7 | DIFF_C-C-T |  |
|  | DO8 | ALLEL-O |  |

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[^0]:    Use $\boldsymbol{\Delta}$ and keys to switch between items

[^1]:    * The cell with a circle "O" under the "DI:ch*" column means that "the DI input is on".

