

Extensive recording of data prior to and after an error event



◆ Features

◆ Diagram

Automatically collect all data prior to and after an error event

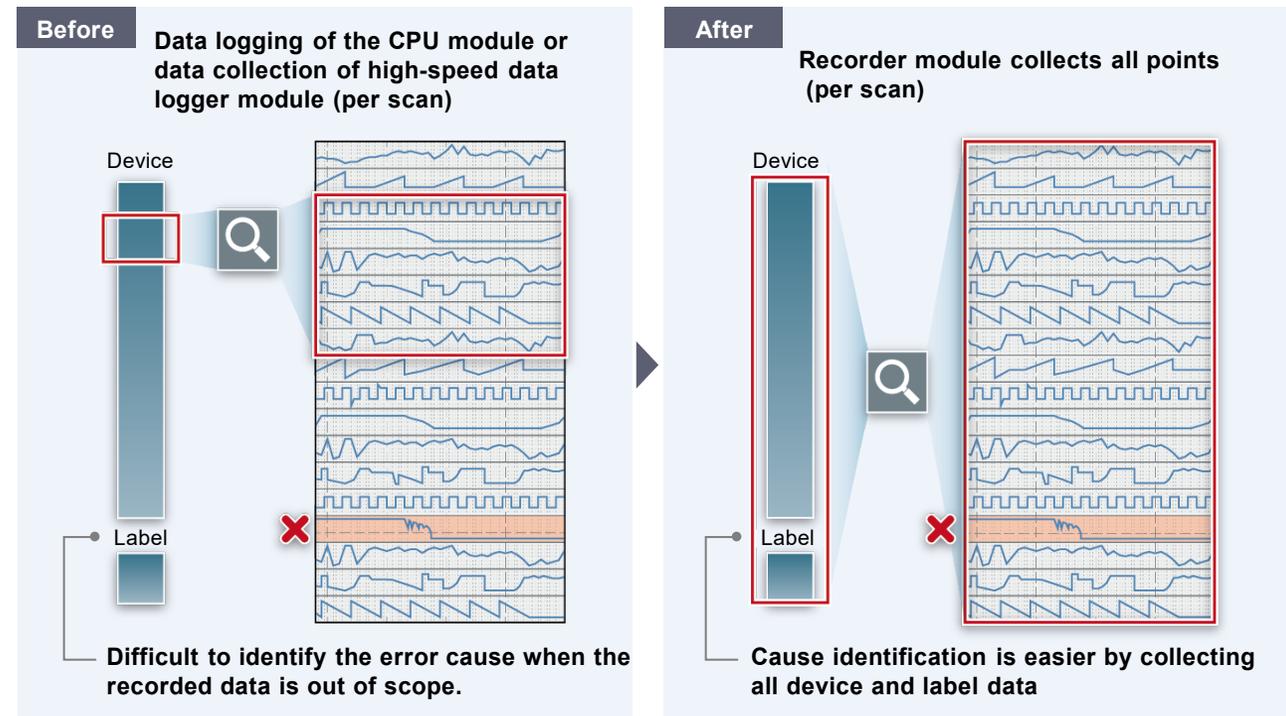
The error cause can be identified quickly as all device and label data prior to and after an error event are automatically collected

Minimal impact on the scan time

Influence on the CPU scan time is minimal as the execution load is separated.

Extensive recording of positional data from servo

Servo systems tend to operate at a much faster cycle time compared with a programmable controller making it difficult to capture. Collecting data using a time-stamp ensures that detailed positional data from the servo can be recorded.



Simplified analysis by checking camera image and device



◆ Features

Register milestone points and share amongst tools

Milestone points (log marker) can be added to the main video, program, waveform data at an error enabling quick identification of points for areas of concern.

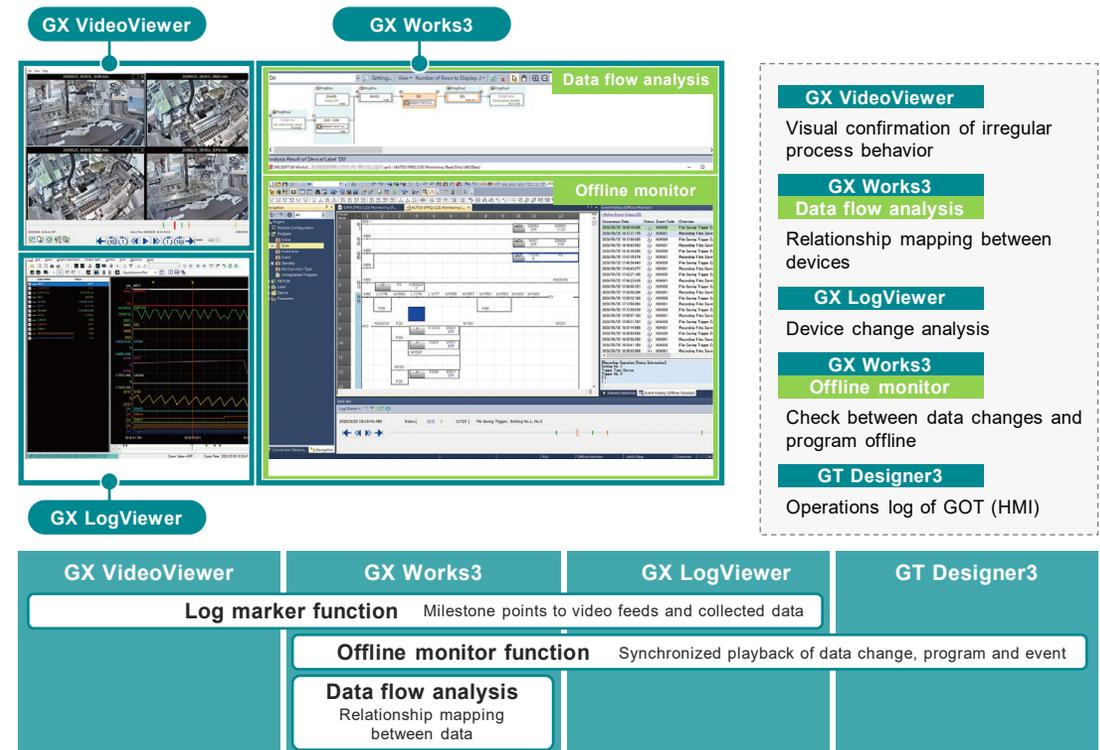
Faster cause analysis by synchronizing various data

Synchronized playback of program, waveform data, and GOT (HMI) screens using the "seek bar" on GX Works3. Multiple data at an error can be reproduced from a remote location.

Main program languages supported

Ladder, FBD, SFC and ST language can be analyzed.

◆ Diagram



Utilize readily available network cameras



◆ Features

Select network camera according to applications

Connectable with industry standards ONVIF[®] Profile S compliant network cameras. Select network cameras according to applications such as speed and environment.

Optimized focusing on camera subject

Can control a camera with PTZ function from either GOT (HMI) or MELIPC MI3000. Fine adjustments are supported while monitoring the live video feed.

Flexible installation

Utilize Ethernet cable for connecting with network cameras. Flexibly installable as the wiring length can be extended.*1

*1. 100 m maximum

◆ Diagram

