SAFETY CONTROLLER BASIC COURSE

This course is intended for beginners of safety controllers who understand safety basics. Click the Next button at the upper right of the screen to proceed to the next page. This course is intended for those using the MELSEC-WS series safety controller for the first time or having just started using it. This course describes basic knowledge of the MELSEC-WS series safety controller, the system configuration method using the Setting and Monitoring Tool for the safety controller, and the error check method.

Taking this course requires that you have completed the following courses or have equivalent knowledge.

• YOUR FIRST FACTORY AUTOMATION (SAFETY OF MACHINERY)

Introduction Course Structure

The contents of this course are as follows. We recommend that you start from Chapter 1.

Chapter 1 - Safety Controller

This chapter provides the overview of the safety controller.

Chapter 2 - System Construction

This chapter describes the system configuration constructed in this course.

Chapter 3 - Connection Check of Safety Controller and Personal Computer

This chapter provides the setting method to connect a safety controller and personal computer and the check method.

Chapter 4 - New Project Creation

This chapter provides how to create projects for a safety controller.

Chapter 5 - Project Download

This chapter provides how to download projects to a safety controller and verify the projects.

Chapter 6 - Safety Controller Connection/Disconnection

This chapter provides how to connect and disconnect a safety controller.

Chapter 7 - System Operation Check

This chapter provides how to check the safety controller operation.

Final Test

6 sections in total (6 questions) Passing grade: 60% or higher.

Introduction How to Use This e-Learning Tool

Go to the next page	>	Go to the next page.
Back to the previous page	<	Back to the previous page.
Move to the desired page	тос	"Table of Contents" will be displayed, enabling you to navigate to the desired page.
Exit the learning	x	Exit the learning. Window such as "Contents" screen and the learning will be closed.

Safety precautions

When you learn by using actual products, please carefully read the safety precautions in the corresponding manuals.

Precautions in this course

- The displayed screens of the software version that you use may differ from those in this course. This course is for the following software version:

- Setting and Monitoring Tool for the safety controller Version 1.3.0.245

Chapter 1 Safety Controller

This chapter provides the overview of the safety controller.

- 1.1 Safety Controller
- 1.2 Feature of Safety Controller
- 1.3 Basic Configuration of Safety Controller
- 1.4 Safety Control can be Easily Added to Existing MELSEC Programmable Controllers (CC-Link/Ethernet)
- 1.5 Summary of This Chapter

Safety Controller

The safety controller is a controller for safety control that conforms to international safety standards. When connected with a safety device, such as an emergency stop switch or light curtain, this programmable controller executes safety control by turning the safety output OFF with a user-created program to stop the power toward a source of hazard, such as a robot. Machine control of robots and conveyors, etc., is executed with standard programmable controllers in the conventional manner.



Safety controller

1.1

1.2

The safety controller is an expandable compact controller suitable for the safety control of small to medium-sized devices and systems.

Up to 12 I/O modules and 2 network interface modules can be connected.

The safety I/O can be expanded to 144 points (input: 96 points, output: 48 points).

The dedicated "Setting and Monitoring Tool" contains is equipped with function blocks for safety sensors and switch

connections and even with safety-dedicated function blocks, facilitating safety system construction.

The "Setting and Monitoring Tool" can be downloaded in the Mitsubishi Electric FA site.

The safety controller complies with ISO 13849-1 PLe and IEC 61508 SIL3 safety standards.

Dedicated "Setting and Monitoring Tool"



CC-Link

Basic Configuration of Safety Controller



Basic Configuration of Safety Controller

Compact safety controller with flexible expandability

- Up to 12 safety input modules and I/O modules, 4 safety relay output modules, and 2 network modules can be added.
- The number of I/O points can be expanded up to 144 (single input). Safety input: 96 points (single input) + safety output: 48 points (single output)

24V 0V A1 A2												
	244 0V X1 X2 A1 A2	X1 X2 X3 X4	244 OV X1 X2 A1 A2	244 0V X1 X2 A1 A2	244 OV X1 X2 A1 A2	24V 0V X1 X2 A1 A2	X1 X2 X3 X4	X1 X2 X3 X4	X1 X2 X3 X4	X1 X2 X3 X4	X1 X2 X3 X4	X1 X2 X3 X4
	11 I2 I3 H	11 12 13 14	11 I2 I3 H	11 12 13 14	11 12 13 14	11 12 13 14	11 12 13 M	11 12 13 14	11 12 13 14	11 12 13 14	11 12 13 H	11 12 13 14
(A1_A2) ▲12842*	X1 X2 A1 A2	11 12 13 14	(X1 X2 A1 A2)	X1 X2 A1 A2	(X1 X2 A1 A2) 11 12 13 H	X1 X2 A1 A2	11 IZ ID H	11 12 13 14	X1 X2 X3 X4	X1 X2 X3 X4	(X1 X2 X3 X4) 11 12 13 14	X1 X2 X3 X4
() () () () () () () () () () () () () (MS	MS 	MS	MS T	MS	MS	MS 	MS	MS U	MS T	MS T	MS T
CPU1	XTIO	XTDI	XTIO	XTIO	XTIO	хтю	XTDI	XTDI	XTDI	XTDI	XTDI	XTDI
1-EF1-2	15 16 17 18 01 02 03 04	15 16 17 18 X5 X6 X7 X8	15 16 17 18 01 02 03 04	10 102 03 04	6 16 17 18 01 02 03 04	6 6 17 8 01 02 03 04	15 16 17 18 X5 X8 X7 X8	15 16 17 18 X5 X6 X7 X8	x5 x8 x7 x8	15 16 17 18 X5 X6 X7 X8	8 8 7 8 x5 x8 x7 x8	15 16 17 18 X5 X8 X7 X8
1-EFI-2	15 16 17 18	15 16 17 18	15 16 17 18	15 16 17 18	15 16 17 18	15 16 17 18	15 16 17 18	15 16 17 18	15 16 17 18	15 16 17 18	15 16 17 18	15 16 17 18
ABAB	Q1 Q2 Q3 Q4	X5 X6 X7 X8	Q1 Q2 Q3 Q4	Q1 Q2 Q3 Q4	Q1 Q2 Q3 Q4	Q1 Q2 Q3 Q4	X5 X6 X7 X8	x5 x6 x7 x8	X5 X6 X7 X8	X5 X6 X7 X8	X5 X6 X7 X8	X5 X6 X7 X8

With a safety controller connected to CC-Link, the existing MELSEC-Q/L programmable controller can execute safety control. Furthermore, operation status and error status of the safety controller can be monitored with the existing MELSEC-Q/L programmable controller.

Visualization in safety can be enhanced, and this improves the efficiency in identifying an emergency stop factor and investigating a faulty spot.

<network function="" interface-compatible=""></network>					
		CC-Link (WS0-GCC1)	Ethernet (WS0-GETH)		
Programmable	Monitoring information	0	0		
controller/personal computer	Data notification	0	0		
Setting and Monitoring tool	Connection via network	-	0		



In this chapter, you have learned:

- Safety Controller
- Features of Safety Controller
- Basic Configuration of Safety Controller
- Safety Control can be Easily Added to Existing MELSEC Programmable Controllers (CC-Link/Ethernet)

Chapter 2 System Construction

This chapter describes the system configuration constructed in this course.

2.1 System Image

2.2 Wiring

2.3 Summary of This Chapter

This section describes the overview of the safety system used in this course.





Set the following conditions to stop the production line safely.

- The light curtain is obstructed.
- The door opens.
- The emergency stop switch is pressed.

2.2 Wiring

This section shows a device wiring diagram.



Figure. Device wiring

In this chapter, you have learned:

- System Image
- Wiring

This chapter provides the setting method to connect a safety controller and personal computer and the check method.

- 3.1 Connecting Safety Controller and Personal Computer
- 3.2 Operation on Setting and Monitoring Tool
- 3.3 Summary of This Chapter

Connecting Safety Controller and Personal Computer

Connect a safety controller and personal computer in either of the following two ways.

■ RS232C connection





Safety controller

- (1) Start the Setting and Monitoring tool for the safety controller.
 - * The following is for the RS232C connection.



(2) Set a connection profile.

This section describes how to set a connection profile of a safety controller and personal computer.



(3) Check the connection profile.

Connection settings					
🖗 Add COM connection profile 🖗 Add TCP/IP connection profile 🖗 Add USB connection profile 🐓	Check all connection profiles	Network settings			
Standard Serial Port: COM1 COM auto detection Baud rate: Auto scan					
Active connection Active connection Standard Standard	To configure the connection, p	lease proceed as follows:			
Setal - COM auto detection Pott: COM1					
Eaud rate: Auto scan Connection profile not saved in the project.	Symbol	Meaning			
		Save profile with the current project			
	•	Activate profile			
		Edit profile			
	Ť	Remove profile			
	×	Check connection			
	Symbols for ec settings dialog	liting the connection profiles in the Connection box			

(4) Edit the connection profile.

Select the "Modify Profile" icon.

P Connection settings		
Add COM connection profile 🗞 Add TCP/IP connection profile 🏮 Add USB connection profile 💉 🤇	Deck all connection profiles 🎾 Network settings	
Standard Serial Port: COM1 COM auto detection Baud rate: Auto scan	= •	↓ ↓ ↓
	Click the "Modify Profile	Change connection profile
Active connection Standard Senta jost - Indeterminate connection state Senta jost - Indeterminate connection state Senta Jost - COM as detection Rev d rev Adv acon Econnection profile not saved in the project.	To configure the connection, please proceed as follows: Choose connection type Check connection to controller. Activate connection profile Preas the button to save the connection Edit connection profile Edit connection profile	Standard Serial port COM auto detection Fixed baud rate 115200 V Auto scan
	ок	OK Cancel

(5) Conduct a communication test.

Active connection parties Subjects Active connection parties Active connection parties Subjects Active connection parties Active connection parties Subjects Active connection parties Active connection parties Subjects Active connection parties Subjects Active connection parties Active connection parties Subjects Active connection parties Subjects Active connection parties Subjects Active connection parties Subjects Subjects Active connection parties Subjects Active connection parties Subjects Subjects Subjects Subjects Subjects Su	Connection settings		
Alter consider Alter consider Contact details in biddenic settings Click the "communication test" icon. Click the indexes in the prior. Communication pole is a detain index and in the prior. Contact on pole is a detain index and in the prior. Contact on pole is a detain index and in the prior. Contact on pole is a detain index and in the prior. Contact on pole is a detain index and in the prior. Contact on pole is a detain index and in the prior. Contact on pole is a detain index and in the prior. Contact on pole is a detain index and in the prior. Contact on pole is a detain index and in the prior. Contact on pole is a detain index and ind	Add COM connection profile on Add TCP/IP of	onnection profile 🉀 Add USB connection profile 🖌 Check all connection profiles 🖗 Network settings	
Click the "communication test" ico.	COM auto detection Bau	irate: Autoscan 🛛 🔍 🕯 🗸	
Click the "communication test" icon.			
Atter correction Particular de la constituing de la constituing de la constituing profile de la consection profile de la		Click the "comm	unication test" icon.
Add COM connection profile Add ICD/IP connection profile Add COM connection profile Add ICD/IP connection profile Add COM connection profile Add ICD/IP connection profile Section - Memory and a detection Section - Memory and a detection Mate connection Mate connection <th></th> <th></th> <th></th>			
Add COM connection profile W Add COPP connection profile W Add SS connection profile W Deck at connecti		Connection settings	
Active connection		Yo Add COM connection profile Add TCP/IP connection profile Add USB connection profile Check Default Default Default COM1	all connection profiles PP Network settings
Active connection Particle Particl		COM auto detection Baud rate: Auto scan	■ ✓
After connection Provide and detection Read rise: As a scan Connection public not seved in the project.			
Survive Service connection attes Service contaction takes Service connection Name Contact Name Contact Name Contact Name Contac	Active connection		
Send pot - Indeterminate connection state Bend pot - Netwerstee connection state Connection prefix not saved in the project. Active connection Default	A Standard		
Active connection Part - COM and detection Pert - COM - Comection public Connection public Connec	Setial port - Indeterminate connection state		
Connection profile not asked in the project.	Serial - COM auto detection Port: COM1 Baud rate: Auto scan		
Active connection Active connection Default Consect connection state Active connection state Service OM acto detection Period Connection public nd seved in the project. The check status is displayed. Connection public Connection pu	Connection profile not saved in the project.		
Active connection			
Active connection			
Default Default Senial pot - Indeterminate connection state Senial -COM auto detection Per: COM I Boud rate: Auto soan Connection profile not saved in the project. The check status is displayed. OK Cancel		Artise connection	To ender a the energiest cherry and a fide at
Serial pot - Indeterminate connection state Coose connection patie Yo Vo Yo Serial - COM auto detection Pot: COM I Boomedian patients: Auto scan Connection patients: Connection patients: Connection patients: Auto scan The check status is displayed. Second patients: East connection patients:		P Default	
Sector best others Sector partie not seved in the project.		Serial pot - Indeterminate connection state	Choose connection type Yo Vo Yo
Baud nate: Auto scan Connection profile not saved in the project. The check status is displayed. Secondon head rates OK Cancel		Serial - COM auto detection Port: COM1	Activate connection profile
The check status is displayed.		Baud rate: Auto scan Connection profile not saved in the project.	Press this button to save the connection profile in the project file.
The check status is displayed.			Edt connection profile
Section has drates		The check status is displayed.	
Standin have finites			
Scanning have finder			
		Scanning baud rates	OK Cancel

(6) Check the communication test result (succeeded).

Communicatio	n test succeed	ed	9	Serial COM auto detection
3 Connection	e sattings		1	
Connector	M connection accelle . M. Add 3	COID connection profile	Check	ark all connection cooling. In Natural's sattings
Pefault	Serial COM auto detection	Port: COM4 Baud rate: Autors Can		
Active com	action It part - connected - COM auto detection		To confie To Ch	nfigure the connection, please proceed as follows: Choose connection to controller.
Fort	2014 Ande Auto scan ction profile not saved in the projec	· · · · · · · · · · · · · · · · · · ·	3	Active connection Default Serial port - connected Serial - COM auto detection Port: COM4 Baud rate: Auto scan
				Connection profile not saved in the project.

(7) Check the communication test result (failed).



In this chapter, you have learned:

- Connecting Safety Controller and Personal Computer
- Operation on the Setting and Monitoring Tool (Connection Profile Specification)

Chapter 4 New Project Creation

This chapter provides how to create projects for a safety controller. Let's create a project with the system configuration described in Chapter 2.

- 4.1 New Project Creation
- 4.2 Hardware Setting
- 4.3 Pasting Elements and Setting Parameters
- 4.4 Tag Name Edit
- 4.5 Logic Creation
- 4.6 Project Simulation
- 4.7 Project Report Creation
- 4.8 Summary of This Chapter

Select "Create new project".





Select modules (CPU1, GETH, and XTIO) used in the hardware setting. (Clicking the icon of a module pastes the module on the right edge.)

* In actual use, configure the settings according to the version of the device to be used.

Set elements on the safety controller according to the device wiring. \rightarrow Activate the "Elements" tag.



4.3.1

→ Select [Input types] - [ESPE], and paste [MiniTwin, Safety light curtain] to the terminals I1 and I2.



Safety Controller Setting and Monitoring Tool 1.7.0 - [New project] cunsaved> - 0 - X -Project Device Extras 🌞 • 🌮 🔛 🥜 Com settings 🔢 Connect 🔢 Disconnect 🖫 Transfer 🚛 Upload 🔳 • Handware configuration
 Decigic editor
 CPU1 module Input types Configuration area Þ9 Rev. V 2.xx Rev. V 1.xx Rev. V 2.xx Control devices **%** × Safety switches Element settings 3 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■
 ■

 ■
 ■
 ■

 ■
 ■
 ■
 247 0V A1 A2 MiniTwin: "MiniTwin" 11 12: MiniTwin curtain B Stephenetial free contacts and restart 83 X1 X2 A1 A2 B ESPE ESPE C400 €Ę 0 Settings Summary Tag name Double-click "MiniTwin curtain". Nr. of devices 1 ÷ GETH MS II 1-EFI-2| A B A B PORT 2 Safety element œ 6 5676 Discrepancy time -----A B A B Ţ Û Value 3000 🚔 ms Parkin 🛐 Modules 🛥 Elements 🚺 Info 🗞 Partial application Operator 👫 Offline 🗥 Se OK Cancel

Double-click the element of the light curtain to set the parameter.

Safety Controller Setting and Monitoring Tool 1.7.0 - [New project]<unsaved> Project Device Extras 🄆 - 🤣 🔛 🖉 Com settings 🔢 🖉 sfer 🕌 Upload 📕 -Logic editor GETH network module [13] Report 🧕 Diagno Drag and drop CPU1 module Hardware configuration a | C (Paste this element Input types to the terminal I3.) Þ devices 🛛 🍟 Con Rev. V 2.xx Rev. V 1.xx **%** E-Stop, ES21
 Single channel
 E-Stop, ES21
 Dual channel
 Enabling switch
 2 position switch
 3 position switch 3 24V 0V A1 A2 83 2 C @₽ iii ii2 ii3 i4 Safety switches 7 0 Interlocks 🗉 🖬 👩 PORT 1 11 12 13 14 Potential free contacts and restart PWR 🕫 📄 ESPE LINKIACT 1 Non contact switches GETH Testable Type 2 / Type 4 MS ∎ Two hand controls B Safety mat & bumpers Sensor muting 15 16 ■ 💮 User mode switches Output types EFI elements Ì ■ <u>物物物</u> Flexi Line Parkir 🛐 Modules 🛃 Elements 🚺 Info 🎕 Partial applications Operator 🔢 Offline 🛕 Setting and Monitoring Tool configuration is not verified

Select [Input types] - [Control devices], and paste [E-Stop, ES21, Single channel] to the terminal I3.

4.3.3



Double-click the element of the emergency stop push-button switch to set the parameter.

4.3.4

4.3.5

- 0 **- X**-Safety Controller Setting and Monitoring Tool 1.7.0 - [New project]<unsaved> Project Device Extras 🌞 • 🌮 🔛 🖉 Com settings 🄢 Connect 🛄 Disconnect 📲 Transfer 🚛 Upload Hardware configuration 🚯 Logic editor 🙀 GETH network module [13] 🖺 Report CPU1 module Drag and drop (Paste this Con element to the terminal I4.) Input types ŀ Control devices Rev. V 2.xx V 2.xx Rev. V • 🕫 🙀 Safety switches 3 24V 0V A1 A2 83 Dotential free co nd rest 2 2 A1 A Single ch Single d nel NO •___ 眼 iii ii2 ii3 ii4 annel NC • 🏒 Sing 0 Du Du D nel NO °#: PORT 1 11 12 13 14 el NC °± Di Brithannel KC
 Di Brithannel
 Di Brithannel KCND
 Di Brithannel KCND
 Di Brithannel KCND
 Di Brithannel
 Star
 Single channel
 Single channel
 Single channel
 Brithe channel
 Single PWR LINKIACT 1 GETH MS Ⅲ PORT 2 1-EFI-2 15 16 1.881 ABAB Ì B ESPE Non contact switches Parki iii 1 Testable Type 2 / Type 4 Operator 🔡 Offline 🛕 Setting and Monitoring Tool configuration is not verified

Select [Input types] - [Potential free contacts and restart], and paste [Reset, Single channel] to the terminal I4.



Double-click the element of the reset switch to set the parameter.

4.3.6
Select [Input types] - [Non contact switches], and paste [RE13/RE23/RE27, Reed switch, dual channel, equivalent] to the terminals I5 and I6.



Safety Controller Setting and Monitoring Tool 1.7.0 - [New project] cunsaved> Device Extras Project CPU1 module Input types ή H Control devices Rev. V 2.xx Rev. V 1.xx Rev. V 2.xx **%** 🗄 🚆 Safety switches 9 240 OV A1 A2 🖩 🙀 🔒 Interlocks 63 Potential free contacts and restart X1 X2 A1 A2 11 I2 IS IA x Element settings BESPE 眼 RE13/RE23/RE27: "RE13/RE23/RE27" I5 I6: Reed switch, dual channel, equivalent B 10 Non contact switches _ Non contact switches

Rest switches
Rest switch, but channel, antivalent
Rest switch, but channel, antivalent
Rests Rests Rests Rest of the res of the rest of the 0 X1 X2 A1 A2 101 AZU A 22002 PORT 1 PWR B Settings Test outputs Summary LINKIACT 1 Tag name GETH ۳ŝ Nr. of devices 1 -1-6F1-2 P0872 E Testable Type 2 / Type 4 15 16 17 18 I Two hand controls A B A B V Safety element 🗉 属 Safety mat & bumpers ۵ œ Sensor muting Double-click "RE13/RE23/RE27". B 🕝 User mode switches ON-OFF filter (reaction time extended by filter time minimum, ≥ 8 ms) Ш ш 🛐 Modules 🛥 Bernents 🜖 Info 🗞 Partial application OFF-ON filter (reaction time extended by filter time minimum, ≥ 8 ms) Operator 腔 Offline 🛕 Setting Ш ш T Element is connected to test output -----Discrepancy time Ţ Value 3000 ≑ ms OK Cancel

Double-click the element of the contactless safety door switch to set the parameter.

4.3.8

4.3.9 Pasting an Element of the Safety Door Switch

Set an element to the safety controller, like the real device.

→ Select [Input types] - [Safety switches], and paste [Safety switches, Dual channel] to the terminals I7 and I8.





Double-click the element of the safety door switch to set the parameter.

4.3.11 Pasting an Element of the Motor

Set an element to the safety controller, like the real device.

→ Select [Output types] - [Electrical symbols], and paste [Motor contactor, Single channel] to the terminal Q1.



Safety Controller Setting and Monitoring Tool 1.7.0 - [New project] <unsaved></unsaved>						
Project Device Estres						
🔆 🍀 🗕 🥙 🔛 🖉 Com settings 🔢 Connect 🛄	Disconnect 🛛 🖓 Transfer 🖁 🖓 Upload 📲	· (2) In	nut a tao name			
Hardware configuration Store Logic editor	ETH network module [13] Report 🛛	S Diagnostics	put a tag name.	L module		
Elements P	Configuration area					
Input types	+ 0 DG	Tag nar	ne motor			
Output types	Berry M 2 war Berry M 1 war	Day V Day				
Bectrical symbols The						
Single channel Val channel Ver class Single channel Ver class <	ALAC ALAC		nt Stitings Motol contactor: "Mot Q1: Sing channel ngs Summary Tag name Nr. of devices 1 Safety element Enabling Test pulses of this Attention: Disabling the test outputs of this module. For the precise values see t	tor contactor"	y values of all	
🛐 Modules 🗃 Elements 🚺 Info 🎕 Partial applications		Operator 🏥 Offline 🛕 S			OK Cancel	

Double-click the element of the motor to set the parameter.

4.3.13 Pasting an Element of the Lamp

Set an element to the safety controller, like the real device.

→ Select [Output types] - [Electrical symbols], and paste [Lamp, Single channel] to the terminals Q2, Q3, and Q4.



4.3.14 Setting the Parameter of the Lamp

Double-click the element of the lamp to set the parameter.

Safety Controller Setting and Monitoring Tool 1.7. Project Device Extras Project Device Extras Produce configuration Produce configuration Produce types Produce types	0 - [New project] 4 111 Disconnect 121 GETH netwo Configure 121 Configure 121 Configure 12	kunsaved>	Beport C	Diagnostics	Seconder Data Recorder	Tag name Tag name Tag name	(2) Input The type can assig LED green LED red LED RESET	a tag name. of these elements is the same, but you in different names to each of them. Tag name of the LED of the terr Tag name of the LED of the terr Tag name of the LED of the terr	ninal Q2 ninal Q3 ninal Q4
Image of contactor Subject channel Image of contactor Image of co		(A) A2 (A) (A) A2 (A) A2 (A) (A) A2 (A) (A) A2 (A) (A) A2 (A)	Ports Ports CURRACE SCH	X110 X110 X110 X110 Cperator 12 Of Constant 12 Of Consta	ED".	Element Strting Campa Q2: Sing Settings Sum Settings Settings Sum Settings Sum S	s Lamp" channel imary iag name k. of devices ment Fest pulses of this ou Deabling the test pu this module. ccise values see the	tput. Ises may lead to a reduction of the safety values of all user's manual (hardware). •	
								ок	Cancel

Tag Name Edit

Edit tag names as necessary.



4.5 Logic Creation

Program on the Logic editor.

4.5.1 Programming (Pasting Inputs)

(1) Switch the view to the Logic editor view. \rightarrow (2) Click the "Inputs" tag. \rightarrow (3) Register the inputs.





(1) Activate the "Function block" tag. \rightarrow (2) Paste function blocks.

4.5.3 Description of FBs Used

FB used	Overview	Registration hierarchy
Reset FB	FB for reset	[Start/Edge] - [Reset]
Routing 1:N FB	The Routing 1: N function block passes an input signal from a preceding function block to up to eight output signals.	[Logic] - [Routing 1:N]
	The inverted input value applies at the output.	[Logic] - [NOT]

Programming (Pasting Outputs)

(1) Activate the "Outputs" tag. \rightarrow (2) Register the outputs.



 \rightarrow Increase the number of input fields of the Reset function block.



 \rightarrow Increase the number of output fields of the Routing function block.





Project Simulation



Figure. Simulation view

Report creation procedure

- (1) Click the Report button to open the Report view.
- (2) Activate or deactivate the check boxes for the components that shall be included in the report in the selection list on the left-hand side.
- (3) After you have completed your selection, click Refresh report. The report is now assembled and displayed in the right-hand window section.

How to save or print a report

The report can be printed or saved as PDF.

- To save the report as PDF, click the Save button.
- To print the report, click the Print button.
 A PDF preview of the report will be created that you can subsequently print.



Report view (part)

In this chapter, you have learned:

- New Project Creation
- Hardware Setting
- Pasting Elements and Setting Parameters
- Tag Name Edit
- Logic Creation
- Project Simulation
- Project Report Creation

This chapter provides how to download projects to a safety controller and verify the projects.

- 5.1 Connection with Safety Controller
- 5.2 Project Download
- 5.3 Project Verification
- 5.4 Project Comparison between Safety Controller and Tool
- 5.5 Summary of This Chapter

Connection with Safety Controller

Safety Controller Setting and Monitoring Tool	1.7.0 - [New project] <unsaved></unsaved>		
Project Device Extras			
🔆 🐳 - 🐉 🔛 🤌 Com settings 🔢 Conner	ct 👫 Disconnect 🔤 Transfer 🚛 Upload 💻 -		
Hardware configuration 🔊 Logi Vitor	GETH network module	mc	
Modules	n area		
Click "Connect"	Progress		
	Rev. V 2.xx R/ Connecting to MELSEC Communication DTM	Cafety Centroller Company Manifester T	and 1.7.0 - (New protect) conservation
	Connecting to CPU1 module	Broject Davice Strat	on 71/10 - Even hullentik nusekens
	200 ov	- Source Service States	nert 1112 Disconnert I Ra Transfer film Unioned
CPU0 CPU1 DD	A1 A2 Connecting to Mitsubishi XTIO		
Revision V 1xx V 1xo		Hardware configuration	tor F GETH network module [13] Report CPU1 module
EFI - 2		Nodules a Con	a CI CI CI
and and			EWV2.01 EWV1.06 EWV2.10
Network Modules		Module 0	Rev. V 2.xx Rev. V 1.xx Rev. V 2.xx
	(<u>A1_A2</u>)	Device: C	
	A 120121	Serial number: 1	2 26 OV A1 42
	MS Messages	🔳 Memory plug 💡	0000
	Copened port CONV	Firmware , @	X1 X2 A1 A2
GETH GCC1	Scanning baud rates	version:	
Revision V 1xx V 1xx	Initializing connection to "CPU1 module"	version: 4 Q	(A1 A2) (X1 X2 A1 A2)
	COM4: Scanning baud rates	Version/Step: 1 #	
I/O modules	EFIL Checking connection state of "CPU1 module"	status: C	10 PM
	Connection of "CPU1 module' is System Online		🔘 🗴 LINKACT I
	1-EFI-2	Module 13	
		Device: C Type code: X	CEUL GETH XTID
		Serial number: 0	0°5 95 1111
XTIO XTDI	1-EFI-2	Firmware version:	
Revision V 1xx • V 1xx •	<u>A B A B</u> Q1 Q2 Q3 Q4	Hardware .	
		Version/Step: 1	5 8 7 8
V OUR 4		Operational c	A B A B
Parking	area	Module has external error	0000 000
🗏 Relays 💌		Module input status invalid Module output status invalid	
🔝 Modurer 🛥 Elemen 🚺 Info 🍫 Partirer			
	Operator 🔢 Offline 🛕 Setting and Monitoring Tool configuration	s not Module 1	
	m	🕨 🔝 Modules 🛥 Elem 🚺 Info 🗞 Partia	
		Valid configuration / Executing	Operator 🖽 System Online 🖌 Device configuration is verified
		() () () () () () () () () ()	

5.2 Project Download

Safety Contro	ller Setting and M	ionitoring To	ol 1.7.0 - [New project] <unsave< th=""><th>d></th><th></th><th></th><th></th><th></th><th></th><th></th></unsave<>	d>						
Project Devi	Com setting	s Itti Con	ect It? Disconnect 🖳 a Tran	fer Upload	-					
Hardware o	configuration a	l onic edit		[13] P Report	CDU1 m	ulo 🖬				
Modules	coningeneration	a Conf	ana Mal or unservor un	(10) Neport	CPUTING					
Only modules w	ith errors	1.1	(1) Click "Transf	er". 🗊	1					
Module 0		î 🍳	Rev. V 2.xx Rev. V 1.xx	Rev. V Change	e user group				×	
_	Device: Type code: Serial number: Memory plug	· @	24/ 04 A1 A2			Device type Type key	MELSE CPU1	c-ws		1
	date code: Firmware version:	. 8		X1 X2		Serial number	1405 00	180 (2) Input t	the password.	
ana.	Hardware version: Version/Step:	4 🧿 1=	(A1 A2)	11 12 (x1 x2 	level		Passw	ord 7	MELSECWS"	
	Operational status:	¢		Adm	ninistrator	•				
Module 13										
1. · · · · · · ·	Device: Type code: Serial number: Firmware version: Hardware version: Version/Step: Operational	0 2 0 1 1 1		xTI 5 6 15 16 15 16 15 16 15 16	Click "Log C	on".	Progress	The CPU modul verified. Do you configuration?	e "CPU1 module" is cur really want to download	rently d the
Module has extern Module input statu Module output stat	status: nai error is invalid tus invalid		0000	00	Log	on Log	of			
Module 1	m 🚺 Info 🗞 P	* artia								
Valid configuratio	n / Executing		Operator	😫 System Online 🖌 D	evice configuration	is verified				
٠.						•	"	4) Click "Yes".		
								Yes		No

Project Download



Project Verification

* If verification processing has not been completed, the CPU module remains in the STOP state at the next power-on. To run the CPU module at the next power-on, verification processing is required.



Match or verified

CPU1 module

_

PORT 1

LINKACT 1

GETH

PORT2

ö

PMR 背

2 2 A1 A2

1 2 3 H

11 2 B H

XTIC

15 16 17 18

01 02 03 04

Mismatch



- If a verified project is downloaded, the verification-completed status is kept. Verifying the project again is not required.
- If a project that is not verified yet is downloaded, the verification is required.

In this chapter, you have learned:

- Connection with Safety Controller
- Project Download
- Project Verification
- Project Comparison between Safety Controller and Tool

Chapter 6 Safety Controller Connection/Disconnection

This chapter provides how to connect and disconnect a safety controller.

- 6.1 Connection with Safety Controller
- 6.2 Disconnection
- 6.3 Reconnection
- 6.4 Summary of This Chapter

Connection with Safety Controller

Connect a safety controller and personal computer by RS-232, and power on the safety controller. Then, start the Setting and Monitoring Tool, and select the following "Connect to physical device".

(1) Select Connect to physical device.



6.1

(2) Upload the setting.



6.2



To change the setting, activate the offline mode by clicking Disconnect.

6.3 Reconnection



* "Connect" can be selected when the tool is not connected with a controller.

In this chapter, you have learned:

- Connection with Safety Controller
- Disconnection
- Reconnection

Chapter 7 System Operation Check

This chapter provides how to check the safety controller operation.

- 7.1 System Operation Check
- 7.2 Program Description
- 7.3 Operating Safety Input Devices
- 7.4 Transition of System Operating State
- 7.5 Program Description
- 7.6 Error Diagnostics
- 7.7 Summary of This Chapter

System Operation Check



Program Description

7.2

If no safety input device is operated and have malfunction after power-on of the safety controller, the components enter the following status.

RUN lamp (= green lamp)	OFF
STOP lamp (= red lamp)	ON
Motor	Stop
Reset lamp	ON flashing



Operating Safety Input Devices

Operating the emergency stop switch

- Holding the emergency stop switch activates a trouble signal.
 → Press the emergency stop switch.
- After the emergency stop switch is restored, pressing the reset lamp or switch clears the trouble signal.
 - \rightarrow Restore the emergency stop switch.

Application: To stop the operation of the hazard source when the emergency stop switch is pressed because danger is found

Operating the contactless safety switch

- Separating the pieces of the contactless safety switch activates a trouble signal.
- After the pieces of the contactless safety switch are brought closer, pressing the reset lamp or switch clears the trouble signal.

Application: To stop the operation of the hazard source when the door installed to the safety fence is opened









7.3
Operating the safety switch

- Pulling out the safety switch activates a trouble signal.
 → Pull out the actuator from the safety door switch.
- After the safety switch is inserted back, pressing the reset lamp or switch clears the trouble signal.

 \rightarrow Return the pulled-out actuator.

Application: To stop the operation of the hazard source when the door installed to the safety fence is opened

Operating the light curtain

- Obstructing the light beam of the light curtain by placing an object activates the trouble signal.
 - \rightarrow Obstruct the light beams of the light curtain.
- After the object obstructing the light beam of the light curtain is removed, pressing the reset lamp or switch clears the trouble signal.
 → Remove the object obstructing the light beam of the light curtain.

Application: To stop the operation of the hazard source when entry of an operator from an opening is detected









Transition of System Operating State



Program Description

7.5

7.5.1 Immediately after the power-on (no device is operated)

If no safety input device is operated and have malfunction after power-on of the safety controller, the components enter the following status.

RUN lamp (= green lamp)	OFF
STOP lamp (= red lamp)	ON
Motor	Stop
Reset lamp	ON flashing



7.5.2 Reset state (during operation: motor rotation)

If no safety input device is operated and have malfunction, the following the components enter the following status when the reset switch is operated.

RUN lamp (= green lamp)	OFF → ON
STOP lamp (= red lamp)	ON → OFF
Motor	Stop → Rotation
Reset lamp	ON flashing → Off



■ After operating the emergency stop switch

If the emergency stop switch is pressed during operation, the components enter the following status.

RUN lamp (= green lamp)	ON → OFF
STOP lamp (= red lamp)	OFF → ON
Motor	Rotation → Stop
Reset lamp	Off



■ After operating the safety switch

If the actuator of the safety switch is pulled out during operation, the components enter the following status.

RUN lamp (= green lamp)	ON → OFF
STOP lamp (= red lamp)	OFF → ON
Motor	Rotation → Stop
Reset lamp	Off



■ After operating the contactless safety switch

If the pieces of the contactless safety switch are separated during operation, the components enter the following status.

RUN lamp (= green lamp)	ON → OFF
STOP lamp (= red lamp)	OFF → ON
Motor	Rotation → Stop
Reset lamp	Off



■ After operating the light curtain

If the light beam of the light curtain is obstructed during operation, the components enter the following status.

RUN lamp (= green lamp)	ON → OFF
STOP lamp (= red lamp)	OFF → ON
Motor	Rotation → Stop
Reset lamp	Off



7.5.4 After clearing the operation of the safety input device

If a safety input device is operated and then the operation is cleared, the components enter the following status.

RUN lamp (= green lamp)	OFF
STOP lamp (= red lamp)	ON
Motor	Stop
Reset lamp	Off → ON flashing



Diagnostic results and operation of the safety controller can be checked on the Setting and Monitoring Tool.



In this chapter, you have learned:

- System Operation Check
- Program Description
- Operating Safety Input Devices
- Transition of System Operating State
- Program Description
- Error Diagnostics

Test Final Test

Now that you have completed all of the lessons of the **SAFETY CONTROLLER BASIC** Course, you are ready to take the final test. If you are unclear on any of the topics covered, please take this opportunity to review those topics.

There are a total of 6 questions (6 items) in this Final Test.

You can take the final test as many times as you like.

Score results

The number of correct answers, the number of questions, the percentage of correct answers, and the pass/fail result will appear on the score page.

		1	2	3	4	5	6	7	8	9	10		
Retry	Final Test 1	1	 Image: A second s	 Image: A second s	X							Total questions: 28	
	Final Test 2	1	√	1	1							Correct answers: 23	
	Final Test 3	1											
	Final Test 4	1	√									Percentage: 82 %	
	Final Test 5	 Image: A second s	√										
Retry	Final Test 6	1	X	X	X								
	Final Test 7	1	√	√	√								
	Final Test 8	 Image: A second s	×	√	1	×		10	To pass the test, 60% of correct				
	Final Test 9	 Image: A second s						answers is required.					
Retry	Final Test 10	X											

Test	Final Test 1
In a safety	controller (MELSEC-W/S) "up to 10" safety I/O modules can be connected to a CPLI module
in a salety	controller (MEESEC-WS), up to to salety i/o modules can be connected to a cr o module.
	*
Q1	
• •	
×	

Test	Final Test 2
The Setting	and Monitoring Tool, a programming tool for the safety controller, is available for free.
	· · · · · · · · · · · · · · · · · · ·
Q1	
• •	
×	

Test	Final Test 3
The progran	nming language of the Setting and Monitoring Tool for the safety controller is "FBD".
Q1	
• •	
×	

Test	Final Test 4	
		1
The report of error histori	creation function of the Setting and Monitoring Tool for the safety controller can output hardware configurations and	
	•	
01		
QI		
0		
×		

Test	Final Test 5
The default	password for the user level "Administrator", which is required for downloading projects in safety controllers, is
IVIELSECVVS	
	
01	
QI	
0	
×	

Test	Final Test 6	
The safety operating	controller cannot be connected with a MELSEC-Q series programmable controller via a network and cannot monitor the status of the programmable controller.	
		-
01		
QI		
• •		
×		

Test	Final Test 1
In a safety	, controller (MELSEC-WS), "up to 10" safety I/O modules can be connected to a CPU module.
	▼
Q1	
• •	
o ×	

Test	Final Test 2
The Setting	and Monitoring Tool, a programming tool for the safety controller, is available for free.
	· · · · · · · · · · · · · · · · · · ·
01	
QI	
0 0	
×	

Test	Final Test 3
The progra	mming language of the Setting and Monitoring Tool for the safety controller is "FBD".
Q1	
00	
×	

Test	Final Test 4	
The report error histor	creation function of the Setting and Monitoring Tool for the safety controller can output hardware configurations and ries to PDF files.	
Q1		
0 0		
×		

Test	Final Test 5
[
The default "MELSECWS	password for the user level "Administrator", which is required for downloading projects in safety controllers, is 5".
Q1	
• •	
×	

Test	Final Test 6	
The safety c operating st	controller cannot be connected with a MELSEC-Q series programmable controller via a network and cannot monitor the tatus of the programmable controller.	•
Q1		
• 0		
• ×		

You have completed the Final To end the Final Test, proceed	Test. You results to the next pag	s area e.	as follo	ows.				-			-	
		1	2	3	4	5	6	7	8	9	10	Total questions: 6
Fina	al Test 1	√										
Fina	al Test 2	~										Correct answers: 6
Fina	al Test 3	√										Deveentered 100 %
Fina	al Test 4	~										Percentage. 100 %
Fina	al Test 5	 Image: A set of the set of the										
Fina	al Test 6	 Image: A second s										

You have completed the **SAFETY CONTROLLER BASIC** Course.

Thank you for taking this course.

We hope you enjoyed the lessons and the information you acquired in this course is useful for configuring systems in the future.

You can review the course as many times as you want.

Review

Close