

# < DIPIPM > PSS05S51F6 / PSS05S51F6-C

TRANSFER MOLDING TYPE INSULATED TYPE

# OUTLINE

### MAIN FUNCTION AND RATINGS

- 3 phase DC/AC inverter
- 600V / 5A (CSTBT)
- N-side IGBT open emitter
- Built-in bootstrap diodes with current limiting resistor

### APPLICATION

 AC 100~240Vrms(DC voltage:400V or below) class low power motor control

### TYPE NAME

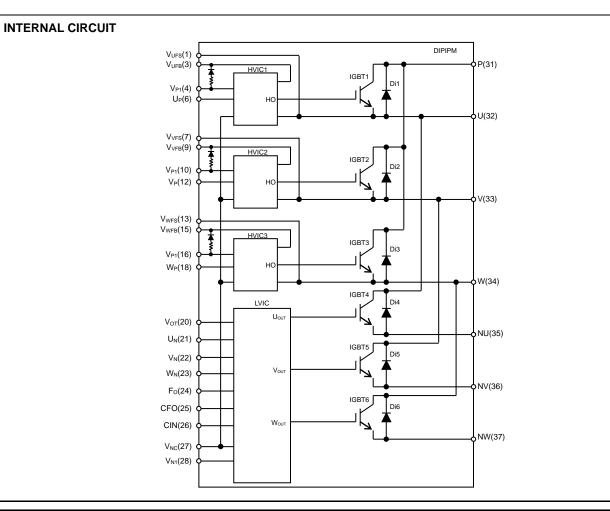
PSS05S51F6 /-C With temperature output function

-C : Control side zigzag terminal (none) : Short terminal

PSSxxS51F6 (Short terminal type)

### INTEGRATED DRIVE, PROTECTION AND SYSTEM CONTROL FUNCTIONS

- For P-side : Drive circuit, High voltage high-speed level shifting, Control supply under-voltage (UV) protection
- For N-side : Drive circuit, Control supply under-voltage protection (UV), Short circuit protection (SC),
- Fault signaling : Corresponding to SC fault (N-side IGBT), UV fault (N-side supply)
- Temperature output : Outputting LVIC temperature by analog signal
- Input interface : 3, 5V line, Schmitt trigger receiver circuit (High Active)
- UL Recognized : UL1557 File E80276



### MAXIMUM RATINGS (T<sub>j</sub> = 25°C, unless otherwise noted)

**INVERTER PART** 

Symbol	Parameter	Condition		Ratings	Unit
V <sub>CC</sub>	Supply voltage	Applied between P-NU,NV,NW		450	V
V <sub>CC(surge)</sub>	Supply voltage (surge)	Applied between P-NU,NV,NW		500	V
V <sub>CES</sub>	Collector-emitter voltage			600	V
$\pm I_{C}$	Each IGBT collector current	Tf = 25°C	(Note1)	5	Α
$\pm I_{CP}$	Each IGBT collector current (peak)	Tf = 25°C, less than 1ms		10	А
Pc	Collector dissipation	Tf = 25°C, per 1 chip		16.7	W
Ti	Junction temperature		(Note2)	-20~+125	°C

Note1: Pulse width and period are limited due to junction temperature. Note2: The maximum junction temperature rating of the power chips integrated within the DIPIPM is 150°C (@Tt≤100°C).However, to ensure safe operation of the DIPIPM, the average junction temperature should be limited to Tj(ave)≤125°C (@Tf≤100°C).

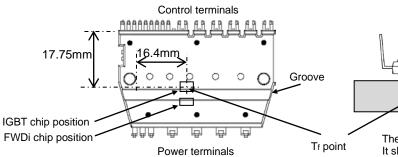
### **CONTROL (PROTECTION) PART**

Symbol	Parameter	Condition	Ratings	Unit
VD	Control supply voltage	Applied between V <sub>P1</sub> -V <sub>NC</sub> , V <sub>N1</sub> -V <sub>NC</sub>	20	V
V <sub>DB</sub>	Control supply voltage	Applied between $V_{UFB}$ - $V_{UFS}$ , $V_{VFB}$ - $V_{VFS}$ , $V_{WFB}$ - $V_{WFS}$	20	V
V <sub>IN</sub>	Input voltage	Applied between UP, VP, WP, UN, VN, WN-VNC	-0.5~V <sub>D</sub> +0.5	V
V <sub>FO</sub>	Fault output supply voltage	Applied between Fo-VNC	-0.5~V <sub>D</sub> +0.5	V
I <sub>FO</sub>	Fault output current	Sink current at Fo terminal	1	mA
V <sub>SC</sub>	Current sensing input voltage	Applied between CIN-V <sub>NC</sub>	-0.5~V <sub>D</sub> +0.5	V

### TOTAL SYSTEM

Symbol	Parameter	Condition	Ratings	Unit
V <sub>CC(PROT)</sub>	Self protection supply voltage limit (Short circuit protection capability)	$V_D = 13.5 \sim 16.5 V$ , Inverter Part T <sub>j</sub> = 125°C, non-repetitive, less than 2µs	400	V
Tf	Module operation temperature	Measurement point of Tr is provided in Fig.1	-20~+100	°C
T <sub>stg</sub>	Storage temperature		-40~+125	°C
V <sub>iso</sub>	Isolation voltage	60Hz, Sinusoidal, AC 1min, between connected all pins and heat sink plate	2500	V <sub>rms</sub>

Fig. 1: Tf MEASUREMENT POINT



Grease should be applied evenly with about +100 $\mu$ m~+200 $\mu$ m and fixing screws are tightened by the specified torque.

Thermocouple detecting point It should be fixed to the contact surface of the outer fin (Surface finish: warpage -50~+100µm, roughness under Rz12)

Outer fin (heatsink)

### THERMAL RESISTANCE

Symbol	Baramatar	Condition		Limits		Unit
Symbol Parameter		Condition		Тур.	Max.	Unit
R <sub>th(j-f)Q</sub>	Junction to fin thermal	Inverter IGBT part (per 1/6 module)	-	-	6.0	K/W
R <sub>th(j-f)F</sub>	resistance (Note 3)	Inverter FWDi part (per 1/6 module)	-	-	6.5	K/W

Note 3: Grease with good thermal conductivity and long-term endurance should be applied evenly with about +100µm~+200µm thickness on the contacting surface of heat sink. Fixing screws are tightened by the specified torque.

### ELECTRICAL CHARACTERISTICS (T<sub>j</sub> = 25°C, unless otherwise noted) **INVERTER PART**

Currente e l	Deveryotar	Gara	lition		Limits		
Symbol	Parameter	Condition		Min.	Тур.	Max.	Unit
V	Collector-emitter saturation	(1 - 1) = 1 = 1 = 1 = 1	I <sub>C</sub> = 5A, T <sub>j</sub> = 25°C	-	1.40	1.90	v
V <sub>CE(sat)</sub>	voltage	$V_{\rm D}=V_{\rm DB}=15V, V_{\rm IN}=5V$	voltage $v_{D}=v_{DB}=15V, v_{IN}=5V$ $I_{C}=5A, T_{i}=125^{\circ}C$	-	1.50	2.00	v
V <sub>EC</sub>	FWDi forward voltage	$V_{IN}=0V, -I_C=5A$		-	1.50	1.90	V
t <sub>on</sub>				0.60	1.20	1.80	μs
t <sub>C(on)</sub>	$V_{CC}$ = 300V, $V_{D}$ = $V_{DB}$ = 15V			-	0.30	0.60	μs
t <sub>off</sub>	Switching times	I <sub>C</sub> = 5A, T <sub>j</sub> = 125°C, V <sub>IN</sub> = 0↔5V		-	1.30	2.20	μs
t <sub>C(off)</sub>	]	Inductive Load (upper-lower a	ırm)	-	0.35	0.80	μs
t <sub>rr</sub>				-	0.30	-	μs
	Collector-emitter cut-off		T <sub>j</sub> = 25°C	-	-	1	A
ICES	current	V <sub>CE</sub> =V <sub>CES</sub>	T <sub>j</sub> = 125°C	-	-	10	mA

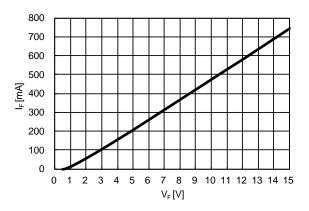
### CONTROL (PROTECTION) PART

Sumbol	Deremeter	Cond	lition		Limits		Unit
Symbol	Parameter	Cond	littori	Min.	Тур.	Max.	Unit
			V <sub>D</sub> =15V, V <sub>IN</sub> =0V	-	-	6.00	
ID	Cinquit quant	Total of V <sub>P1</sub> -V <sub>NC</sub> , V <sub>N1</sub> -V <sub>NC</sub>	V <sub>D</sub> =15V, V <sub>IN</sub> =5V	-	-	6.00	
	Circuit current	Each part of VUFB- VUFS,	$V_D = V_{DB} = 15V, V_{IN} = 0V$	-	-	0.55	mA
I <sub>DB</sub>		$V_{VFB}$ - $V_{VFS}$ , $V_{WFB}$ - $V_{WFS}$	$V_D = V_{DB} = 15V, V_{IN} = 5V$	-	-	0.55	
V <sub>SC(ref)</sub>	Short circuit trip level	V <sub>D</sub> = 15V	(Note 4)	0.45	0.48	0.51	V
UV <sub>DBt</sub>	P-side Control supply		Trip level	10.0	-	12.0	V
$UV_{DBr}$	under-voltage protection(UV)	T <105%C	Reset level	10.5	-	12.5	V
UV <sub>Dt</sub>	N-side Control supply	T <sub>j</sub> ≤125°C	Trip level	10.3	-	12.5	V
$UV_{Dr}$	under-voltage protection(UV)		Reset level		-	13.0	V
V <sub>OT</sub>	Temperature Output	Pull down R=5kΩ (Note 5)	LVIC Temperature=100°C	2.90	3.02	3.15	V
$V_{\text{FOH}}$		$V_{SC}$ = 0V, F <sub>0</sub> terminal pulled u	p to 5V by 10kΩ	4.9	-	-	V
$V_{\text{FOL}}$	Fault output voltage	$V_{SC} = 1V$ , $I_{FO} = 1mA$		-	-	0.95	V
t <sub>FO</sub>	Fault output pulse width	C <sub>FO</sub> =22nF	(Note 6)	1.6	2.4	-	ms
I <sub>IN</sub>	Input current	$V_{IN} = 5V$		0.70	1.00	1.50	mA
V <sub>th(on)</sub>	ON threshold voltage			-	2.10	2.60	
V <sub>th(off)</sub>	OFF threshold voltage	Applied between U <sub>P</sub> , V <sub>P</sub> , W <sub>P</sub> , I	hi Va Wu-Vao	0.80	1.30	-	v
$V_{\text{th(hys)}}$	ON/OFF threshold hysteresis voltage	Applied between $O_P$ , $V_P$ , $V_P$ , $O_N$ , $V_N$ , $V_N$ , $V_N$		0.35	0.80	-	v
$V_{F}$	Bootstrap Di forward voltage	IF=10mA including voltage drop I	by limiting resistor (Note 7)	0.5	0.9	1.3	V
R	Built-in limiting resistance	Included in bootstrap Di		16	20	24	Ω

Note 4 : SC protection works only for N-side IGBT. Please select the external shunt resistance such that the SC trip-level is less than 2.0 times of the current rating. 5 : DIPIPM don't shutdown IGBTs and output fault signal automatically when temperature rises excessively. When temperature exceeds the protective level that user defined, controller (MCU) should stop the DIPIPM. Temperature of LVIC vs. VOT output characteristics is described in Fig. 3.

6 : Fault signal Fo outputs when SC or UV protection works. Fo pulse width is different for each protection modes. At SC failure, Fo pulse width is a fixed width which is specified by the capacitor connected to C<sub>FO</sub> terminal. (C<sub>FO</sub>=9.1 x 10<sup>-6</sup> x t<sub>FO</sub> [F]), but at UV failure, Fo outputs continuously until recovering from UV state. (But minimum Fo pulse width is the specified time by C<sub>Fo</sub>.) 7 : The characteristics of bootstrap Di is described in Fig.2.

Fig. 2 Characteristics of bootstrap Di V<sub>F</sub>-I<sub>F</sub> curve including voltage drop by limiting resistor (Right chart is enlarged chart.)



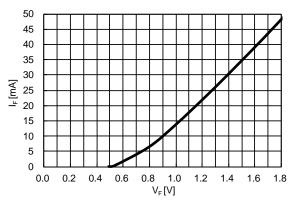


Fig. 3 Temperature of LVIC vs. Vot output characteristics

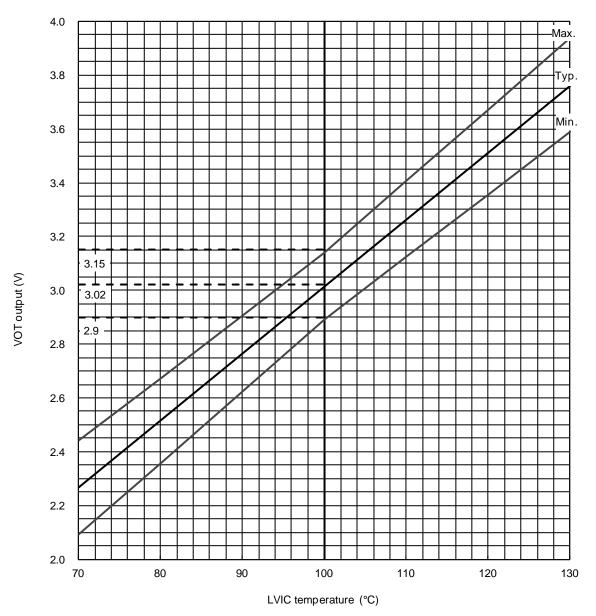
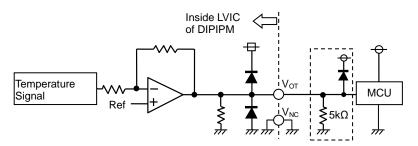


Fig. 4 Vot output circuit



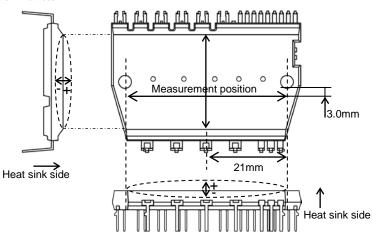
- (1) It is recommended to insert  $5k\Omega$  (5.1 $k\Omega$  is recommended) pull down resistor for getting linear output characteristics at low temperature below room temperature. When the pull down resistor is inserted between V<sub>OT</sub> and V<sub>NC</sub>(control GND), the extra circuit current, which is calculated approximately by V<sub>OT</sub> output voltage divided by pull down resistance, flows as LVIC circuit current continuously. In the case of using V<sub>OT</sub> for detecting high temperature over room temperature only, it is unnecessary to insert the pull down resistor.
- (2) In the case of using V<sub>OT</sub> with low voltage controller like 3.3V MCU, V<sub>OT</sub> output might exceed control supply voltage 3.3V when temperature rises excessively. If system uses low voltage controller, it is recommended to insert a clamp Di between control supply of the controller and V<sub>OT</sub> output for preventing over voltage destruction.
- (3) In the case of not using  $V_{\text{OT}}$ , leave  $V_{\text{OT}}$  output NC (No Connection).

Refer the application note for this product about the usage of  $V_{\mbox{\scriptsize OT}}.$ 

### **MECHANICAL CHARACTERISTICS AND RATINGS**

Parameter	Cond	ition	Limits		Unit	
Parameter	Cond	llion	Min. Typ. Max.			Unit
Mounting torque	Mounting screw : M3 (Note 8)	Recommended 0.78N·m	0.59	-	0.98	N∙m
Terminal pulling strength	Load 9.8N	JEITA-ED-4701	10	-	-	s
Terminal bending strength	Load 4.9N, 90deg. bend JEITA-ED-4701		2	-	-	times
Weight			-	20	-	g
Heat-sink flatness	(Note 9)			-	100	μm

Note 8: Plain washers (ISO 7089~7094) are recommended. Note 9: Measurement point of heat sink flatness



### **RECOMMENDED OPERATION CONDITIONS**

Symbol	Parameter	Condition			Limits		Unit
Symbol	Falameter	Condition		Min.	Тур.	Max.	Unit
V <sub>cc</sub>	Supply voltage	Applied between P-NU, NV, NW		0	300	400	V
V <sub>D</sub>	Control supply voltage	Applied between $V_{P1}$ - $V_{NC}$ , $V_{N1}$ - $V_{NC}$		13.5	15.0	16.5	V
V <sub>DB</sub>	Control supply voltage	Applied between V <sub>UFB</sub> -V <sub>UFS</sub> , V <sub>VFB</sub> -V <sub>VFS</sub> , V	WFB-VWFS	13.0	15.0	18.5	V
$\Delta V_D, \Delta V_{DB}$	Control supply variation			-1	-	+1	V/µs
t <sub>dead</sub>	Arm shoot-through blocking time	For each input signal		1.5	-	-	μs
f <sub>PWM</sub>	PWM input frequency	Tf ≤ 100°C, T <sub>j</sub> ≤ 125°C		-	-	20	kHz
		$V_{CC} = 300V, V_D = 15V, P.F = 0.8,$	f <sub>PWM</sub> = 5kHz	-	-	3.5	Armo
IO	Allowable r.m.s. current		f <sub>PWM</sub> = 15kHz	-	-	3.2	Arms
PWIN(on)					-	-	
PWIN(off)	Minimum input pulse width	(Note 11)		1.0		-	μs
V <sub>NC</sub>	V <sub>NC</sub> variation	Between V <sub>NC</sub> -NU, NV, NW (including surge)		-5.0	-	+5.0	V
Tj	Junction temperature			-20	-	+125	°C

Note 10: Allowable r.m.s. current depends on the actual application conditions.

11: DIPIPM might not make response if the input signal pulse width is less than PWIN(on), PWIN(off)

Fig. 5 Timing Charts of The DIPIPM Protective Functions

[A] Short-Circuit Protection (N-side only with the external shunt resistor and RC filter)

- a1. Normal operation: IGBT ON and outputs current.
- a2. Short circuit current detection (SC trigger)
  - (It is recommended to set RC time constant 1.5~2.0µs so that IGBT shut down within 2.0µs when SC.)
- a3. All N-side IGBT's gates are hard interrupted.
- a4. All N-side IGBTs turn OFF.
- a5.  $F_{\text{O}}$  outputs. The pulse width of the Fo signal is set by the external capacitor  $C_{\text{FO}}.$
- a6. Input = "L": IGBT OFF
- a7. Fo finishes output, but IGBTs don't turn on until inputting next ON signal (L $\rightarrow$ H).
- (IGBT of each phase can return to normal state by inputting ON signal to each phase.) a8. Normal operation: IGBT ON and outputs current.
  - Lower-side control a6 input SET ·?? RESET Protection circuit state v Internal IGBT gate SC trip current level a8₩ Output current Ic SC reference volta Sense voltage of the shunt resistor Delay by RC filtering

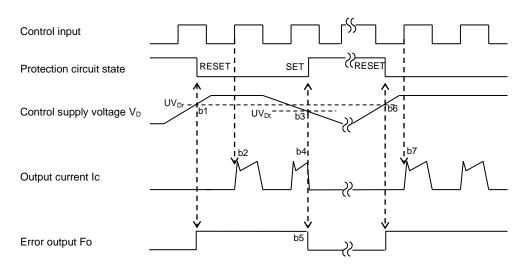
[B] Under-Voltage Protection (N-side, UV<sub>D</sub>)

Error output Fo

b1. Control supply voltage V<sub>D</sub> exceeds under voltage reset level (UV<sub>Dr</sub>), but IGBT turns ON by next ON signal (L $\rightarrow$ H). (IGBT of each phase can return to normal state by inputting ON signal to each phase.)

a5

- b2. Normal operation: IGBT ON and outputs current.
- b3. V<sub>D</sub> level drops to under voltage trip level. (UV<sub>Dt</sub>).
- b4. All N-side IGBTs turn OFF in spite of control input condition.
- b5. Fo outputs for the period set by the capacitance C<sub>FO</sub>, but output is extended during V<sub>D</sub> keeps below UV<sub>Dr</sub>.
- b6.  $V_D$  level reaches  $UV_{Dr}$ .
- b7. Normal operation: IGBT ON and outputs current.



[C] Under-Voltage Protection (P-side, UV<sub>DB</sub>)

- c1. Control supply voltage V<sub>DB</sub> rises. After the voltage reaches under voltage reset level UV<sub>DBr</sub>, IGBT turns on by next ON signal (L→H).
- c2. Normal operation: IGBT ON and outputs current.
- c3. V<sub>DB</sub> level drops to under voltage trip level (UV<sub>DBt</sub>).
- c4. IGBT of the correspond phase only turns OFF in spite of control input signal level, but there is no Fo signal output.
- c5.  $V_{DB}$  level reaches  $UV_{DBr}$ .
- c6. Normal operation: IGBT ON and outputs current.

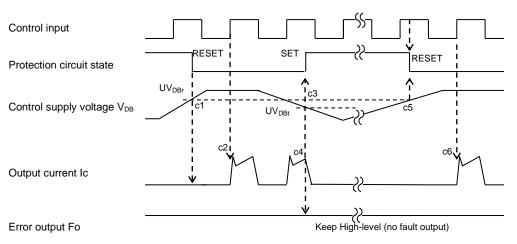
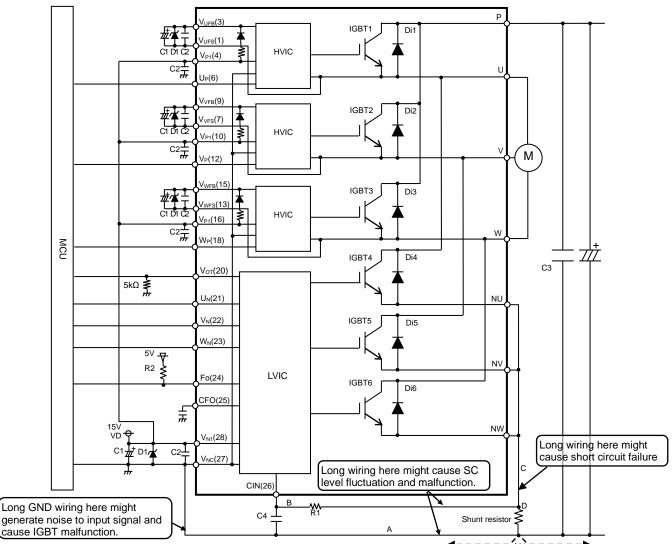


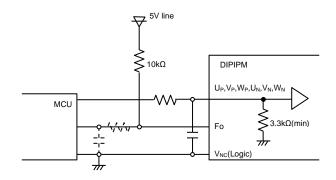
Fig. 6 Example of Application Circuit



Control GND wiring N1 Power GND wiring

- (1) If control GND is connected with power GND by common broad pattern, it may cause malfunction by power GND fluctuation. It is recommended to connect control GND and power GND at only a point N1 (near the terminal of shunt resistor).
- (2) It is recommended to insert a Zener diode D1(24V/1W) between each pair of control supply terminals to prevent surge destruction.
  (3) To prevent surge destruction, the wiring between the smoothing capacitor and the P, N1 terminals should be as short as possible. Generally a 0.1-0.22µF snubber capacitor C3 between the P-N1 terminals is recommended.
- (4) R1, C4 of RC filter for preventing protection circuit malfunction is recommended to select tight tolerance, temp-compensated type. The time constant R1C4 should be set so that SC current is shut down within 2µs. (1.5µs~2µs is recommended generally.) SC interrupting time might vary with the wiring pattern, so the enough evaluation on the real system is necessary.
- (5) To prevent malfunction, the wiring of A, B, C should be as short as possible.
- (6) The point D at which the wiring to CIN filter is divided should be near the terminal of shunt resistor. NU, NV, NW terminals should be connected at near NU, NV, NW terminals when it is used by one shunt operation. Low inductance SMD type with tight tolerance, temp-compensated type is recommended for shunt resistor.
- (7) All capacitors should be mounted as close to the terminals as possible. (C1: good temperature, frequency characteristic electrolytic type and C2:0.22µ-2µF, good temperature, frequency and DC bias characteristic ceramic type are recommended.)
- (8) Input logic is High-active. There is a 3.3kΩ(min.) pull-down resistor in the input circuit of IC. To prevent malfunction, the input wiring should be as short as possible. When using RC coupling, make the input signal level meet the turn-on and turn-off threshold voltage.
- (9) Fo output is open drain type. It should be pulled up to power supply of MCU (e.g. 5V,3.3V) by a resistor that makes I<sub>Fo</sub> up to 1mA. (I<sub>FO</sub> is estimated roughly by the formula of control power supply voltage divided by pull-up resistance. In the case of pulled up to 5V, 10kΩ (5kΩ or more) is recommended.) When using opto coupler, Fo also can be pulled up to 15V (control supply of DIPIPM) by the resistor.
- (10) Fo pulse width can be set by the capacitor connected to CFO terminal.  $C_{FO}(F) = 9.1 \times 10^{-6} \times t_{FO}$  (Required Fo pulse width).
- (11) If high frequency noise superimposed to the control supply line, IC malfunction might happen and cause DIPIPM erroneous operation. To avoid such problem, line ripple voltage should meet dV/dt ≤+/-1V/µs, Vripple≤2Vp-p.
- (12) For DIPIPM, it isn't recommended to drive same load by parallel connection with other phase IGBT or other DIPIPM.

Fig. 7 MCU I/O Interface Circuit

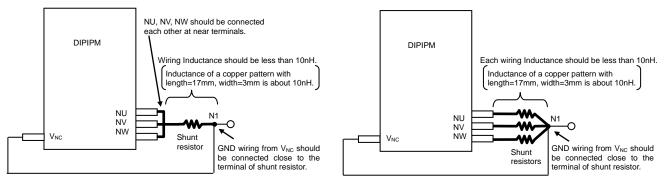


Note)

Design for input RC filter depends on PWM control scheme used in the application and wiring impedance of the printed circuit board. DIPIPM input signal interface integrates a minimum  $3.3 k\Omega$  pull-down resistor. Therefore, when inserting RC filter, it is necessary to satisfy turn-on threshold voltage requirement.

Fo output is open drain type. It should be pulled up to control power supply (e.g. 5V, 15V) with a resistor that makes Fo sink current  $I_{Fo}\,$  1mA or less. In the case of pulled up to 5V supply,  $10k\Omega$  $(5k\Omega \text{ or more})$  is recommended.

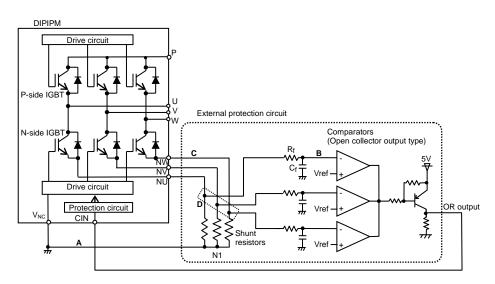
### Fig. 8 Pattern Wiring Around the Shunt Resistor



Low inductance shunt resistor like surface mounted (SMD) type is recommended.

### Fig. 9 Pattern Wiring Around the Shunt Resistor (for the case of open emitter)

When DIPIPM is operated with three shunt resistors, voltage of each shunt resistor cannot be input to CIN terminal directly. In that case, it is necessary to use the external protection circuit as below.



(1) It is necessary to set the time constant R<sub>1</sub>C<sub>f</sub> of external comparator input so that IGBT stops within 2µs when short circuit occurs.

SC interrupting time might vary with the wiring pattern, comparator speed and so on.

(2) It is recommended for the threshold voltage Vref to set to the same rating of short circuit trip level (Vsc(ref): typ. 0.48V). (3) Select the external shunt resistance so that SC trip-level is less than specified value (=2.0 times of rating current).

- (4) To avoid malfunction, the wiring A, B, C should be as short as possible.
- (5) The point D at which the wiring to comparator is divided should be close to the terminal of shunt resistor. (6) OR output high level when protection works should be over 0.51V (=maximum Vsc(ref) rating).
- (7) GND of Comparator, GND of Vref circuit and Cf should be not connected to power GND but to control GND wiring.

Fig. 10 Package Outlines PSSxxS51F6 (Short terminal type)

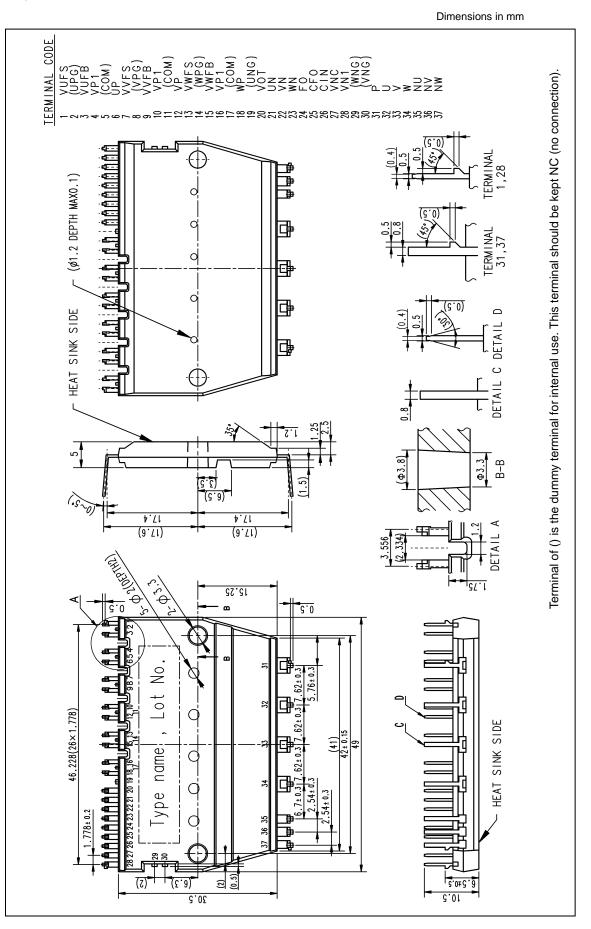
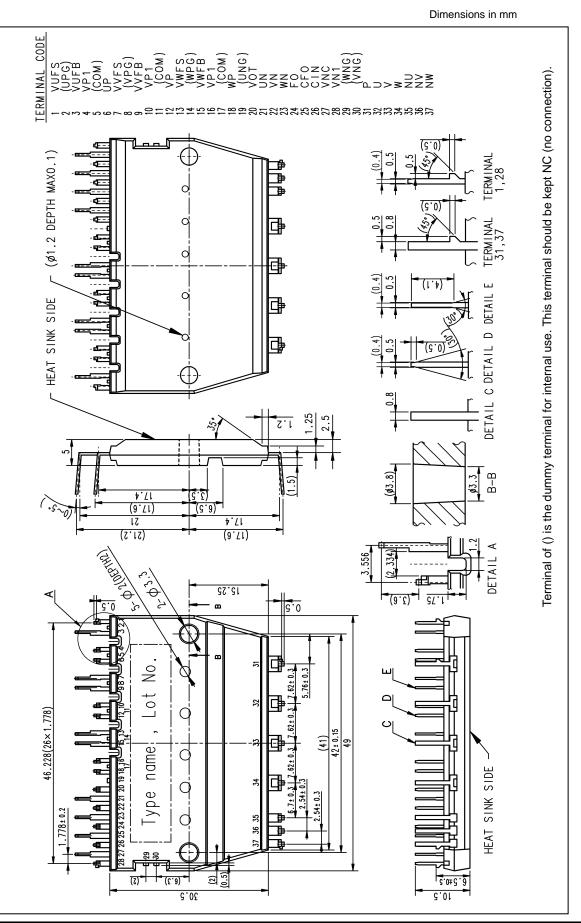


Fig. 11 Package Outlines PSSxxS51F6-C (Control side zigzag terminal type)



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